PCM-DAS16D/16
PCM-DAS16S/16

ComputerBoards, Inc.
Revision 3
March 1999

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1 INTRODUCTION

The PCM-DAS16x/16 is a data acquisition and control board for IBM PC compatible computers with PCMCIA type 2 slots. The heart of the board is an analog to digital converter. Analog signals are routed to the A/D via either an 8:1 differential multiplexor PCM-DAS16D/16 or a 16:1 single ended multiplexor PCM-DAS16S/16 controlled by a register on the PCM-DAS16x/16. The analog input range is fully programmable in several bipolar ranges. An on board pacer clock and external pacer input as well as software polling may trigger A/D conversions. Transfers may be via software polling, interrupt service or REP-INSW. A FIFO buffer provides buffering between the A/D circuit and the PCMCIA bus. Eight digital I/O lines (8 in or out , or, 4 in 4 out) provide a means of sensing and controlling discrete events.

2 WINDOWS 95, 98 INSTALLATION

2.1 INSTALL THE *Insta*Cal SOFTWARE PACKAGE

2.1.1 INTRODUCTION

*Insta*Cal is the installation, calibration and test software supplied with your data acquisition / IO hardware. The complete *Insta*Cal package is also included with the Universal Library. If you have ordered the Universal Library, use the Universal Library disk set to install *Insta*Cal. The installation will create all required files and unpack the various pieces of compressed software. To install *Insta*Cal, simply run setup.exe, and follow the on-screen instructions.

2.1.2 INSTALLATION OPTIONS

If you are installing on a Windows 95 or 98 operating system, the "Installation Options" dialog box will allow you to install the 16 bit, the 32 bit or both versions of *Insta*Cal. Select the 32 bit version unless you intend to use a 16 bit application or library to control your data acquisition hardware.

If you are installing from the Universal Library disk set, the "Installation Options" dialog box also presents options to install example programs for each language supported. Select the appropriate example programs for the language you will be using.

2.1.3 FILE DEFAULT LOCATION

*Insta*Cal will place all appropriate files in "C:\CB." If you change this default location remember where the installed files are placed as you may need to access them later.

2.1.4 INSTALLATION QUESTIONS

At the end of the installation process there will be a series of questions: unless you have knowledge to the contrary, simply accept the default when prompted.

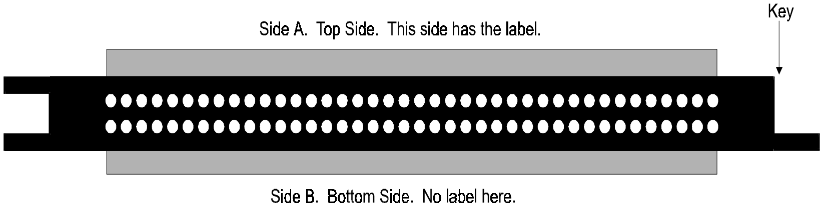
2.1.5 INSTALLATION COMPLETION

After the installation of *Insta*Cal is complete you should restart your computer to take advantage of changes made to the system.

2.2 INSTALL THE PCMCIA CARD

Your PCM card is completely plug and play. There are no switches or jumpers to set prior to installation in your computer. Simply follow the steps shown below to install your PCM - hardware.

1. Insert the card into a free PC Card/PCMCIA type II or III slot. You do not have to turn the computer off. The system is designed for power on installation. Shown here is a PCM card case looking into the connector which is inserted into the PCMCIA slot of your computer. The KEY helps to insure that the PCM board is inserted in the correct orientation.



PCMCIA CARD ORIENTATION - View into PCMCIA connector. The end which goes into the PCMCIA slot.

2. If the appropriate drivers are already loaded on the PC, the card should be detected, recognized, and configured by Windows and you should hear an insertion beep. If the card is not detected by Windows, go to step 3. To verify the card has been recognized, go to Control Panel\System\Device Manager and the card should now appear under "DAS Component." If your card appears in the list you can now proceed to the "RUN *Insta*Cal" section of this manual.

3. If the drivers are not already loaded on the PC, you will be prompted for a driver. If you are not prompted for a driver after inserting the card, go to step 4. The appropriate driver is located on disk 1 of the installation disk set. Insert this disk. Windows should detect the driver file automatically, install it and then the card should be detected by Windows and you should hear an insertion beep. To verify the card has been recognized, go to Control Panel\System\Device Manager and the card should now appear under "DAS Component." If your card appears in the list you can now proceed to the "RUN *Insta*Cal" section of this manual.

4. If the card is not detected by Windows and you are not prompted for a driver after inserting the card, check that your computer's 32-bit PCMCIA drivers are enabled. If they are not, enable them and then restart your computer and try the above procedure again.

2.3 RUN *Insta*Cal

Run the *Insta*Cal program in order to configure the board for run-time use. By configuring the board, you add information to the configuration file, cb.cfg, that is used by the Universal Library and other third-party data acquisition packages that use the Universal Library to access the board.

2.3.1 RUNNING THE 32 BIT VERSION

You can run the 32 bit version of *Insta*Cal by finding the file named "inscal32.exe" in your installation directory and double clicking it. You can also run *Insta*Cal by going to your Start Menu then to Programs, then to ComputerBoards, and finally choosing *Insta*Cal.

If you have a PCM board inserted in a PCM slot in your computer, *Insta*Cal displays a dialog box indicating the device has been detected. Simply click "OK" to proceed with InstaCal.

If there are no other boards currently installed by *Insta*Cal, then the PCM board will be assigned board number 0. Otherwise it will be assigned the next available board number.

You can now view and change the board configuration by clicking the properties icon or selecting the Install\Configure menu.

2.3.2 RUNNING THE 16 BIT VERSION

You can run the 16 bit version of *Insta*Cal by finding the file named "instacal.exe" in your installation directory and double clicking it. You can also run *Insta*Cal by going to your Start Menu then to Programs, then to ComputerBoards, and finally choosing "InstaCal 16."

If you have a PCM board inserted in a PCM slot in your computer, *Insta*Cal displays a dialog box titled "Add PCM Card." Select "Yes." The next dialog box allows you to select a board number. Choose the default (0 if no other cards are already installed) or select a board number.

You can now select the Install menu (using the mouse or the letter "I" on the keyboard) to view or change the configuration of the board.

2.4 TESTING THE INSTALLATION

After you have run the install program, it is time to test the installation. The following section describes the *Insta*Cal procedure to test that your board is properly installed.

With *Insta*Cal running:

1. Select the board you just installed.

2. Select the "Test" function.

Follow the instructions provided to test for proper board operation.

3 WINDOWS 3.X OR DOS INSTALLATION

3.1 INSTALL THE *Insta*Cal SOFTWARE PACKAGE

*Insta*Cal is the installation, calibration and test software supplied with your data acquisition / IO hardware. The complete *Insta*Cal package is also included with the Universal Library. If you have ordered the Universal Library, use the Universal Library disk set to install Instacal. The installation will create all required files and unpack the various pieces of compressed software. To install *Insta*Cal, simply run setup.exe, and follow the on-screen instructions.

3.1.1 INSTALLATION OPTIONS

If you are installing from the Universal Library disk set, the "Installation Options" dialog box presents options to install libraries and example programs for each language supported. Select the appropriate library version and example programs for the language you will be using.

If your computer does not have the Windows operating system installed (only the DOS operating system is available), install the separate DOS-only InstaCal package called "InstaCal for DOS, Universal Library for DOS" available from your vendor.

Computers running Windows 3.x and/or DOS need to use the DOS based Card & Socket Services (CSS) drivers. CSS is included with most newer computers, but if you need to purchase these drivers, they are available from your vendor (order PCM CSS). During the InstaCal installation, you will be prompted to indicate whether or not to install CBCLIENT. Respond "Yes." CBCLIENT is used by CSS to configure the PCMCIA data acquisition cards. Remember, if you do not have CSS loaded, install it before attempting to use the PCMCIA card. More information about CSS is available in section 3.5 titled "About DOS Card & Socket Services."

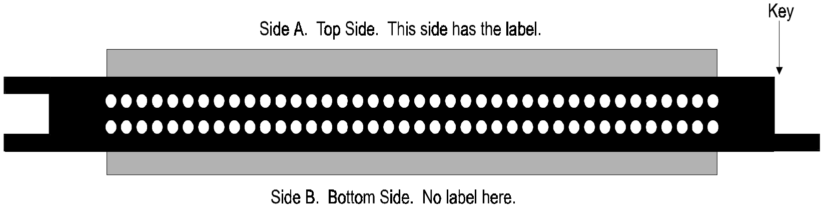
*Insta*Cal will place all appropriate files in "C:\CB." If you change this default location remember where the installed files are placed as you may need to access them later. At the end of the installation process there will be a series of questions: unless you have knowledge to the contrary, simply accept the default when prompted.

After the installation of *Insta*Cal is complete you should restart your computer to take advantage of changes made to the system.

3.2 INSTALL THE PCMCIA CARD

Insert the card into a free PCM card slot and wait for the insertion tone (a double beep).

Shown here is a PCM card case looking into the connector which is inserted into the PCMCIA slot of your computer. The KEY helps to insure that the PCM board is inserted in the correct orientation.



PCMCIA CARD ORIENTATION - View into PCMCIA connector. The end which goes into the PCMCIA slot.

3.3 RUN *Insta*Cal

Run the *Insta*Cal program in order to configure the board for run-time use. By configuring the board, you add information to the configuration file, cb.cfg, that is used by the Universal Library and other third-party data acquisition packages that use the Universal Library to access the board.

To run *Insta*Cal in Windows 3.x, find the file named InstaCal.exe in your installation directory or simply double click the InstaCal.exe icon.

From DOS, jsut type "Instacal" at the DOS prompt and hit "Enter."

If you have a PCM board inserted in a PCM slot in your computer, *Insta*Cal displays a dialog box titled "Add PCM Card." Select "Yes." The next dialog box allows you to select a board number. Choose the default (0 if no other cards are already installed) or select a board number.

You can now select the install menu (using the mouse or the letter "I" on the keyboard) to view or change the configuration of the board.

3.4 TESTING THE INSTALLATION

After you have run the install program and set your base address with *Insta*Cal, it is time to test the installation. The following section describes the *Insta*Cal procedure to test that your board is properly installed.

With *Insta*Cal running, choose the TEST item on the main menu.

a. Select the board you just installed

b. If the choice “Internal Test” is available, then select Internal Test. If not, proceed to "e." below.

c. The internal control registers of the board will then be tested. If this test is successful, your board is installed correctly.

d. If the Internal Test is completed successfully, you may want to check that the I/O pins are working correctly. To check this select External Test and follow the instruction provided. This will require you to use the shorting wires supplied with the board to connect inputs to outputs for I/O testing. Some external tests may require an external voltage source and ohmmeter. All required equipment and connections will be listed by *Insta*Cal.

e. If the “I/O Test Menu” lists the option “Plot”, the select it and make the connections as shown to test your card.

3.5 ABOUT DOS CARD & SOCKET SERVICES

The following section describes Card & Socket Services and should help you determine whether or not you need to install CSS.

Some operating systems, such as Windows 95, include an integrated version of CSS. If you are running such an operating system, do not install DOS CSS unless you have a specific reason to do so.

Card and socket services for your PCM card are on a disk labeled "DOS Card & Socket Services." The software from that disk should be installed if you do not already have CSS support on your PC.

3.5.1 WHAT IS CSS?

CSS is a program that communicates with your computers PCMCIA interface controller and configures it. The PCMCIA interface is configurable, unlike the standard ISA bus you may be familiar with. If you plug a PCMCIA board into a PCMCIA slot and have not yet run CSS, you will have no access to the functions of that PCMCIA board.

3.5.2 DOES CSS USE SYSTEM RESOURCES?

Yes. The CardSoft Card and Socket Services device drivers which are installed in your CONFIG.SYS use about 61K of memory. These files can be installed DEVICE-HIGH.

The CBCLIENT.EXE installed in your AUTOEXEC.BAT uses about 10K of memory. The CBCLIENT.EXE program is a TSR (Terminate and Stay Resident). You may modify the program line to LOADHIGH the TSR. We have tested it both high and low with and without Windows and a variety of other applications. We believe it is a safe TSR that will not cause any system problems.

3.5.3 HOW DO I KNOW CSS IS INSTALLED AND RUNNING?

There is a simple test. Just plug in your PCM-card. If CSS is installed and working the computer will beep. You can remove and replace your PCM-card as often as you like and need not power down to do so. The computer should beep each time you insert the PCM-card.

3.5.4 WHAT ABOUT CSS FOR MULTIPLE PCM BOARDS?

Once the current version of CSS is installed, CSS is installed for all PCM boards included in that version of CSS. As new PCM boards become available, they will be added to the CSS and you will want to always have the most recent version of CBCLIENT.EXE installed in the C:\CB directory. Let the installation software do this for you.

You can run multiple PCMCIA boards with the CBCLIENT.EXE CSS, and, if you have another CLIENT program running for other PCMCIA boards, it will not interfere.

4 OPERATION

4.1 ANALOG RESOLUTION & RANGE

The 16 bit A/D converter provides a resolution of 1/65,536 parts of full scale. The smallest reading of full scale (1 part in 65,536) is called a Least Significant Bit (LSB). Accuracy is specified in LSBs. The PCM-DAS16x/16 is accurate to +/- 1.5 LSB. Four different bipolar ranges are fully controlled by software. These are:

Bipolar	1LSB
+/-10V	0.000305V
+/-5V	0.000153V
+/-2.5V	0.000076V
+/-1.25V	0.000038V

The input range is controlled by a programmable amplifier and is completely under software control.

4.2 CONVERSION SPEED & AMPLIFICATION

The A/D chip always runs at full speed. The A/D converter and sample & hold circuit captures and digitizes a signal in 10 microseconds (10uS). The conversion speed of the A/D remains constant in all conditions and at all throughput rates. This is important. When you request a sample rate of say 20KHz, the A/D converter is still converting the signal in 10uS. The 20KHz rate comes from the fact that conversions are being initiated only every 50uS.

What factors limit conversion speed?
The first is clearly the A/D. A 10uS conversion speed translates to a maximum throughput of 100KHz. The second limiting factor may be the analog front end.

The front end may consist of a multiplexor and a programmable gain amplifier. The speed at which these circuits can switch may also limit the throughput of the A/D board. That is, the rate at which it can acquire, convert and transfer a signal with full accuracy. Accuracy is the key term here. The A/D can always run at full speed, but has the front end settled and captured a true, accurate signal?

What about input range vs. speed?

Here is where the design of the analog front end is critical to maintaining total throughput. Every A/D chip has a fixed input range, typically +/-5V. It is the analog front end that amplifies low level signals and adjusts unipolar signals to match the A/D converter's standard input.

A poorly designed analog front end will show up very quickly in the throughput specifications. If you see that an A/D board has high throughput in only one or two ranges but is slowed greatly at all other ranges, you are seeing the practical implications of a poor front end design. The PCM-DAS16x/16 achieves 100KHz in all of the four ranges.

4.3 TRIGGERING & TRANSFER

A Trigger is the event that begins an acquisition/transfer cycle. There are three ways to trigger a PCM-DAS16x/16; programmable pacer, software or external. The trigger source is programmable. The programmable pacer is the product of two 16 bit counters dividing a 10MHz or 1MHz wave derived from a 10MHz XTAL which may be used to trigger any number of paced conversions. A single conversion may be triggered by software at any time. External trigger, pacer clock and interrupt signals may also be used to control conversions and synchronize to external events.

Once a conversion is made the sample is placed into a 512 sample FIFO buffer from which it may be retrieved one sample at a time or in blocks via REP-INSW transfers.

***How do FIFO size and design affect throughput*?**

The FIFO buffer stores samples from the A/D converter as they are being converted. When a block of samples is ready and when the PC is ready, the FIFO is emptied into system memory. A properly designed FIFO of the correct size is a requirement for Windows, or samples will be lost at all but the slowest speeds.

Design of the FIFO is critical. Simply having a FIFO is not enough. Most FIFO designs employ a half-full transfer initiation circuit. When the FIFO is half full, the transfer request is made. Samples continue to fill the second half of the FIFO while the CPU responds to the transfer request and transfers data to system memory.

Some other manufacturer's boards have only a 'FIFO full' circuit. What do you think happens to samples taken after the FIFO is full while waiting for the CPU to begin unloading the FIFO?

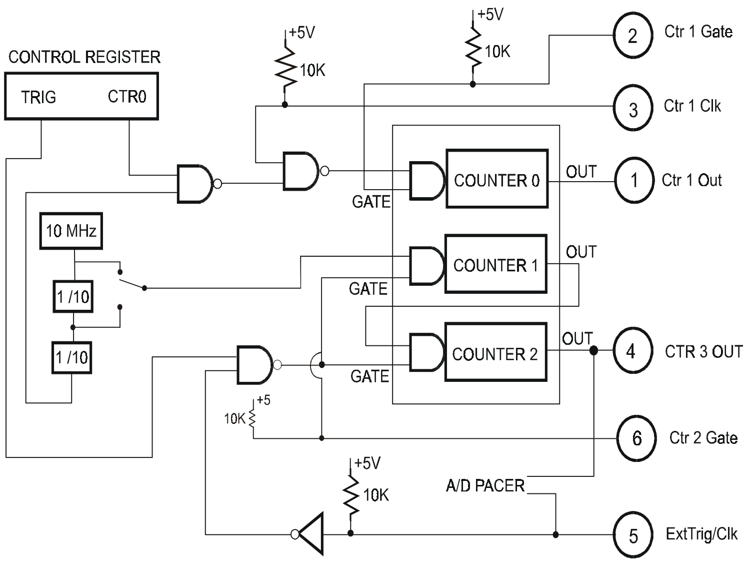
FIFO size is critical also. We have seen boards with FIFOs as small as 16 samples. The PCM-DAS16x/16 has a 512 sample FIFO buffer! A size we have determined through extensive testing to be a requirement for real situations.

4.4 A/D PACER CLOCK

Many analog acquisitions can be handled by a simple on-board rate divider created by combining an XTAL with a programmable counter. For those, the on-board 82C54 programmable rate generator supplies the pacing. Some applications require more flexible rate control.

The PCM-DAS16x/16 analog conversions may be externally triggered and thereby synchronized with events external to the PC. Conversions may be held off until some external event, such as a not-to-exceed condition is met. Conversions may be externally gated so that samples are taken only when an event of interest is occurring, such as process over normal limits.

Shown here is the A/D pacer clock schematic and the routing of off board trigger signals.



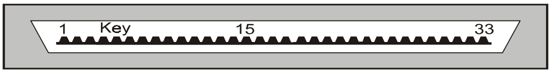
CLOCK, PACER & INTERRUPT CONTROL

5 I/O CONNECTOR

The PCM-DAS16S/16 has 16 single ended analog inputs. The PCM-DAS16D/16 has 8 differential inputs. Both boards have an analog ground, 1 A/D trigger input, 1 interrupt input, 1 gate input, complete access to one 16 bit counter's clock, gate and output lines, and access to the A/D pacer's counter output line and 8 digital output/inputs. A digital ground is in the cable shield clips to either side of the 33 pins of the connector as well as one of the connector pins. Please look at the connector diagram for your board.

5.1 PCM-DAS16x/16 CONNECTOR

Shown here is a PCM-DAS16S/16 and PCM-DAS16D/16 case looking into the connector which a signal cable or screw terminal box and cable are connected to. The KEY helps to insure that the cable is inserted in the correct orientation.



Chassis Ground & Digital Ground on Connector Housing & Shield

Pin	8 CHANNEL DIFFERENTIAL	Pin	16 CHANNEL SINGLE-ENDED
1	Ctr 1 Out	1	Ctr 1 Out
2	Ctr 1 Gate	2	Ctr 1 Gate
3	Ctr 1 Clk	3	Ctr 1 Clk
4	Ctr 3 Out	4	Ctr 3 Out
5	Ext Trig/Clk	5	Ext Trig/Clk
6	Ctr 2 Gate	6	Ctr 2 Gate
7	Ext Int	7	Ext Int
8	Digital Ground	8	Digital Ground
9	DIO 0	9	DIO 0
10	DIO 1	10	DIO 1
11	DIO 2	11	DIO 2
12	DIO 3	12	DIO 3
13	DIO 4	13	DIO 4
14	DIO 5	14	DIO 5
15	DIO 6	15	DIO 6
16	DIO 7	16	DIO 7
17	Analog Ground	17	Analog Ground
18	Channel 0 Low	18	Channel 0 High
19	Channel 0 High	19	Channel 1 High
20	Channel 1 Low	20	Channel 2 High
21	Channel 1 High	21	Channel 3 High
22	Channel 2 Low	22	Channel 4 High
23	Channel 2 High	23	Channel 5 High
24	Channel 3 Low	24	Channel 6 High
25	Channel 3 High	25	Channel 7 High
26	Channel 4 Low	26	Channel 8 High
27	Channel 4 High	27	Channel 9 High
28	Channel 5 Low	28	Channel 10 High
29	Channel 5 High	29	Channel 11 High
30	Channel 6 Low	30	Channel 12 High
31	Channel 6 High	31	Channel 13 High
32	Channel 7 Low	32	Channel 14 High
33	Channel 7 High	33	Channel 15 High

33 PIN I/O CONNECTOR

Analog signals should be connected with the high side to the numbered analog input and the low side to the low input or the analog ground. Please see the instructions for single-ended and differential inputs.

Digital signals should not be grounded to the analog ground. Use the cable shield or the digital ground pin.

INPUT WARNING!
Do not exceed the input specifications. There are no socketed or user serviceable parts in a PCM board. ***Any repair will be expensive.***

Analog inputs are limited to +/-15V, unlike the higher ratings of ISA boards.

If you apply a voltage < -0.5V or greater than 5.5V to a digital input, you will burn out the transistor.

Please turn now to the table of specifications and familiarize yourself with them <u>before</u> connecting any signals.

6 ANALOG CONNECTIONS

6.1 ANALOG INPUTS

Analog signal connection is one of the most challenging aspects of applying a data acquisition board. If you are an Analog Electrical Engineer then this section is not for you, but if you are like most PC data acquisition users, the best way to connect your analog inputs may not be obvious. Though complete coverage of this topic is well beyond the scope of this manual, the following section provides some explanations and helpful hints regarding these analog input connections. This section is designed to help you achieve the optimum performance from your PCM-DAS16x/16 series board.

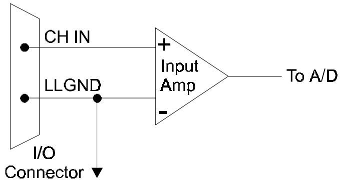
Prior to jumping into actual connection schemes, you should have at least a basic understanding of Single-Ended/Differential inputs and system grounding/isolation. If you are already comfortable with these concepts you may wish to skip to the next section (on wiring configurations).

6.1.1 Single-Ended and Differential Inputs

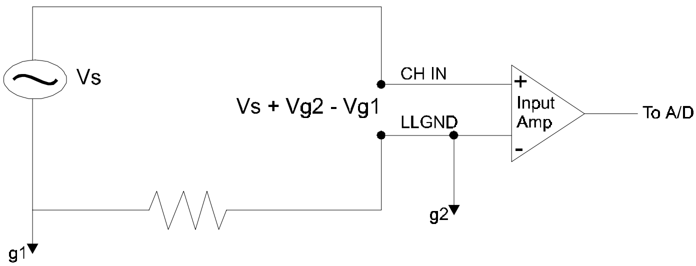
The PCM-DAS16x/16 provides either 8 differential or 16 single-ended input channels. The concepts of single-ended and differential inputs are discussed in the following section.

6.1.2 Single-Ended Inputs

A single-ended input measures the voltage between the input signal and ground. In this case, in single-ended mode the PCM-DAS16x/16 measures the voltage between the input channel and LLGND. The single-ended input configuration requires only one physical connection (wire) per channel and allows the PCM-DAS16x/16 to monitor more channels than the (2-wire) differential configuration using the same connector and onboard multiplexor. However, since the PCM-DAS16x/16 is measuring the input voltage relative to its own low level ground, single-ended inputs are more susceptible to both EMI (Electro Magnetic Interference) and any ground noise at the signal source. The following diagrams show the single-ended input configuration.



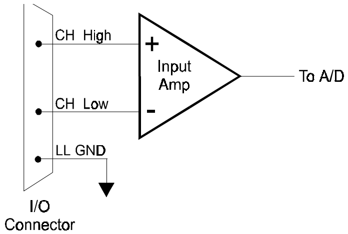
SINGLE-ENDED INPUT



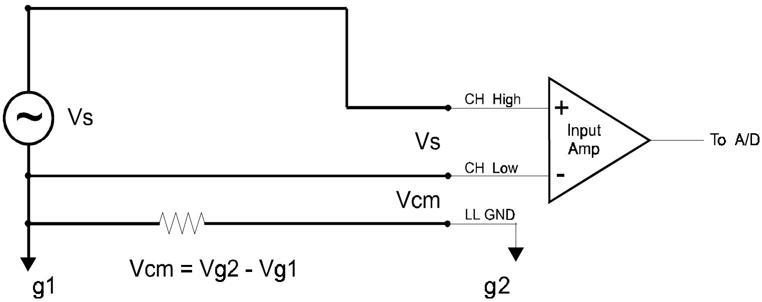
SINGLE-ENDED INPUT WITH COMMON MODE VOLTAGE - Any voltage differential between grounds g1 and g2 shows up as an error signal at the input amplifier.

6.1.3 Differential Inputs

Differential inputs measure the voltage between two distinct input signals. Within a certain range (referred to as the common mode range), the measurement is almost independent of signal source to PCM-DAS16x/16 ground variations. A differential input is also much more immune to EMI than a single-ended one. Most EMI noise induced in one lead is also induced in the other, the input only measures the difference between the two leads, and the EMI common to both is ignored. This effect is a major reason there is twisted pair wire as the twisting assures that both wires are subject to virtually identical external influence. The diagram below shows a typical differential input configuration.

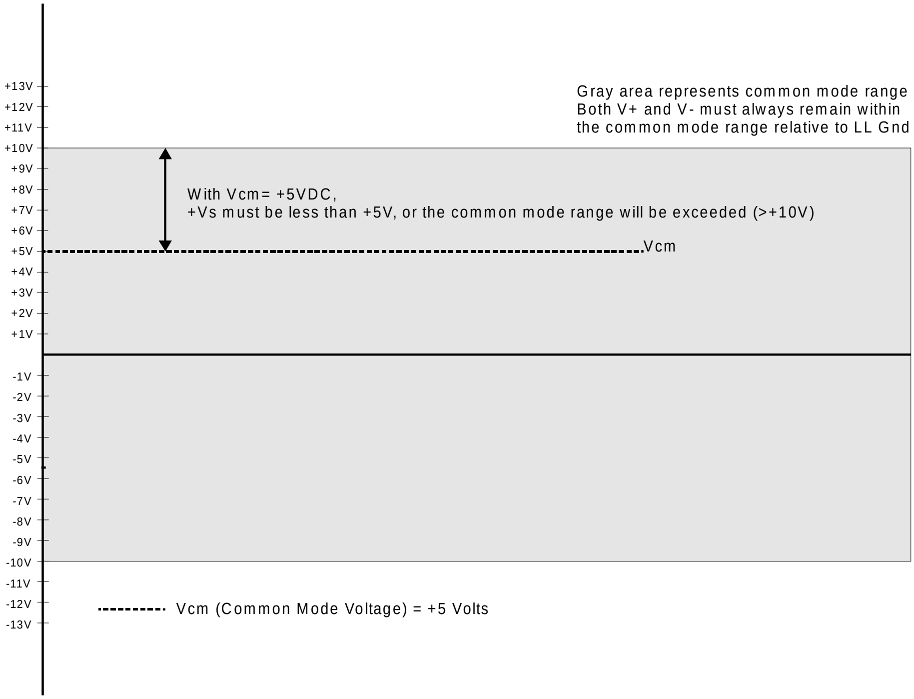


DIFFERENTIAL INPUT



DIFFERENTIAL INPUT - Common Mode Voltage (Vcm) is ignored by differential input configuration. However, note that Vcm + Vs must remain within the amplifier's common mode range of ±10V.

Before moving on to the discussion of grounding and isolation, it is important to explain the concepts of common mode, and common mode range (CM Range). Common mode voltage is depicted in the diagram below as Vcm. Though differential inputs measure the voltage between two signals, without (almost) respect to the either signal's voltages relative to ground, there is a limit to how far away from ground either signal can go. Though the PCM-DAS16x/16 has differential inputs, it will not measure the difference between 100V and 101V as 1 Volt (in fact the 100V would destroy the board!). This limitation or common mode range is depicted graphically in the following diagram. The PCM-DAS16x/16 common mode range is +/- 10 Volts. Even in differential mode, no input signal can be measured if it is more than 10V from the board's low level ground (LLGND).



6.1.4 System Grounds and Isolation

There are three scenarios possible when connecting your signal source to your PCM-DAS16x/16 board.

1. The PCM-DAS16x/16 and the signal source may have the same (or common) ground. This signal source may be connected directly to the PCM-DAS16x/16.

2. The PCM-DAS16x/16 and the signal source may have an offset voltage between their grounds (AC and/or DC). This offset it commonly referred to a common

mode voltage. Depending on the magnitude of this voltage, it may or may not be possible to connect the PCM-DAS16x/16 directly to your signal source. We will discuss this topic further in a later section.

3. The PCM-DAS16x/16 and the signal source may already have isolated grounds. This signal source may be connected directly to the PCM-DAS16x/16.

6.1.5 Which system do you have?

Try the following experiment. Using a battery powered voltmeter[1], measure the voltage (difference) between the ground signal at your signal source and at your PC. Place one voltmeter probe on the PC ground and the other on the signal source ground. Measure both the AC and DC Voltages.

If both AC and DC readings are 0.00 volts, you may have a system with common grounds. However, since voltmeters will average out high frequency signals, there is no guarantee. Please refer to the section below titled Common Grounds.

If you measure reasonably stable AC and DC voltages, your system has an offset voltage between the grounds category. This offset is referred to as a Common Mode Voltage. Please be careful to read the following warning and then proceed to the section describing Common Mode systems.

WARNING

If either the AC or DC voltage is greater than 10 volts, do not connect the PCM-DAS16x/16 to this signal source. You are beyond the boards usable common mode range and will need to either adjust your grounding system or add special Isolation signal conditioning to take useful measurements. A ground offset voltage of more than 30 volts will likely damage the PCM-DAS16x/16 board and possibly your computer. Note that an offset voltage much greater than 30 volts will not only damage your electronics, but it may also be hazardous to your health.

This is such an important point, that we will state it again. If the voltage between the ground of your signal source and your PC is greater than 10 volts, your board will not take useful measurements. If this voltage is greater than 30 volts, it will likely cause damage, and may represent a serious shock hazard! In this case you will need to either reconfigure your system to reduce the ground differentials, or purchase and install special electrical isolation signal conditioning.

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[1]*If you do not have access to a voltmeter, skip the experiment and take a look at the following three sections. You may be able to identify your system type from the descriptions provided.*

If you cannot obtain a reasonably stable DC voltage measurement between the grounds, or the voltage drifts around considerably, the two grounds are most likely isolated. The easiest way to check for isolation is to change your voltmeter to it's ohm scale and measure the resistance between the two grounds. It is recommended that you turn both systems off prior to taking this resistance measurement. If the measured resistance is more than 100 Kohm, it's a fairly safe bet that your system has electrically isolated grounds.

6.1.7 Systems with Common Grounds

In the simplest (but perhaps least likely) case, your signal source will have the same ground as the PCM-DAS16x/16. This would typically occur when providing power or excitation to your signal source directly from the PCM-DAS16x/16. There may be other common ground configurations, but it is important to note that any voltage between the PCM-DAS16x/16 ground and your signal ground is a potential error voltage if you set up your system based on a common ground assumption.

As a safe rule of thumb, if your signal source or sensor is not connected directly to an LLGND pin on your PCM-DAS16x/16, it's best to assume that you do not have a common ground even if your voltmeter measured 0.0 Volts. Configure your system as if there is ground offset voltage between the source and the PCM-DAS16x/16.

6.1.8 Systems with Common Mode (ground offset) Voltages

The most frequently encountered grounding scenario involves grounds that are somehow connected, but have AC and/or DC offset voltages between the PCM-DAS16x/16 and signal source grounds. This offset voltage my be AC, DC or both and may be caused by a wide array of phenomena including EMI pickup, resistive voltage drops in ground wiring and connections, etc. Ground offset voltage is a more appropriate term to describe this type of system, but since our goal is to keep things simple, and help you make appropriate connections, we'll stick with our somewhat loose usage of the phrase Common Mode.

6.1.9 Small Common Mode Voltages

If the voltage between the signal source ground and PCM-DAS16x/16 ground is small, the combination of the ground voltage and input signal will not exceed the PCM-DAS16D/16 maximum input voltage, stays within +/-10V), This input is compatible with the PCM-DAS16x/16 and the system may be connected without additional signal conditioning. Fortunately, most systems will fall in this category and have a small voltage differential between grounds.

6.1.10 Large Common Mode Voltages

If the ground differential is large enough, the PCM-DAS16D/16 +/- 10V common mode range will be exceeded (i.e. the voltage between PCM-DAS16x/16 and signal source grounds, added to the maximum input voltage you're trying to measure exceeds +/-10V). In this case the PCM-DAS16x/16 cannot be directly connected to the signal source. You will need to change your system grounding configuration or add isolation signal conditioning. (Please look at our ISO-RACK and ISO-5B-series products to add electrical isolation, or give our technical support group a call to discuss other options).

NOTE

Relying on the earth prong of a 120VAC for signal ground connections is not advised.. Different ground plugs may have large and potentially even dangerous voltage differentials. Remember that the ground pins on 120VAC outlets on different sides of the room may only be connected in the basement. This leaves the possibility that the "ground" pins may have a significant voltage differential (especially if the two 120 VAC outlets happen to be on different phases!)

6.1.11 PCM-DAS16x/16 and Signal Source already have Isolated Grounds

Some signal sources will already be electrically isolated from the PCM-DAS16x/16. The diagram below shows a typical isolated ground system. These signal sources are often battery powered, or are fairly expensive pieces of equipment (since isolation is not an inexpensive proposition), isolated ground systems provide excellent performance, but require some extra effort during connections to assure optimum performance is obtained. Please refer to the following sections for further details.

6.2 WIRING CONFIGURATIONS

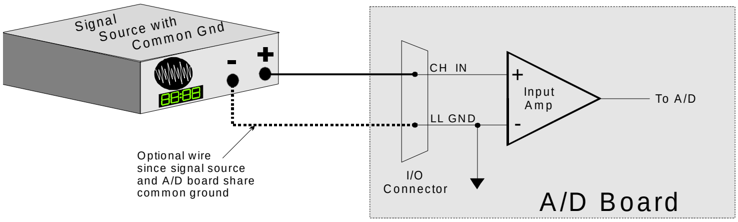
Combining all the grounding and input type possibilities provides us with the following potential connection configurations. The combinations along with our recommendations on usage are shown in the chart below.

GROUND CATEGORY	INPUT CONFIGURATION	OUR VIEW
Common Ground	Single-Ended Inputs	Recommended
Common Ground	Differential Inputs	Acceptable
Common Mode Voltage < +/-10V	Single-Ended Inputs	Not Recommended
Common Mode Voltage < +/-10V	Differential Inputs	Recommended
Common Mode Voltage > +/- 10V	Single-Ended Inputs	Unacceptable without adding Isolation
Common Mode Voltage > +/-10V	Differential Inputs	Unacceptable without adding Isolation
Already Isolated Grounds	Single-ended Inputs	Acceptable
Already Isolated Grounds	Differential Inputs	Recommended

The following sections depicts recommended input wiring schemes for each of the 8 possible input configuration/grounding combinations.

6.2.1 Common Ground / Single-Ended Inputs

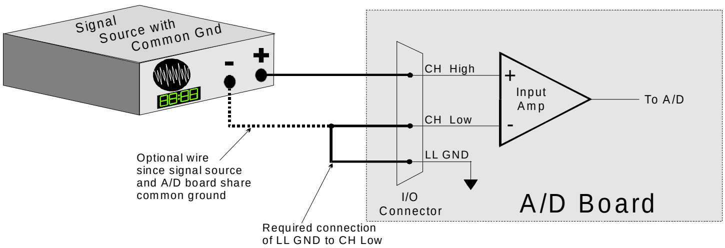
Single-ended is the recommended configuration for common ground connections. However, if some of your inputs are common ground and some are not, we recommend you use the differential mode. There is no performance penalty (other than loss of channels) for using a differential input to measure a common ground signal source. However the reverse is not true. The diagram below shows a recommended connection diagram for a common ground / single-ended input system.



Signal source and A/D board
sharing common ground connected
to single-ended input.

6.2.2 Common Ground / Differential Inputs

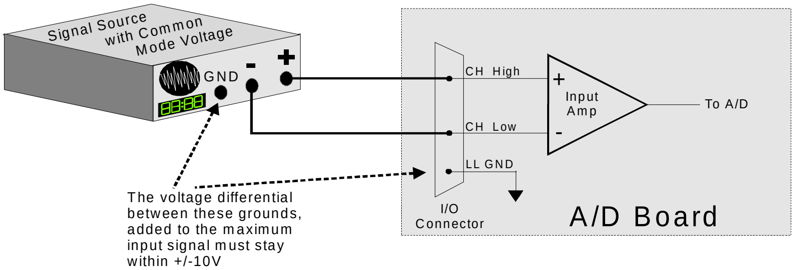
The use of differential inputs to monitor a signal source with a common ground is a acceptable configuration though it requires more wiring and offers fewer channels than selecting a single-ended configuration. The diagram below shows the recommended connections in this configuration.



Signal source and A/D board
sharing common ground connected
to differential input.

6.2.3 Common Mode Voltage < +/-10V/Single-Ended Inputs

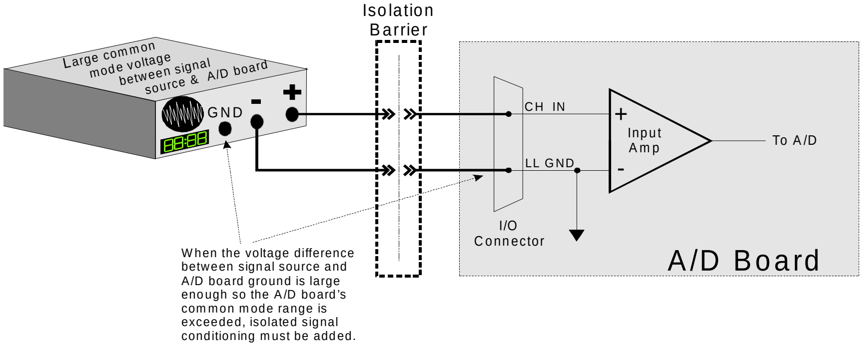
This is not a recommended configuration. In fact, the phrase common mode has no meaning in a single-ended system and this case would be better described as a system with offset grounds. Anyway, you are welcome to try this configuration, no system damage should occur and depending on the overall accuracy you require, you may receive acceptable results.



Signal source and A/D board with common mode voltage connected to a differential input.

6.2.4 Common Mode Voltage < +/-10V/Differential Inputs

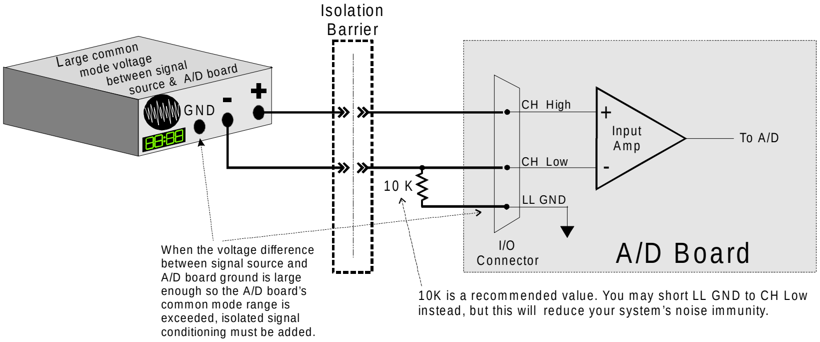
Systems with varying ground potentials should always be monitored in the differential mode. Care is required to assure that the sum of the input signal and the ground differential (referred to as the common mode voltage) does not exceed the common mode range of the A/D board (+/-10V on the PCM-DAS16x/16). The diagram below show recommended connections in this configuration.



System with a Large Common Mode Voltage, Connected to a Single-Ended Input

6.2.5 Common Mode Voltage > +/-10V

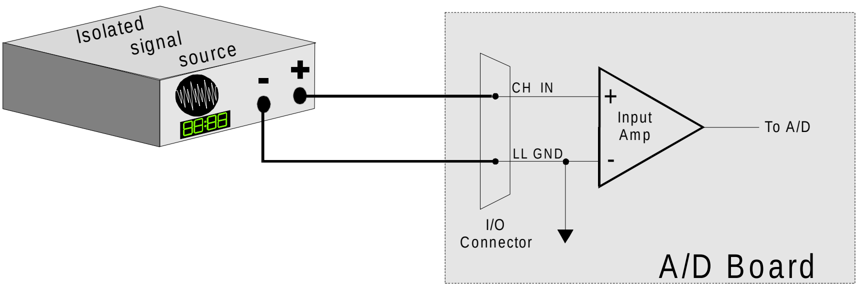
The PCM-DAS16x/16 will not directly monitor signals with common mode voltages greater than +/-10V. You will either need to alter the system ground configuration to reduce the overall common mode voltage, or add isolated signal conditioning between the source and your board.



System with a Large Common Mode Voltage,
Connected to a Differential Input

6.2.6 Isolated Grounds / Single-Ended Inputs

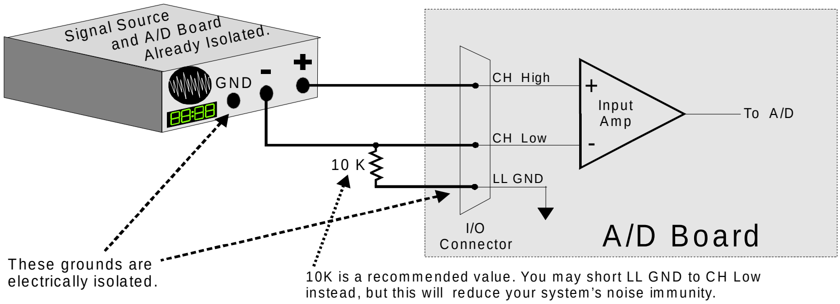
Single-ended inputs can be used to monitor isolated inputs, though the use of the differential mode will increase you system's noise immunity. The diagram below shows the recommended connections is this configuration.



Isolated Signal Source
Connected to a Single-Ended Input

6.2.7 Isolated Grounds / Differential Inputs

Optimum performance with isolated signal sources is assured with the use of the differential input setting. The diagram below shows the recommend connections is this configuration..



Already isolated signal source
and A/D board connected to
a differential input.

7 PROGRAMMING & APPLICATIONS

Your PCM-DAS16x/16 is now installed and ready for use. Although the PCM-DAS16x/16 is part of the larger DAS16 family, there is no correspondence between registers. Software written at the register level for the other DAS16's will not work with the PCM-DAS16x/16.

7.1 PROGRAMMING LANGUAGES

UniversalLibrary provides complete access to the PCM-DAS16x/16 functions from a range of programming languages; both DOS and Windows. If you are planning to write programs, or would like to run the example programs for Visual Basic or any other language, please turn now to the UniversalLibrary manual.

7.2 PACKAGED APPLICATIONS PROGRAMS

Many packaged application programs, such as Labtech Notebook now have drivers for the PCM-DAS16x/16. If the package you own does not appear to have drivers for the PCM-DAS16x/16 please fax the package name and the revision number from the install disks. We will research the package for you and advise by return fax how to obtain PCM-DAS16x/16 drivers.

8 CALIBRATION

The PCM-DAS16x/16 is calibrated via software. The case may not be opened and there are no parts inside which you can service. There are no socketed components.

The PCM-DAS16x/16 should not need re-calibration more frequently than once every six months. You can check the calibration of offset and gain at any time with InstaCal.

8.1 SOFTWARE CALIBRATION

If you are using the UniversalLibrary, you can set software calibration factors for off-set and gain using the Calibration option of *Insta*Cal. These factors will be applied to readings made by any of the A/D routines called from any of the language libraries of UniversalLibrary.

They are also stored in on-board EEPROM. The calibration factors are stored in the on-board EEPROM. Of course, the calibration factors may be recalculated at any time by running *Insta*Cal calibration.

Choose Calibration from the InstaCal menu, and follow the instructions. Press F1 for help.

9 I/O ADDRESS MAP & REGISTER FUNCTIONS

A base address register controls the beginning, or 'Base Address' of the I/O addresses occupied by the control registers of the PCM-DAS16x/16. In all, 16 addresses are occupied. The base address assigned by CSS read by InstaCAL and stored in the CB.CFG file installed in your computer. Please read about installing and using Insta-CAL.

9.1 CONTROL REGISTERS

Once CSS is installed and a base address has been established, the PCM-DAS16x/16 may be controlled by writing to and reading from the control registers. While it is possible to write your own control routines for the PCM-DAS16x/16, routines have been written and are available in ComputerBoards' Universal Library for DOS and Windows programming languages.

NOTE ON REGISTER PROGRAMMING SUPPORT

While the complete register map is explained here, only very limited support for assembly language or direct register programming is available. Register level programming should only be attempted by experieced programmers. We support the use of the PCM-D24/CTR3 through high level languages using UniversalLibrary and the expample programs provided.

Major functions of the control registers:

I/O ADDRESS	PCM-DAS16x/16 FUNCTION R | W
BASE + 0	A/D Data & Channel | Start A/D
BASE + 2	Digital In|Out & Channel Scan Limits
BASE + 4	Interrupt Control & Status
BASE + 6	Input Range and Trigger Method
BASE + 8	Counter 0 Read | Load
BASE + A	Counter 1 Read | Load
BASE + C	Counter 2 Read | Load
BASE + E	None | Counter Control

Interrupt Source Control
The interrupt source is controlled by three bits.

INT2	INT1	INT0	Source
0	0	1	Pacer - Counter 2
0	1	0	External - Pin 7
0	1	1	FIFO Not Empty
1	0	0	FIFO Half Full
1	0	1	End of Channel Scan

The A/D trigger source is controlled by two bits.

TS1	TS0	Source
0	X	Software Trigger
1	0	Rising Trigger Input, Pin 5
1	1	Pacer - Counter 2

The range of analog input is set by 4 bits.

G3	G2	G1	G0	Range
1	0	0	0	+/- 10 V
0	0	0	0	+/- 5 V (A/D Std.)
0	0	0	1	+/- 2.5 V
0	0	1	0	+/- 1.25 V

The digital I/O lines may be set as follows via 2 control bits.

UDIR	LDIR	Bits 7:4	Bits 3:0
0	0	Input	Input
0	1	Input	Output
1	0	Output	Input
1	1	Output	Output

10 CABLE & SCREW TERMINAL BOARD

The **PCM-C37/33** is a 10 inch 33 conductor cable assembly for use with 33 pin PCMCIA cards. The PCM-C37/33 has a connector on one end and a 37 pin D type connector at the other. The chart below describes the color coding of the wires for each of the 33 pins.

PIN	COLOR	PIN	COLOR	PIN	COLOR
1	Black	12	Pink	23	Red/White
3	Red	13	White/Blue	24	Black/White
3	White	14	White/Brown	25	White/Grey
4	Green	15	Blue/White	26	Red/Blue
5	Brown	16	Brown/White	27	Grey/White
6	Orange	17	White/Orange	28	Blue/Red
7	Blue	18	White/Green	29	Red/Orange
8	Yellow	19	Orange/White	30	Red/Green
9	Purple	20	Green/White	31	Orange/Red
10	Lt Brown	21	White/Red	32	Green/Red
11	Grey	22	White/Black	33	Green/Yellow

If you want to wire directly to your signal source, simply cut off the 37 pin connector and wire up the signals using the color to pin number guide above.

If you wish to use a screw terminal board, please purchase a CIO-MINI37 and connect it to the 37 pin connector end of the cable. Of course pins 34 to 37 will not have any function. Use the PCM-DAS16x/16 connector diagram elsewhere in this manual to determine the function of the signals at the screw terminals. The screw terminals are numbered 1 to 37, and the cable is wired so pin 1 of the PCM board connects to pin 1 of the screw terminal, and so on.

11 SPECIFICATIONS

11.1 POWER CONSUMPTION

+5V quiescent	65mA typical, 90mA max
+5V during CIS read	75mA typical, 110mA max

11.2 ANALOG

A/D converter type	ADS7805
Resolution	16 bits
Programmable ranges	±10V, ±5V, ±2.5V, ±1.25V
A/D pacing	Programmable: internal counter, external source (Ext Trig/Clk) or software polled
A/D Trigger sources	External polled gate trigger (Ext Trig/Clk)
A/D Triggering Modes	
Digital:	Gated pacer, software polled. (Gate must be disabled by software after trigger event.)
Data transfer	From 512 sample FIFO via REPINSW, interrupt, or soft ware polled
Polarity	Bipolar
Number of channels	
PCM-DAS16D/16	8 differential
PCM-DAS16S/16	16 single-ended

A/D conversion time	10µs
Throughput (post-process calibration)	100KHz min

Relative Accuracy (software calibrated)	±1.5LSB
Differential Linearity error	±1.5 LSB
Integral Linearity error	±1.5 LSB

Gain drift (A/D specs)	±410ppm/°C
Zero drift (A/D specs)	±305ppm/°C

Common Mode Range

PCM-DAS16D/16	±10V

CMRR @ 60Hz	
PCM-DAS16D/16	-76dB
Input leakage current	±20nA
Input impedance	10Meg Ohms min
Absolute maximum input voltage	±15V

Noise Distribution (Rate = 1-100KHz, Average % +/- 2 bins, Average % +/- 1 bin, Average # bins)

Bipolar (10V)	79% / 97% / 10 bins
Bipolar (5V)	84% / 97% / 12 bins
Bipolar (2.5V)	79% / 97% / 12 bins
Bipolar (1.25V)	57% / 68% / 14 bins

11.3 COUNTER

Counter type 82C54
Configuration 3 down counters, 16 bits each

Counter 0 - User counter 1
- Source: Programmable external (Ctr 1 Clk) or 100kHz internal source
- Gate: Available at connector (Ctr 1 Gate)
- Output: Available at connector (Ctr 1 Out)

Counter 1 - ADC Pacer Lower Divider
- Source: Programmable, 1MHz or 10 MHz internal source
- Gate: Available at connector (Ctr 2 Gate), pulled to logic high through 10k resistor
- Output: Chained to Counter 2 Clock

Counter 2 - ADC Pacer Upper Divider
- Source: Counter 1 Output
- Gate: Programmable, external (Ext Trig/Clk) or Not Connected (pulled high through 10k resistor)
- Output: Programmable as ADC Pacer clock, hardwired to user connector (Ctr 3 Out)

Clock input frequency	10Mhz max
High pulse width (clock input)	30ns min
Low pulse width (clock input)	50ns min
Gate width high	50ns min
Gate width low	50ns min
Input low voltage	0.8V max
Input high voltage	2.0V min
Output low voltage	0.4V max
Output high voltage	3.0V min

Crystal oscillator

Frequency	10MHz
Frequency accuracy	100ppm

11.4 DIGITAL INPUT/OUTPUT

Digital type	FPGA
Configuration	Two ports, four bits each. Programmable as 8 input / 8 output or 4 input / 4 output
Input low voltage	0.8V max
Input high voltage	2.0V min
Output low voltage (IOL = 4mA)	0.32V max
Output high voltage (IOH = -4mA)	3.86V min
Absolute maximum input voltage	-0.5V , +5.5V

Interrupts	Programmable: levels 2 - 15
Interrupt enable	Programmable
Interrupt sources	End-of-conversion, FIFO-half-full, external (Ext Int)

11.5 ENVIRONMENTAL

Operating temperature range	0 to 70°C
Storage temperature range	-40 to 100°C
Humidity	0 to 90% non-condensing

EC Declaration of Conformity

We, ComputerBoards, Inc., declare under sole responsibility that the product:

Part Number	Description
PCM-DAS16x/16	PCMCIA, High-Resolution analog input boards

to which this declaration relates, meets the essential requirements, is in conformity with, and CE marking has been applied according to the relevant EC Directives listed below using the relevant section of the following EC standards and other normative documents:

EU EMC Directive 89/336/EEC: Essential requirements relating to electromagnetic compatibility.

EU 55022 Class B: Limits and methods of measurements of radio interference characteristics of information technology equipment.

EN 50082-1: EC generic immunity requirements.

IEC 801-2: Electrostatic discharge requirements for industrial process measurement and control equipment.

IEC 801-3: Radiated electromagnetic field requirements for industrial process measurements and control equipment.

IEC 801-4: Electrically fast transients for industrial process measurement and control equipment.

Carl Haapaoja, Director of Quality Assurance

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