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## The TBX AMS 620 distributed input/output module

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### Subject of this chapter

This chapter presents the **TBX AMS 620** module, its characteristics and terminal wiring.

### What's in this Chapter?

This chapter contains the following topics:

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## Introduction to the TBX AMS 620 module

### General

The module **TBX AMS 620** is a module with 6 non-isolated high level analog inputs and 2 isolated outputs. It must be used with a **TBX LEP 030** communicator. This module can be used as a basic module or as an extension.

This module can provide each input with the following ranges:

- high level voltage: 0/5 V -10 V,
- high level current: 0/20 mA and -4/20 mA,

and the inputs on this module have the following ranges:

- high level voltage: 10 V,
- high level current: 0/20 mA and -4/20 mA.

### Technical specifications

The following table provides the technical specifications of the module.

<b>TBX AMS 620</b>		
<b>Supply voltage +SV</b>		19,2 to 60 V
<b>Nominal voltage +SV</b>		24 V      48 V
<b>Current drawn at +SV by the AMS used as a basic module (1)</b>		224 mA typically 321 mA max.      114 mA typically 164 mA max.
<b>Additional current drawn from a basic module when the AMS module is used as an extension</b>		59 mA typically 87 mA max.      30 mA typically 44 mA max.
<b>Current drawn at +SV by the AMS used as an extension</b>		162 mA typically 202 mA max.      84 mA typically 104 mA max.
<b>Isolation</b>	between input channels	non isolated
	between output channels	500 V rms - 50/60 Hz for 1 min
	between channels and ground (GND)	500 V rms - 50/60 Hz for 1 min
	between channel and supply	1500 V rms - 50/60 Hz for 1 min
<b>Permissible common mode voltage between channel and ground and between channels during operation</b>		150 V rms - 50/60 Hz for 1 min

## Characteristics of the outputs of module TBX AMS 620

### General characteristics of the inputs

This table presents the characteristics of the inputs of module **TBX AMS 620**:

Module <b>TBX AMS 620</b>					
<b>Number of channels</b>		6			
<b>Electrical range</b>		+ or -10 V	0/5 V	0/20 mA	4/20 mA
<b>Full scale (FS)</b>		10 V	5 V	20 mA	20 mA
<b>Resolution</b>		11 bits + sign	12 bits	12 bits	12 bits
<b>LSB</b>		5,13 mV	1,30 mV	4,97 $\mu$ A	4,97 $\mu$ A
<b>Converter</b>		by successive approximation			
<b>Maximum error</b>	at 25 °C	0,2 % FS	0,15 % FS	0,25 % FS	0,25 % FS
	at 60 °C	0,26 % FS	0,22 % FS	0,43 % FS	0,43 % FS
<b>Temperature drift</b>		20 ppm (FS) °C	15 ppm (FS) °C	40 ppm (FS) °C	40 ppm (FS) / °C
<b>Impedance</b>		10 M $\Omega$	10 M $\Omega$	250 M $\Omega$	250 M $\Omega$
<b>Time to read</b>	one channel	5,3 ms			
	6 channels	42.4 ms			
<b>Permissible overload</b>	voltage	+ or -30 V DC (voltage range)			
	current	30 mA ; + or -7.9 V (current range)			
<b>Digital filtering</b>		1° order with configurable time constant			
<b>Linearization</b>		automatic			
<b>Monotonocity</b>		Yes			

### General characteristics of the outputs

This table presents the characteristics of the outputs of module **TBX AMS 620**:

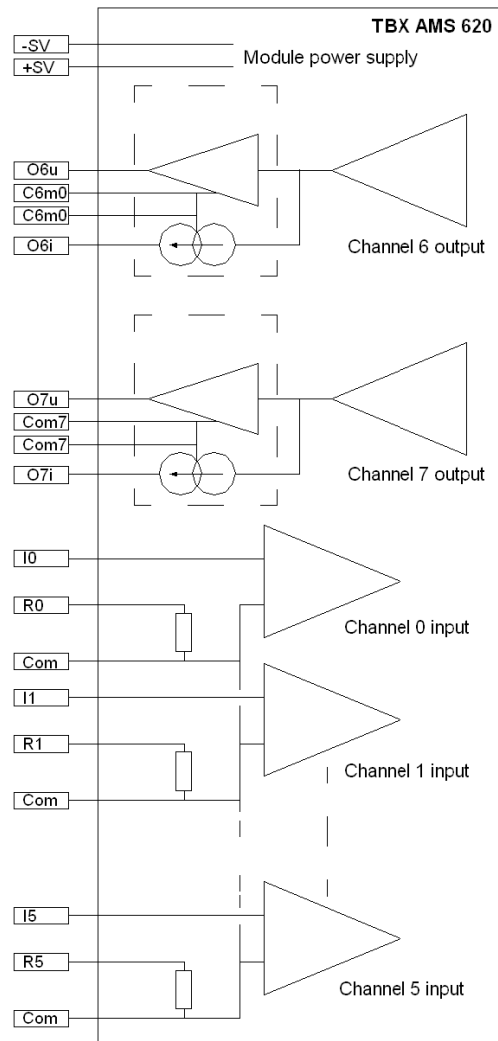
Module <b>TBX AMS 620</b>		
<b>Number of channels</b>	2	
<b>Range</b>	+ or -10V	0/20 mA 0/40 mA
<b>Full scale (FS)</b>	10 V	20 mA
<b>Resolution</b>	11 bits + sign	11 bits
<b>LSB</b>	4,88 mV	9,76 $\mu$ A
<b>Load impedance</b>	$\geq$ 1 k $\Omega$	$\leq$ 600 $\Omega$

<b>Maximum error</b>	at 25 °C	0,45 % FS	0,52 % FS
	at 60 °C	0,75 % FS	0,98 % FS
<b>Maximum drift</b>	65 ppm (FS) / °C		103 ppm (FS) / °C
<b>Update period</b>	5 ms		
<b>Continuous overvoltage</b>	+ or - 30 V		
<b>Monotonicity</b>	Yes		
<b>Maximum leakage current</b>	-	50 µA (0/20 mA)	

## Connecting the module TBX AMS 620

### Circuit diagram

The following illustration shows the circuit diagram for the module **TBX AMS 620**.

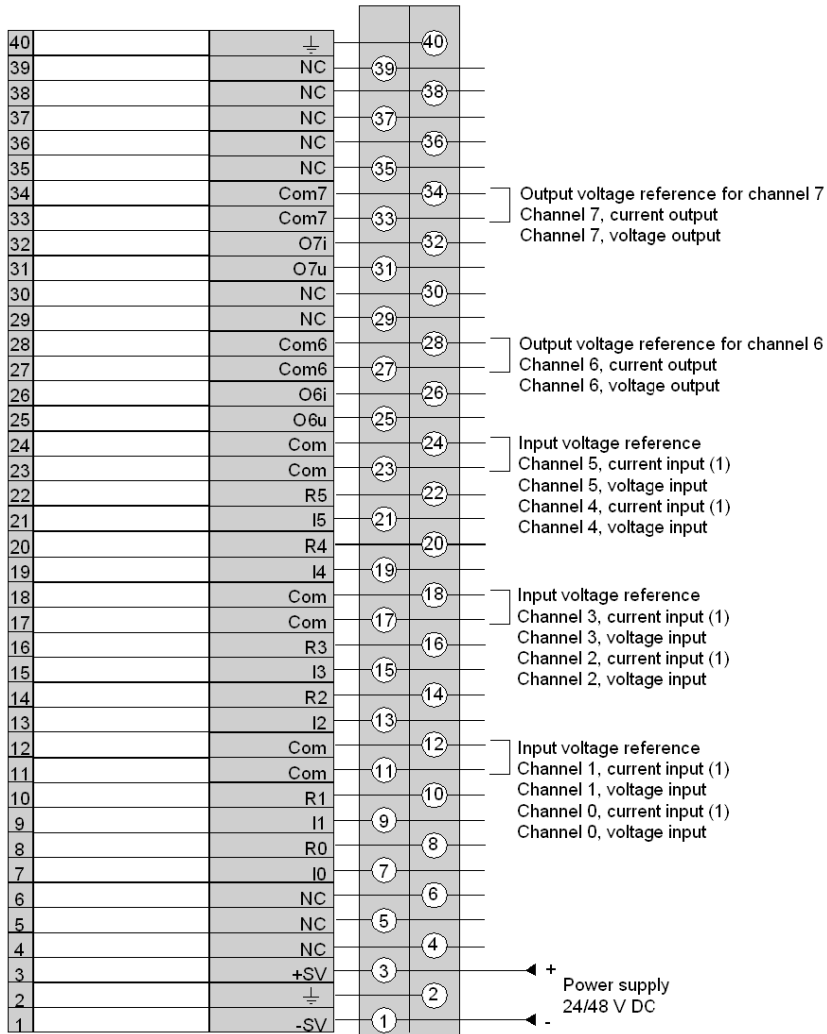


**NOTE:** to use an input channel in current, the I and R terminals must be connected to the channel concerned.

All terminals referenced COM are connected in the module interior.

### Terminal block wiring

The following diagram illustrates the wiring of the terminal. *(see page 127).*

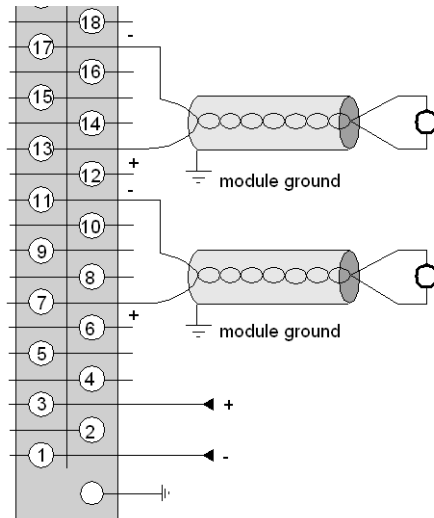


## Wiring and installation recommendations for the model TBX AMS 620

### Wiring recommendations

To protect the signal from induced external noise in serial mode and noise in common mode, it is advisable to take the following precautions regarding:

Precautions to take	
<b>Type of conductors</b>	Use screened twisted pairs, with a minimum conductor cross-section of 0.28 mm <sup>2</sup> .
<b>Cable screening</b>	Connect the cable screening to the shortest TBX module ground on the <b>TBX GND 015</b> grounding strip.
<b>Arrangement of the conductors in cables</b>	Multipair cables can be rearranged for signals of a similar type which have the same reference to ground.
<b>Cable routing</b>	Keep the measurement wires separate from the discrete I/O cables (in particular from relay outputs) and from power cables.
<b>Preactuator and sensor reference to ground</b>	<p>The <b>TBX AMS 620</b> module has 6 inputs which are not isolated from each other but which are isolated from the PLC bus, and 2 outputs which are isolated from each other and from the PLC bus.</p> <p>The sensor cold points are connected to each other internally by the Com terminals.</p> <p>To ensure good immunity to high frequency interference, a 4.7 nF capacitor is connected between the channel voltage and the ground.</p> <p>To ensure correct operation of the analog measurement system, the following precautions must be taken:</p> <ul style="list-style-type: none"> <li>● The sensors must be in close proximity to each other (several meters apart).</li> <li>● All sensors must be referenced at the same point. This point is then connected to the terminal ground.</li> </ul> <p><b>Note:</b> There are no technical restrictions in referencing the preactuators to ground. However, for safety reasons, it is advisable to avoid using a ground voltage which is some distance from the terminal, as this ground voltage may be very different from the nearby ground voltage. Distributed I/O modules minimize this risk as they are usually close to the process.</p>





Precautions to take		
<p><b>Sensor reference to ground</b></p>	<p>If the following characteristics are respected, then each sensor can be assigned a voltage rate according to ground:</p> <ul style="list-style-type: none"> <li>• The sensors must be in close proximity to each other (several meters apart).</li> <li>• all sensors are referenced to the same point. This point is then connected to the COM terminal on the terminal block.</li> </ul>	
<p><b>Preactuator reference to ground</b></p>	<ul style="list-style-type: none"> <li>• Recommended voltage and current wiring: It is advisable to use preactuators which are not referenced with respect to ground, with each channel reference being connected to the ground via a 4.7 nF capacitor.</li> </ul>	
<p><b>Preactuator reference to ground (cont.)</b></p>	<ul style="list-style-type: none"> <li>• Possible voltage wiring: The preactuators can be referenced to ground if the modules have voltage outputs and if the following precautions are taken: <ul style="list-style-type: none"> <li>• The common mode voltages must be below the safety voltage (48 V peak),</li> <li>• Connecting a point in the preactuator to a reference voltage causes a leakage current to be generated. If several analog modules are used, measure the total leakage current and check that it will not interfere with the application.</li> </ul> </li> </ul>	



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