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# 1398 ULTRA Series™ 230V Brushless Servo Motors

## *Product Data*



This publication provides product information for the 0.17 to 50 N-m (1.5 to 450 lb-in.) 1398 ULTRA Series™ 230V, Low-to-Medium Inertia, Brushless Servo Motors. This publication includes:

- Detailed lists of the features and options available for 1398 ULTRA Series 230V, Low-to-Medium Inertia, Brushless Servo Motors
- Performance data and speed-torque curves for the entire 1398 ULTRA Series Servo motor family
- Servo motor dimensions

Rockwell Automation
Allen-Bradley

## Table of Contents

**Servo Motor Introduction . . . . . 7**

Determining Which Motor to Use . . . . . 7
Determining Possible Drive/Motor Combinations . . . . . 8

**F-Series Motors . . . . . 9**

Features . . . . . 9
Typical Applications . . . . . 10
Characteristics . . . . . 10
Selecting a Drive/Motor Combination . . . . . 10

**F-Series Specifications . . . . . 11**

F-Series Mechanical Specifications . . . . . 11
F-Series Winding Specifications . . . . . 12
Storage and Operating Specifications . . . . . 12
F-Series Thermostat Specifications . . . . . 12
F-Series Standard Motor Radial Load Force Ratings . . . . . 13
ULTRA 100 Series Specifications for F-Series Motors . . . . . 14
ULTRA 200 Series Specifications for F-Series Motors . . . . . 14
ULTRA Plus Specifications for F-Series Motors . . . . . 15
F-Series Brake Specifications . . . . . 15
Brake Motor Application Guidelines . . . . . 15
F-Series Standard Motors Dimensions . . . . . 16
Supplemental Motor Dimensions . . . . . 17
F-4000 NEMA 56C Dimensions . . . . . 17
Supplemental Motor Dimensions . . . . . 18
Encoder Data . . . . . 18
Encoder Outputs . . . . . 19
F-Series Connector Pins and Signals . . . . . 19
Motor Power Connector (All F-Series Motors) . . . . . 19
Motor Encoder Connector (F-4000 and F-6000 Motors) . . . . . 20
Optional Motor Brake Connector (F-Series Motors with an 04 Designator) . . . . 20
Wire and Contact Sizing Recommendations . . . . . 21
Power Connector . . . . . 21
Encoder Connector . . . . . 21
Brake Connector . . . . . 21

**H-Series Motors . . . . . 22**

Features . . . . . 22
Typical Applications . . . . . 23
Characteristics . . . . . 23
Selecting a Drive/Motor Combination . . . . . 24

**H-Series Specifications . . . . . 25**

H-Series Mechanical Specifications . . . . . 25
H-Series Winding Specifications . . . . . 26
Storage and Operating Specifications . . . . . 27
H-Series Thermostat Specifications . . . . . 27
H-Series Standard Motor Radial Load Force Ratings . . . . . 28

ULTRA 100 Series Specifications for H-Series Motors . . . . . 29
ULTRA 200 Series Specifications for H-Series Motors . . . . . 30
ULTRA Plus Specifications for H-Series Motors . . . . . 31
H-Series Brake Specifications . . . . . 31
Brake Motor Application Guidelines . . . . . 32
H-Series Standard Motors Dimensions . . . . . 32
H-2000 Motors Dimensions . . . . . 33
H-3000, -4000, -6000, and -8000 Motors Dimensions . . . . . 33
Supplemental Motor Dimensions . . . . . 35
H-4000 NEMA 56C Dimensions . . . . . 35
Supplemental Motor Dimensions . . . . . 36
Encoder Data . . . . . 37
Encoder Outputs . . . . . 37
H-Series Connector Pins and Signals . . . . . 38
Motor Power Connector (All H-Series Motors) . . . . . 38
Motor Encoder Connector . . . . . 38
Optional Motor Brake Connector . . . . . 39
Wire and Contact Sizing Recommendations . . . . . 39
Power Connector . . . . . 39
Encoder Connector . . . . . 40
Brake Connector . . . . . 40

**Y-Series Motors . . . . . 41**

Features . . . . . 41
Typical Applications . . . . . 42
Selecting a Drive/Motor Connection . . . . . 42

**Y-Series Specifications . . . . . 43**

Y-Series Mechanical Specifications . . . . . 43
Y-Series Winding Specifications . . . . . 44
Storage and Operating Specifications . . . . . 44
Brake Motor Application Guidelines . . . . . 44
Y-Series Brake Specifications . . . . . 45
Y-Series Motor Brake and Shaft Load Data . . . . . 45
ULTRA 100 Series Specifications for Y-Series Motors . . . . . 46
ULTRA 200 Specifications for Y-Series Motors . . . . . 46
Y-Series Standard Motors Dimensions . . . . . 47
Supplemental Motor Dimensions . . . . . 48
Cable Diameters . . . . . 48
Encoder Data . . . . . 48
Encoder Outputs . . . . . 49
Y-Series Connector Pins and Signals . . . . . 49
Motor Power Connector (All Y-Series Motors) . . . . . 49
Motor Feedback Connector (All Y-Series Motors) . . . . . 50
Wire and Contact Sizing Recommendations . . . . . 50
Power/Brake Connector . . . . . 50
Encoder Connector . . . . . 51

**N-Series Motors . . . . . 52**
Features . . . . . 52
Typical Applications . . . . . 53
Characteristics . . . . . 53
Selecting a Drive/Motor Combination . . . . . 53

**N-Series Specifications . . . . . 54**
N-Series Mechanical Specifications . . . . . 54
N-Series Thermostat Specifications . . . . . 55
N-Series Winding Specifications . . . . . 55
Storage and Operating Specifications . . . . . 56
N-Series Standard Motor Radial Load Force Ratings . . . . . 57
N-Series Motors Shaft Load Specifications . . . . . 58
ULTRA 100 Series Specifications for N-Series Motors . . . . . 58
ULTRA 200 Series Specifications for N-Series Motors . . . . . 59
ULTRA Plus Specifications for N-Series Motors . . . . . 59
N-Series Brake Specifications . . . . . 60
Brake Motor Application Guidelines . . . . . 60
N-2300 Motors Dimensions . . . . . 61
N-3400, -4200, and -5600 Motors Dimensions . . . . . 61
Supplemental Motor Dimensions . . . . . 63
Encoder Data . . . . . 63
Encoder Outputs . . . . . 64
N-Series Connector Pins and Signals . . . . . 64
Encoder Connectors (All N-Series Motors) . . . . . 64
Power and Brake Connectors (All N-Series Motors) . . . . . 65

**ULTRA 100™/200™ System Ordering Guide . . . . . 66**
ULTRA Servo Drives with F-Series Motors . . . . . 66
ULTRA Servo Drives with F-Series Motors . . . . . 67
ULTRA Servo Drives with F-Series Motors . . . . . 68
ULTRA Servo Drives with H-Series Motors . . . . . 69
ULTRA Servo Drives with H-Series Motors . . . . . 70
ULTRA Servo Drives with H-Series Motors . . . . . 71
ULTRA Servo Drives with H-Series Motors . . . . . 72
ULTRA Servo Drives with H-Series Motors . . . . . 73
ULTRA Servo Drives with Y-Series Motors (115V AC RMS Input Voltage) . . . . . 74
ULTRA Servo Drives with Y-Series Motors (230V AC RMS Input Voltage) . . . . . 75
ULTRA Servo Drives with N-Series Motors . . . . . 76
ULTRA Servo Drives with N-Series Motors . . . . . 77
ULTRA Servo Drives with N-Series Motors . . . . . 78
ULTRA Servo Drives with N-Series Motors . . . . . 79
ULTRA Servo Drives with N-Series Motors . . . . . 80

**ULTRA Plus System Ordering Guide . . . . . 81**
ULTRA Plus Drives with F-Series Motors (1398-PDM-20, -30, and -75) . . . . . 81
ULTRA Plus Drives with F-Series Motors (1398-PDM-20, -30, and -75) . . . . . 82

ULTRA Plus Drives with F-Series Motors(1398-PDM-25, -50, -100, and -150) . . . 83
ULTRA Plus Drives with F-Series Motors (1398-PDM-25, -50, -100, and -150) . . 84
ULTRA Plus Drives with H-Series Motors (1398-PDM-10, -20, -30, and -75) . . . . 85
ULTRA Plus Drives with H-Series Motors (1398-PDM-10, -20, -30, and -75) . . . . 86
ULTRA Plus Drives with H-Series Motors (1398-PDM-10, -20, -30, and -75) . . . . 87
ULTRA Plus Drives with H-Series Motors (1398-PDM-25, -50, -100, and -150) . . 88
ULTRA Plus Drives with H-Series Motors (1398-PDM-25, -50, -100, and -150) . . 89
ULTRA Plus Drives with N-Series Motors (1398-PDM-20 and 1398-PDM-30) . . . 90
ULTRA Plus Drives with N-Series Motors(1398-PDM-20 and 1398-PDM-30) . . . . 91
F-Series Motor and Connector Ordering Information . . . . . 92
H-Series Motor and Connector Ordering Information . . . . . 93
Y-Series Motor and Connector Ordering Information . . . . . 94
N-Series Motor and Connector Ordering Information . . . . . 95

## Servo Motor Introduction

The 1398 ULTRA Series servo motors feature ferrite, neodymium-iron-boron, high-energy ring and high-energy neodymium magnet rotors. These compact, brushless servo motors are intended to be used with the Allen-Bradley 1398 Motion Control System. The motors in this series are:

- F-Series
- H-Series
- N-Series
- Y-Series

### Determining Which Motor to Use

Use the following table to determine which family of motors you need.

| Motors | Description | Typical Applications |
|---|---|---|
| F-Series (see page 9) | • Medium inertia brushless servo motors<br>• Ferrite magnet that provides greater inertia for matching larger loads<br>• Available in two frame sizes—mechanically interchangeable with H-Series<br>• Continuous torque from 3.5 to 28 N-m (31 to 245 lb-in.)<br>• Speeds up to 4000 RPM<br>• 2000-line incremental encoder standard<br>• Environmental connectors, IP65 enclosure rating | • Web processing<br>• Machine tool<br>• Textile machinery<br>• CAM replacement |
| H-Series (see page 22) | • Low inertia brushless servo motors<br>• Neodymium-iron boron magnet to provide low inertias for high acceleration<br>• Available in five frame sizes<br>• Continuous torque from 0.5 to 50 N-m (5 to 450 lb-in.)<br>• Speeds up to 6000 RPM<br>• 2000-line incremental encoder standard<br>• Environmental connectors, IP65 enclosure rating | • Smart conveyors<br>• Packaging machinery<br>• Material feeding<br>• Pick-and-place machines<br>• High duty cycle applications |
| Y-Series (see page 41) | • Small, low inertia brushless servo motors<br>• High-energy Neodymium magnet to provide low inertias for high acceleration<br>• Available in three popular metric frame sizes<br>• Continuous torque from 0.17 to 2.5 N-m (1.5 to 22 lb-in.)<br>• Speeds up to 4500 RPM<br>• Available in either 115V or 230V windings<br>• IP43 enclosure rating | • Robotics<br>• Material handling<br>• X-Y tables<br>• Specialty machinery<br>• Semiconductor manufacturing |
| N-Series (see page 52) | • NEMA style brushless servo motors<br>• High energy ring magnet rotor construction to provide low inertias for high acceleration<br>• Available in four common NEMA style frame sizes<br>• Continuous torque from 0.18 to 5.9 N-m (1.6 to 52 lb-in.)<br>• Speeds up to 6000 RPM<br>• 1000-, 2000-line incremental encoder standard<br>• Environmental connectors, IP65 enclosure rating | • Web processing<br>• Machine tool<br>• Textile machinery<br>• CAM replacements<br>• Stepper replacement |

## Determining Possible Drive/Motor Combinations

Use the following table to determine which motors can be used with which drives:

| Motors: | Drives: | | |
|---|---|---|---|
| | ULTRA 100 | ULTRA 200 | ULTRA Plus |
| F-Series | X | X | X |
| H-Series | X | X | X |
| Y-Series | X | X | NA |
| N-Series | X | X | X[1] |

[1] Excluding N-23*xx* motors.

Note: To learn more about the ULTRA Series drives family, see publication 1398-2.0.

## F-Series Motors



F-Series motors, mechanically interchangeable with H-Series motors, use a Ferrite magnet to provide nearly four times greater inertia than the H-Series family for matching larger load inertias. Available in two frame sizes, the F-Series motors range in continuous torque capability from 3.5 to 28 N-m, (31 to 245 lb-in.) and reach speeds up to 4000 RPM. The F-Series motors use an optical 2000-line incremental encoder with a 5000-line option for superior low-speed performance with the ULTRA Series. Typical applications for the F-Series include web processing, machine tool, textile machinery, and CAM replacements. When you install the optional motor shaft seal, the motor meets the IP65 requirements of the IEC standard.

### Features

The F-Series motors have the following features:

- Compact design that is mechanically interchangeable with the H-Series family
- Two frame sizes, six models
- Continuous torque from 3.5 to 28 N-m (31 to 245 lb-in.)
- Speeds up to 4000 RPM
- Ferrite permanent magnet rotors provide approximately four times greater rotor inertia than the H-Series family for matching larger load inertias
- Internal thermal switch indicates overheating
- Motor-mounted optical encoder included 2000 quadrature pulses, index pulse, and standard commutation channels for drives
- Water tight MS connections are compatible with standard cable assemblies; in addition, the extruded aluminum housing and environmental connectors provide an IP65 package (with the addition of the optional shaft seal kit)
- Economical, compact design ready for harsh environments
- Optional spring-set holding brakes available with 24V DC
- Axially-trapped front bearing in a steel insert for long life at high speeds
- Vibration: 2.5 g peak 3-2000Hz
- Shock: 10.0 g peak 6 ms duration
- UL recognized

## Typical Applications

Typical applications for the F-Series motors are:

- Web and film processing
- Machine tool/metal cutting
- Textile machinery
- CAM replacements

## Characteristics

- Higher inertia matching capability
- Heavy duty continuous operations
- Environmentally rugged

## Selecting a Drive/Motor Combination

The following drive/motor combinations are available for the F-Series motors:

| Motor | ULTRA 100 | ULTRA 200 | ULTRA Plus |
|---|---|---|---|
| F-4030-Q-H00AA | 1398-DDM-019 | 1398-DDM-020 | 1398-PDM-20 |
| | | | 1398-PDM-25 |
| F-4050-Q-H00AA | 1398-DDM-019[1] | 1398-DDM-030 | 1398-PDM-30 |
| | | | 1398-PDM-50 |
| F-4075-R-H00AA | NA | 1398-DDM-030[2] | 1398-PDM-30 |
| | | | 1398-PDM-50 |
| | | 1398-DDM-075 | 1398-PDM-75 |
| F-6100-R-H00AA | NA | 1398-DDM-075 | 1398-PDM-75 |
| | | | 1398-PDM-50 |
| F-6200-R-H00AA | NA | 1398-DDM-075 | 1398-PDM-75 |
| | | 1398-DDM-150 | 1398-PDM-100 |
| F-6300-R-H00AA | NA | 1398-DDM-075 | 1398-PDM-75 |
| | | 1398-DDM-150 | 1398-PDM-100 |

1 Continuous current/torque is limited to 5.2 N-m (46.0 lb-in.).
2 Peak torque is limited to 18.6 N-m (164.6 lb-in.).

## F-Series Specifications

This section contains the mechanical, thermostat and winding specifications for the F-Series motor family, as well as the load force ratings and performance specifications for every combination of ULTRA series drives and F-Series motors. It also provides motor dimensions, connector pin and signal designations, and all motor and connector ordering information.

### F-Series Mechanical Specifications

| Specifications | Units | F-4030 | F-4050 | F-4075 | F-6100 | F-6200 | F-6300 |
|---|---|---|---|---|---|---|---|
| Rotor moment of inertia | $kg\text{-}m^2$ ($lb\text{-}in.\text{-}s^2$) | 0.0010 (0.009) | 0.0021 (0.019) | 0.0032 (0.029) | 0.0064 (0.057) | 0.0107 (0.095) | 0.0162 (0.144) |
| Rotor moment of inertia (brake motors) | $kg\text{-}m^2$ ($lb\text{-}in.\text{-}s^2$) | 0.0011 (0.010) | 0.0022 (0.020) | 0.0033 (0.030) | 0.007 (0.061) | 0.011 (0.098) | 0.017 (0.147) |
| Motor shipping weight | kg (lb) | 11.0 (23.0) | 15.8 (34.8) | 21.5 (47.2) | 25.2 (55.4) | 33.5 (73.8) | 46 (101.2) |
| Motor net weight | kg (lb) | 9.0 (19.6) | 14.1 (31.0) | 14.1 (42.0) | 22.3 (49.2) | 30.9 (68.2) | 43.2 (95.2) |
| Brake motor shipping weight | kg (lb) | 12.5 (27.6) | 17.8 (39.2) | 23.9 (52.6) | 30 (66.0) | 38.4 (84.4) | 51.4 (113.1) |
| Brake motor net weight | kg (lb) | 10.9 (24.0) | 16.0 (35.2) | 21.2 (46.8) | 27.1 (59.8) | 35.6 (78.4) | 48.0 (105.8) |
| Damping | N-m/kRPM (lb-in./kRPM) | 0.06 (0.5) | 0.10 (0.94) | 0.15 (1.3) | 0.16 (1.4) | 0.24 (2.1) | 0.37 (3.3) |
| Friction torque | N-m (lb-in.) | 0.063 (0.56) | 0.10 (0.94) | 0.17 (1.5) | 0.17 (1.5) | 0.24 (2.1) | 0.46 (4.1) |
| Maximum Operating Speed | rpm | 4000 | 4000 | 3000 | 3000 | 3000 | 3000 |

## F-Series Winding Specifications

| Specifications | Units | F-4030 | F-4050 | F-4075 | F-6100 | F-6200 | F-6300 |
|---|---|---|---|---|---|---|---|
| Sine wave $K_T$ torque Constant at 25°C [1] | N-m/A (lb-in./A) | 0.54 (4.8) | 0.54 (4.8) | 0.73 (6.5) | 0.71 (6.3) | 0.70 (6.2) | 0.73 (6.5) |
| Square wave $K_T$ torque Constant at 25°C [2] | N-m/A (lb-in./A) | 0.60 (5.3) | 0.60 (5.3) | 0.80 (7.1) | 0.78 (6.9) | 0.80 (6.8) | 0.81 (7.1) |
| $K_E$ voltage constant [3] | V/kRPM | 66 | 66 | 89 | 86 | 85 | 89 |
| Winding resistance Phase to phase at 25°C | Ohm | 2.2 | 0.89 | 0.98 | 0.51 | 0.26 | 0.16 |
| Winding inductance Phase to phase | mH | 6.8 | 3.3 | 3.4 | 3.3 | 1.7 | 1.1 |
| Thermal resistance [4] | °C/Watt | 0.63 | 0.48 | 0.40 | 0.45 | 0.37 | 0.30 |
| Poles | | 8 | 8 | 8 | 8 | 8 | 8 |

1 Peak value of per phase sine wave amps.
2 Peak value of per phase square wave amps
3 Peak value of sinusoidal phase to phase volts
4 At 125°C winding temperature, in a 40°C ambient, with motor mounted on 0.5 in. x 12 in. x 12 in. aluminum heat sink.

## Storage and Operating Specifications

| Storage and Operating Conditions | |
|---|---|
| Ambient Temperature | Operating: 0 to 40°C (32 to 104°F)<br>Storage: -30 to 70°C (-25 to 158°F) |
| Relative Humidity | 5% to 95% non-condensing |

## F-Series Thermostat Specifications

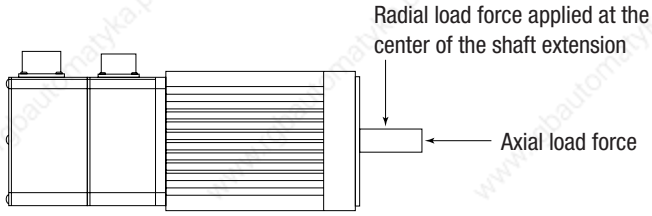
| Specifications | |
|---|---|
| Rated voltage | 0 - 250V DC or 50/60 Hz AC[1] |
| Rated current | 2.5A at power factor of 1.0<br>1.6A at power factor of 0.6 |
| Maximum switching current | 5 A |
| Contact resistance | Less than 0.10 Ohms maximum |
| Contacts | Normally closed |
| Insulation dielectric | Mylar Nomex capable of withstanding<br>1500V AC RMS 50/60 Hz for 1 minute |
| Opening temperature (±5°C) | 140°C |

1 The thermostat is normally used as a switch for a 24V DC logic signal.

## F-Series Standard Motor Radial Load Force Ratings

| Specifications | Units | F-4030 | F-4050 | F-4075 | F-6100 | F-6200 | F-6300 |
|---|---|---|---|---|---|---|---|
| 500 RPM | kg<br>(lbs) | 34.5<br>(76) | 39.9<br>(88) | 41.7<br>(92) | 72.1<br>(159) | 78.0<br>(172) | 83.0<br>(183) |
| 1000 RPM | kg<br>(lbs) | 27.2<br>(60) | 31.3<br>(69) | 33.1<br>(73) | 57.1<br>(126) | 61.7<br>(136) | 65.8<br>(145) |
| 2000 RPM | kg<br>(lbs) | 21.3<br>(47) | 24.9<br>(55) | 26.3<br>(58) | 45.4<br>(100) | 49.0<br>(108) | 52.2<br>(115) |
| 3000 RPM | kg<br>(lbs) | 18.6<br>(41) | 21.8<br>(48) | 23.1<br>(51) | 39.5<br>(87) | 42.6<br>(94) | 45.8<br>(101) |
| 4000 RPM | kg<br>(lbs) | 17.2<br>(38) | 20.0<br>(44) | 20.9<br>(46) | NA | NA | NA |

Motors are capable of carrying an axial load in most applications according to the following general guidelines. These guidelines should only be used as approximations.




- When the motor shaft has no radial load, the axial load rating is 100% of the radial load rating from the table above.
- When the motor shaft has both a radial and an axial load, the axial load rating is 44% of the radial load rating from the table above.

## ULTRA 100 Series Specifications for F-Series Motors[1]

| Specifications | | F-4030 | F-4050 | F-4075 | F-6100 | F-6200 | F-6300 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-DDM | 019 | 019 | NA | NA | NA | NA |
| Maximum continuous operating speed [2] | RPM | 3600 | 3500 | NA | NA | NA | NA |
| Continuous stall torque [3,4] | N-m (lb-in.) | 3.5 (31) | 5.2 (46) | NA | NA | NA | NA |
| Peak torque [5] | N-m (lb-in.) | 11.3 (100) | 13.6 (120) | NA | NA | NA | NA |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230V AC line voltage input.
3 At 125°C winding temperature, in a 40°C ambient, with motor mounted on 0.5 in. x 12 in. x 12 in. aluminum heat sink.
4 Brake motor continuous stall torque derated by 15%.
5 System limit.

## ULTRA 200 Series Specifications for F-Series Motors[1]

| Specifications | | F-4030 | F-4050 | F-4075 | F-6100 | F-6200 | F-6300 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | 020 | 030 | 030/075 | 075 | 075/150 | 075/150 |
| Maximum continuous operating speed [2] | RPM | 4000 | 4000 | 3000 | 3000 | 3000 | 3000 |
| Continuous stall torque [3,4] | N-m (lb-in.) | 3.5 (31) | 6.9 (61) | 9.3 (82) | 13 (115) | 19.8 (175) | 23.7 (210) |
| Peak torque [5] | N-m (lb-in.) | 9.0 (80) | 13.6 (120) | 19.2 (170) | 31.1 (275) | 39.5 (350) | 49.7/56.5 (440/500) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230 V AC line voltage input.
3 At 125°C winding temperature, in a 40°C ambient, with motor mounted on 0.5 in. x 12 in. x 12 in. aluminum heat sink.
4 Brake motor continuous stall torque derated by 15%.
5 System limit.

## ULTRA Plus Specifications for F-Series Motors[1]

| Specifications | | F-4030 | F-4050 | F-4075 | F-6100 | F-6200 | F-6300 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-PDM- | 20 | 30 | 30/75 | 75 | 75 | 75 |
| Maximum continuous operating speed [2] | RPM | 4000 | 4000 | 3000 | 3000 | 3000 | 3000 |
| Continuous stall torque [3,4] | N-m (lb-in.) | 3.5 (31) | 6.9 (61) | 9.3 (82) | 13 (115) | 19.8 (175) | 23.7 (210) |
| Peak torque [5] | N-m (lb-in.) | 9.0 (80) | 13.6 (120) | 19.2 (170) | 31.1 (275) | 39.5 (350) | 49.7 (440) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230 V AC line voltage input.
3 At 125°C winding temperature, in a 40°C ambient, with motor mounted on 0.5 in. x 12 in. x 12 in. aluminum heat sink.
4 Brake motor continuous stall torque derated by 15%.
5 System limit.

## F-Series Brake Specifications

| Specifications | F-4000 | F-6000 |
|---|---|---|
| Maximum backlash (brake engaged) | 44 minutes | 29 minutes |
| Holding torque | 90 lb-in. (10.2 N-m) | 300 lb-in. (22.6 N-m) |
| Coil current at 24V DC | 0.88 ADC | 1.13 ADC |

## Brake Motor Application Guidelines

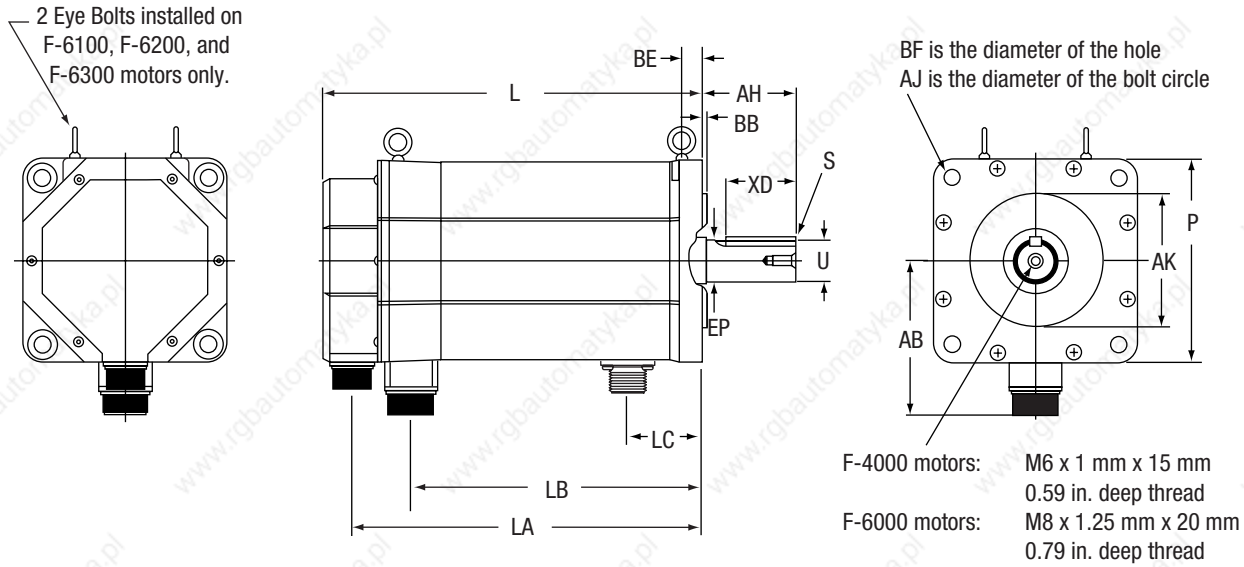
The brakes offered as options on these servo motors are holding brakes. They are designed to hold the motor shaft at 0 rpm for up to the rated brake holding torque. The brakes are spring-set type, and release when voltage is applied to the brake coil.

The brakes are *not* designed for stopping rotation of the motor shaft. Servo drive inputs should be used to stop motor shaft rotation. The recommended method of stopping motor shaft rotation is to command the servo drive to decelerate the motor to 0 rpm, and engage the brake after the servo drive has decelerated the motor to 0 rpm.

If system main power fails, the brakes can withstand use as stopping brakes. However, use of the brakes as stopping brakes creates rotational mechanical backlash that is potentially damaging to the system, increases brake pad wear and reduces brake life. The brakes are *not* designed nor are they intended to be used as a safety device.

A separate power source is required to disengage the brake. This power source may be controlled by the servo motor controls, in addition to manual operator controls.

## F-Series Standard Motors Dimensions




| Dimen-sions | AB | AH | AJ | AK | BB | BE | BF | EP | L | L with brake | P | S | U | XD |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| **Motor Models** | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm x mm (in. x in.) | mm (in.) | mm (in.) |
| F-4030 | 102 (4.02) | 50 (1.97) | 145 (5.71) | 110 (4.33) | 3 (0.12) | 16 (0.64) | 10 (0.39) | 22.2 (0.875) | 194 (7.64) | 257 (10.12) | 127 (5.00) | 6 x 6 (0.24 x 0.24) | 19 (0.75) | 38 (1.49) |
| F-4050 | 102 (4.02) | 50 (1.97) | 145 (5.71) | 110 (4.33) | 3 (0.12) | 16 (0.64) | 10 (0.39) | 22.2 (0.875) | 272 (10.71) | 335 (13.19) | 127 (5.00) | 6 x 6 (0.24 x 0.24) | 19 (0.75) | 38 (1.49) |
| F-4075 | 102 (4.02) | 50 (1.97) | 145 (5.71) | 110 (4.33) | 3 (0.12) | 16 (0.64) | 10 (0.39) | 22.2 (0.875) | 350 (13.78) | 413 (16.26) | 127 (5.00) | 6 x 6 (0.24 x 0.24) | 19 (0.75) | 38 (1.49) |
| F-6100 | 131 (5.16) | 80 (3.15) | 200 (7.87) | 114.3 (4.50) | 4 (0.16) | 19 (0.75) | 13 (0.53) | 36.5 (1.438) | 255 (10.04) | 326 (12.83) | 173 (6.81) | 10 x 8 (0.39 x 0.32) | 35 (1.38) | 60 (2.36) |
| F-6200 | 131 (5.16) | 80 (3.15) | 200 (7.87) | 114.3 (4.50) | 4 (0.16) | 19 (0.75) | 13 (0.53) | 36.5 (1.438) | 320 (12.60) | 390 (15.35) | 173 (6.81) | 10 x 8 (0.39 x 0.32) | 35 (1.38) | 60 (2.36) |
| F-6300 | 131 (5.16) | 80 (3.15) | 200 (7.87) | 114.3 (4.50) | 4 (0.16) | 19 (0.75) | 13 (0.53) | 36.5 (1.438) | 420 (16.53) | 490 (19.29) | 173 (6.81) | 10 x 8 (0.39 x 0.32) | 35 (1.38) | 60 (2.36) |

Motors are manufactured to millimeter dimensions shown. Inch dimensions shown are appropriate conversions from millimeters. For further motor detail, engineering specification drawings are available upon request.

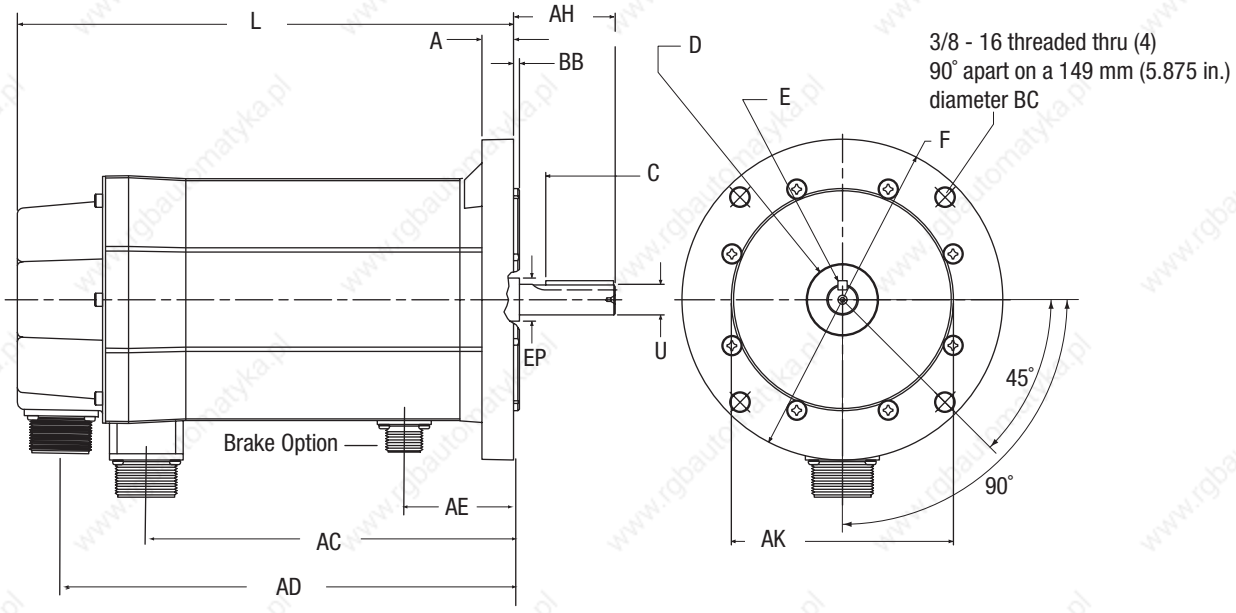
Note: Dimension EP is manufactured in inches.

## Supplemental Motor Dimensions

| Connector | | F-4030 | Brake | F-4050 | Brake | F-4075 | Brake | F-6100 | Brake |
|---|---|---|---|---|---|---|---|---|---|
| Brake (mm/in) | LC | – | 56/22.0 | – | 56/22.0 | – | 56/22.0 | – | 59/23.2 |
| Encoder (mm/in) | LB | 126/49.6 | 189/74.4 | 204/80.3 | 267/105.1 | 282/111.0 | 345/135.8 | 183/72.0 | 254/100.0 |
| Power (mm/in) | LA | 172/67.7 | 235/92.5 | 250/98.4 | 313/123.2 | 228/89.8 | 301/118.5 | 233/91.7 | 304/119.7 |

| Connector | | F-6200 | Brake | F-6300 | Brake |
|---|---|---|---|---|---|
| Brake (mm/in) | LC | – | 59/23.2 | – | 59/23.2 |
| Encoder (mm/in) | LB | 248/97.6 | 318/125.2 | 348/137.0 | 418/164.6 |
| Power (mm/in) | LA | 298/117.3 | 368/144.9 | 398/156.7 | 468/184.2 |

## F-4000 NEMA 56C Dimensions



### F-4000 NEMA 56C Dimensions, cont'd

| Dimensions | F-4030 NEMA 56C | F-4050 NEMA 56C | F-4075 NEMA 56C |
|---|---|---|---|
| A | 16.3 mm (0.64 in.) | | |
| AH | 52 mm (2.06 in.) | | |
| AK | 114.3 mm (4.500 in.) diameter | | |
| BB | 3 mm (0.12 in.) | | |
| C | 36 mm (1.41 in.) full depth | | |
| D | Motor will accept 36.5 mm (1.437 in.) x 22.2 mm (0.875 in.)<br>6.3 mm (0.25 in.) shaft seal (optional, not included) | | |
| E | Key supplied<br>4.8 mm (0.1875 in.) square x 35 mm (1.375 in.) long) | | |
| EP | 22 mm (0.875 in.) diameter | | |
| F | 165 mm (6.50 in.) diameter | | |
| L (without brake) | 194 mm (7.64 in.) | 272 mm (10.71 in.) | 350 mm (13.78 in.) |
| L (with brake) | 257 mm (10.12 in.) | 335 mm (13.19 in.) | 413 mm (16.26 in.) |
| U | 15.9 mm (0.625 in.) diameter | | |

### Supplemental Motor Dimensions

| Connector | | F-4030 | Brake | F-4050 | Brake | F-4075 | Brake |
|---|---|---|---|---|---|---|---|
| Brake (mm/in) | AE | – | 2.21/5.6 | – | 2.21/5.6 | – | 2.21/5.6 |
| Encoder (mm/in) | AD | 6.77/17.2 | 9.25/23.5 | 9.84/25.0 | 12.32/31.3 | 12.92/32.8 | 15.39/39.1 |
| Power (mm/in) | AC | 4.97/12.6 | 7.45/18.9 | 8.04/20.4 | 10.52/26.7 | 11.12/28.2 | 13.59/34.5 |

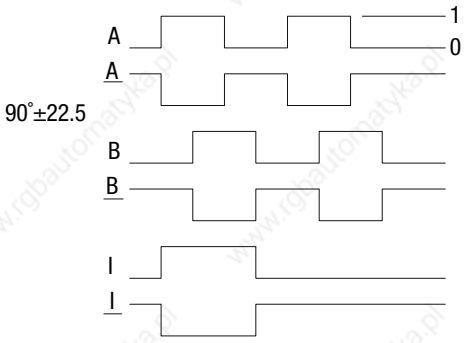
## Encoder Data

Encoders are factory aligned and must not be adjusted outside the factory.

| Specifications | |
|---|---|
| Line Count | 2000[1] |
| Supply Voltage | 5 VDC |
| Supply Current | 250 mA max. |
| Line Driver | 26LS31 |
| Line Driver Output | TTL |
| Index Pulse | F-4000 and F-6000 Series when key faces the connectors ($0^{o} \pm 10$) |

[1] Standard line count before quadrature.

## Encoder Outputs

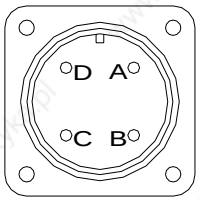



WAVEFORMS RESULT FROM CW SHAFT ROTATION
(CLOCKWISE AS VIEWED FACING THE SHAFT EXTENSION)

## F-Series Connector Pins and Signals

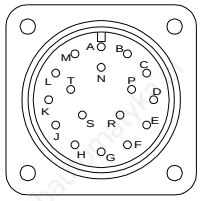
### Motor Power Connector (All F-Series Motors)

| Pin | Signal |
|---|---|
| A | R |
| B | S |
| C | T |
| D | Motor Case |



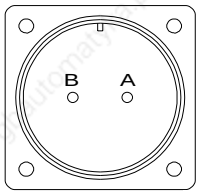
## Motor Encoder Connector (F-4000 and F-6000 Motors)

| Pin | Signal | Pin | Signal |
|---|---|---|---|
| A | A+ | K | +5V DC |
| B | A- | L | COM |
| C | B+ | M | COM |
| D | B- | N | Hall B |
| E | I+ | P | Hall C |
| F | I- | R | TS+ |
| G | Encoder Case | S | TS- |
| H | ABS | T | Hall A |
| J | +5V DC | | |




## Optional Motor Brake Connector (F-Series Motors with an 04 Designator)

| Pin | Signal |
|---|---|
| A | BR+ |
| B | BR- |



## Wire and Contact Sizing Recommendations

### Power Connector

The following connector contact sizes and wiring gages are recommended for cabling to a motor.

| Motor | Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|---|
| F-4030 | 12 (3.0) | 16 (1.5) |
| F-4050 | | 14 (2.5) |
| F-4075 | | |
| F-6100 | 8 (8.6) | 12 (4) |
| F-6200 | | 8 (10) |
| F-6300 | | |

- Sizes are recommended minimum values for 4 conductors (R, S, T and GND).
- Wiring should be twisted.
- Local regulations should always be observed.

### Encoder Connector

| Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|
| All F-Series<br>16 (1.5) | 24 (0.25)<br>22 (0.34) with BRU Drives<br>22 (0.34) with BSA Drives |

### Brake Connector

| Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|
| All F-Series<br>16 (1.5) | 18 (0.75) |

- These specifications are the recommended minimum mechanical size.
- Local regulations should always be observed.

## H-Series Motors



H-Series motors use a neodymium-iron-boron magnet to provide low inertias and high accelerations. Available in five frame sizes, the H-Series motors range in continuous torque capability from 0.5 to 50 N-m (5 to 450 lb-in.) and reach speeds up to 6000 RPM. The H-Series motors use an optical 2000-line incremental encoder with a 5000-line option for superior low-speed performance with the ULTRA Series. Typical applications for the H-Series include smart conveyors, packaging machinery, material feeding, pick-and-place machines, and high duty cycle applications. When you install the optional motor shaft seal, the motor meets the IP65 requirements of the IEC standard.

### Features

The H-Series motors have the following features:

- Compact design that is mechanically interchangeable with the F-4000 and F-6000 Series motors
- Five frame sizes, twelve models
- Continuous torque from 0.5 to 50 N-m (5 to 450 lb-in.)
- Speeds up to 6000 RPM
- Neodymium-iron-boron permanent magnet rotors provide low inertias for high accelerations
- Internal thermal switch indicates overheating
- Motor-mounted optical encoder included 2000 quadrature pulses, index pulse, and standard commutation channels for trapezoidal drives
- Water tight MS connections are compatible with standard cable assemblies; in addition, the extruded aluminum housing and environmental connectors provide an IP65 package (with the addition of the optional shaft seal kit)
- Economical, compact design ready for harsh environments
- Optional spring-set holding brakes available with 24V DC
- Axially-trapped front bearing in a steel insert for long life at high speeds
- Vibration: 2.5 g peak 30-2000Hz
- Shock: 10.0 g peak 6 ms duration
- UL recognized

## Typical Applications

Typical applications for the H-Series motors are:

- Smart conveyors
- Packaging machinery
- Punch press/material feeding
- Robotic pick-and-place
- High duty cycle applications

## Characteristics

- High acceleration and peak torques
- High-speed point-to-point positioning
- Environmentally rugged

## Selecting a Drive/Motor Combination

The following drive/motor combinations are available for the H-Series motors:

| Motor | ULTRA 100 | ULTRA 200 | ULTRA Plus |
|---|---|---|---|
| H-2005-K-H00AA | 1398-DDM-009 | 1398-DDM-010 | 1398-PDM-10 |
| H-3007-N-H00AA | 1398-DDM-009 | 1398-DDM-010 | 1398-PDM-10 |
| H-3016-N-H00AA | 1398-DDM-019 | 1398-DDM-020 | 1398-PDM-20 |
| | | | 1398-PDM-25 |
| H-4030-M-H00AA | NA | 1398-DDM-030 | 1398-PDM-30 |
| H-4030-P-H00AA | 1398-DDM-019 | 1398-DDM-020 | 1398-PDM-20 |
| | | | 1398-PDM-25 |
| H-4050-P-H00AA | NA | 1398-DDM-030 | 1398-PDM-30[1] |
| | | 1398-DDM-075 | 1398-PDM-75 |
| | | | 1398-PDM-50 |
| H-4075-R-H00AA | NA | 1398-DDM-030 | 1398-PDM-30[2] |
| | | 1398-DDM-075 | 1398-PDM-75 |
| | | | 1398-PDM-50 |
| H-6100-Q-H00AA | NA | 1398-DDM-075 | 1398-PDM-75 |
| | | | 1398-PDM-50 |
| H-6200-Q-H00AA | NA | 1398-DDM-075 | 1398-PDM-75 |
| | | | 1398-PDM-100 |
| H-6300-Q-H00AA | NA | 1398-DDM-150 | 1398-PDM-150 |
| H-8350-S-H00AA | NA | 1398-DDM-150 | 1398-PDM-100 |
| H-8500-S-H00AA | NA | 1398-DDM-150 | 1398-PDM-150 |

[1] Peak torque is limited to 13.5 N-m (119.5 lb-in.).
[2] Peak torque is limited to 19.8 N-m (175.2 lb-in.).

## H-Series Specifications

This section contains the mechanical, thermostat and winding specifications for the H-Series motor family, as well as the load force ratings and performance specifications for every combination of ULTRA series drives and H-Series motors. It also provides motor dimensions, connector pin and signal designations, and all motor and connector ordering information.

### H-Series Mechanical Specifications

| Specifications | Units | H-2005 | H-3007 | H-3016 | H-4030-M | H-4030-P | H-4050 |
|---|---|---|---|---|---|---|---|
| Rotor moment of inertia | kg-m$^2$ (lb-in.-s$^2$) | 0.000015 (0.000013) | 0.000030 (0.00027) | 0.000080 (0.00072) | 0.00025 (0.0022) | 0.00025 (0.0022) | 0.00046 (0.0041) |
| Rotor moment of inertia (brake motors) | kg-m$^2$ (lb-in.-s$^2$) | NA | 0.000038 (0.00034) | 0.000089 (0.00079) | 0.00033 (0.0029) | 0.00033 (0.0029) | 0.00054 (0.0048) |
| Motor shipping weight | kg (lb) | 2.7 (6.0) | 3.2 (7.0) | 4.7 (10.4) | 7.3 (16.1) | 7.3 (16.1) | 10.9 (24.0) |
| Motor net weight | kg (lb) | 2.2 (4.9) | 2.6 (5.8) | 4.1 (9.0) | 6.8 (14.9) | 6.8 (14.9) | 9.7 (21.4) |
| Brake motor shipping weight | kg (lb) | NA | 3.8 (8.4) | 5.5 (12.1) | 9.4 (20.7) | 9.4 (20.7) | 12.7 (28.0) |
| Brake motor net weight | kg (lb) | NA | 3.4 (7.5) | 4.9 (10.8) | 8.8 (19.4) | 8.8 (19.4) | 11.8 (26.0) |
| Damping | N-m/kRPM (lb-in./kRPM) | 0.007 (0.06) | 0.010 (0.09) | 0.014 (0.12) | 0.034 (0.30) | 0.034 (0.30) | 0.045 (0.40) |
| Friction torque | N-m (lb-in.) | 0.014 (0.12) | 0.014 (0.12) | 0.028 (0.25) | 0.034 (0.30) | 0.034 (0.30) | 0.068 (0.60) |
| Maximum Operating Speed | rpm | 6000 | 5000 | 5000 | 4000 | 4000 | 4000 |

| Specifications | Units | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| Rotor moment of inertia | kg-m$^2$ (lb-in.-s$^2$) | 0.00068 (0.0060) | 0.0014 (0.012) | 0.0024 (0.021) | 0.0034 (0.030) | 0.0063 (0.056) | 0.0094 (0.083) |
| Rotor moment of inertia (brake motors) | kg-m$^2$ (lb-in.-s$^2$) | 0.00076 (0.0067) | 0.0017 (0.015) | 0.0027 (0.024) | 0.0037 (0.033) | 0.0093 (0.082) | 0.012 (0.109) |
| Motor shipping weight | kg (lb) | 14.1 (31.1) | 19.2 (42.3) | 28.6 (63.0) | 37.7 (83.1) | 46.8 (103) | 58.1 (128) |
| Motor net weight | kg (lb) | 12.9 (28.4) | 18.3 (40.4) | 27.0 (59.4) | 34.8 (76.8) | 44.1 (97) | 56.1 (123.6) |
| Brake motor shipping weight | kg (lb) | 16.0 (35.3) | 23.8 (52.5) | 32.9 (72.5) | 42.2 (93.0) | 53.5 (118) | 64.9 (143) |
| Brake motor net weight | kg (lb) | 14.9 (32.8) | 22.5 (49.5) | 31.6 (69.5) | 39.2 (86.4) | 50.9 (112) | 61.8 (136) |
| Damping | N-m/kRPM (lb-in./kRPM) | 0.068 (0.60) | 0.10 (0.90) | 0.16 (1.4) | 0.19 (1.7) | 0.38 (3.4) | 0.43 (3.8) |

| Specifications | Units | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| Friction torque | N-m<br>(lb-in.) | 0.14<br>(1.2) | 0.14<br>(1.2) | 0.24<br>(2.1) | 0.36<br>(3.2) | 0.32<br>(2.8) | 0.40<br>(3.5) |
| Maximum Operating Speed | rpm | 3000 | 3000 | 3000 | 3000 | 2000 | 2000 |

## H-Series Winding Specifications

| Specifications | Units | H-2005 | H-3007 | H-3016 | H-4030-M | H-4030-P | H-4050 |
|---|---|---|---|---|---|---|---|
| Sine wave $K_T$ torque Constant at 25°C [1] | N-m/A<br>(lb-in./A) | 0.13<br>(1.2) | 0.28<br>(2.5) | 0.28<br>(2.5) | 0.25<br>(2.2) | 0.50<br>(4.4) | 0.50<br>(4.4) |
| Square wave $K_T$ torque Constant at 25°C [2] | N-m/A<br>(lb-in./A) | 0.14<br>(1.3) | 0.31<br>(2.7) | 0.31<br>(2.7) | 0.27<br>(2.4) | 0.54<br>(4.8) | 0.54<br>(4.8) |
| $K_E$ voltage constant [3] | V/kRPM | 16 | 34 | 34 | 30 | 60 | 60 |
| Winding resistance Phase to phase at 25°C | Ohm | 2.6 | 6.6 | 1.3 | 0.5 | 2.0 | 0.69 |
| Winding inductance Phase to phase | mH | 4.1 | 12 | 3.4 | 1.9 | 9.0 | 3.3 |
| Thermal resistance [4] | °C/Watt | 1.5 | 1.2 | 0.89 | 0.79 | 0.79 | 0.57 |
| Poles | | 4 | 6 | 6 | 6 | 6 | 6 |

| Specifications | Units | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| Sine wave $K_T$ torque Constant at 25°C [1] | N-m/A<br>(lb-in./A) | 0.74<br>(6.6) | 0.68<br>(6.0) | 0.66<br>(5.8) | 0.70<br>(6.2) | 0.86<br>(7.6) | 0.92<br>(8.2) |
| Square wave $K_T$ torque Constant at 25°C [2] | N-m/A<br>(lb-in./A) | 0.81<br>(7.2) | 0.74<br>(6.6) | 0.72<br>(6.4) | 0.77<br>(6.8) | 0.94<br>(8.3) | 1.0<br>(9.0) |
| $K_E$ voltage constant [3] | V/kRPM | 90 | 82 | 80 | 85 | 104 | 112 |
| Winding resistance Phase to phase at 25°C | Ohm | 0.90 | 0.49 | 0.18 | 0.12 | 0.13 | 0.10 |
| Winding inductance Phase to phase | mH | 5.4 | 4.4 | 2.2 | 1.2 | 2.5 | 2.4 |
| Thermal resistance [4] | °C/Watt | 0.48 | 0.34 | 0.31 | 0.24 | 0.23 | 0.21 |
| Poles | | 6 | 8 | 8 | 8 | 8 | 8 |

1 Peak value of per phase sine wave amps.
2 Peak value of per phase square wave amps
3 Peak value of sinusoidal phase to phase volts
4 At 125°C winding temperature, in a 40°C ambient; motors 3007, 3016 mounted 0.25 in. x 10 in. x 10 in.; motors 4030, 4050, 4075 mounted on 0.5 in. x 12 in. x 12 in.; motors 6100, 6200, 6300, 8350, 8500 mounted on 1 in. x 12 in. x 12 in. aluminum heat sink.

## Storage and Operating Specifications

| Storage and Operating Conditions | |
|---|---|
| Ambient Temperature | Operating: 0 to 40ºC (32 to 104ºF)<br>Storage: -30 to 70ºC (-25 to 158ºF) |
| Relative Humidity | 5% to 95% non-condensing |

## H-Series Thermostat Specifications

| Specifications | |
|---|---|
| Rated voltage | 0 - 250V DC or 50/60 Hz AC[1] |
| Rated current | 2.5A at power factor of 1.0<br>1.6A at power factor of 0.6 |
| Maximum switching current | 5 A |
| Contact resistance | Less than 0.10 Ohms maximum |
| Contacts | Normally closed |
| Insulation dielectric | Mylar Nomex capable of withstanding<br>1500V AC RMS 50/60 Hz for 1 minute |
| Opening temperature (±5ºC) | 140ºC |

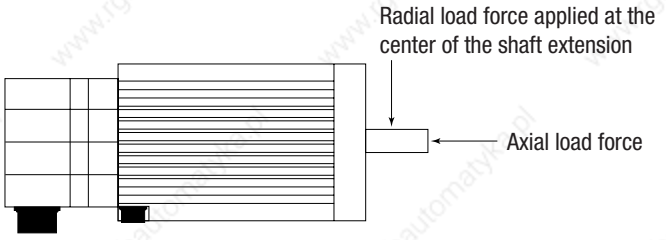
1 The thermostat is normally used as a switch for a 24V DC logic signal.

## H-Series Standard Motor Radial Load Force Ratings

| Ratings | Units | H-2005 | H-3007 | H-3016 | H-4030-M | H-4030-P | H-4050 |
|---|---|---|---|---|---|---|---|
| 500 RPM | kg<br>(lbs) | 63.5<br>(105) | 68.0<br>(113) | 76.2<br>(126) | 102.1<br>(169) | 102.1<br>(169) | 123.8<br>(205) |
| 1000 RPM | kg<br>(lbs) | 50.8<br>(84) | 54.4<br>(90) | 60.8<br>(101) | 91.6<br>(152) | 91.6<br>(152) | 98.9<br>(164) |
| 2000 RPM | kg<br>(lbs) | 39.9<br>(66) | 43.1<br>(71) | 47.6<br>(79) | 72.6<br>(120) | 72.6<br>(120) | 78.0<br>(129) |
| 3000 RPM | kg<br>(lbs) | 34.9<br>(58) | 37.6<br>(62) | 41.7<br>(69) | 63.5<br>(105) | 63.5<br>(105) | 68.0<br>(113) |
| 4000 RPM | kg<br>(lbs) | 31.8<br>(53) | 34.0<br>(56) | 38.1<br>(63) | 57.6<br>(95) | 57.6<br>(95) | 62.1<br>(103) |
| 5000 RPM | kg<br>(lbs) | 29.5<br>(49) | 31.8<br>(53) | 35.4<br>(59) | NA | NA | NA |
| 6000 RPM | kg<br>(lbs) | 20.4<br>(45) | NA | NA | NA | NA | NA |

| Ratings | Units | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| 500 RPM | kg<br>(lbs) | 129.7<br>(215) | 263.1<br>(435) | 283.5<br>(469) | 299.4<br>(495) | 299.4<br>(495) | 313.0<br>(518) |
| 1000 RPM | kg<br>(lbs) | 104.3<br>(173) | 208.7<br>(345) | 226.8<br>(375) | 235.9<br>(390) | 238.1<br>(394) | 249.5<br>(413) |
| 2000 RPM | kg<br>(lbs) | 82.6<br>(137) | 165.6<br>(274) | 179.2<br>(296) | 188.2<br>(311) | 188.2<br>(311) | 197.3<br>(326) |
| 3000 RPM | kg<br>(lbs) | 71.2<br>(118) | 145.2<br>(240) | 156.5<br>(259) | 163.3<br>(270) | NA | NA |
| 4000 RPM | kg<br>(lbs) | 65.3<br>(108) | NA | NA | NA | NA | NA |

Motors are capable of carrying an axial load in most applications according to the following general guidelines. These guidelines should only be used as approximations.




- When the motor shaft has no radial load, the axial load rating is 100% of the radial load rating from the table above.
- When the motor shaft has both a radial and an axial load, the axial load rating is 44% of the radial load rating from the table above.

## ULTRA 100 Series Specifications for H-Series Motors[1]

| Specifications | | H-2005 | H-3007 | H-3016 | H-4030-M | H-4030-P | H-4050 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | 009 | 009 | 019 | NA | 019 | NA |
| Maximum continuous operating speed [2] | RPM | 6000 | 5000 | 5000 | NA | 4000 | NA |
| Continuous stall torque [3] | N-m (lb-in.) | 0.57 (5) | 0.79 (7) | 2.26 (20) | NA | 3.39 (30) | NA |
| Peak torque [4] | N-m (lb-in.) | 1.6 (14) | 2.48 (22) | 4.97 (44) | NA | 8.25 (73) | NA |

| Specifications | Units | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | NA | NA | NA | NA | NA | NA |
| Maximum continuous operating speed [2] | RPM | NA | NA | NA | NA | NA | NA |
| Continuous stall torque [3] | N-m (lb-in.) | NA | NA | NA | NA | NA | NA |
| Peak torque [4] | N-m (lb-in.) | NA | NA | NA | NA | NA | NA |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230 V AC line voltage input.
3 At 125°C winding temperature, in a 40°C ambient; motors 3007, 3016 mounted 0.25 in. x 10 in. x 10 in.; motors 4030, 4050, 4075 mounted on 0.5 in. x 12 in. x 12 in.; motors 6100, 6200, 6300, 8350, 8500 mounted on 1 in. x 12 in. x 12 in. aluminum heat sink.
4 System limit.

## ULTRA 200 Series Specifications for H-Series Motors[1]

| Specifications | | H-2005 | H-3007 | H-3016 | H-4030-M | H-4030-P | H-4050 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | 010 | 010 | 020 | 030 | 020 | 030/075 |
| Maximum continuous operating speed [2] | RPM | 6000 | 5000 | 5000 | 4000[5] | 4000 | 4000/4000 |
| Continuous stall torque [3] | N-m<br>(lb-in.) | 0.57<br>(5.0) | 0.79<br>(7.0) | 2.3<br>(20) | 3.4<br>(30) | 3.4<br>(30) | 6.8<br>(60) |
| Peak torque [4] | N-m<br>(lb-in.) | 1.2<br>(10) | 2.5<br>(22) | 5.0<br>(44) | 6.8<br>(60) | 8.3<br>(73) | 13.6/21.5<br>(120/190) |

| Specifications | | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | 030/075 | 075 | 075 | 150 | 150 | 150 |
| Maximum continuous operating speed [2] | RPM | 3000/3000 | 3000 | 3000 | 3000 | 2000 | 2000 |
| Continuous stall torque [3] | N-m<br>(lb-in.) | 9.9<br>(88) | 12.4<br>(110) | 21.4<br>(190) | 36.7<br>(300) | 39.5<br>(350) | 50.8<br>(450) |
| Peak torque [4] | N-m<br>(lb-in.) | 20.3/30.5<br>(180/270) | 32.8<br>(290) | 40.7<br>(360) | 79.1<br>(700) | 67.8<br>(600) | 108<br>(960) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.

2 With 230V AC line voltage input.

3 At 125°C winding temperature, in a 40°C ambient; motors 3007, 3016 mounted 0.25in. x 10 in. x 10 in.; motors 4030, 4050, 4075 mounted on 0.5 in. x 12 in. x 12 in.; motors 6100, 6200, 6300, 8350, 8500 mounted on 1 in. x 12 in. x 12 in. aluminum heat sink.

4 System limit.

5 With either 115 or 230V AC line voltage input.

## ULTRA Plus Specifications for H-Series Motors[1]

| Specifications | | H-2005 | H-3007 | H-3016 | H-4030-M | H-4030-P | H-4050 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-PDM- | 10 | 10 | 20 | 30 | 20 | 30/75 |
| Maximum continuous operating speed [2] | RPM | 6000 | 5000 | 5000 | 4000[5] | 4000 | 4000/4000 |
| Continuous stall torque [3] | N-m (lb-in.) | 0.57 (5.0) | 0.79 (7.0) | 2.3 (20) | 3.4 (30) | 3.4 (30) | 6.8 (60) |
| Peak torque [4] | N-m (lb-in.) | 1.2 (10) | 2.5 (22) | 5.0 (44) | 6.8 (60) | 8.3 (73) | 13.6/21.5 (120/190) |

| Specifications | | H-4075 | H-6100 | H-6200 | H-6300 | H-8350 | H-8500 |
|---|---|---|---|---|---|---|---|
| Drive | 1398-PDM- | 30/75 | 75 | 75 | 150 | NA | 150 |
| Maximum continuous operating speed [2] | RPM | 3000/3000 | 3000 | 3000 | 3000 | NA | 2000 |
| Continuous stall torque [3] | N-m (lb-in.) | 9.9 (88) | 11.30 (100) | 20.9 (185) | 36.7 (325) | NA | 50.8 (450) |
| Peak torque [4] | N-m (lb-in.) | 20.3/30.5 (180/270) | 25.42 (225) | 40.68 (360) | 79.1 (700) | NA | 108 (960) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.

2 With 230V AC line voltage input.

3 At 125°C winding temperature, in a 40°C ambient; motors 3007, 3016 mounted 0.25in. x 10 in. x 10 in.; motors 4030, 4050, 4075 mounted on 0.5 in. x 12 in. x 12 in.; motors 6100, 6200, 6300, 8350, 8500 mounted on 1 in. x 12 in. x 12 in. aluminum heat sink.

4 System limit.

5 With either 115 or 230V AC line voltage input.

## H-Series Brake Specifications

| Specifications | H-3000 | H-4000 | H-6000 | H-8000 |
|---|---|---|---|---|
| Maximum backlash (brake engaged) | 1 degree, 30 minutes | 44 minutes | 29 minutes | 21 minutes |
| Holding torque | 2.26 N-m (20 lb-in.) | 10.2 N-m (90 lb-in.) | 22.6 N-m (200 lb-in.) | 50.8 N-m (450 lb-in.) |
| Coil current at 24V DC | 0.6 ADC | 0.88 ADC | 1.13 ADC | 2.2 ADC |
| Coil current at 90V DC | 0.21 ADC | 0.26 ADC | 0.33 ADC | 0.62 ADC |

## Brake Motor Application Guidelines

The brakes offered as options on these servo motors are holding brakes. They are designed to hold the motor shaft at 0 rpm for up to the rated brake holding torque. The brakes are spring-set type, and release when voltage is applied to the brake coil.

The brakes are *not* designed for stopping rotation of the motor shaft. Servo drive inputs should be used to stop motor shaft rotation. The recommended method of stopping motor shaft rotation is to command the servo drive to decelerate the motor to 0 rpm, and engage the brake after the servo drive has decelerated the motor to 0 rpm.

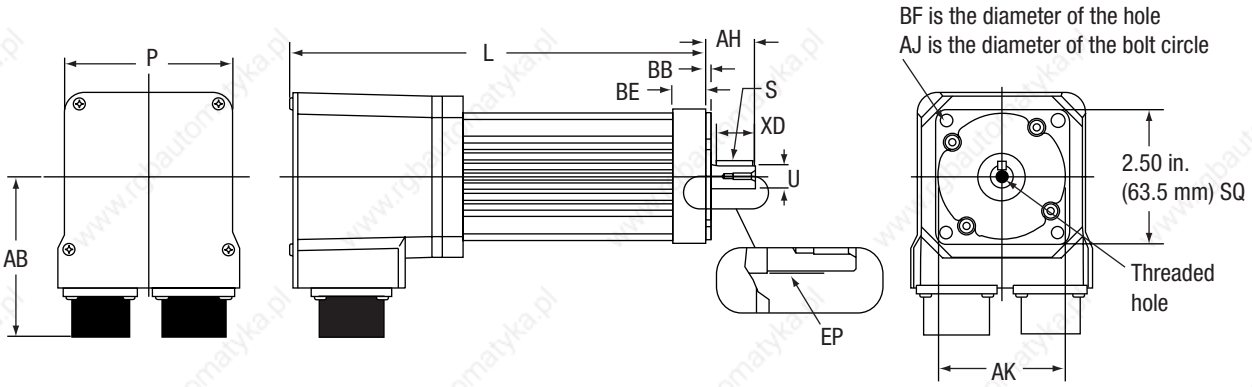
If system main power fails, the brakes can withstand use as stopping brakes. However, use of the brakes as stopping brakes creates rotational mechanical backlash that is potentially damaging to the system, increases brake pad wear and reduces brake life. The brakes are *not* designed nor are they intended to be used as a safety device.

A separate power source is required to disengage the brake. This power source may be controlled by the servo motor controls, in addition to manual operator controls.

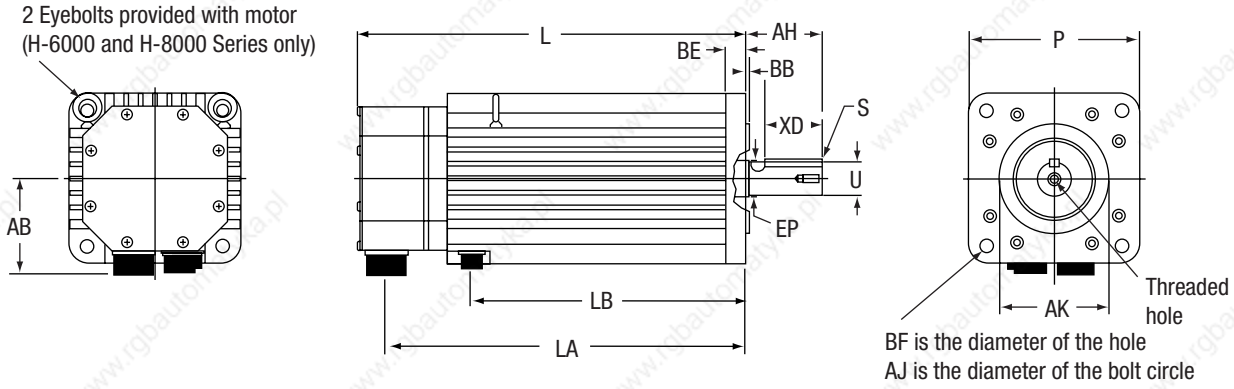
## H-Series Standard Motors Dimensions

| Dimensions | Thread | Thread/Depth |
|---|---|---|
| H-2000 | M3 x 0.5 mm | 10 mm/0.39 in. |
| H-3000 | M4 x 0.7 mm | 10 mm/0.39 in. |
| H-4000 | M6 x 1.0 mm | 15 mm/0.59 in. |
| H-6000 | M8 x 1.25 mm | 20 mm/0.79 in. |
| H-8000 | M8 x 1.25 mm | 20 mm/0.79 in. |

## H-2000 Motors Dimensions (see page 34 for dimension values)




## H-3000, -4000, -6000, and -8000 Motors Dimensions (see page 34 for dimension values)



| Dimen-sions | AB | AH[3] | AJ | AK | BB[4] | BE | BF | EP | L | L with brake | P | S | U | XD |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| **Motor Models** | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm x mm (in. x in.) | mm (in.) | mm (in.) |
| H-2005 | 75 (2.95) | 23 (0.93) | 75 (2.95) | 60[1] (2.36) | 2.4 (0.09) | 15.2 (0.60) | 5.8 (0.23) | 12 (0.47) | 197 (7.7) | NA | 80 (3.15) | 4 x 4 (0.16 x 0.16) | 11[2] (0.43) | 18 (0.71) |
| H-3007 | 75 (2.95) | 30 (1.18) | 100 (3.94) | 80[1] (3.15) | 3 (0.12) | 10.9 (0.43) | 7 (0.28) | 15 (0.59) | 172 (6.77) | 211 (8.31) | 89 (3.50) | 5 x 5 (0.20 x 0.20) | 14[2] (0.55) | 20 (0.79) |
| H-3016 | 75 (2.95) | 30 (1.18) | 100 (3.94) | 80[1] (3.15) | 3 (0.12) | 10.9 (0.43) | 7 (0.28) | 15 (0.59) | 233 (8.77) | 262 (10.31) | 89 (3.50) | 5 x 5 (0.20 x 0.20) | 14[2] (0.55) | 20 (0.79) |
| H-4030 | 76 (3.00) | 50 (1.97) | 145 (5.71) | 110[5] (4.33) | 3 (0.12) | 15.5 (0.61) | 10 (0.39) | 20 (0.79) | 213 (8.39) | 266 (10.47) | 121 (4.76) | 6 x 6 (0.24 x 0.24) | 19[6] (0.75) | 40 (1.57) |
| H-4050 | 76 (3.00) | 50 (1.97) | 145 (5.71) | 110[5] (4.33) | 3 (0.12) | 15.5 (0.61) | 10 (0.39) | 20 (0.79) | 264 (10.39) | 317 (12.48) | 121 (4.76) | 6 x 6 (0.24 x 0.24) | 19[6] (0.75) | 40 (1.57) |
| H-4075 | 76 (3.00) | 50 (1.97) | 145 (5.71) | 110[5] (4.33) | 3 (0.12) | 15.5 (0.61) | 10 (0.39) | 20 (0.79) | 315 (12.40) | 368 (14.49) | 121 (4.76) | 6 x 6 (0.24 x 0.24) | 19[6] (0.75) | 40 (1.57) |
| H-6100 | 101 (4.00) | 80 (3.15) | 200 (7.87) | 114.3[5] (4.50) | 4 (0.16) | 21.3 (0.84) | 13.5 (0.53) | 38 (1.50) | 277 (10.91) | 330 (12.99) | 178 (7.01) | 10 x 8 (0.39 x 0.31) | 35[7] (1.38) | 60 (2.36) |
| H-6200 | 101 (4.00) | 80 (3.15) | 200 (7.87) | 114.3[5] (4.50) | 4 (0.16) | 21.3 (0.84) | 13.5 (0.53) | 38 (1.50) | 353 (13.90) | 406 (15.98) | 178 (7.01) | 10 x 8 (0.39 x 0.31) | 35[7] (1.38) | 60 (2.36) |
| H-6300 | 101 (4.00) | 80 (3.15) | 200 (7.87) | 114.3[5] (4.50) | 4 (0.16) | 21.3 (0.84) | 13.5 (0.53) | 38 (1.50) | 429 (16.89) | 442 (17.40) | 178 (7.01) | 10 x 8 (0.39 x 0.31) | 35[7] (1.38) | 60 (2.36) |
| H-8350 | 112 (4.41) | 85 (3.35) | 265 (10.43) | 230[8] (9.06) | 4 (0.16) | 22.4 (0.88) | 15 (0.59) | 45 (1.77) | 375 (14.76) | 478 (18.82) | 241 (9.49) | 12 x 8 (0.41 x 0.31) | 42[7] (1.65) | 60 (2.36) |
| H-8500 | 112 (4.41) | 85 (3.35) | 265 (10.43) | 230[8] (9.06) | 4 (0.16) | 22.4 (0.88) | 15 (0.59) | 45 (1.77) | 426 (16.77) | 529 (20.83) | 241 (9.49) | 12 x 8 (0.41 x 0.31) | 42[7] (1.65) | 60 (2.36) |

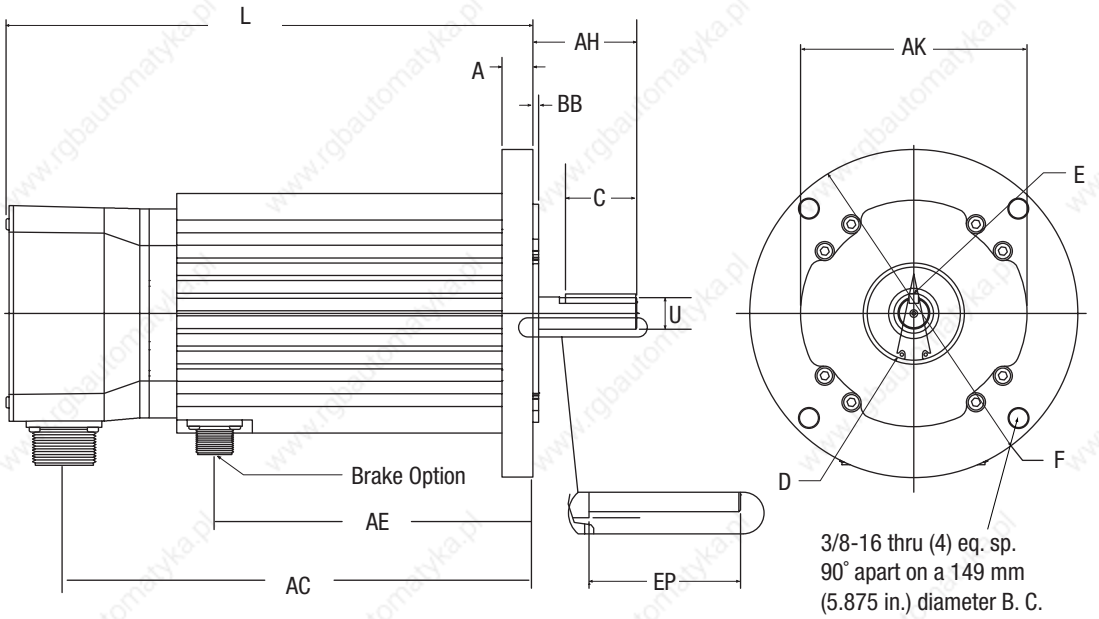
1 Tolerance is -0.0012 in. (-0.03 mm).
2 Tolerance is -0.0004 in. (-0.01 mm).
3 Tolerance is ±0.0196 in. (±0.5 mm).
4 Tolerance is ±0.0079 in. (±0.2 mm).
5 Tolerance is -0.0014 in. (-0.035 mm).
6 Tolerance is -0.0051 in. (-0.013 mm).
7 Tolerance is -0.0006 in. (-0.16 mm).
8 Tolerance is -0.0181 in. (-0.46 mm).

## Supplemental Motor Dimensions

| Connector | | H-2005 | H-3007 | Brake | H-3016 | Brake | H-4030 | Brake | H-4050 | Brake | H-4075 | Brake |
|---|---|---|---|---|---|---|---|---|---|---|---|---|
| Brake (mm/in) | LC | – | – | 107/4.21 | – | 158/6.22 | – | 160/6.30 | – | 211/8.31 | – | 262/ 10.31 |
| Encoder (mm/in) | LB | 167/6.58 | 143/5.63 | 181/7.13 | 194/7.64 | 232/9.13 | 184/7.24 | 236/9.29 | 235/9.25 | 287/ 11.30 | 286/ 11.26 | 338/ 13.30 |
| Power (mm/in) | LA | | | | | | | | | | | |

| Connector | | H-6100 | Brake | H-6200 | Brake | H-6300 | Brake | H-8350 | Brake | H-8500 | Brake |
|---|---|---|---|---|---|---|---|---|---|---|---|
| Brake (mm/in) | LB | – | 189/7.44 | – | 265/10.43 | | 341/13.42 | | 334/13.13 | | 384/15.13 |
| Encoder (mm/in) | LA | 251/9.88 | 299/11.77 | 327/12.87 | 375/14.76 | 403/15.87 | 451/17.75 | 326/12.83 | 429/16.83 | 377/14.83 | 480/18.83 |
| Power (mm/in) | | | | | | | | | | | |

## H-4000 NEMA 56C Dimensions



| Dimensions | H-4030 NEMA 56C | H-4050 NEMA 56C | H-4075 NEMA 56C |
|---|---|---|---|
| A | 15.5 mm (0.61 in.) | | |
| AH | 52 mm (2.06 in.) | | |
| AK | 114.3 mm (4.500 in.) diameter | | |
| BB | 3 mm (0.12 in.) | | |
| C | 36 mm (1.41 in.) full depth | | |
| D | Motor will accept 47 mm (1.850 in.) x 20 mm (0.788 in.)<br>7 mm (0.276 in.) shaft seal (optional, not included) | | |
| E | Key supplied<br>4.8 mm (0.1875 in.) square x 35 mm (1.375 in.) long) | | |
| EP | 50.8 mm (2.00 in.) diameter | | |
| F | 165 mm (6.50 in.) diameter | | |
| L (without brake) | 213 mm (8.39 in.) | 264 mm (10.39 in.) | 315 mm (12.40 in.) |
| L (with brake) | 266 mm (10.47 in.) | 317 mm (12.48 in.) | 368 mm (14.49 in.) |
| U | 15.9 mm (0.625 in.) diameter | | |

## Supplemental Motor Dimensions

| | Brake (AE) | Power (AC) | Encoder (AC) |
|---|---|---|---|
| **Motors** | (in/mm) | (in/mm) | (in/mm) |
| H-4030<br>H-4030 Brake | –<br>6.30/160 | 7.24/184<br>9.29/236 | 7.24/184<br>9.29/236 |
| H-4050<br>H-4050 Brake | –<br>8.31/211 | 9.25/235<br>11.30/287 | 9.25/235<br>11.30/287 |
| H-4075<br>H-4075 Brake | –<br>10.31/262 | 11.26/286<br>13.30/338 | 11.26/286<br>13.30/338 |

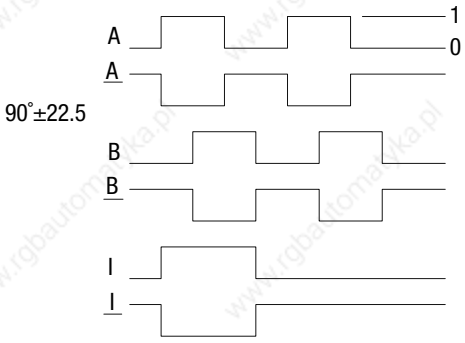
## Encoder Data

Encoders are factory aligned and must not be adjusted outside the factory.

| Specifications | |
|---|---|
| Line Count | 2000[1] |
| Supply Voltage | 5 VDC |
| Supply Current | 250 mA max. |
| Line Driver | 26LS31 |
| Line Driver Output | TTL |
| Index Pulse | H-2000 and H-3000 Series when key faces 180° ± 10 away from the connectors |
| | H-4000, H-6000 and H-8000 Series when key faces the connectors (0° ± 10) |

[1] Standard line count before quadrature.

## Encoder Outputs

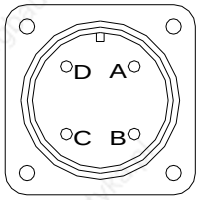



WAVEFORMS RESULT FROM CW SHAFT ROTATION
(CLOCKWISE AS VIEWED FACING THE SHAFT EXTENSION)

## H-Series Connector Pins and Signals

### Motor Power Connector (All H-Series Motors)

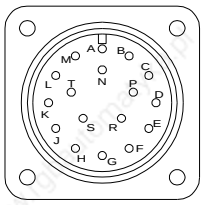
| Pin | Signal |
|---|---|
| A | R |
| B | S |
| C | T |
| D | Motor Case |




### Motor Encoder Connector

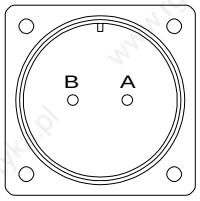
| Pin | Signal |
|---|---|
| A | A+ |
| B | A- |
| C | B+ |
| D | B- |
| E | I+ |
| F | I- |
| G | Encoder Case |
| H | ABS |
| J | +5V DC |

| Pin | Signal |
|---|---|
| K | +5V DC |
| L | COM |
| M | COM |
| N | Hall B |
| P | Hall C |
| R | TS+ |
| S | TS- |
| T | Hall A |



### Optional Motor Brake Connector

| Pin | Signal |
|---|---|
| A | BR+ |
| B | BR- |




## Wire and Contact Sizing Recommendations

### Power Connector

The following connector contact sizes and wiring gages are recommended for cabling to a motor.

| Motor | Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|---|
| H-2005 | 16 (1.5) | 16 (1.5) |
| H-3007 | | |
| H-3016 | | |
| H-4030 | 12 (4.0) | |
| H-4050 | | 14 (2.5) |
| H-4075 | | |
| H-6100 | 8 (8.6) | 12 (4.0) |
| H-6200 | | 8 (10.0) |
| H-6300 | | |
| H-8350 | 4 (21.6) | 6 (16.0) |
| H-8500 | | |

- Sizes are recommended minimum values for 4 conductors (R, S, T and GND).
- Wiring should be twisted.
- Local regulations should always be observed.

### Encoder Connector

| Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|
| All H-Series<br>16 (1.5) | 24 (0.25) with ULTRA Plus Series Drives |
| | 22 (0.34) with ULTRA Series 100-200 Drives |

### Brake Connector

| Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|
| All H-Series<br>16 (1.5) | 18 (0.75) |

- These specifications are the recommended minimum mechanical size.
- Local regulations should always be observed.

## Y-Series Motors



Y-Series motors, available in either 115V or 230V windings, use high energy neodymium magnets that provide low inertias for fast accelerations. Available in three popular metric frame sizes, the Y-Series motors range in continuous torque capability from 0.17 to 2.5 N-m (1.5 to 22 lb-in.) and reach speeds up to 4500 RPM. Their outstanding torque-to-size ratios make the Y-Series a powerful combination with the ULTRA 100 and 200 drives. Typical applications for the Y-Series include robotics, material handling, X-Y tables, specialty machinery, and semiconductor manufacturing. IP43 enclosure protection is standard.

### Features

The Y-Series motors have the following features:

- 115V and 230V windings
- Popular metric mounting dimensions
- Three frame sizes, ten models
- Continuous torque from 0.17 to 2.5 N-m (1.5 to 22 lb-in.)
- Motor-mounted optical encoder with differential line driver data (2000-line) and commutation signal
- Low inertia rotor
- High energy neodymium magnets
- Speeds up to 4500 RPM
- Optional internally mounted spring set, magnetic release 24V DC holding brake
- IP43 package
- Vibration: 2.5 g peak 30-2000 Hz
- Shock: 10.0 g peak 6 ms duration

## Typical Applications

Typical applications for the Y-Series motors are:

- Robotics
- Material handling
- Specialty machinery
- Medical and laboratory equipment
- X-Y tables
- Light packaging machines
- Office machinery
- Postal sorting

## Selecting a Drive/Motor Connection

The following drive/motor combinations are available for the Y-Series motors:

| Motor | ULTRA 100 | ULTRA 200 | ULTRA Plus |
|---|---|---|---|
| Y-1002-1-H00AA | 1398-DDM-005 | 1398-DDM-010 | NA |
| Y-1002-2-H00AA | 1398-DDM-005 | 1398-DDM-010 | NA |
| Y-1003-1-H00AA | 1398-DDM-009 | 1398-DDM-010 | NA |
| Y-1003-2-H00AA | 1398-DDM-005 | 1398-DDM-010 | NA |
| Y-2006-1-H00AA | 1398-DDM-019 | 1398-DDM-010 | NA |
| Y-2006-2-H00AA | 1398-DDM-009 | 1398-DDM-020 | NA |
| Y-2012-1-H00AA | 1398-DDM-019 | 1398-DDM-020 | NA |
| Y-2012-2-H00AA | 1398-DDM-009 | 1398-DDM-010 | NA |
| Y-3023-2-H00AA | 1398-DDM-019 | 1398-DDM-020 | NA |

## Y-Series Specifications

This section contains the mechanical, thermostat and winding specifications for the Y-Series motor family, as well as the load force ratings and performance specifications for every combination of ULTRA series drives and Y-Series motors. It also provides motor dimensions, connector pin and signal designations, and all motor and connector ordering information.

### Y-Series Mechanical Specifications

| Specifications | Units | Y-1002-1<br>Y-1002-2 | Y-1003-1<br>Y-1003-2 | Y-2006-1<br>Y-2006-2 | Y-2012-1<br>Y-2012-2 | Y-3023-2 |
|---|---|---|---|---|---|---|
| Rotor moment of inertia | kg-$m^2$<br>(lb-in.-$s^2$) | 0.0000031<br>(0.000027) | 0.0000051<br>(0.000045) | 0.000015<br>(0.00013) | 0.000026<br>(0.00023) | 0.000064<br>(0.00056) |
| Rotor moment of inertia<br>(brake motors) | kg-$m^2$<br>(lb-in.-$s^2$) | 0.0000039<br>(0.000034) | 0.0000059<br>(0.000052) | 0.000020<br>(0.00018) | 0.000032<br>(0.00028) | 0.000069<br>(0.00062) |
| Motor shipping weight | kg<br>(lb) | 0.9<br>(2.0) | 1.0<br>(2.3) | 1.7<br>(3.8) | 2.3<br>(5.1) | 3.9<br>(8.7) |
| Motor net weight | kg<br>(lb) | 0.5<br>(1.1) | 0.7<br>(1.5) | 1.3<br>(2.9) | 1.9<br>(4.1) | 3.5<br>(7.8) |
| Damping | N-m/kRPM<br>(lb-in./kRPM) | 0.002<br>(0.022) | 0.003<br>(0.03) | 0.009<br>(0.08) | 0.01<br>(0.10) | 0.021<br>(0.19) |
| Friction torque | N-m<br>(lb-in.) | 0.005<br>(0.04) | 0.007<br>(0.06) | 0.022<br>(0.20) | 0.03<br>(0.29) | 0.072<br>(0.64) |
| Maximum Operating Speed | rpm | 4500 | 4500 | 4500 | 4500 | 4500 |

## Y-Series Winding Specifications

| Specifications | Units | Y-1002- | | Y-1003- | | Y-2006- | | Y-2012- | | Y-3023-2 |
|---|---|---|---|---|---|---|---|---|---|---|
| | | 1 | 2 | 1 | 2 | 1 | 2 | 1 | 2 | |
| Sine wave $K_T$ torque Constant at 25°C [1] | N-m/A (lb-in./A) | 0.08 (0.73) | 0.16 (1.4) | 0.11 (1.0) | 0.20 (1.8) | 0.10 (0.95) | 0.22 (1.9) | 0.24 (2.1) | 0.37 (3.3) | 0.33 (2.9) |
| Square wave $K_T$ torque Constant at 25°C [2] | N-m/A (lb-in./A) | 0.09 (0.8) | 0.18 (1.6) | 0.12 (1.1) | 0.22 (2.0) | 0.12 (1.1) | 0.24 (2.2) | 0.26 (2.3) | 0.40 (3.6) | 0.36 (3.2) |
| $K_E$ voltage constant [3] | V/kRPM | 10 | 20 | 14 | 25 | 13 | 27 | 29 | 45 | 40 |
| Winding resistance Phase to phase at 25°C | Ohm | 4.6 | 18.8 | 3.2 | 8.9 | 0.79 | 3.2 | 1.3 | 2.9 | 0.78 |
| Winding inductance Phase to phase | mH | 5.5 | 22.3 | 3.8 | 11.5 | 2.7 | 12 | 5.1 | 12.4 | 6 |
| Thermal resistance [4] | °C/Watt | 2.3 | 2.3 | 2.2 | 2.2 | 1.3 | 1.3 | 1.3 | 1.3 | 0.85 |
| Encoder resolution | P/R | 2000 | 2000 | 2000 | 2000 | 2000 | 2000 | 2000 | 2000 | 2000 |
| Poles | | 8 | 8 | 8 | 8 | 8 | 8 | 8 | 8 | 8 |

1 Peak value of per phase sine wave amps.
2 Peak value of per phase square wave amps
3 Peak value of sinusoidal phase to phase volts
4 At 125°C winding temperature, in a 40°C ambient, with motor mounted on aluminum heat sinks: motors 1002, 1003—0.125 in. x 6 in. x 6 in.; motors 2006, 2012—0.250 in. x 8 in. x 8 in.; motor 3023— 0.25 in. x 10 in. x 10 in.

## Storage and Operating Specifications

| Storage and Operating Conditions | |
|---|---|
| Ambient Temperature | Operating: 0 to 40°C (32 to 104°F)<br>Storage: -20 to 65°C (-4 to 149°F) |
| Relative Humidity | 20% to 90% non-condensing |

## Brake Motor Application Guidelines

The brakes offered as options on these servo motors are holding brakes. They are designed to hold the motor shaft at 0 rpm for up to the rated brake holding torque. The brakes are spring-set type, and release when voltage is applied to the brake coil.

The brakes are *not* designed for stopping rotation of the motor shaft. Servo drive inputs should be used to stop motor shaft rotation. The recommended method of stopping motor shaft rotation is to command the servo drive to decelerate the motor to 0 rpm, and engage the brake after the servo drive has decelerated the motor to 0 rpm.

If system main power fails, the brakes can withstand use as stopping brakes. However, use of the brakes as stopping brakes creates rotational mechanical backlash that is potentially damaging to the system, increases brake pad wear and reduces brake life. The brakes are *not* designed nor are they intended to be used as a safety device.

A separate power source is required to disengage the brake. This power source may be controlled by the servo motor controls, in addition to manual operator controls.

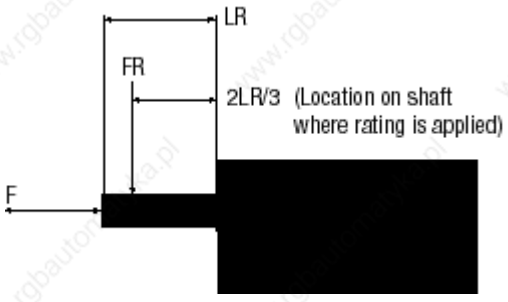
## Y-Series Brake Specifications

| Specifications | Y-1002 | Y-1003 | Y-2006 | Y-2012 | Y-3023 |
|---|---|---|---|---|---|
| Holding Torque | 1.39 lb-in. (0.157 N-m) | 2.83 lb-in. (0.32 N-m) | 5.64 lb-in. (0.637 N-m) | 11.24 lb-in. (1.274 N-m) | 21.06 lb-in. (2.38 N-m) |
| Coil Current at 24 VDC | 0.26 Amps | | 0.31 Amps | | 0.37 Amps |

## Y-Series Motor Brake and Shaft Load Data

| Motor | Brake Holding Torque | Shaft Radial Load (FR) | Axial Load (F) | Coil Current |
|---|---|---|---|---|
| Y-1002 | 0.157 N-m | 10 kg | 3 kg | 0.26A |
| Y-1003 | 0.32 N-m | 10 kg | 3 kg | 0.26A |
| Y-2006 | 0.637 N-m | 20 kg | 8 kg | 0.31A |
| Y-2012 | 1.27 N-m | 25 kg | 10 kg | 0.31A |
| Y-3023 | 2.38 N-m | 35 kg | 20 kg | 0.37A |

[1] The FR and F refer to loads applied as shown in the drawing above.



## ULTRA 100 Series Specifications for Y-Series Motors[1]

| Specifications | | Y-1002- | | Y-1003- | | Y-2006- | | Y-2012- | | Y-3023-2 | |
|---|---|---|---|---|---|---|---|---|---|---|---|
| | | 1 | 2 | 1 | 2 | 1 | 2 | 1 | 2 | 115V | 230V |
| Drive | 1398-DDM- | 005 | 005 | 009 | 005 | 019 | 009 | 019 | 009 | 019 | 019 |
| Maximum continuous operating speed | RPM | 4500 | 4500 | 4500 | 4500 | 4500 | 4500 | 3800 | 4500 | 2500 | 4500 |
| Continuous stall torque[3] | N-m (lb-in.) | 0.17 (1.5) | 0.17 (1.5) | 0.35 (3.1) | 0.35 (3.1) | 0.69 (6.1) | 0.69 (6.1) | 1.4 (12) | 1.4 (12) | 2.5 (22.5) | 2.5 (22.5) |
| Peak torque[4] | N-m (lb-in.) | 0.48 (4.3) | 0.48 (4.3) | 0.97 (8.6) | 0.97 (8.6) | 1.92 (17) | 1.92 (17) | 3.8 (33.7) | 3.8 (33.7) | 7.1 (63) | 7.1 (63) |

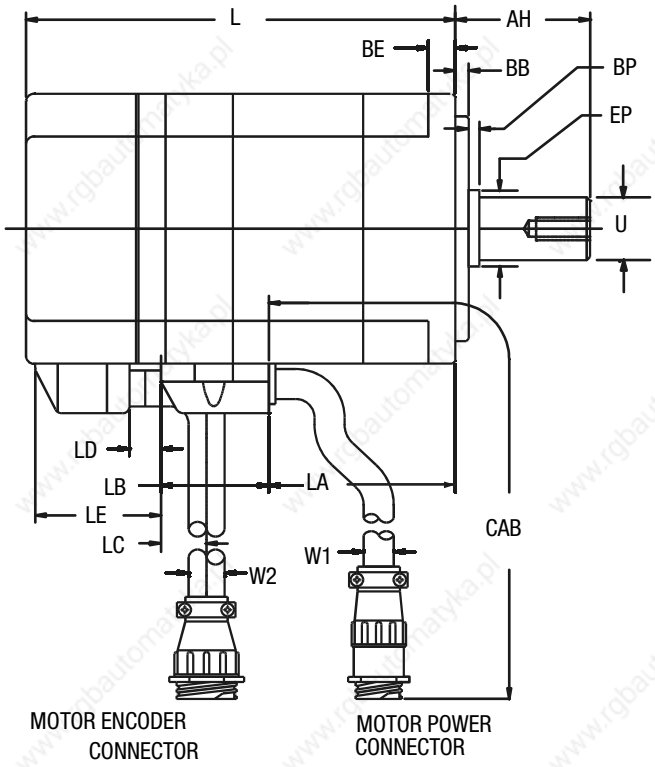
1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 At drive input voltage.
3 At 125°C winding temperature, in a 40°C ambient, with motor mounted on aluminum heat sinks: motors 1002, 1003—0.125 in. x 6 in. x 6 in.; motors 2006, 2012—0.250 in. x 8 in. x 8 in.; motor 3023— 0.25 in. x 10 in. x 10 in.
4 System limit.

## ULTRA 200 Specifications for Y-Series Motors[1 2]

| Specifications | | Y-1002- | | Y-1003- | | Y-2006- | | Y-2012- | | Y-3023- | |
|---|---|---|---|---|---|---|---|---|---|---|---|
| | | 1 | 2 | 1 | 2 | 1 | 2 | 1 | 2 | 115V | 230V |
| Drive | 1398-DDM- | 010 | 010 | 010 | 010 | 010 | 020 | 020 | 020 | 020 | 020 |
| Maximum continuous operating speed | RPM | 4500 | 4500 | 4500 | 4500 | 4500 | 4500 | 4500 | 4500 | 2500 | 4500 |
| Continuous stall torque[3] | N-m (lb-in.) | 0.17 (1.5) | 0.17 (1.5) | 0.35 (3.1) | 0.35 (3.1) | 0.69 (6.1) | 0.69 (6.1) | 1.4 (12) | 1.4 (12) | 2.5 (22.5) | 2.5 (22.5) |
| Peak torque[4] | N-m (lb-in.) | 0.48 (4.3) | 0.48 (4.3) | 0.97 (8.6) | 0.97 (8.6) | 1.9 (16.6) | 1.9 (16.6) | 3.4 (30.0) | 3.8 (33.7) | 6.0 (53.0) | 7.1 (63.0) |

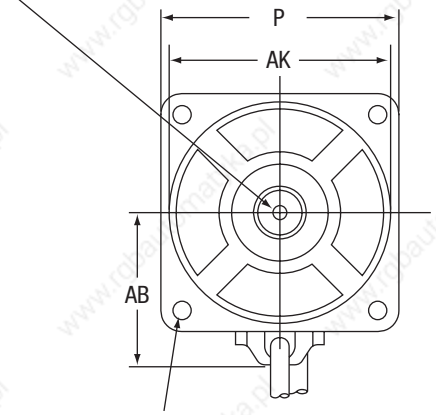
1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 At drive input voltage.
3 At 125°C winding temperature, in a 40°C ambient, with motor mounted on aluminum heat sinks: motors 1002, 1003—0.125 in. x 6 in. x 6 in.; motors 2006, 2012—0.250 in. x 8 in. x 8 in.; motor 3023— 0.25 in. x 10 in. x 10 in.
4 System limit.

## Y-Series Standard Motors Dimensions




**Shaft End Threaded Hole**

| Motor Series | Thread | Thread Depth |
|---|---|---|
| Y-2006 | M5 x 0.8 | 0.47 in. (12 mm) |
| Y-2012 | M5 x 0.8 | 0.47 in. (12 mm) |
| Y-3203 | M5 x 0.8 | 0.47 in. (12 mm) |




BF is the diameter of the hole
AJ is the diameter of the bolt circle

| Dimensions | AB | AF | AH | AJ | AK | BB | BE | BF | BP | CAB | EP | L | L with brake | P | U |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| **Motor Models** | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) |
| Y-1002 | 30 (1.18) | NA | 25 (0.98) | 46 (1.81) | 30 (1.18) | 2.5 (0.10) | 5 (0.20) | 4.5 (0.18) | NA | 1000 (39.37) | NA | 70 (2.75) | 108 (4.25) | 40 (1.58) | 8 (0.31) |
| Y-1003 | 30 (1.18) | NA | 25 (0.98) | 46 (1.81) | 30 (1.18) | 2.5 (0.10) | 5 (0.20) | 4.5 (0.18) | NA | 1000 (39.37) | NA | 88 (3.46) | 126 (4.96) | 40 (1.58) | 8 (0.31) |
| Y-2006 | 41 (1.61) | NA | 30 (1.18) | 70 (2.75) | 50 (1.97) | 3 (0.12) | 6 (0.24) | 5.5 (0.22) | NA | 1000 (39.37) | NA | 95 (3.74) | 133 (4.54) | 60 (2.36) | 14 (0.55) |
| Y-2012 | 41 (1.61) | NA | 30 (1.18) | 70 (2.75) | 50 (1.97) | 3 (0.12) | 6 (0.24) | 5.5 (0.22) | NA | 1000 (39.37) | NA | 123 (4.84) | 161 (6.34) | 60 (2.36) | 14 (0.55) |
| Y-3023 | 52 (2.05) | 35 (1.38) | 40 (1.57) | 90 (3.54) | 70 (2.75) | 3 (0.12) | 8 (0.31) | 6.5 (0.25) | 2.0 (0.08) | 1000 (39.37) | 19 (0.75) | 140 (5.57) | 180 (7.09) | 80 (3.15) | 16 (0.63) |

Motors are manufactured to millimeter dimensions shown. Inch dimensions shown are appropriate conversions from millimeters. For further motor detail, engineering specification drawings are available upon request.

### Supplemental Motor Dimensions

| Dimension | Y-1002 | Y-1003 | Y-2006 | Y-2012 | Y-3023 |
|---|---|---|---|---|---|
| LA | 23.5/0.90 | 41.5/1.60 | | 69.5/2.7 | 80.5/3.2 |
| LB | 21.5/0.84 | | 24.0/0.95 | | 30.0/1.2 |
| LC[1]<br>LC (Brake)[1] | 17.5/0.70<br>56/2.2 | | – | | |
| LD<br>LD (Brake) | – | | 7.0/0.28<br>45/1.77 | | |
| LE<br>LE (Brake)[1] | – | | 28.0/1.10<br>66/2.60 | | |

[1] Measurement is to the center of the perpendicular motor encoder cable.
Motor encoder cable exits the perpendicular to the motor frame on Y-1002 and Y-1003 motors (not as shown).

### Cable Diameters

| Motor | W1 - Power/Brake | W2 - Encoder |
|---|---|---|
| Y-1002 | 6.0/0.24 | 8.0/0.31 |
| Y-1003 | | |
| Y-2006 | 6.7/0.26 | |
| Y-2012 | | |
| Y-3023 | | |

Minimum 90º cable bend allowance is 15mm.

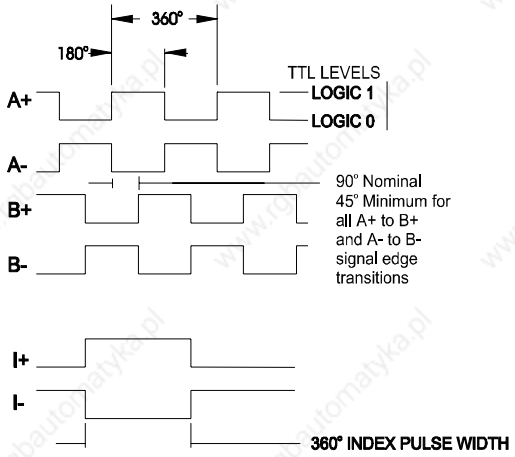
## Encoder Data

Encoders are factory aligned and must not be adjusted outside the factory.

| Specifications | |
|---|---|
| Line Counts | • Data A+, A-, B+, B-: 2000 pulse/rev<br>• Index I+, I-: 1 pulse/rev<br>• Hall A+, A-, B+, B-, C+, C-: 2 pulse/rev |
| Supply Voltage | 4.75 to 5.25 VDC |
| Supply Current | 450 mA DC |
| Line Driver | AM26LS31 equivalent |
| Line Driver Output | • Output: Logic 1 - Sourcing 2.5 VDC @ 20 mA<br>• Output: Logic 0 - Sinking 0.5 VDC @ 20 mA |

The line count is standard before quadrature.

## Encoder Outputs



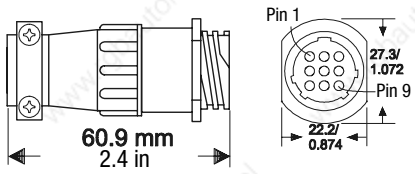

Waveforms result from clockwise rotation. “Clockwise” as viewed facing the shaft extension.

## Y-Series Connector Pins and Signals

### Motor Power Connector (All Y-Series Motors)

| Pin | Signal | Wire Color |
|---|---|---|
| 1 | Phase R | Red |
| 2 | Phase S | Black |
| 3 | Phase T | White |
| 4 | – | – |
| 5 | Ground | Green/ Yellow |

| Pin | Signal | Wire Color |
|---|---|---|
| 6 | – | – |
| 7 | Brake+[1] (Option) | Yellow |
| 8 | – | – |
| 9 | Brake-[1] (Option) | Yellow |
| | | |

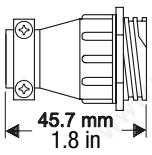


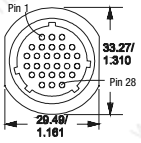

1 No connection for nonbrake motors.

### Motor Feedback Connector (All Y-Series Motors)

| Pin | Signal | Wire Color |
|---|---|---|
| 1 - 8 | – | – |
| 9 | A+ | Purple |
| 10 | A- | Green |
| 11 | B+ | Blue |
| 12 | B- | Brown |
| 13 | I+ | White |
| 14 | I- | Yellow |
| 15 | Hall A+ | Green/ Black |
| 16 | Hall A- | Purple/ Black |

| Pin | Signal | Wire Color |
|---|---|---|
| 17 | Hall B+ | Blue/Black |
| 18 | Hall B- | Brown/ Black |
| 19 | Hall C+ | Red/Black |
| 20 | Hall C- | Yellow/ Black |
| 21 | – | – |
| 22 | +5V DC | Red |
| 23 | COM | Black[1] |
| 24 | SHIELD | Black[2] |
| 25 - 28 | – | – |




1 COM (+5VDC) is not connected to the motor ground.
2 SHIELD is connected to the motor case ground.

## Wire and Contact Sizing Recommendations

### Power/Brake Connector

The following connector contact sizes and wiring gages are recommended for cabling to a motor.

| Motor | Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|---|
| Y-1002 | 0.75 - 2.5 (18-14) | 0.75 (18) |
| Y-1003 | | |
| Y-2006 | | 1.5 (16) |
| Y-2012 | | |
| Y-3023 | | |

- Sizes are recommended minimum values.
- Wiring should be twisted.
- Local regulations should always be observed.

### Encoder Connector

| Contact AWG ($mm^2$) | Wire AWG ($mm^2$) |
|---|---|
| All Y-Series<br>0.25 - 0.50 (24-20) | 0.34 (22) |

- Sizes are recommended minimum values.
- Wiring should be twisted.
- Local regulations should always be observed.

## N-Series Motors



N-Series motors use a high-energy ring magnet rotor construction for an outstanding torque-to-size ratio. Available in four common NEMA style frame sizes, N-Series motors, matched with an ULTRA Series drive, create a high performance alternative to stepper systems. It also provides an excellent solution when interfacing to gear boxes, sprockets, and pulleys because of the standard NEMA mounting frames. The nine motors in the N-Series family range in continuous torque capability from 0.18 to 5.9 N-m (1.6 to 52 lb-in.) and reach speeds up to 6000 RPM. Typical applications for the N-Series include web processing, machine tool, textile machinery, and CAM replacements. When you install the optional motor shaft seal, the motor meets the IP65 requirements of the IEC standard.

### Features

The N-Series motors have the following features:

- Rugged industrial construction
- NEMA 23, 34, 42, and 56 style mounting frames
- Continuous torque from 0.18 to 5.9 N-m (1.6 to 52 lb-in.)
- Speeds up to 6000 RPM
- High torque-to-size ratio
- High energy ring magnet rotor
- Internal thermal switch indicating overheating
- Optional internally mounted spring set, magnetic release 24V DC holding brake
- Motor mounted optical encoder includes 2000 quadrature pulses (1000 pulses for N-23xx motors), index pulse, and standard commutation channels for drives
- Water-tight, nickel-plated MS connections are compatible with standard cable assemblies.
- The extruded aluminum housing and environmental connectors provide an IP65 package (with the optional shaft seal kit)

## Typical Applications

Typical applications for the N-Series motors are:

- Machine tools
- Material handling
- Web processing
- Robotics
- Packaging machinery

## Characteristics

- High performance stepper replacement
- NEMA mounting provides excellent mechanical interface
- Environmentally rugged

## Selecting a Drive/Motor Combination

The following drive/motor combinations are available for the N-Series motors:

| Motor | ULTRA 100 | ULTRA 200 | ULTRA Plus |
|---|---|---|---|
| N-2302-1-F00AA | 1398-DDM-005 | 1398-DDM-010 | NA |
| N-2304-1-F00AA | 1398-DDM-005 | 1398-DDM-010 | NA |
| N-3406-2-H00AA | 1398-DDM-009 | 1398-DDM-020 | 1398-PDM-20 |
| N-3412-2-H00AA | 1398-DDM-009 | 1398-DDM-020 | 1398-PDM-20 |
| N-4214-2-H00AA | 1398-DDM-009 | 1398-DDM-020 | 1398-PDM-20 |
| N-4220-2-H00AA | 1398-DDM-019 | 1398-DDM-030 | 1398-PDM-30 |
| N-5630-2-H00AA | 1398-DDM-019 | 1398-DDM-030 | 1398-PDM-30 |
| N-5637-2-H00AA | 1398-DDM-019 | 1398-DDM-030 | 1398-PDM-30 |
| N-5647-2-H00AA | 1398-DDM-019 | 1398-DDM-030 | 1398-PDM-30 |

## N-Series Specifications

This section contains the mechanical, thermostat and winding specifications for the N-Series motor family, as well as the load force ratings and performance specifications for every combination of ULTRA series drives and N-Series motors. It also provides motor dimensions, connector pin and signal designations, and all motor and connector ordering information.

### N-Series Mechanical Specifications

| Specifications | Units | N-2302 | N-2304 | N-3406 | N-3412 | N-4214 |
|---|---|---|---|---|---|---|
| Rotor moment of inertia | kg-m$^2$ (lb-in.-s$^2$) | 0.000009 (0.00008) | 0.00002 (0.00016) | 0.00008 (0.0007) | 0.00015 (0.0013) | 0.00024 (0.0021) |
| Rotor moment of inertia (brake motors) | kg-m$^2$ (lb-in.-s$^2$) | 0.000018 (0.00016) | 0.000032 (0.00028) | 0.000122 (0.00108) | 0.000202 (0.00179) | 0.000210 (0.00186 |
| Motor net weight | kg (lb) | 1.0 (2.3) | 1.5 (3.4) | 2.6 (5.7) | 3.5 (7.6) | 4.7 (10.4) |
| Brake motor net weight | kg (lb) | 1.3 (2.9) | 2.0 (4.3) | 3.4 (7.5) | 4.3 (9.5) | 5.1 (11.2) |
| Damping | N-m/kRPM (lb-in./kRPM) | 0.0015 (0.013) | 0.0021 (0.019) | 0.0078 (0.069) | 0.012 (0.106) | 0.013 (0.113) |
| Friction torque | N-m (lb-in.) | 0.012 (0.11) | 0.014 (0.13) | 0.021 (0.19) | 0.035 (0.31) | 0.043 (0.38) |
| Maximum Operating Speed | rpm | 6000 | 6000 | 6000 | 6000 | 6000 |

| Specifications | Units | N-4220 | N-5630 | N-5637 | N-5647 |
|---|---|---|---|---|---|
| Rotor moment of inertia | kg-m$^2$ (lb-in.-s$^2$) | 0.00035 (0.0031) | 0.0009 (0.008) | 0.0011 (0.01) | 0.0015 (0.013) |
| Rotor moment of inertia (brake motors) | kg-m$^2$ (lb-in.-s$^2$) | 0.000320 (0.00283) | 0.000651 (0.00576) | 0.000778 (0.00689) | 0.000893 (0.00791) |
| Motor net weight | kg (lb) | 5.9 (13.0) | 9.1 (20.0) | 11.0 (24.2) | 13.0 (28.7) |
| Brake motor net weight | kg (lb) | 6.9 (15.2) | 10.9 (24.0) | 13.2 (29.0) | 15.9 (35.0) |
| Damping | N-m/kRPM (lb-in./kRPM) | 0.012 (0.106) | 0.022 (0.194) | 0.02 (0.175) | 0.028 (0.25) |
| Friction torque | N-m (lb-in.) | 0.048 (0.406) | 0.078 (0.688) | 0.1 (0.875) | 0.11 (0.938) |
| Maximum Operating Speed | rpm | 5000 | 4000 | 4000 | 3000 |

## N-Series Thermostat Specifications

| Specifications | |
|---|---|
| Rated voltage | 0 - 250V DC or 50/60 Hz AC[1] |
| Rated current | 3.0A at power factor of 1.0<br>2.0A at power factor of 0.6 |
| Maximum switching current | 5 A |
| Contact resistance | Less than 0.040 Ohms maximum |
| Contacts | Normally closed |
| Insulation dielectric | Mylar Nomex capable of withstanding<br>1500V AC RMS 50/60 Hz for 1 minute |
| Opening temperature (±5ºC) | 135ºC |

[1] The thermostat is normally used as a switch for a 15V DC logic signal (recommended).

## N-Series Winding Specifications

| Specifications | Units | N-2302 | N-2304 | N-3406 | N-3412 | N-4214 |
|---|---|---|---|---|---|---|
| Sine wave $K_T$ torque Constant at 25°C [1] | N-m/A<br>(lb-in./A) | 0.08<br>(0.73) | 0.18<br>(1.6) | 0.17<br>(1.5) | 0.34<br>(3.0) | 0.41<br>(3.6) |
| Square wave $K_T$ torque Constant at 25°C [2] | N-m/A<br>(lb-in./A) | 0.09<br>(0.80) | 0.20<br>(1.8) | 0.18<br>(1.6) | 0.37<br>(3.3) | 0.45<br>(4.0) |
| $K_E$ voltage constant [3] | V/kRPM | 10 | 22 | 21 | 41 | 49 |
| Winding resistance Phase to phase at 25°C | Ohm | 3.2 | 4.9 | 2.2 | 2.7 | 2.8 |
| Winding inductance Phase to phase | mH | 4.1 | 8.1 | 6.1 | 8.6 | 11.0 |
| Thermal resistance [4] | °C/Watt | 3.0 | 2.2 | 1.6 | 1.2 | 1.1 |
| Poles | | 4 | 4 | 4 | 4 | 4 |

| Specifications | Units | N-4220 | N-5630 | N-5637 | N-5647 |
|---|---|---|---|---|---|
| Sine wave $K_T$ torque Constant at 25°C [1] | N-m/A (lb-in./A) | 0.28 (2.5) | 0.38 (3.4) | 0.50 (4.4) | 0.63 (5.6) |
| Square wave $K_T$ torque Constant at 25°C [2] | N-m/A (lb-in./A) | 0.31 (2.7) | 0.42 (3.7) | 0.54 (4.8) | 0.70 (6.2) |
| $K_E$ voltage constant [3] | V/kRPM | 34 | 47 | 60 | 77 |
| Winding resistance Phase to phase at 25°C | Ohm | 0.77 | 0.89 | 1.0 | 1.23 |
| Winding inductance Phase to phase | mH | 2.9 | 4.3 | 5.2 | 7.0 |
| Thermal resistance [4] | N-m/A (lb-in./A) | 0.83 | 0.81 | 0.76 | 0.70 |
| Poles | | 4 | 4 | 4 | 4 |

1 Peak value of per phase sine wave amps.
2 Peak value of per phase square wave amps
3 Peak value of sinusoidal phase to phase volts
4 At 125°C winding temperature, in a 40°C ambient, with motor mounted on aluminum heat sinks: motors 2302, 2304—0.25 in. x 8 in. x 8 in.; motors 3406, 3412—0.25 in. x 10 in. x 10 in.; motors 4214, 4220, 5630, 5637, 5647— 0.5 in. x 12 in. x 12 in.

## Storage and Operating Specifications

| Storage and Operating Conditions | |
|---|---|
| Ambient Temperature | Operating: 0 to 40ºC (32 to 104ºF)<br>Storage: 0 to 50ºC (32 to 122ºF) |
| Relative Humidity | 5% to 95% non-condensing |

## N-Series Standard Motor Radial Load Force Ratings

| Ratings | Units | N-2302 | N-2304 | N-3406 | N-3412 | N-4214 |
|---|---|---|---|---|---|---|
| 500 RPM | kg<br>(lbs) | 8<br>(17) | 9<br>(19) | 47<br>(103) | 51<br>(113) | 62<br>(137) |
| 1000 RPM | kg<br>(lbs) | 7<br>(16) | 8<br>(17) | 37<br>(82) | 40<br>(89) | 49<br>(109) |
| 2000 RPM | kg<br>(lbs) | 6<br>(14) | 7<br>(15) | 29<br>(65) | 32<br>(71) | 39<br>(86) |
| 3000 RPM | kg<br>(lbs) | 6<br>(14) | 6<br>(14) | 26<br>(56) | 28<br>(62) | 34<br>(76) |
| 4000 RPM | kg<br>(lbs) | 5<br>(11) | 5<br>(11) | 23<br>(51) | 26<br>(56) | 31<br>(68) |
| 5000 RPM | kg<br>(lbs) | 4<br>(9) | 5<br>(11) | 22<br>(48) | 24<br>(53) | 29<br>(64) |
| 6000 RPM | kg<br>(lbs) | 3<br>(8) | 3<br>(8) | 20<br>(45) | 22<br>(49) | NA |

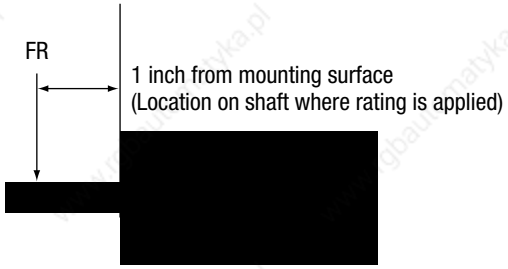
| Ratings | Units | N-4220 | N-5630 | N-5637 | N-5647 |
|---|---|---|---|---|---|
| 500 RPM | kg<br>(lbs) | 66<br>(146) | 85<br>(188) | 89<br>(197) | 92<br>(203) |
| 1000 RPM | kg<br>(lbs) | 52<br>(116) | 67<br>(149) | 71<br>(156) | 73<br>(161) |
| 2000 RPM | kg<br>(lbs) | 41<br>(92) | 53<br>(118) | 56<br>(124) | 58<br>(128) |
| 3000 RPM | kg<br>(lbs) | 36<br>(80) | 47<br>(103) | 49<br>(108) | 51<br>(112) |
| 4000 RPM | kg<br>(lbs) | 33<br>(73) | 43<br>(94) | 45<br>(98) | NA |
| 5000 RPM | kg<br>(lbs) | 31<br>(68) | NA | NA | NA |

Motors are capable of carrying an axial load in most applications according to the following general guidelines. These guidelines should only be used as approximations.

- When the motor shaft has no radial load, the axial load rating is 100% of the radial load rating from the table above.
- When the motor shaft has both a radial and an axial load, the axial load rating is 44% of the radial load rating from the table above.

## N-Series Motors Shaft Load Specifications

| Motor | Shaft Radial Load (FR) |
|---|---|
| N-2300 | 2.26 kg (5 lb) |
| N-3406 | 13.6 kg (30 lb) |
| N-3412 | 15.9 kg (35 lb) |
| N-4214 | 20.4 kg (45 lb) |




## ULTRA 100 Series Specifications for N-Series Motors[1]

| Specifications | | N-2302 | N-2304 | N-3406 | N-3412 | N-4214 |
|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | 005 | 005/009 | 009 | 009 | 009 |
| Maximum continuous operating speed [2] | RPM | 6000 | 6000 | 6000 | 5500 | 4500 |
| Continuous stall torque[2] | N-m (lb-in.) | 0.2 (1.6) | 0.4/0.5 (3.5/4.4) | 0.8 (6.8) | 1.6 (13.8) | 2.0 (15.5) |
| Peak torque[3] | N-m (lb-in.) | 0.5 (4.6) | 1.1/1.4 (10.0/13.0) | 2.1 (18.5) | 4.1 (36.0) | 5.7 (45.0) |

| Specifications | | N-4220 | N-5630 | N-5637 | N-5647 |
|---|---|---|---|---|---|
| Drive | 1398-DDM- | 019 | 019 | 019 | 019 |
| Maximum continuous operating speed [2] | RPM | 5000 | 4000 | 4000 | 3000 |
| Continuous stall torque[2] | N-m (lb-in.) | 2.5 (22.0) | 3.4 (30.0) | 4.5 (40.0) | 5.9 (52.0) |
| Peak torque[3] | N-m (lb-in.) | 7.1 (63.0) | 10.7 (95.0) | 13.0 (120) | 17.0 (150) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230V AC line voltage input, except for N-2302 and N-2304, which are used with 115V AC line voltage input.
3 System limit.

## ULTRA 200 Series Specifications for N-Series Motors[1]

| Specifications | | N-2302 | N-2304 | N-3406 | N-3412 | N-4214 |
|---|---|---|---|---|---|---|
| Drive | 1398-DDM- | 010 | 010 | 020 | 020 | 020 |
| Maximum continuous operating speed [2] | RPM | 6000 | 6000 | 6000 | 5500 | 4500 |
| Continuous stall torque[2] | N-m (lb-in.) | 0.2 (1.7) | 0.5 (4.4) | 0.8 (6.8) | 1.6 (13.8) | 2 (18) |
| Peak torque[3] | N-m (lb-in.) | 0.5 (4.7) | 1.4 (13.0) | 2.1 (18.5) | 4.1 (36) | 5.7 (50) |

| Specifications | | N-4220 | N-5630 | N-5637 | N-5647 |
|---|---|---|---|---|---|
| Drive | 1398-DDM- | 030 | 030 | 030 | 030 |
| Maximum continuous operating speed [2] | RPM | 5000 | 4000 | 4000 | 3000 |
| Continuous stall torque[2] | N-m (lb-in.) | 2.9 (26.0) | 3.8 (34.0) | 5.2 (46.0) | 6.0 (53.0) |
| Peak torque[3] | N-m (lb-in.) | 7.1 (63.0) | 10.7 (95.0) | 13.0 (120) | 17.0 (150) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230V AC line voltage input, except for N-2302 and N-2304, which are used with 115V AC line voltage input.
3 System limit.

## ULTRA Plus Specifications for N-Series Motors[1]

| Specifications | | N-2302 | N-2304 | N-3406 | N-3412 | N-4214 |
|---|---|---|---|---|---|---|
| Drive | 1398-PDM- | NA | NA | 20 | 20 | 20 |
| Maximum continuous operating speed [2] | RPM | NA | NA | 6000 | 6000 | 5000 |
| Continuous stall torque[2] | N-m (lb-in.) | NA | NA | 0.8 (6.8) | 1.6 (13.8) | 2 (18) |
| Peak torque[3] | N-m (lb-in.) | NA | NA | 2.1 (18.5) | 4.1 (36) | 5.7 (50) |

| Specifications | | N-4220 | N-5630 | N-5637 | N-5647 |
|---|---|---|---|---|---|
| Drive | 1398-PDM- | 30 | 30 | 30 | 30 |
| Maximum continuous operating speed [2] | RPM | 5000 | 4000 | 4000 | 3000 |
| Continuous stall torque[2] | N-m (lb-in.) | 2.9 (26.0) | 3.8 (34.0) | 5.2 (46.0) | 6.0 (53.0) |
| Peak torque[3] | N-m (lb-in.) | 7.1 (63.0) | 10.7 (95.0) | 13.0 (120) | 17.0 (150) |

1 Ambient temperature is 0°C to 40°C for motors and 0°C to 50°C for drives.
2 With 230V AC line voltage input.
3 System limit.

## N-Series Brake Specifications

| Specifications | N-2300 | N-3400 | N-4200 | N-5600 |
|---|---|---|---|---|
| Maximum Backlash (brake engaged) | 31 minutes | 72 minutes | 36 minutes | 102 minutes |
| Holding Torque | 5 lb-in. (0.56 N-m) | 15 lb-in. (1.69 N-m) | 30 lb-in. (3.39 N-m) | 50 lb-in. (5.64 N-m |
| Coil Current at 24 VDC | 0.28 ADC | 0.36 ADC | 0.36 ADC | 0.71 ADC |

## Brake Motor Application Guidelines

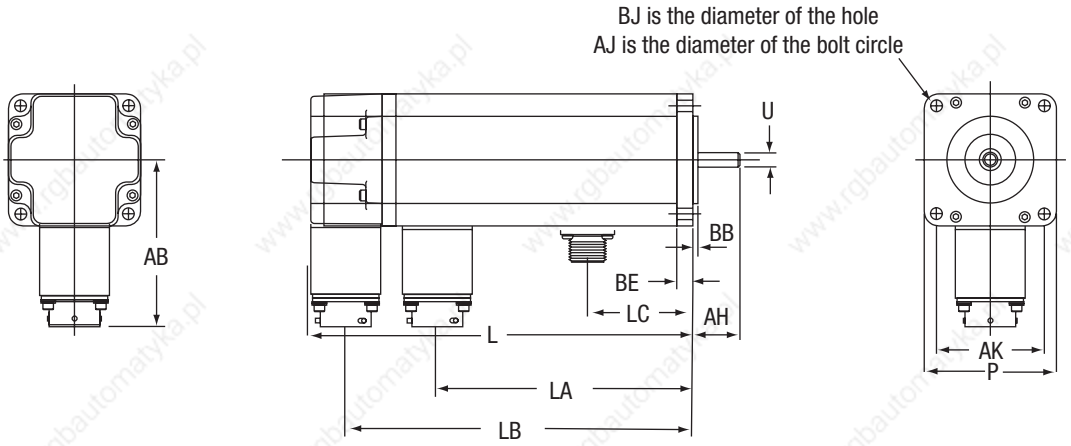
The brakes offered as options on these servo motors are holding brakes. They are designed to hold the motor shaft at 0 rpm for up to the rated brake holding torque. The brakes are spring-set type, and release when voltage is applied to the brake coil.

The brakes are *not* designed for stopping rotation of the motor shaft. Servo drive inputs should be used to stop motor shaft rotation. The recommended method of stopping motor shaft rotation is to command the servo drive to decelerate the motor to 0 rpm, and engage the brake after the servo drive has decelerated the motor to 0 rpm.

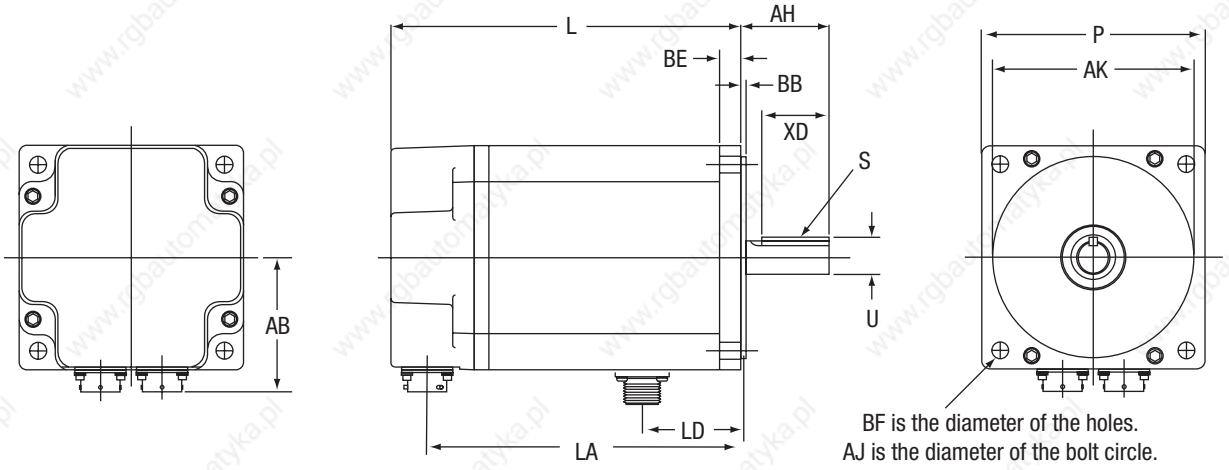
If system main power fails, the brakes can withstand use as stopping brakes. However, use of the brakes as stopping brakes creates rotational mechanical backlash that is potentially damaging to the system, increases brake pad wear and reduces brake life. The brakes are *not* designed nor are they intended to be used as a safety device.

A separate power source is required to disengage the brake. This power source may be controlled by the servo motor controls, in addition to manual operator controls.

## N-2300 Motors Dimensions (see page 62 for dimension values)




## N-3400, -4200, and -5600 Motors Dimensions (see page 62 for dimension values)



| Dimensions | AB | AH[1] | AJ | AK | BB | BE | BF | L | L with brake | LA | LB | P | S (width x depth)[5] | U[3] | XD[6] |
|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| **Motor Models** | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm (in.) | mm x mm (in. x in.) | mm (in.) | mm (in.) |
| N-2302 | 69 (2.71) | 21 (0.81) | 67 (2.625) | 38[2] (1.50) | 2 (0.09) | 7 (0.275) | 5 (0.205) | 118 (4.64) | 161 (6.35) | 62 (2.43) | 106 (4.05) | 58 (2.27) | NA | 6 (0.25) | NA |
| N-2304 | 69 (2.71) | 21 (0.81) | 67 (2.625) | 38[2] (1.50) | 2 (0.09) | 7 (0.275) | 5 (0.205) | 156 (6.14) | 199 (7.85) | 100 (3.93) | 141 (5.55) | 58 (2.27) | NA | 6 (0.25) | NA |
| N-3406 | 64 (2.53) | 30 (1.19) | 98 (3.875) | 73[4] (2.878) | 3 (0.12) | 8 (0.315) | 6 (0.220) | 147 (5.8) | 193 (7.59) | 124 (4.87) | NA | 88 (3.48) | 3 x 2 (0.127 x 0.085) | 13 (0.50) | 20 (0.79) |
| N-3412 | 64 (2.53) | 30 (1.19) | 98 (3.875) | 73[4] (2.878) | 3 (0.12) | 8 (0.315) | 6 (0.220) | 173 (6.8) | 218 (8.59) | 149 (5.87) | NA | 88 (3.48) | 3 x 2 (0.127 x 0.085) | 13 (0.50) | 20 (0.79) |
| N-4214 | 63 (2.48) | 35 (1.38) | 126 (4.95) | 56[7] (2.187) | 3 (0.12) | 10 (0.394) | 7 (0.280) | 174 (6.8) | 221 (8.69) | 152 (5.99) | NA | 102 (4.00) | 5 x 3 (0.189 x 0.108) | 16 (0.625) | 25 (1.00) |
| N-4220 | 63 (2.48) | 35 (1.38) | 126 (4.95) | 56[7] (2.187) | 3 (0.12) | 10 (0.394) | 7 (0.280) | 200 (7.87) | 246 (9.69) | 178 (6.99) | NA | 102 (4.00) | 5 x 3 (0.189 x 0.108) | 16 (0.625) | 25 (1.00) |
| N-5630 | 76 (2.99) | 50 (1.97) | 149 (5.875) | 114[8] (4.50) | 3 (0.12) | 12 (0.472) | 9.5 (0.375) in UNC | 199 (7.845) | 256 (10.06) | 178 (7.0) | NA | 127 (5.00) | 5 x 3 (0.189 x 0.121) | 19 (0.75) | 40 (1.57) |
| N-5637 | 76 (2.99) | 50 (1.97) | 149 (5.875) | 114[8] (4.50) | 3 (0.12) | 12 (0.472) | 9.5 (0.375) in UNC | 225 (8.845) | 281 (11.06) | 203 (8.0) | NA | 127 (5.00) | 5 x 3 (0.189 x 0.121) | 19 (0.75) | 40 (1.57) |
| N-5647 | 76 (2.99) | 50 (1.97) | 149 (5.875) | 114[8] (4.50) | 3 (0.12) | 12 (0.472) | 9.5 (0.375) in UNC | 250 (9.845) | 306 (12.06) | 229 (9.0) | NA | 127 (5.00) | 5 x 3 (0.189 x 0.121) | 19 (0.75) | 40 (1.57) |

1 Tolerance is ±0.03 in. (±0.76 mm).
2 Tolerance is -0.002 in. (-0.05 mm).
3 Tolerance is -0.005 in. (-0.13 mm) diameter.
4 Tolerance is -0.006 in. (-0.15 mm).
5 Tolerance is -0.002 in. (-0.05 mm) width, -0.015 in. (-0.38 mm) depth.
6 Tolerance is +0.06 in. (+1.5 mm).
7 Tolerance is -0.001 in. (-0.025 mm) diameter.
8 Tolerance is -0.003 in. (-0.076mm) diameter.

Note: NEMA motors are manufactured to inch dimensions. Millimeter dimensions are approximate conversions from inches. Engineering specifications showing motor detail are available upon request.

### Supplemental Motor Dimensions

| Dimen-sions | LC | LD |
|---|---|---|
| Motor Models | mm(in.) | mm(in.) |
| N-2302 | 3.861(0.152) | |
| N-2304 | 5.636(0.222) | |
| N-3406 | NA | 4.490(0.177) |
| N-3412 | NA | 5.490(0.216) |
| N-4214 | NA | 5.694(0.224) |
| N-4220 | NA | 6.694(0.263) |
| N-5630 | NA | 6.887(0.271) |
| N-5637 | NA | 7.887(0.31) |
| N-5647 | NA | 8.887(0.35) |

## Encoder Data

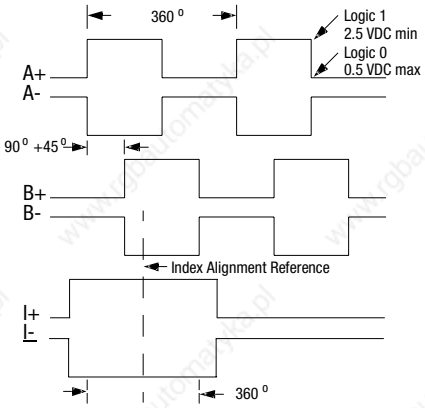
Encoders are factory aligned and must not be adjusted outside the factory.

| Specifications | N-2300 | N-3400, N-4200 and N-5600 |
|---|---|---|
| Line Count | 1000[1, 2] | 2000[1] |
| Supply Voltage | 5 VDC | 5 VDC |
| Supply Current | 175 mA maximum | 300 mA maximum |
| Line Driver | LM339 | 26LS31 |
| Line Driver Output | TTL | • A, B, and I signals: Logic 1 = 2.5 VDC min @ 20 mA DC source, Logic 0 = 0.5 VDC max @ 20 mA DC sink<br>• HALL signals: Logic 1 = 3.5 VDC min @ 1mA DC source, Logic 0 = 0.5 VDC max @ 5mA DC sink |
| Index Pulse | Refer to diagrams below. There is no key for physical reference. | When facing the motor, the key is oriented 90°±10 clockwise (mechanical) from the connectors. |

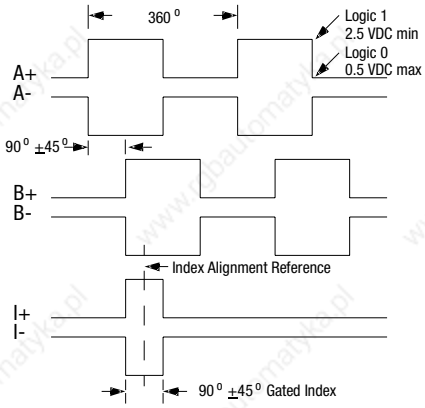
1 Standard line count before quadrature.
2 N-2300 encoder lacks Absolute Signal (ABS).

## Encoder Outputs

**N-2300 Encoder Output**



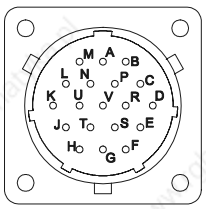

**N-3400, 4200 and 5600 Encoder Output**



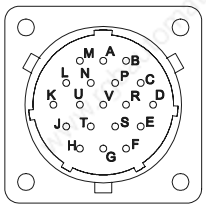

## N-Series Connector Pins and Signals

### Encoder Connectors (All N-Series Motors)

| NEMA 23-Series Encoder | | | |
|---|---|---|---|
| **Pin** | **Signal** | **Pin** | **Signal** |
| A | A+ | L | Common |
| B | A- | M | Common |
| C | B+ | N | Open |
| D | B- | P | Open |
| E | I+ | R | Thermostat+ |
| F | I- | S | Thermostat- |
| G | Ground | T | Hall A |
| H | Open | U | Hall B |
| J | 5 VDC | V | Hall C |
| K | 5 VDC | | |

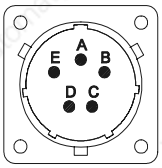


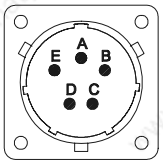
| NEMA 34, 42, & 56-Series Encoder | | | |
|---|---|---|---|
| **Pin** | **Signal** | **Pin** | **Signal** |
| A | A+ | L | Common |
| B | A- | M | Common |
| C | B+ | N | Open |
| D | B- | P | Open |
| E | I+ | R | Thermostat+ |
| F | I- | S | Thermostat- |
| G | Ground | T | Hall A |
| H | ABS | U | Hall B |
| J | 5 VDC | V | Hall C |
| K | 5 VDC | | |

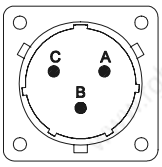



## Power and Brake Connectors (All N-Series Motors)

| NEMA 23-Series Power Connector | | NEMA 34, 42 & 56-Series Power Connector | | Brake Option Connector | |
|---|---|---|---|---|---|
| **Pin** | **Signal** | **Pin** | **Signal** | **Pin** | **Signal** |
| A | Phase R | A | Phase R | A | BR+ |
| B | Phase S | B | Phase S | B | BR- |
| C | Phase T | C | Phase T | C | Open |
| D | Ground | D | Ground | | |
| E | Open | E | Open | | |



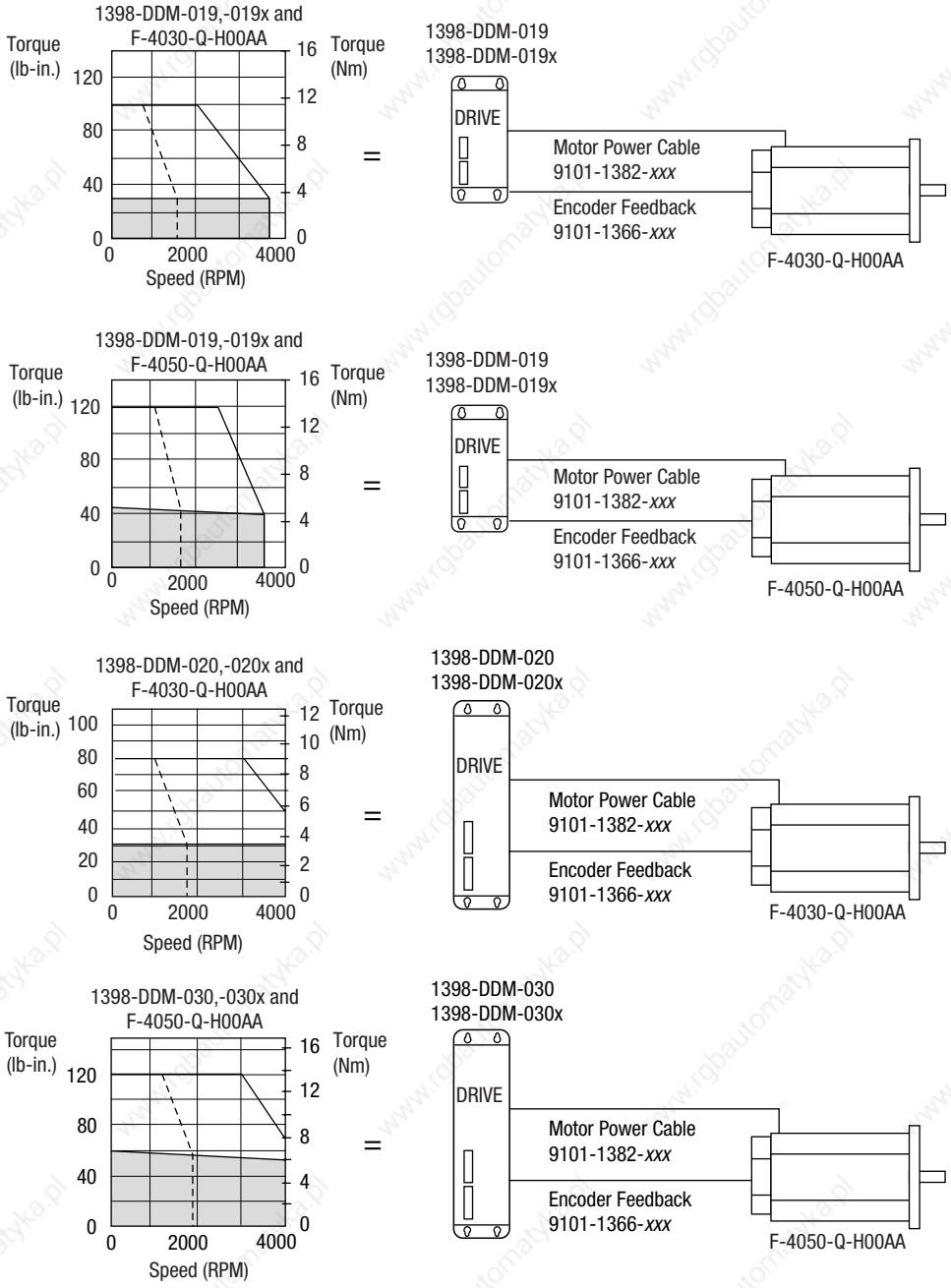



## ULTRA 100™/200™ System Ordering Guide

### ULTRA Servo Drives with F-Series Motors

The following section illustrates the drive-motor combinations, motor power cables and encoders available for purchase, as well as the speed/torque reference table for each combination.



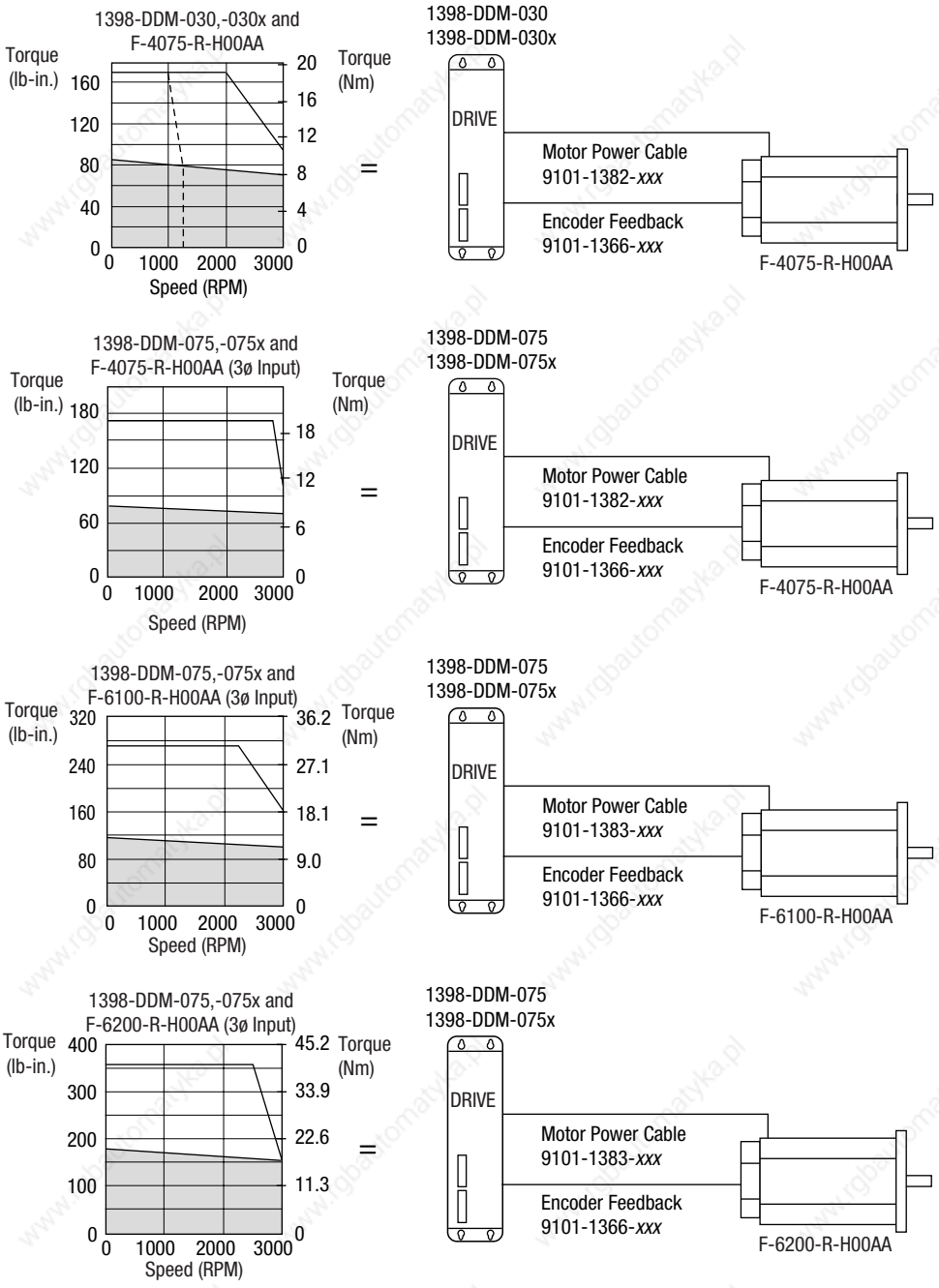

**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100

Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with F-Series Motors

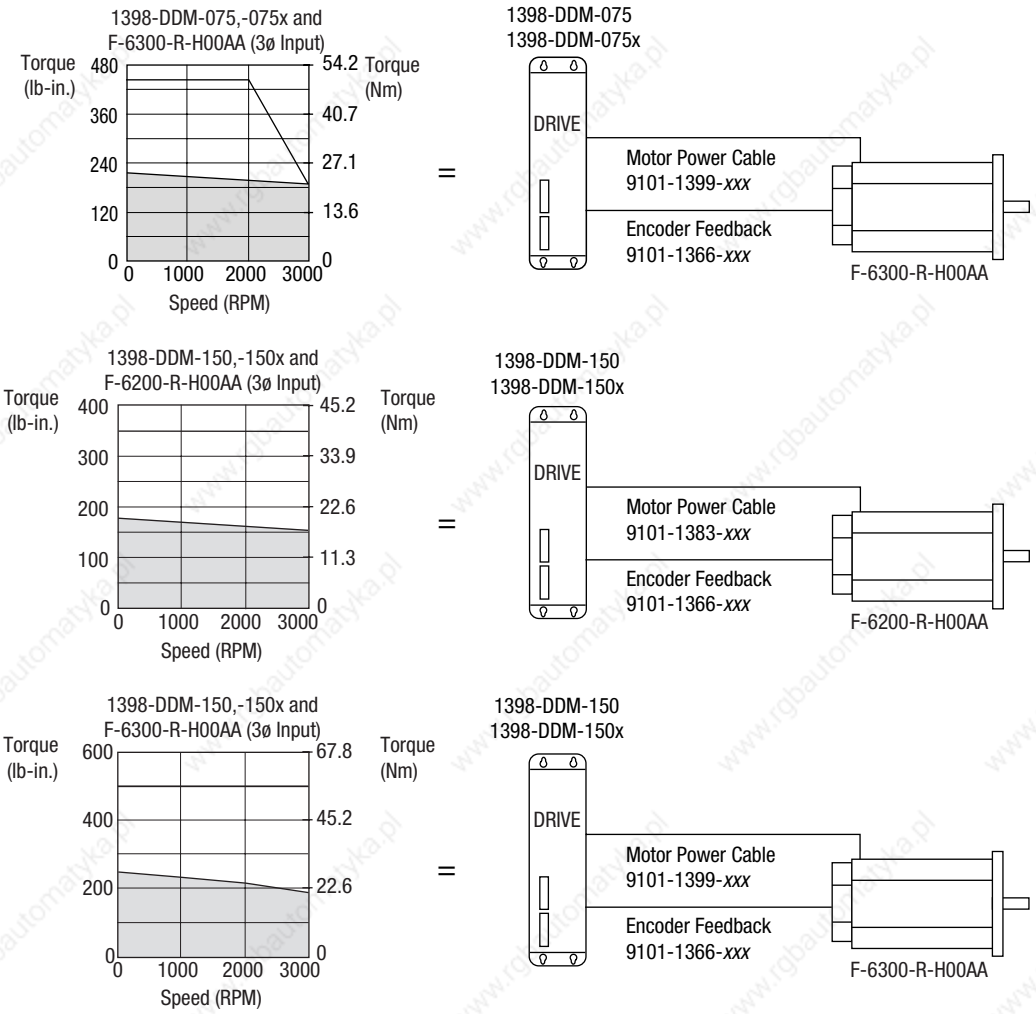



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with F-Series Motors



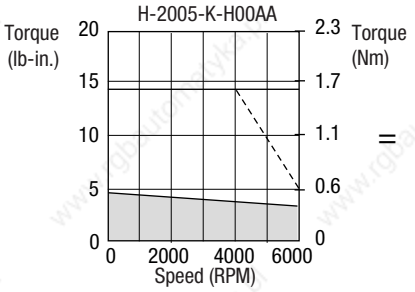

**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

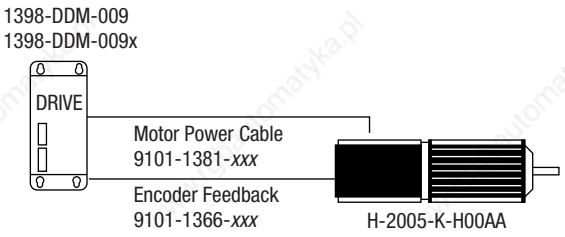
* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with H-Series Motors

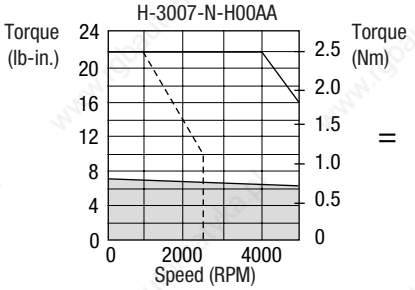
1398-DDM-009,-009x and H-2005-K-H00AA



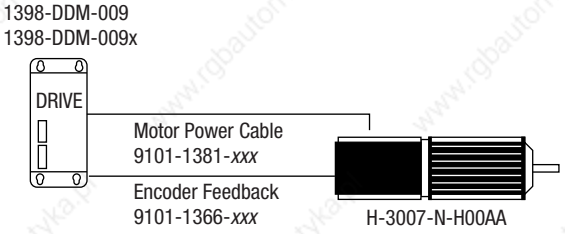

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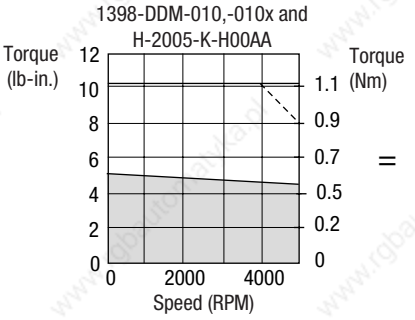

1398-DDM-009,-009x and H-3007-N-H00AA



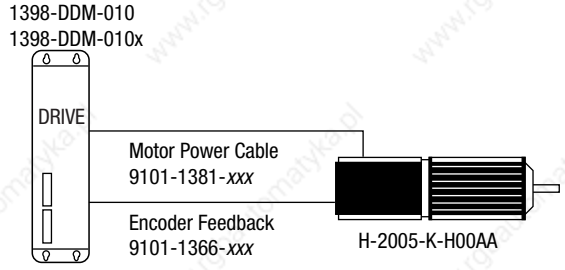

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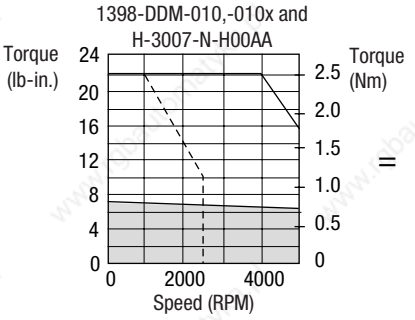

1398-DDM-010,-010x and H-2005-K-H00AA



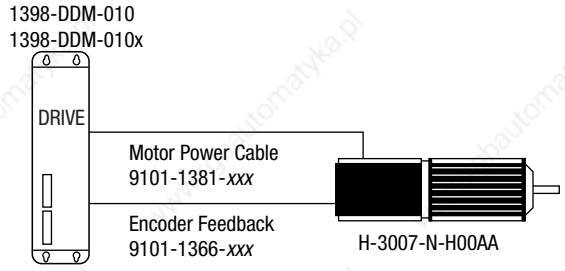

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1398-DDM-010,-010x and H-3007-N-H00AA




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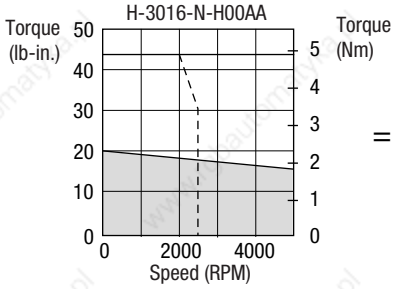

**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

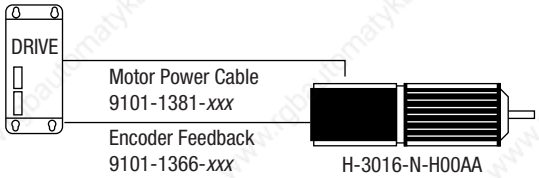
## ULTRA Servo Drives with H-Series Motors

1398-DDM-019,-019x and H-3016-N-H00AA

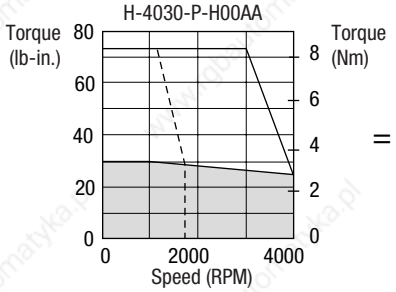



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1398-DDM-019
1398-DDM-019x

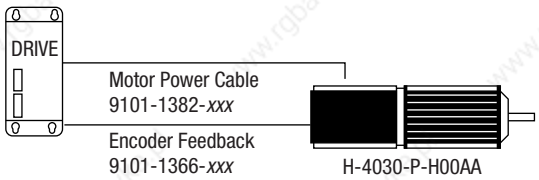



1398-DDM-019,-019x and H-4030-P-H00AA

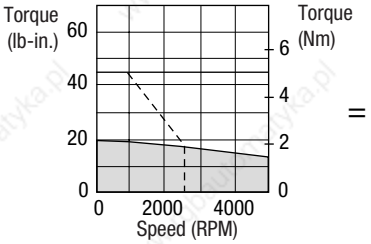



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1398-DDM-019
1398-DDM-019x

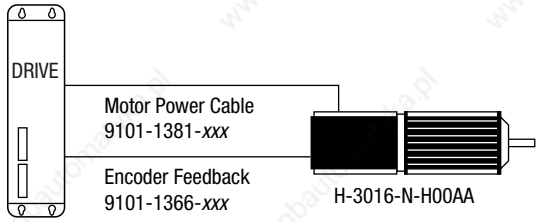



1398-DDM-020,-020x and H-3016-N-H00AA

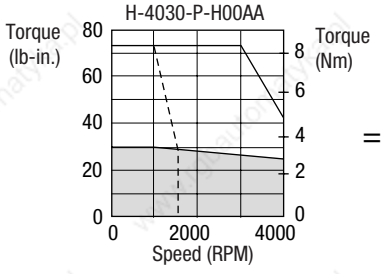



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1398-DDM-020
1398-DDM-020x

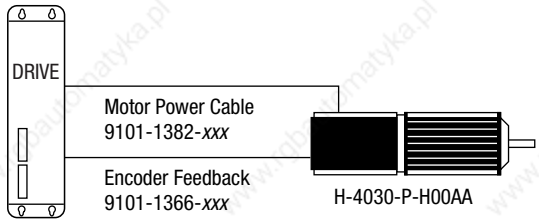



1398-DDM-020,-020x and H-4030-P-H00AA




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1398-DDM-020
1398-DDM-020x

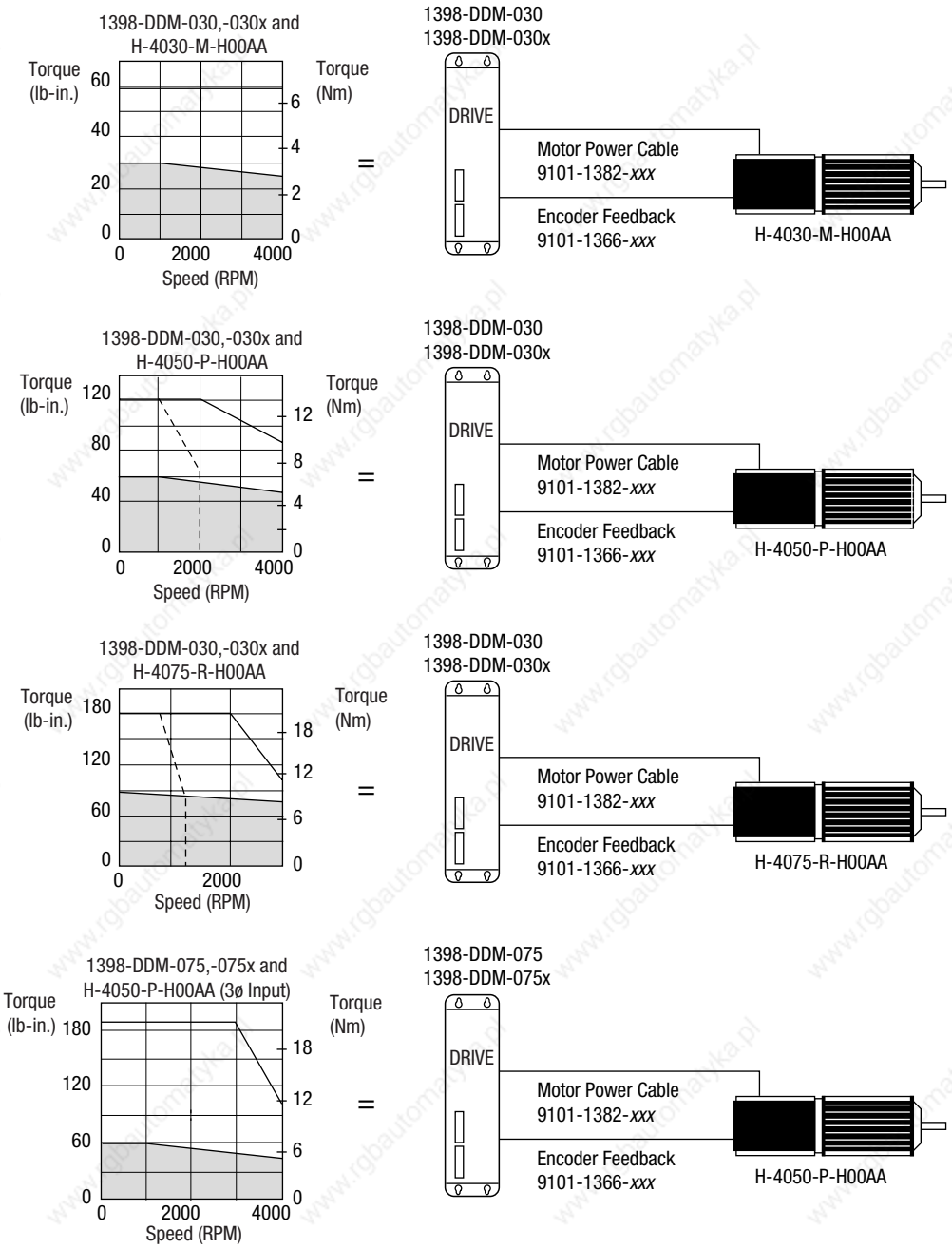



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with H-Series Motors

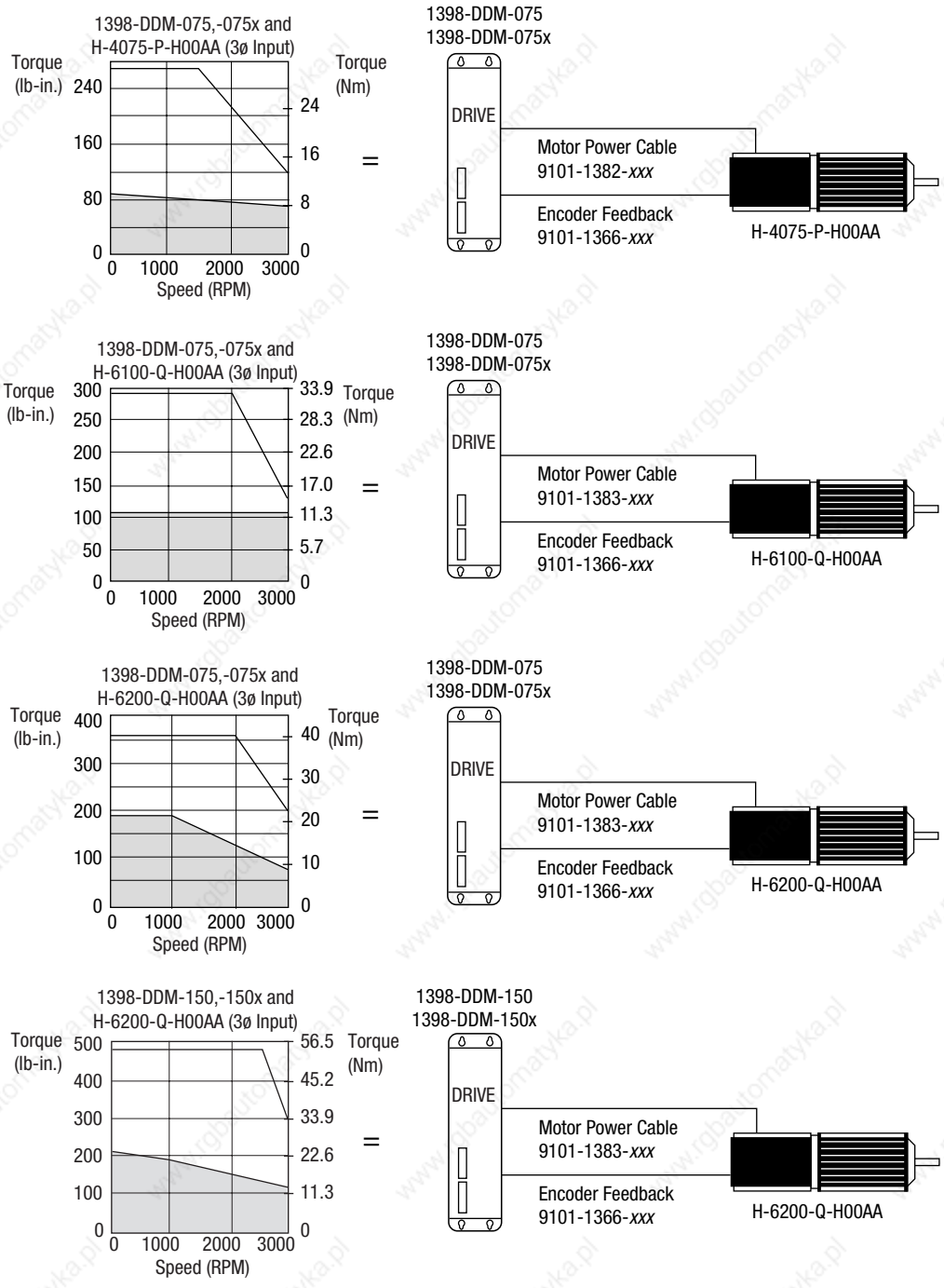



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with H-Series Motors

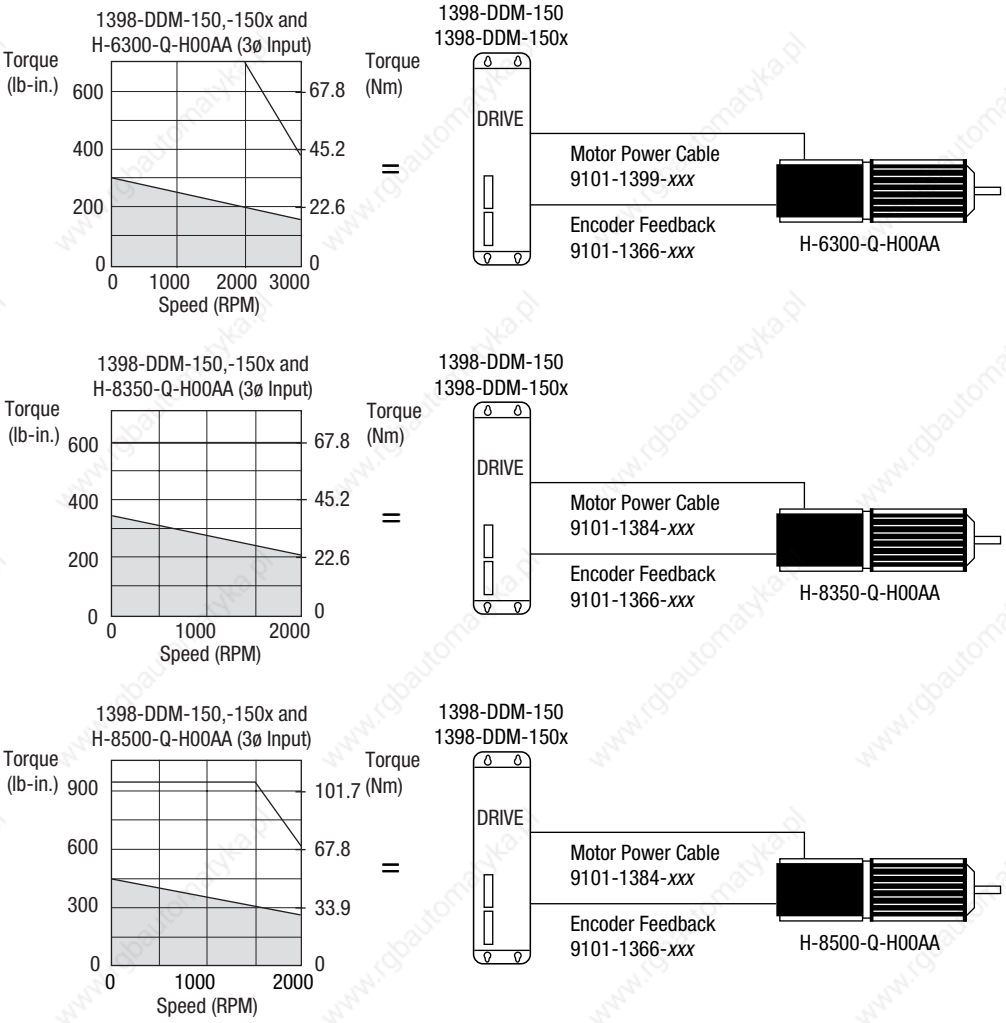



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with H-Series Motors

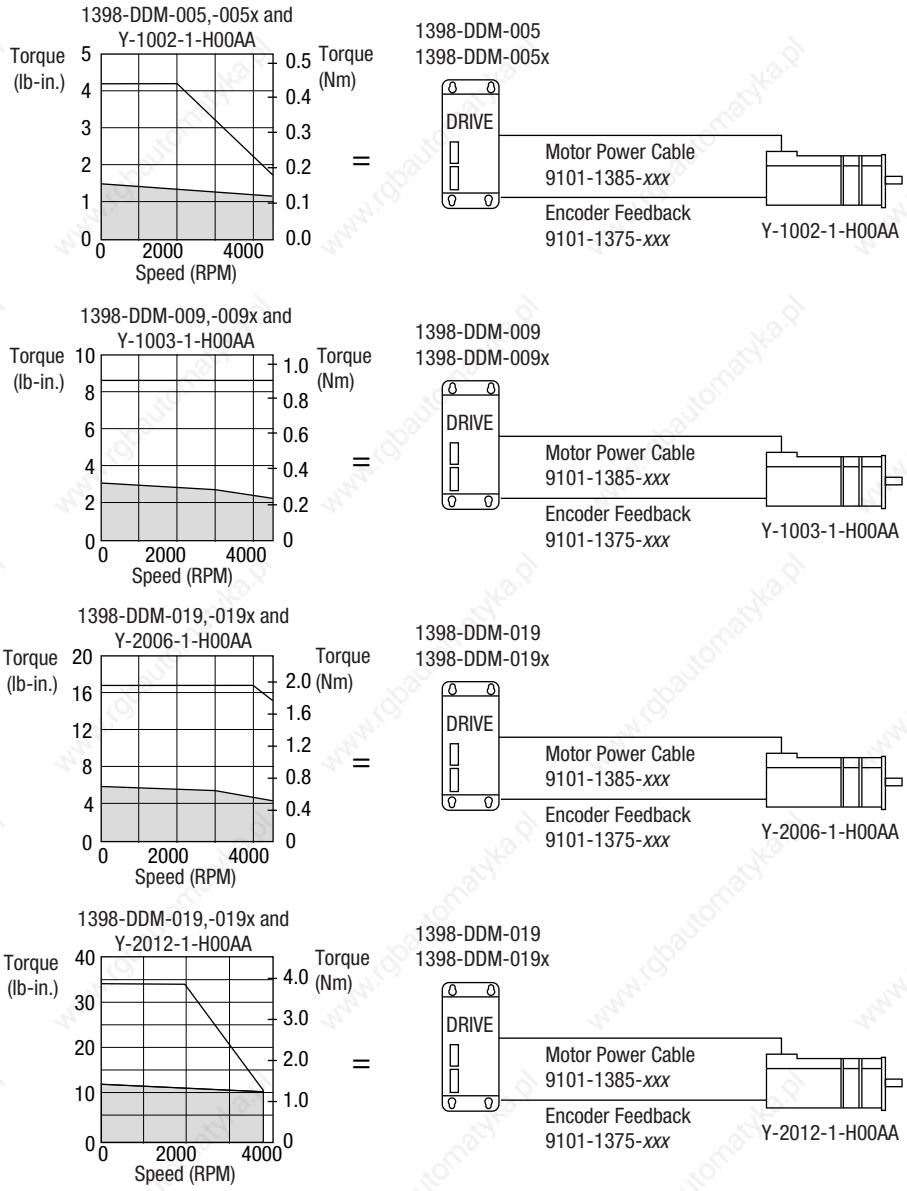



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with Y-Series Motors (115V AC RMS Input Voltage)



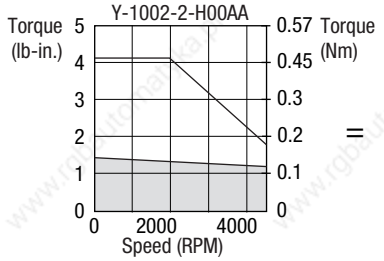

**System speed-torque characteristics**
Drive module input voltage = 115V AC RMS

= Intermittent operating region
= Continuous operating region

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

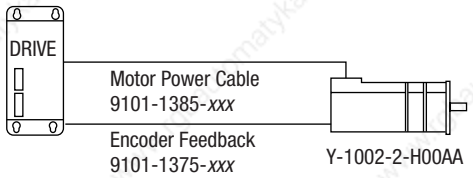
## ULTRA Servo Drives with Y-Series Motors (230V AC RMS Input Voltage)

1398-DDM-005,-005x and Y-1002-2-H00AA

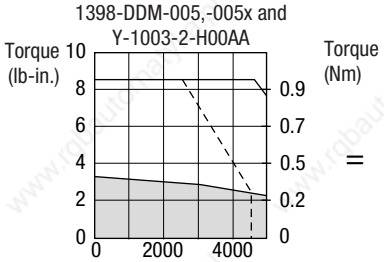



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1398-DDM-005
1398-DDM-005x

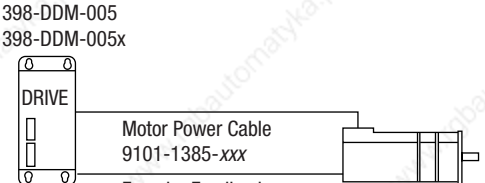



1398-DDM-005,-005x and Y-1003-2-H00AA

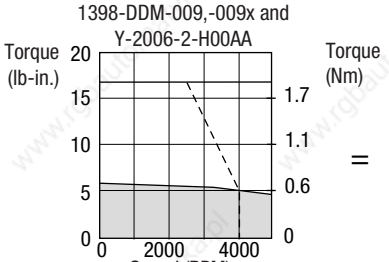



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1398-DDM-005
1398-DDM-005x

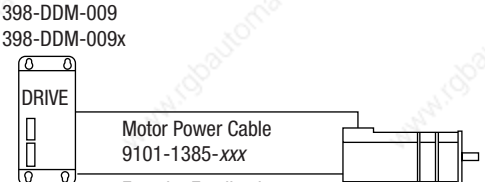



1398-DDM-009,-009x and Y-2006-2-H00AA

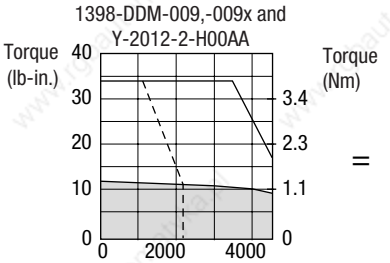



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1398-DDM-009
1398-DDM-009x

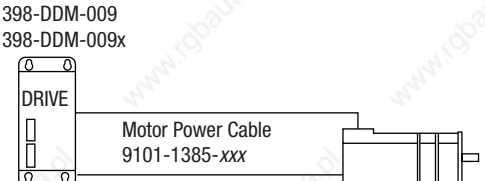



1398-DDM-009,-009x and Y-2012-2-H00AA

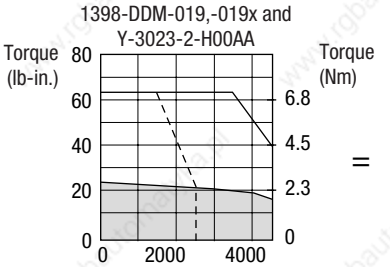



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1398-DDM-009
1398-DDM-009x

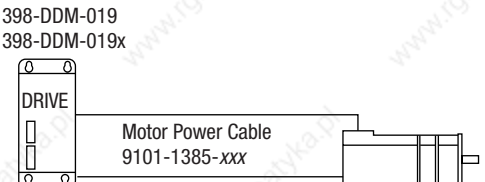



1398-DDM-019,-019x and Y-3023-2-H00AA




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1398-DDM-019
1398-DDM-019x

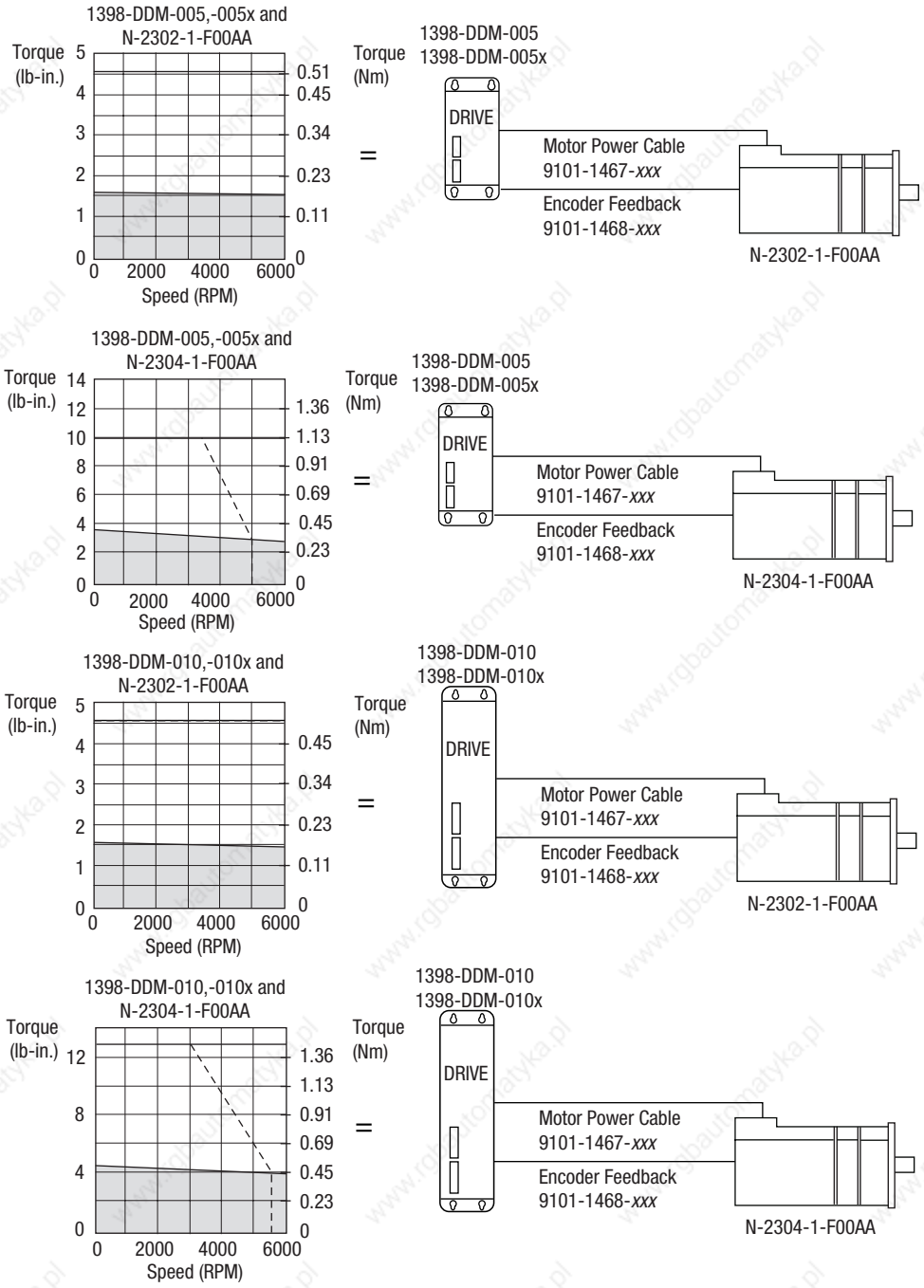



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with N-Series Motors



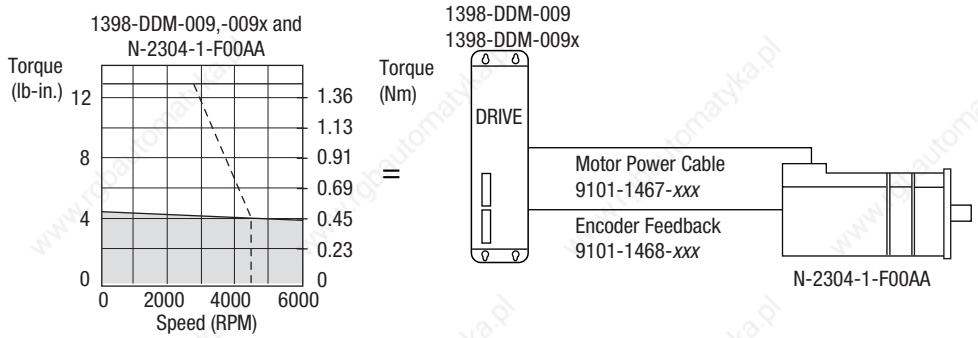

**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

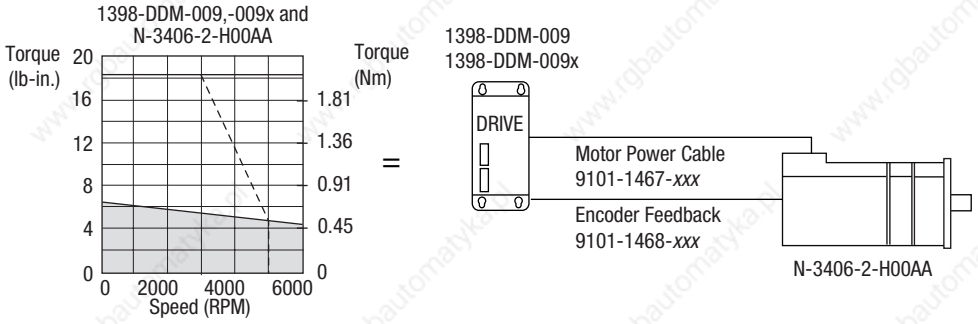
= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

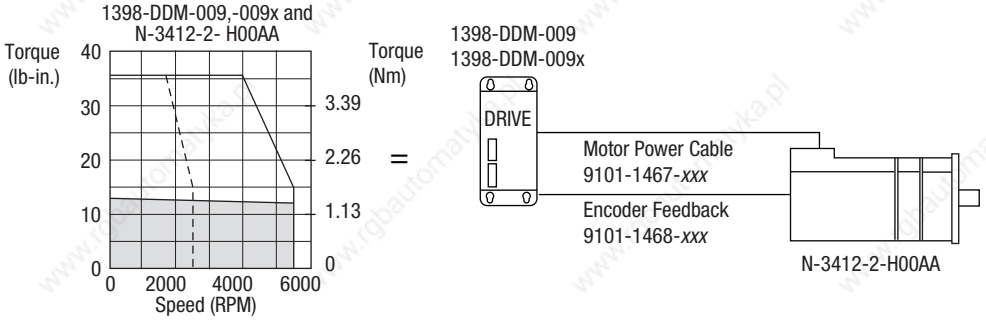
* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31.0 m)-100

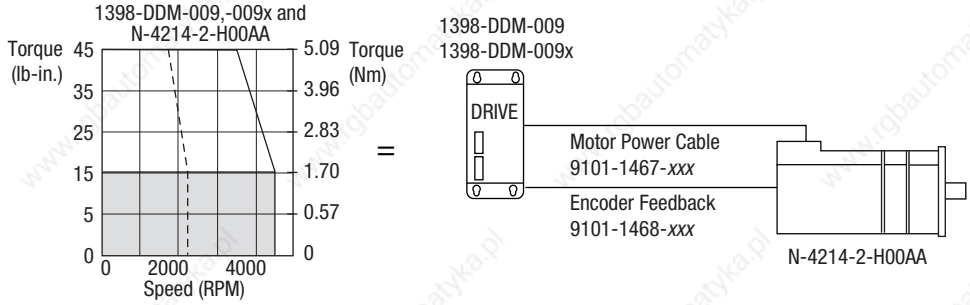
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with N-Series Motors



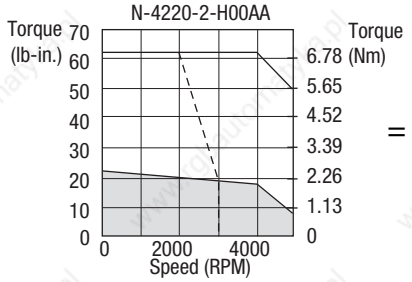

**System speed-torque characteristics**
Drive module input voltage = 230V AC

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31.0 m)-100
Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

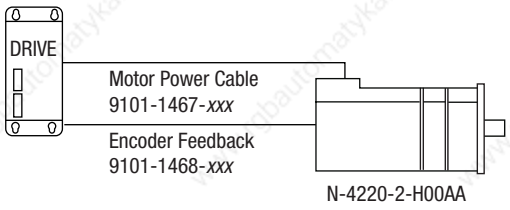
## ULTRA Servo Drives with N-Series Motors

1398-DDM-019,-019x and N-4220-2-H00AA

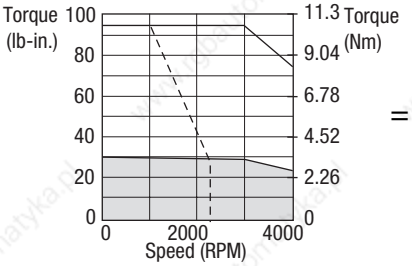



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1398-DDM-019
1398-DDM-019x

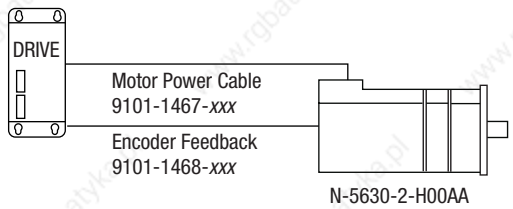



1398-DDM-019,-019x and N-5630-2-H00AA

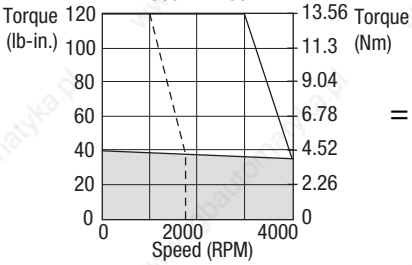



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1398-DDM-019
1398-DDM-019x

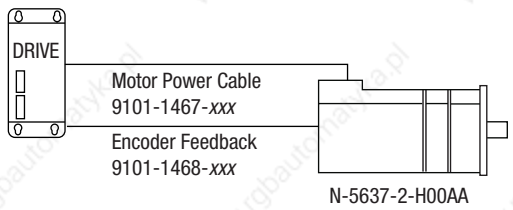



1398-DDM-019,-019x and N-5637-2-H00AA

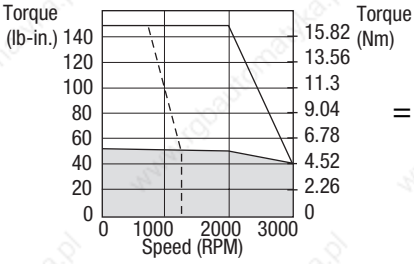



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1398-DDM-019
1398-DDM-019x

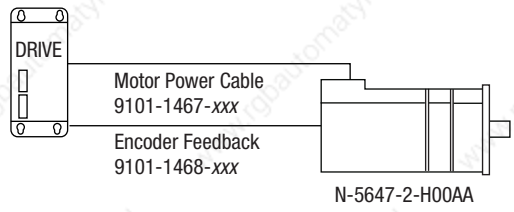



1398-DDM-019,-019x and N-5647-2-H00AA




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1398-DDM-019
1398-DDM-019x



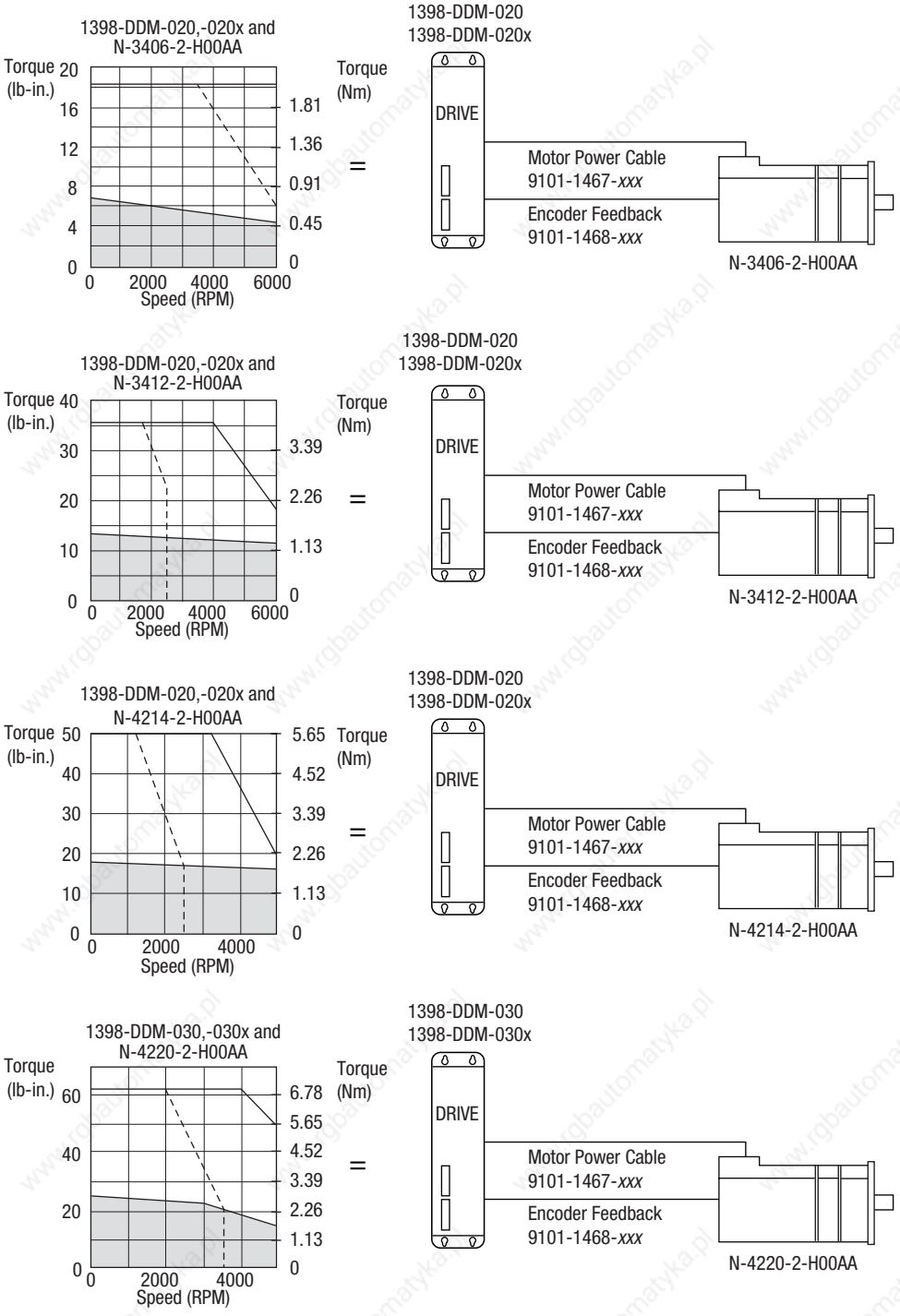

**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31.0 m)-100

Note: Serial interface cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Servo Drives with N-Series Motors

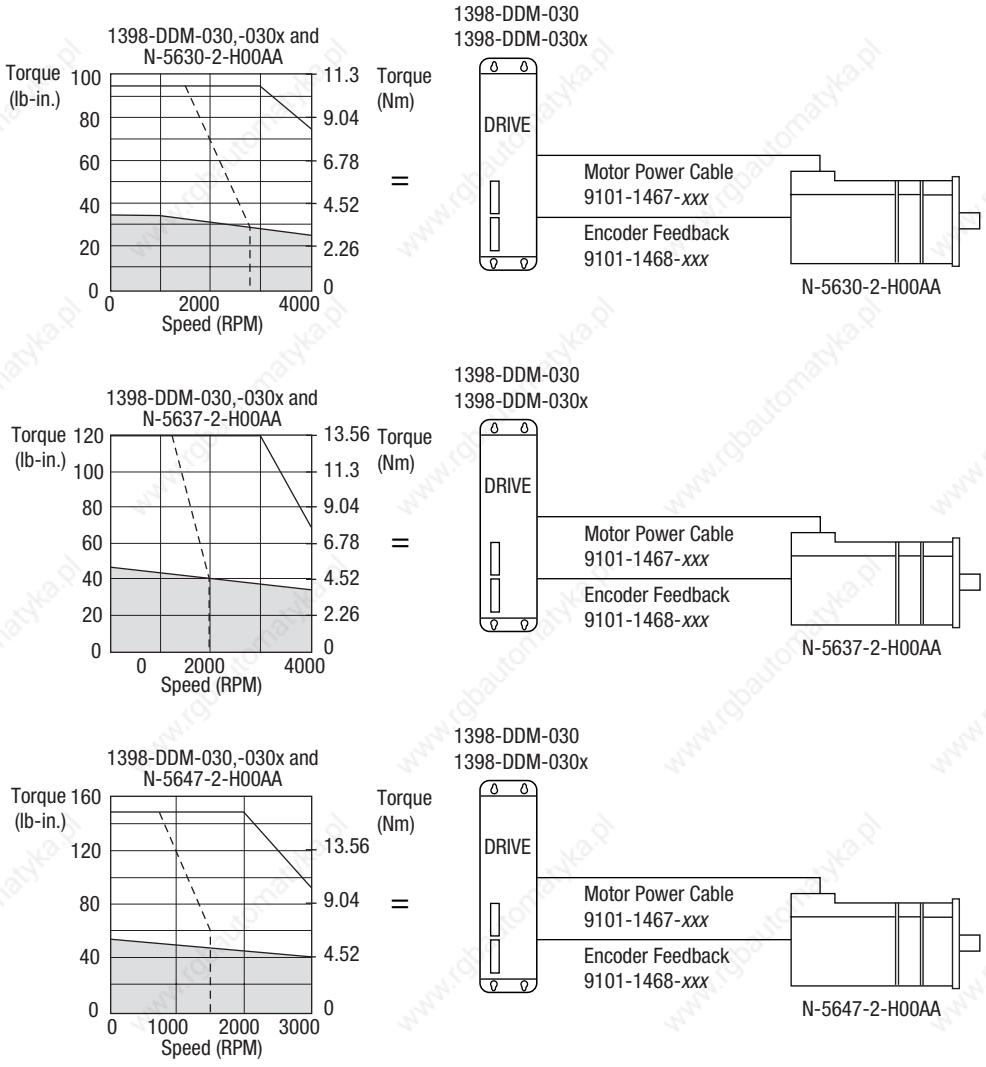



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31.0 m)-100

## ULTRA Servo Drives with N-Series Motors




**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

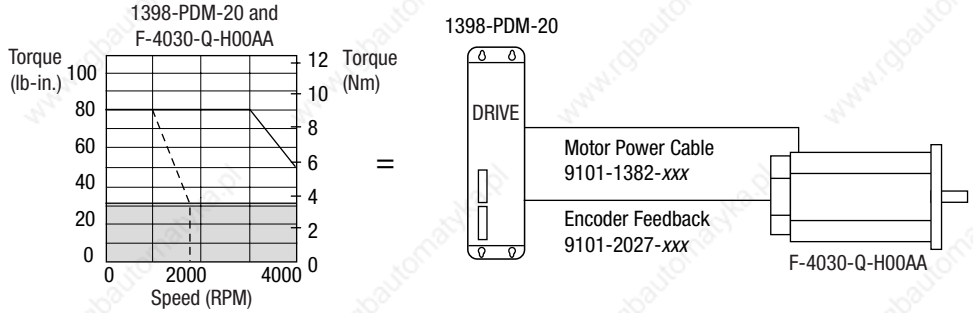
= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

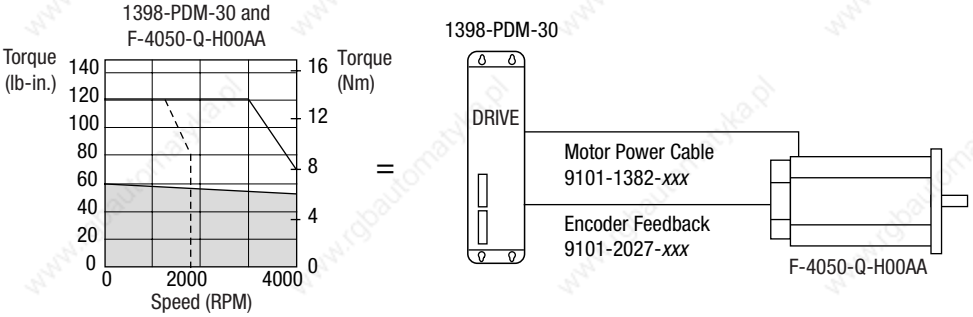
* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075; 100 ft (31.0 m)-100

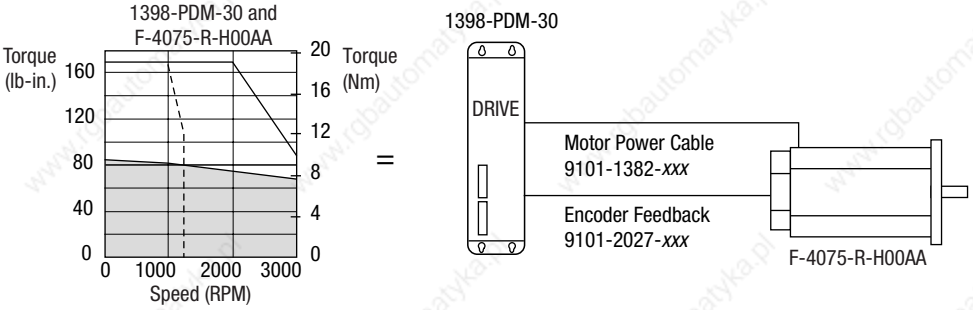
## ULTRA Plus System Ordering Guide

### ULTRA Plus Drives with F-Series Motors (1398-PDM-20, -30, and -75)

The following section illustrates the drive-motor combinations, motor power cables, and encoders available for purchase, as well as the speed/torque reference table for each combination.



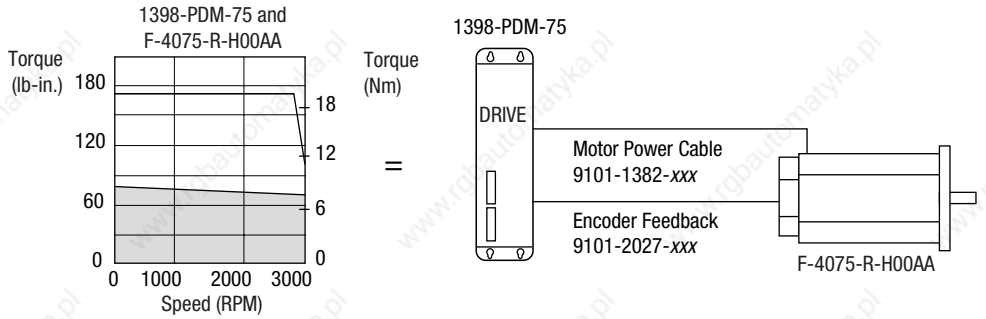



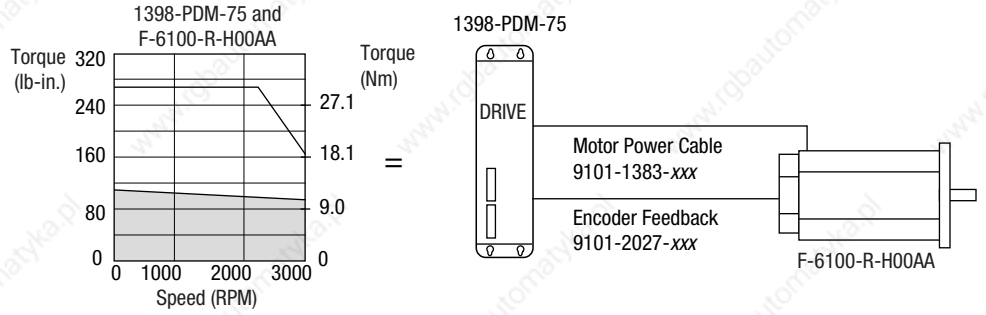

**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

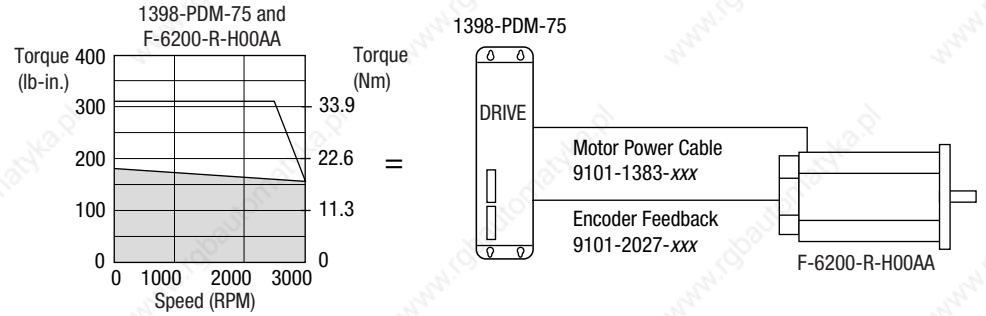
= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

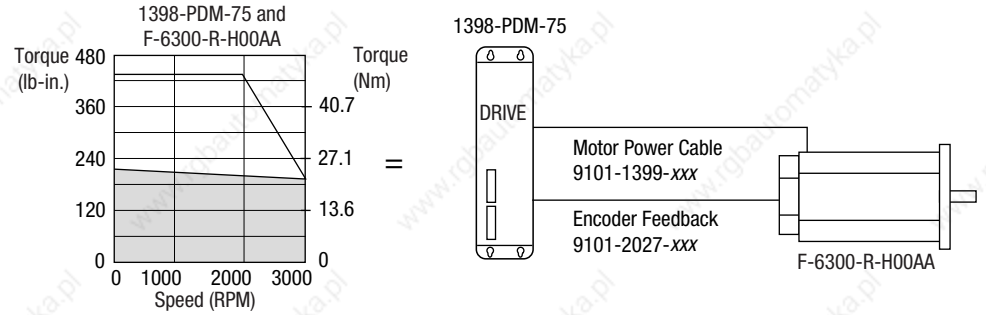
* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with F-Series Motors (1398-PDM-20, -30, and -75)



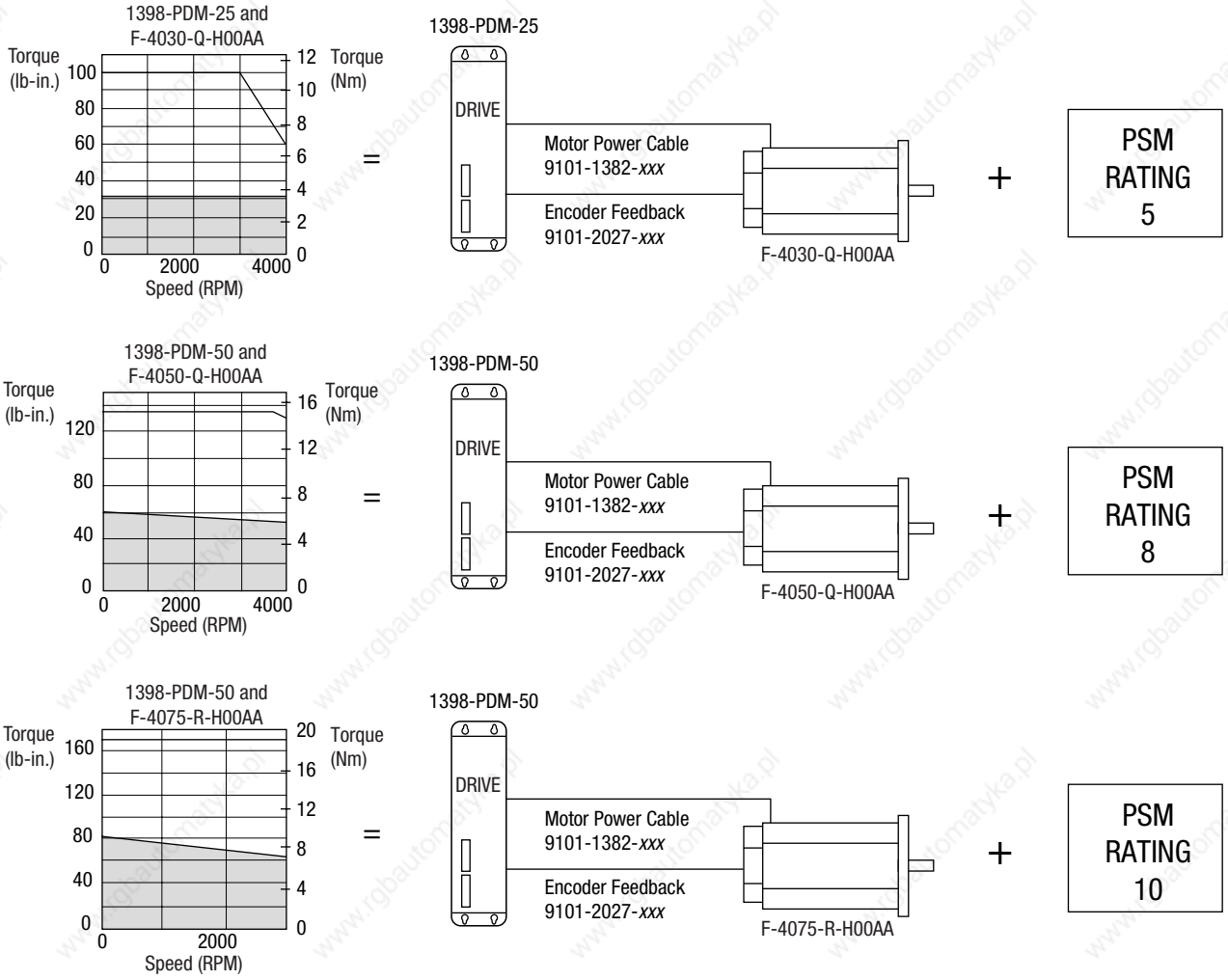




**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with F-Series Motors (1398-PDM-25, -50, -100, and -150)

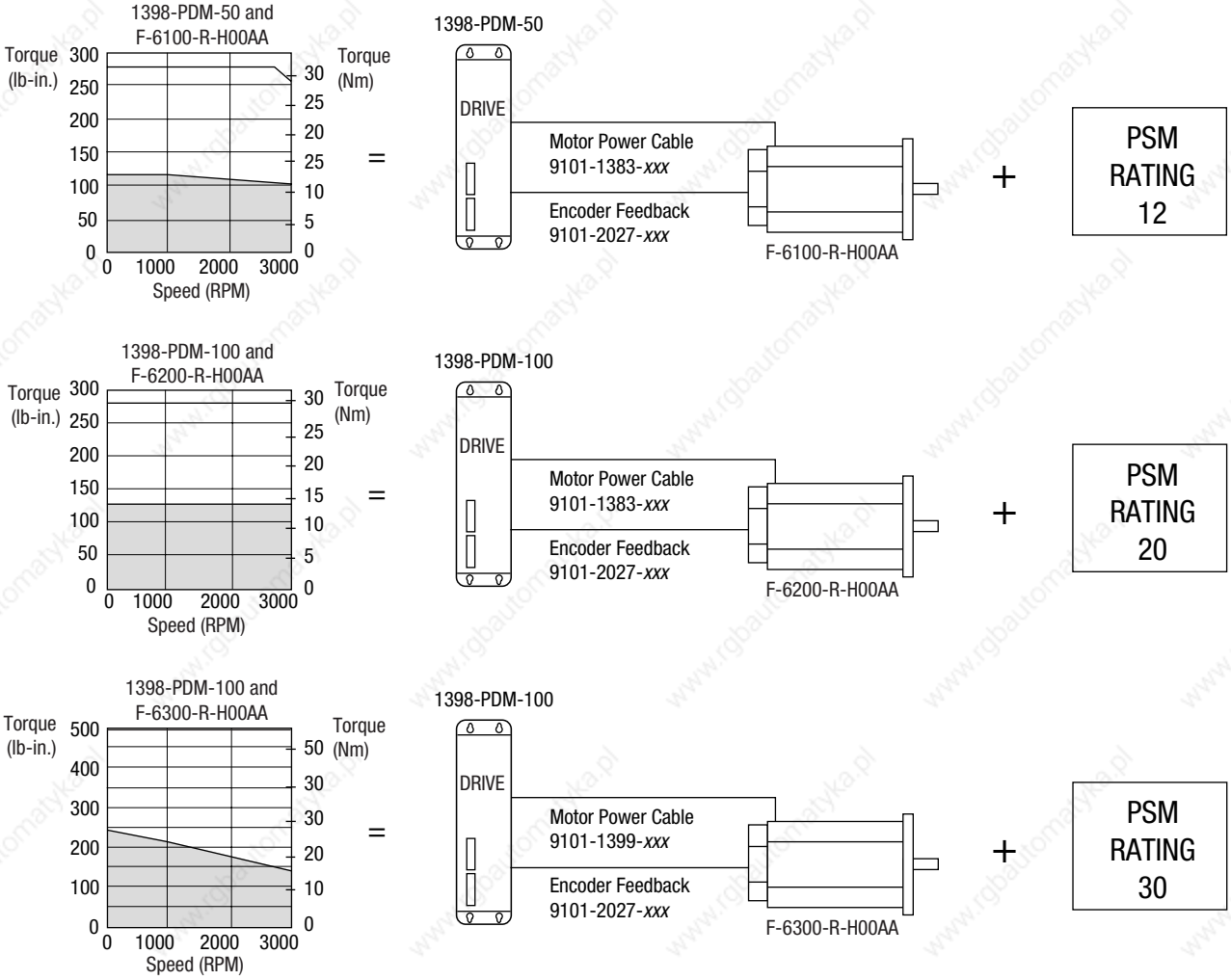



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with F-Series Motors (1398-PDM-25, -50, -100, and -150)

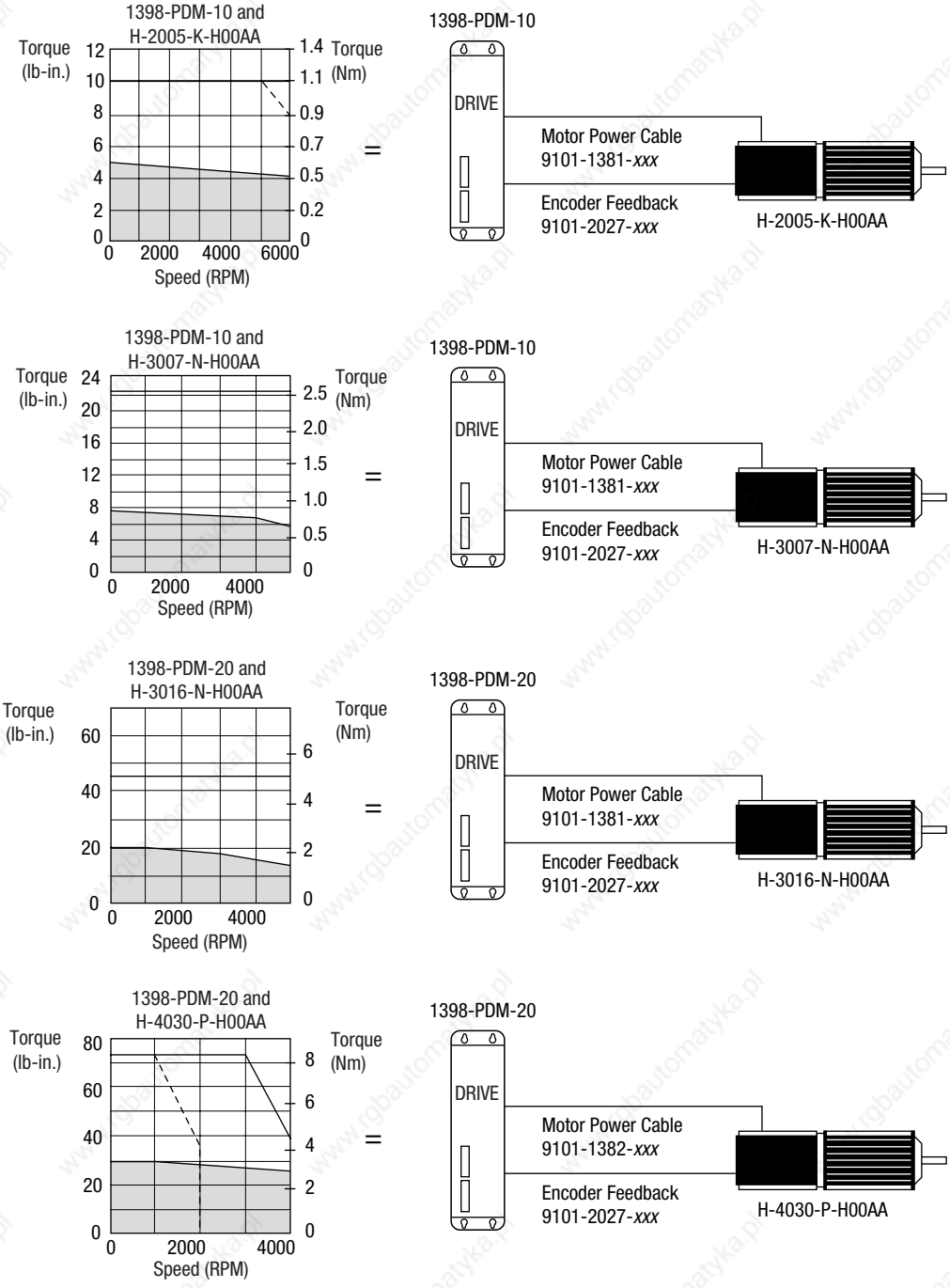



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075
Note: Serial interface and encoder cables for use with the ULTRA 100 drives cannot exceed 50 ft.

## ULTRA Plus Drives with H-Series Motors (1398-PDM-10, -20, -30, and -75)

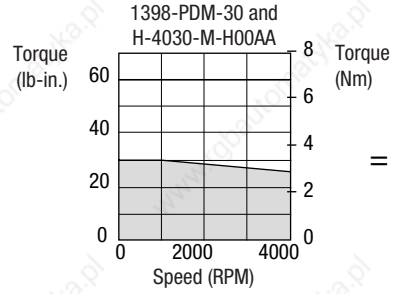



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

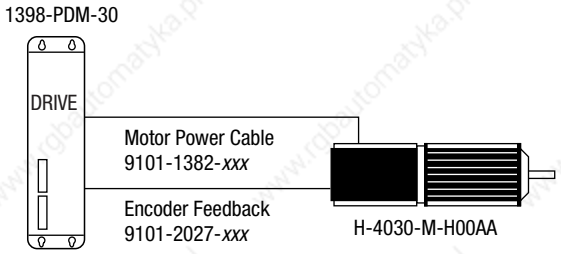
= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

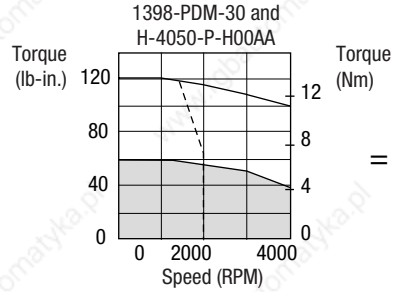
## ULTRA Plus Drives with H-Series Motors (1398-PDM-10, -20, -30, and -75)



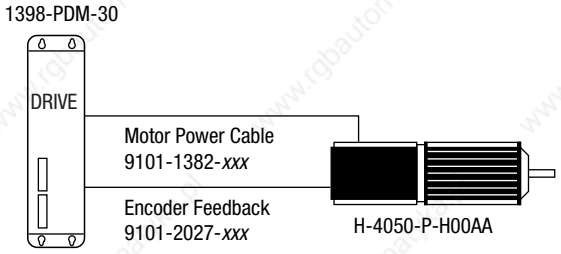

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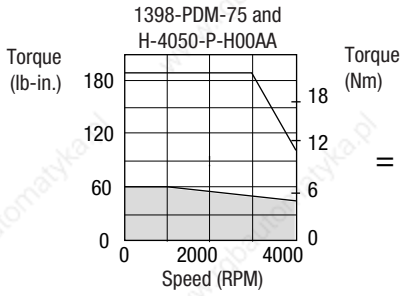



Note: For the H-4030-M-H00AA, the drive module input voltage may be either 115 or 230 VAC RMS.

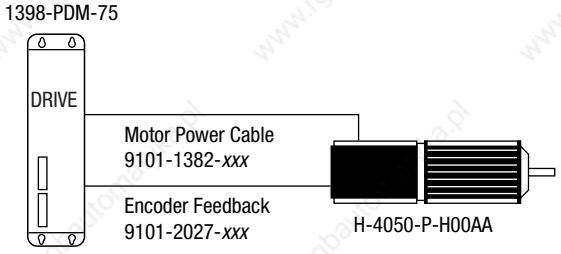


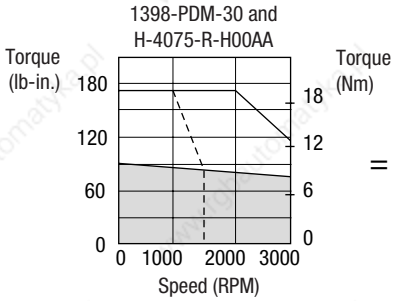

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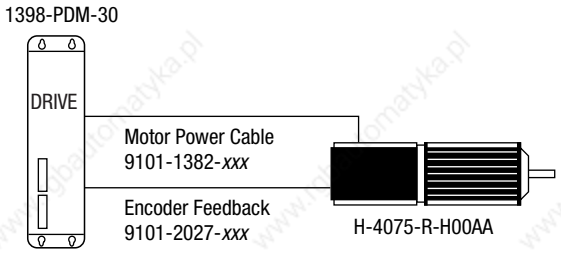




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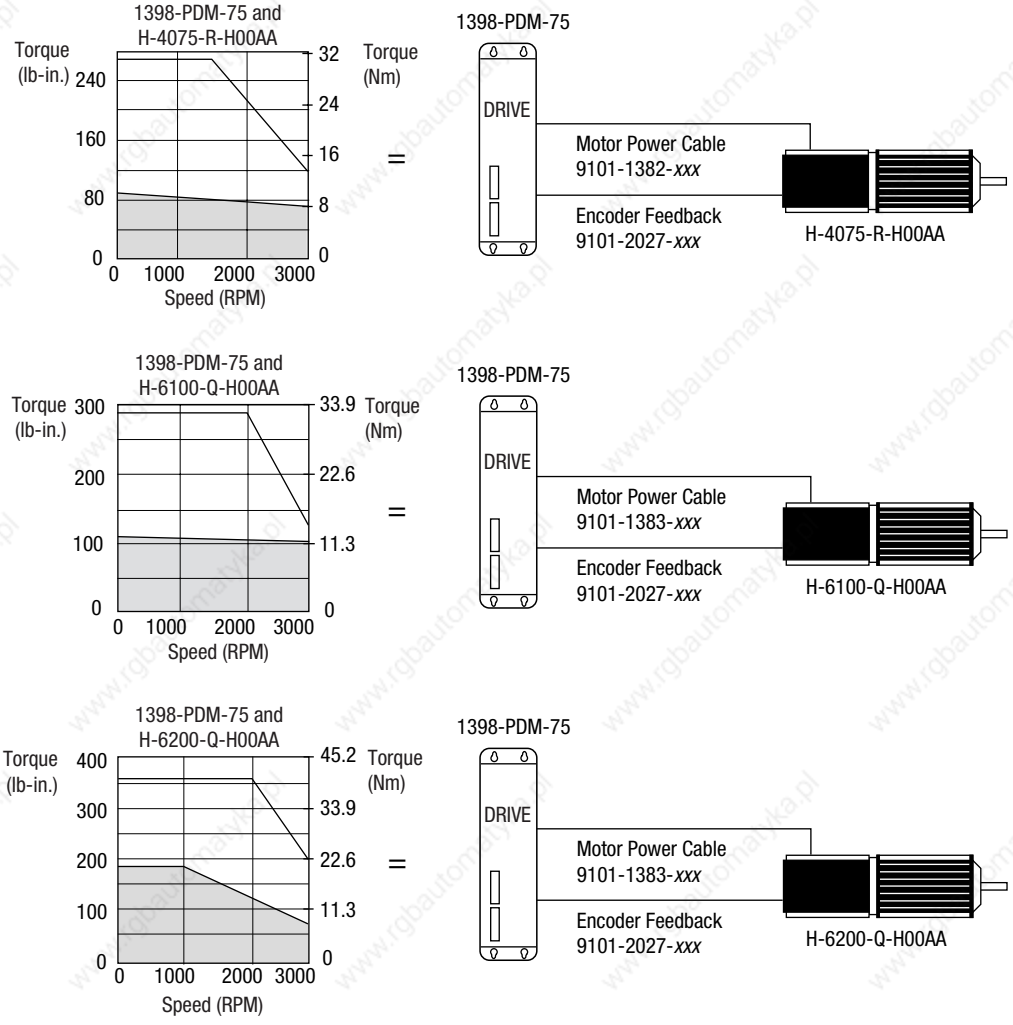



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with H-Series Motors (1398-PDM-10, -20, -30, and -75)

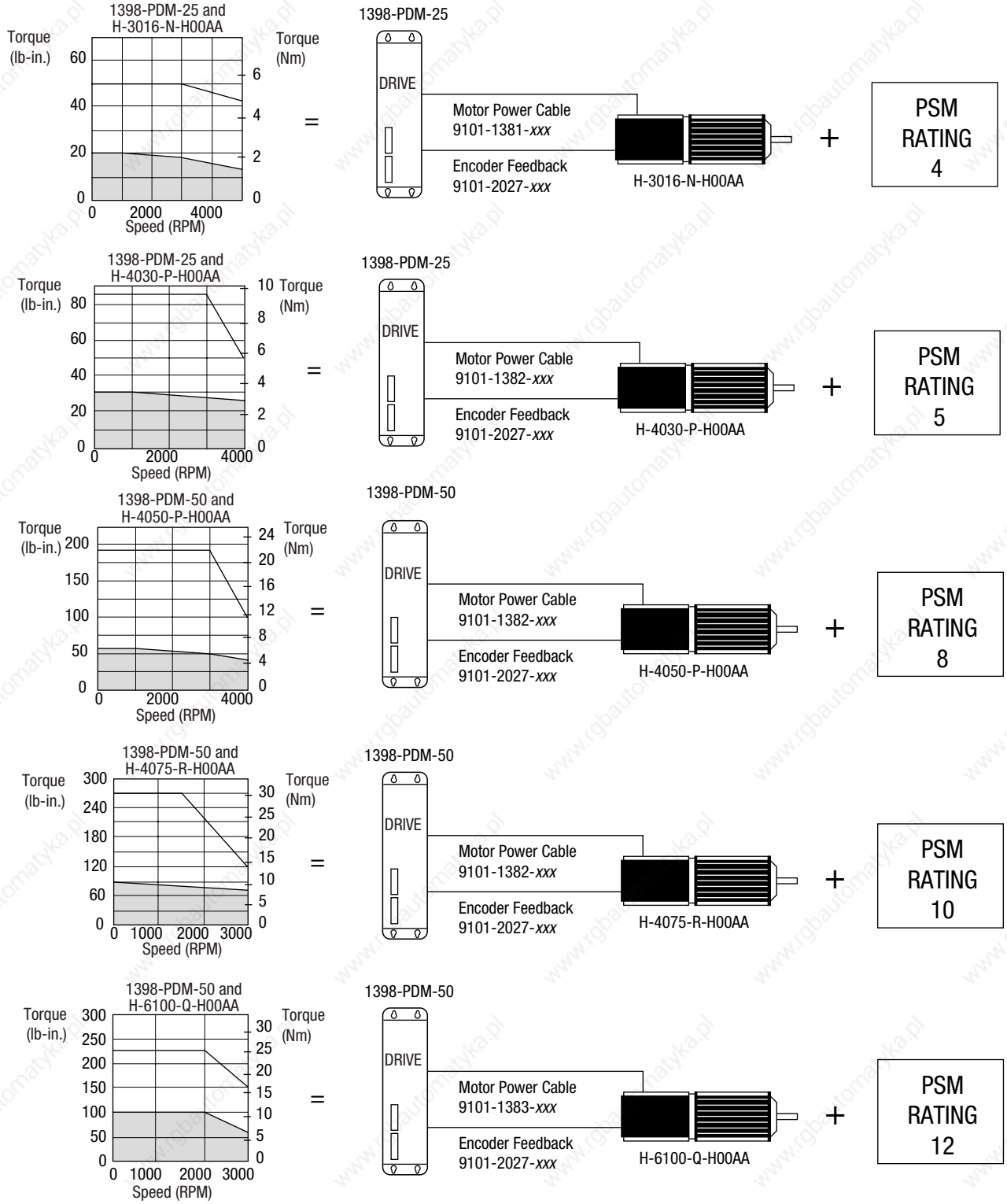



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with H-Series Motors (1398-PDM-25, -50, -100, and -150)

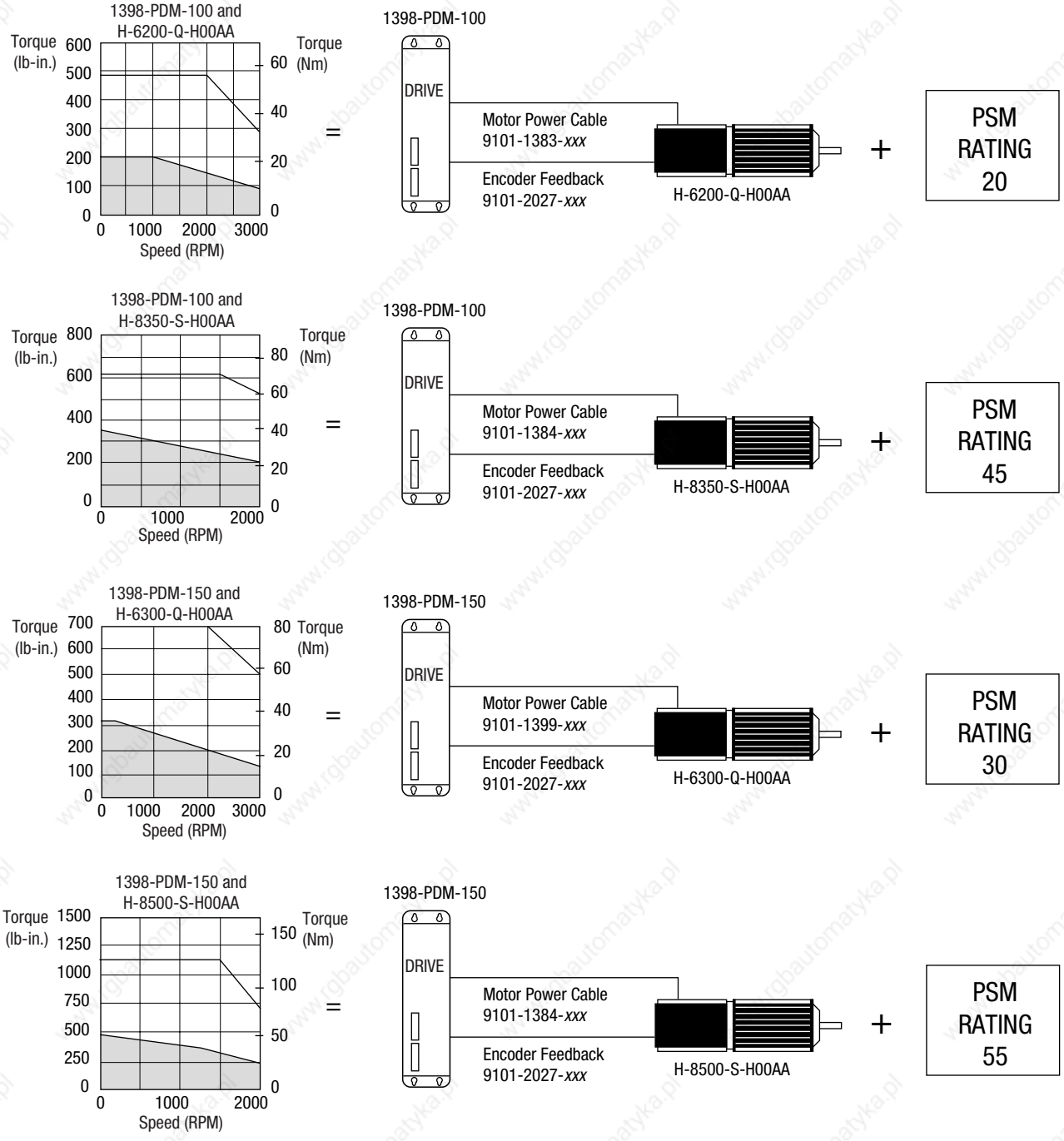



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with H-Series Motors (1398-PDM-25, -50, -100, and -150)

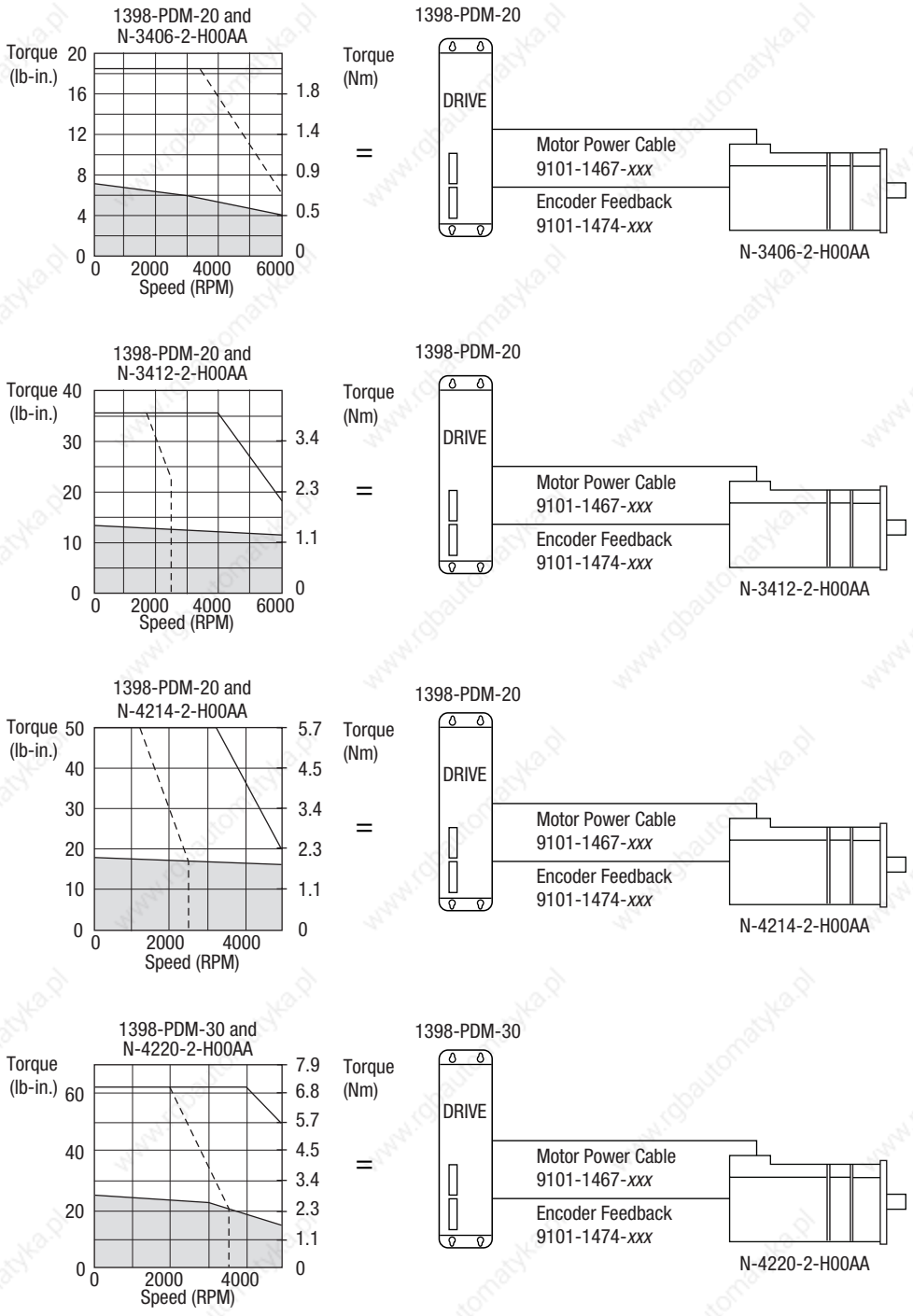



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with N-Series Motors (1398-PDM-20 and 1398-PDM-30)

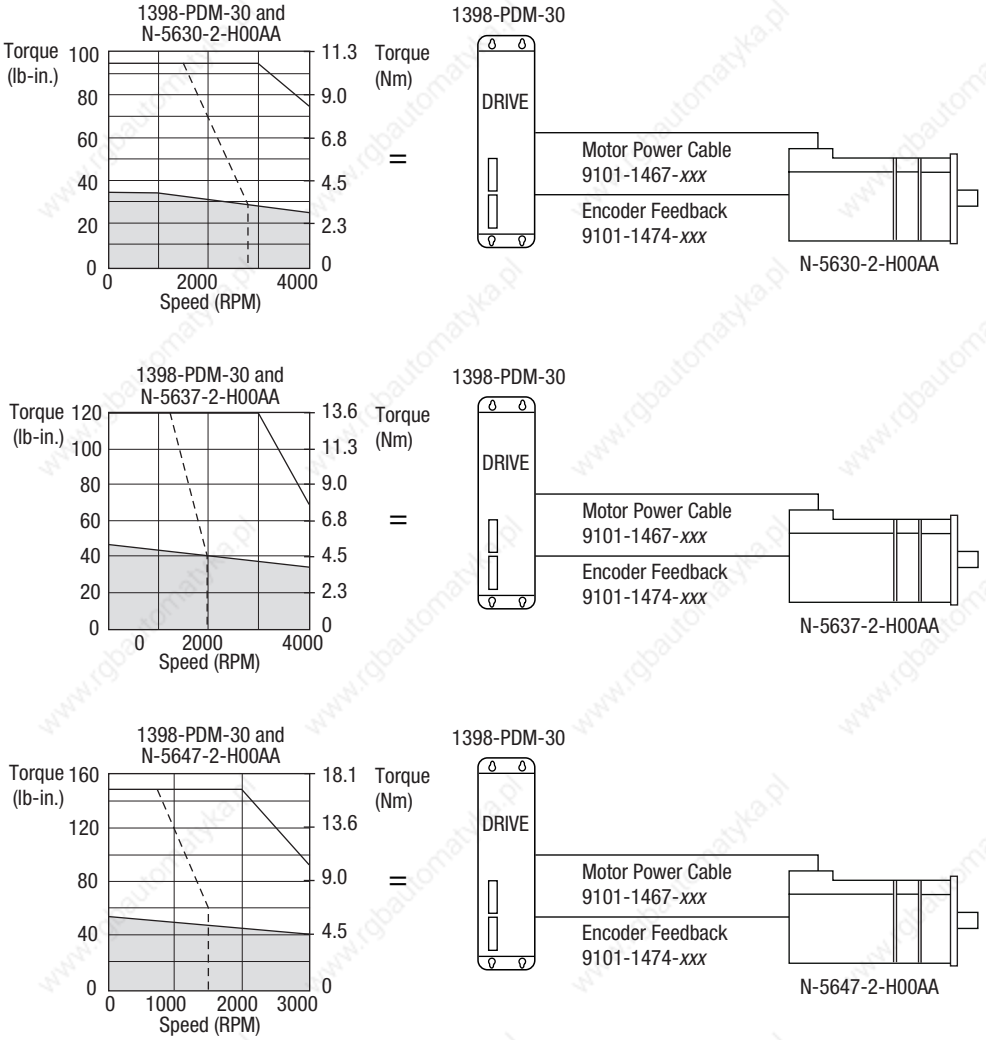



**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

## ULTRA Plus Drives with N-Series Motors (1398-PDM-20 and 1398-PDM-30)




**System speed-torque characteristics**
Drive module input voltage = 230V AC RMS

= Intermittent operating region
= Continuous operating region
= Drive operation with 115V AC RMS input voltage

* Last three digits select standard cable lengths of:
10 ft (3.0 m)-010; 25 ft (7.7 m)-025; 50 ft (15.0 m)-050; 75 ft (23.0 m)-075

# F-Series Motor and Connector Ordering Information

F - 4030 - Q - H 00 AA

- Factory Designated Special Options
  - AA = **STANDARD**
  - AN = NEMA (4000 Series Only)
- Options
  - 00 = **STANDARD**
  - 04 = 24V DC Brake
- Optical Encoder Line Count
  - F = 1000
  - H = 2000 (**STANDARD**)
  - K = 5000
  - L = 500
  - M = 3000
- Motor Winding Ke Designator
- Frame Size
- Series Designator
  - F = Medium Inertia

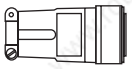
Note: Optional configurations or encoder line counts have extended lead times and additional charges

Note: Options are not available in all sizes

* The maximum speed with the 5000-line encoder is 2400 RPM because of the frequency output limit of the encoder.

**MOTOR MATING CONNECTORS**

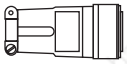
MS CONN KITS F-SERIES MOTOR POWER



| | STRAIGHT | RIGHT ANGLE |
|---|---|---|
| F-4000 SERIES: | 9101-0326 | 9101-0399 |
| F-6000 SERIES: | 9101-0327 | 9101-0400 |

MS CONN KIT

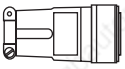
| STRAIGHT | RIGHT ANGLE |
|---|---|
| 9101-0329 | 9101-0402 |



F-Series Encoder Feedback

MS CONN KIT

| STRAIGHT | RIGHT ANGLE |
|---|---|
| 9101-0330 | 9101-0403 |



Brake Power

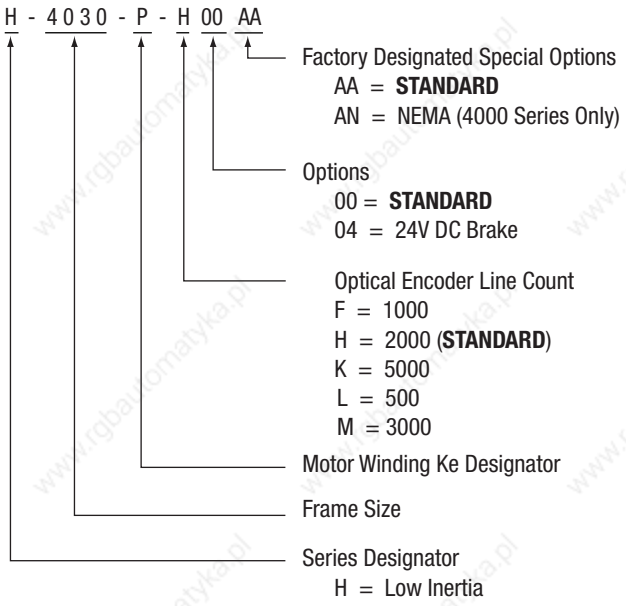
F-SERIES MOTOR SHAFT SEAL KITS

F-4000 SERIES: 0041-5060
F-6000 SERIES: 0041-5061

Shaft seals generally require the presence of a lubricant to reduce premature wear

Note: The mating connectors listed above are not CE compliant. See the cable options for CE compliant cable assemblies.

## H-Series Motor and Connector Ordering Information




Note: Optional configurations or encoder line counts have extended lead times and additional charges

Note: Options are not available in all sizes

Note: 5000 line count encoder, motor top speed is limited to 3600 RPM due to frequency output limit of encoder. Check drive system configuration data for any additional restrictions imposed by drive input.

**Motor Mating Connectors**

| MOTOR SERIES | STRAIGHT | RIGHT ANGLE |
|---|---|---|
| H-2000, -3000 | 9101-0325 (MS3106F18-4S) | 9101-0398 (MS3108F18-4S) |
| H-4000 | 9101-0326 (MS3106F20-4S) | 9101-0399 (MS3108F20-4S) |
| H-6000 | 9101-0327 (MS3106F24-22S) | 9101-0400 (MS3108F24-22S) |
| H-8000 | 9101-0328 (MS3106F32-17S) | 9101-0401 (MS3108F32-17S) |

BRAKE POWER CONNECTORS

| STRAIGHT | RIGHT ANGLE |
|---|---|
| 9101-0330 (MS3106F12S-3S) | 9101-0403 (MS3108F12S-3S) |

ENCODER FEEDBACK CONNECTORS

| STRAIGHT | RIGHT ANGLE |
|---|---|
| 9101-0329 (MS3106F20-29S) | 9101-0402 (MS3108F20-29S) |

H-SERIES MOTOR SHAFT SEAL KITS

| | |
|---|---|
| H-2000 Series: | 0041-5065 |
| H-3000 Series: | 0041-5058 |
| H-4000 Series: | 0041-5059 |
| H-6000 Series: | 0041-5053-005 |
| H-8000 Series: | |

Shaft seal kits generally require the presence of a lubricant to reduce premature wear.

Note: The mating connectors listed above are not CE compliant. See the cable options for CE compliant cable assemblies.

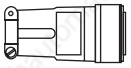
## Y-Series Motor and Connector Ordering Information

Y - 1002 - 2 - H 00 AA

- Factory Designated Special Options
  - AA = **STANDARD**
- Options
  - 00 = **STANDARD**
  - 04 = 24V DC Brake
- Optical Encoder Line Count
  - H = 2000 (**STANDARD**)
- Motor Winding Voltage Designator
  - 1 = 115 V Drive Input Voltage
  - 2 = 230 V Drive Input Voltage
- Frame Size
- Series Designator
  - Y = Light Industrial

**Motor Mating Connectors**

CONNECTOR KITS FOR Y-SERIES MOTORS



ALL Y-SERIES MOTORS
9106-0066

This kit includes connector, pins, and backshell for both the power and encoder connectors.

Note: The mating connectors listed above are not CE compliant. See the cable options for CE compliant cable assemblies.

# N-Series Motor and Connector Ordering Information

N - 4 2 1 4 - 2 - H 00 AA

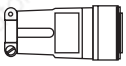
- Factory Designated Special Options
  - AA = **STANDARD**
- Options
  - 00 = **STANDARD**
  - 04 = 24V DC Brake
- Optical Encoder Line Count
  - F = 1000 (**STANDARD** for 2300 Series)
  - H = 2000 (**STANDARD**)
  - K = 5000
- Motor Winding Voltage
  - 1 = 115 V Drive Input Voltage
  - 2 = 230 V Drive Input Voltage
- Continuous Torque Capability
- NEMA Style Frame Size
- Series Designator
  - N = NEMA Style Frame

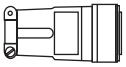
Note: Optional configurations or encoder line counts have extended lead times and additional charges

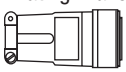
Note: Options are not available in all sizes

Note: 5000 line count encoder, motor top speed is limited to 3600 RPM due to frequency output limit of encoder. Check drive system configuration data for any additional restrictions imposed by drive input.

## Motor Mating Connectors

MS CONN KIT
Mating Power Connector

9101-1557

MS CONN KIT
Mating Encoder Connector

9101-1558

MS CONN KIT
Mating Brake Connector

9101-1698

POWER CONNECTOR

| | STRAIGHT | RIGHT ANGLE |
|---|---|---|
| Solder | MS3116F14-5S | KPT08F14-5S |
| Crimp | MS3126F14-5S | KPSE08F14-5S |

BRAKE POWER CONNECTOR

| | STRAIGHT | RIGHT ANGLE |
|---|---|---|
| Solder | MS3116F12-3S | KPT08F12-3S |
| Crimp | MS3126F12-3S | KPSE08F12-3S |

F-SERIES MOTOR SHAFT SEAL KITS

N-2300 SERIES: 0041-5068
N-3400 SERIES: 0041-5069
N-4200 SERIES: 0041-5070
N-5600 SERIES: 0041-5071

Shaft seals generally require the presence of a lubricant to reduce premature wear

ENCODER CONNECTOR

| | STRAIGHT | RIGHT ANGLE |
|---|---|---|
| Solder | MS3116F14-19S | KPT08F14-19S |
| Crimp | MS3126F14-19S | KPSE08F14-19S |

Note: The mating connectors listed above are not CE compliant. See the cable options for CE compliant cable assemblies.

**For more information refer to our web site: www.ab.com/motion**

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