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# BM Series

## *Brushless Rotary Servomotors*

- Standard NEMA frame sizes
- Neodymium iron boron rare-earth magnets maximize performance
- Skewed stator with multi-pole design minimizes torque ripple and cogging for smooth velocity control over a greater speed range
- Optional IP65-level construction allows use in harsh environments
- Optional brake, front shaft seal, and precision gear reducers



### High-Performance Design

The BM series consists of Aerotech's high-performance brushless rotary servomotors. The motors feature neodymium iron boron magnets for maximum torque and acceleration in a small package. A skewed stator design and an eight-pole rotor provide low torque ripple and smooth velocity. Unlike DC brush-type servomotors, the BM series are brushless and maintenance free. This makes them ideal for critical applications where downtime cannot be tolerated.

In addition, the BM series motors have very high power density resulting in high torque in a compact package. Optional IP65 sealing make these motors ideal for harsh environments such as machine tool.

### Wide Torque Range

The BM motor series covers a wide range of torque and package sizes. Continuous output torque ranges from 0.16 N-m (22.5 oz-in) to 31.6 N-m (280 lb-in), with peak torques to 94.9 N-m (840 lb-in). Standard frame sizes include NEMA 17, 23, 34, 42 and 56. This makes it easy to mount any motor to Aerotech's gearbox line with no adapter plates. These motors are well-suited to general purpose and high-end servo applications.

### Application Flexibility

The standard motor has a 1000-line encoder (4000-line count after quadrature), RS-422 line driver output with Hall effect device outputs for commutation, and MS connectors. Options include increased encoder resolution, sealing for IP65 level protection, brakes, and gearboxes. Standard models can be delivered from stock and custom variations can be engineered to your requirements with minimal lead time.



*All Aerotech motors are manufactured following ISO9001 standards.*



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## BM Series SPECIFICATIONS

| Model | | BM22 | BM75 | BM130 | BM200 |
|---|---|---|---|---|---|
| **Performance Specifications**[1,2] | | | | | |
| **Stall Torque, Continuous**[3] | N·m | 0.16 | 0.51 | 1.02 | 1.45 |
| | oz·in | 22.5 | 72 | 144 | 205 |
| **Peak Torque**[4] | N·m | 0.48 | 1.3 | 2.5 | 3.6 |
| | oz·in | 68 | 181 | 361 | 512 |
| **Rated Speed** | rpm | 3,000 | 4,000 | 4,000 | 4,000 |
| **Rated Power Output, Continuous** | W | 50 | 192 | 333 | 455 |
| **Electrical Specifications**[2] | | | | | |
| **BEMF Constant (Line-Line, Max)** | $V_{pk}$/krpm | 3.9 | 9 | 19 | 18 |
| **Continuous Current, Stall**[3] | $A_{pk}$ | 4.9 | 9.0 | 6.9 | 10.3 |
| | $A_{rms}$ | 3.5 | 6.4 | 4.9 | 7.3 |
| **Peak Current, Stall**[4] | $A_{pk}$ | 14.7 | 22.5 | 17.3 | 25.8 |
| | $A_{rms}$ | 10.4 | 15.9 | 12.2 | 18.2 |
| **Torque Constant**[5,6] | N·m / $A_{pk}$ | 0.032 | 0.06 | 0.15 | 0.14 |
| | oz·in / $A_{pk}$ | 4.5 | 8.0 | 20.9 | 19.9 |
| | N·m / $A_{rms}$ | 0.045 | 0.08 | 0.21 | 0.20 |
| | oz·in / $A_{rms}$ | 6.4 | 11.4 | 29.6 | 28.1 |
| **Motor Constant**[3,5] | N·m / √W | 0.038 | 0.053 | 0.098 | 0.125 |
| | oz·in / √W | 5.37 | 7.52 | 13.84 | 17.77 |
| **Resistance, 25°C (Line-Line)** | Ω | 0.67 | 1.0 | 2.0 | 1.1 |
| **Inductance (Line-Line)** | mH | 0.73 | 0.8 | 1.8 | 1.1 |
| **Maximum Bus Voltage** | VDC | 80 | 340 | 340 | 340 |
| **Thermal Resistance** | °C/W | 6.26 | 1.41 | 1.20 | 0.98 |
| **Number of Poles** | - | 8 | 8 | 8 | 8 |
| **Mechanical Specifications** | | | | | |
| **Frame Size** | NEMA | 17 | 23 | 23 | 23 |
| **Motor Weight** | kg | 0.4 | 1.1 | 1.5 | 2.0 |
| | lb | 0.88 | 2.42 | 3.30 | 4.40 |
| **Rotor Moment of Inertia** | kg·m$^2$ | 2.00x10$^{-6}$ | 5.20x10$^{-6}$ | 9.20X10$^{-6}$ | 1.30x10$^{-5}$ |
| | oz·in·s$^2$ | 0.00028 | 0.0007 | 0.0013 | 0.0018 |
| **Max. Radial Load** | N | 78 | 89 | 89 | 89 |
| | lb | 18 | 20 | 20 | 20 |
| **Max. Axial Load** | N | 39 | 89 | 89 | 89 |
| | lb | 9 | 20 | 20 | 20 |

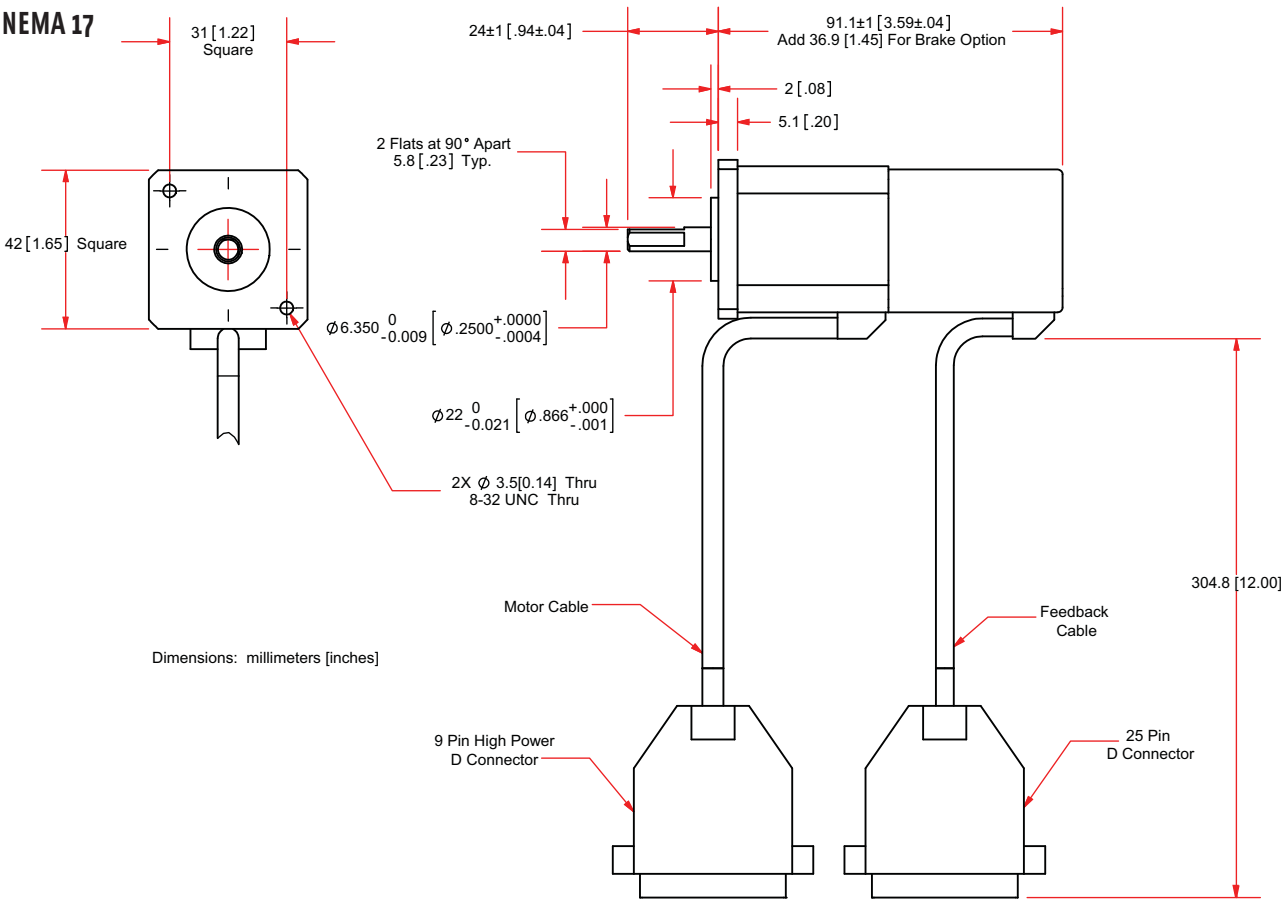
Notes:
1. Performance is dependent upon heat sink configuration, system cooling conditions, and ambient temperature.
2. All performance and electrical specifications ±10%.
3. Values shown @ 105°C rise above a 25°C ambient temperature, with motor mounted to a 250 mm x 250 mm x 6 mm aluminum heat sink.
4. Peak torque assumes correct rms current; consult Aerotech.
5. Torque constant and motor constant specified at stall.
6. De-rate continuous torque an continuous current by 10% when using an encoder (does not apply to BM22).
7. Maximum winding temperature is 130°C.
8. Ambient operating temperature range 0°C - 25°C; consult Aerotech for performance in elevated ambient temperatures.
9. All Aerotech amplifiers are rated $A_{pk}$; use torque constant in N-m/$A_{pk}$ when sizing.



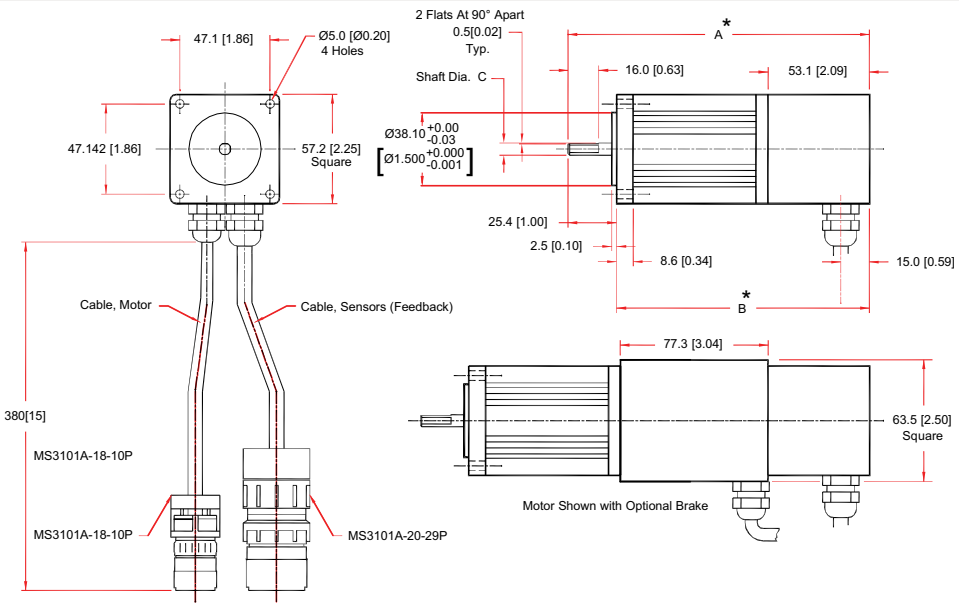
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## BM Series DIMENSIONS

### NEMA 17




### NEMA 23




Dimensions - millimeters [inches]

| Motor Model No. | A* | B* | C |
|---|---|---|---|
| BM75 | 157.5 / 6.20" | 132.1 / 5.20" | Ø 6,345 / 0.2498" +0.000, -0.013 / +0.0000", -0.0005" |
| BM130 | 187.9 / 7.40" | 162.6 / 6.40" | Ø 9,517 / 0.3747" +0.000, -0.013 / +0.0000", -0.0005" |
| BM200 | 218.4 / 8.60" | 193.0 / 7.60" | Ø 9,517 / 0.3747" +0.000, -0.013 / +0.0000", -0.0005" |

* Add 77.3 [3.04 IN.] To Length For Optional Brake.



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## BM Series SPECIFICATIONS

| Model | | BM250 | BM500 |
|---|---|---|---|
| **Performance Specifications**[1,2] | | | |
| **Stall Torque, Continuous**[3] | N·m | 2.3 | 3.6 |
| | oz·in | 322 | 515 |
| **Peak Torque**[4] | N·m | 5.7 | 9.1 |
| | oz·in | 805 | 1,286 |
| **Rated Speed** | rpm | 4,000 | 4,000 |
| **Rated Power Output, Continuous** | W | 739 | 1065 |
| **Electrical Specifications**[2] | | | |
| **BEMF Constant (Line-Line, Max)** | $V_{pk}$/krpm | 28 | 29 |
| **Continuous Current, Stall**[3] | $A_{pk}$ | 10.3 | 17.5 |
| | $A_{rms}$ | 7.2 | 12.4 |
| **Peak Current, Stall**[4] | $A_{pk}$ | 25.6 | 43.8 |
| | $A_{rms}$ | 18.1 | 30.9 |
| **Torque Constant**[5,6] | N·m / $A_{pk}$ | 0.22 | 0.21 |
| | oz·in / $A_{pk}$ | 31.4 | 29.4 |
| | N·m / $A_{rms}$ | 0.31 | 0.29 |
| | oz·in / $A_{rms}$ | 44.4 | 41.6 |
| **Motor Constant**[3,5] | N·m / √W | 0.198 | 0.275 |
| | oz·in / √W | 28.04 | 38.94 |
| **Resistance, 25°C (line to line)** | Ω | 1.1 | 0.5 |
| **Inductance (line to line)** | mH | 2.74 | 1.42 |
| **Maximum Bus Voltage** | VDC | 340 | 340 |
| **Thermal Resistance** | °C/W | 0.99 | 0.74 |
| **Number of Poles** | - | 8 | 8 |
| **Mechanical Specifications** | | | |
| **Frame Size** | NEMA | 34 | 34 |
| **Motor Weight** | kg | 3.6 | 5.0 |
| | lb | 7.92 | 11.00 |
| **Rotor Moment of Inertia** | kg·m$^2$ | 7.85x10$^{-5}$ | 1.39x10$^{-4}$ |
| | oz·in·s$^2$ | 0.0111 | 0.0197 |
| **Max. Radial Load** | N | 178 | 178 |
| | lb | 40 | 40 |
| **Max. Axial Load** | N | 89 | 89 |
| | lb | 20 | 20 |

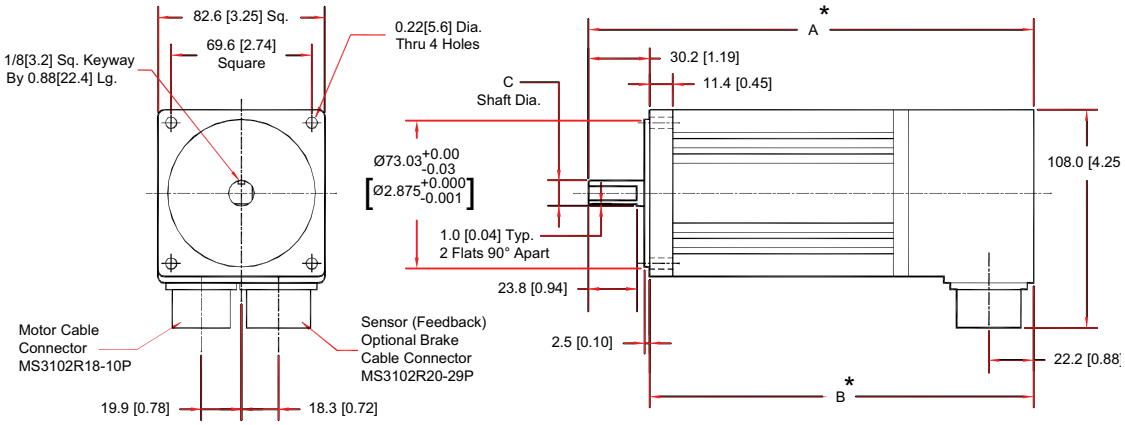
Notes:
1. Performance is dependent upon heat sink configuration, system cooling conditions, and ambient temperature.
2. All performance and electrical specifications ±10%.
3. Values shown @ 105°C rise above a 25°C ambient temperature, with motor mounted to a 250 mm x 250 mm x 6 mm aluminum heat sink.
4. Peak torque assumes correct rms current; consult Aerotech.
5. Torque constant and motor constant specified at stall.
6. De-rate continuous torque and continuous current by 10% when using an encoder (does not apply to BM22).
7. Maximum winding temperature is 130°C.
8. Ambient operating temperature range 0°C - 25°C; consult Aerotech for performance in elevated ambient temperatures.
9. All Aerotech amplifiers are rated $A_{pk}$; use torque constant in N-m/$A_{pk}$ when sizing.



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## BM Series DIMENSIONS

### NEMA 34




Dimensions - millimeters [inches]

| Motor Model No. | A* | B* | C |
|---|---|---|---|
| BM250 | 220.3 / 8.67" | 190.0 / 7.48" | Ø 12.69 / 0.4997" +0.000, -0.013 / +0.0000", -0.0005" |
| BM500 | 275.1 / 10.83" | 244.9 / 9.64" | Ø 12.69 / 0.4997" +0.000, -0.013 / +0.0000", -0.0005" |

*Add 55.6[2.19 IN.] To Length For Optional Brake.



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## BM Series SPECIFICATIONS

| Model | | BM800 | BM1400 |
|---|---|---|---|
| **Performance Specifications**[1,2] | | | |
| **Stall Torque, Continuous**[3] | N·m | 6.1 | 11.0 |
| | oz·in | 866 | 1562 |
| **Peak Torque**[4] | N·m | 15.3 | 27.6 |
| | oz·in | 2166 | 3905 |
| **Rated Speed** | rpm | 3,000 | 3,000 |
| **Rated Power Output, Continuous** | W | 1446 | 2529 |
| **Electrical Specifications**[2] | | | |
| **BEMF Constant (Line-Line, Max)** | $V_{pk}$/krpm | 69 | 69 |
| **Continuous Current, Stall**[3] | $A_{pk}$ | 11.9 | 20.5 |
| | $A_{rms}$ | 8.4 | 14.5 |
| **Peak Current, Stall**[4] | $A_{pk}$ | 29.8 | 51.3 |
| | $A_{rms}$ | 21.0 | 36.2 |
| **Torque Constant**[5,6] | N·m / $A_{pk}$ | 0.51 | 0.54 |
| | oz·in / $A_{pk}$ | 72.8 | 76.2 |
| | N·m / $A_{rms}$ | 0.73 | 0.76 |
| | oz·in / $A_{rms}$ | 103 | 107.8 |
| **Motor Constant**[3,5] | N·m / √W | 0.439 | 0.713 |
| | oz·in / √W | 62.24 | 100.93 |
| **Resistance, 25°C (line to line)** | Ω | 1.2 | 0.5 |
| **Inductance (line to line)** | mH | 3.8 | 1.7 |
| **Maximum Bus Voltage** | VDC | 340 | 340 |
| **Thermal Resistance** | °C/W | 0.67 | 0.54 |
| **Number of Poles** | - | 8 | 8 |
| **Mechanical Specifications** | | | |
| **Frame Size** | NEMA | 42 | 42 |
| **Motor Weight** | kg | 6.6 | 10.7 |
| | lb | 14.52 | 23.54 |
| **Rotor Moment of Inertia** | kg·m² | $3.00 \times 10^{-4}$ | $5.60 \times 10^{-4}$ |
| | oz·in·s² | 0.0425 | 0.0793 |
| **Max. Radial Load** | N | 222 | 222 |
| | lb | 50 | 50 |
| **Max. Axial Load** | N | 89 | 89 |
| | lb | 20 | 20 |

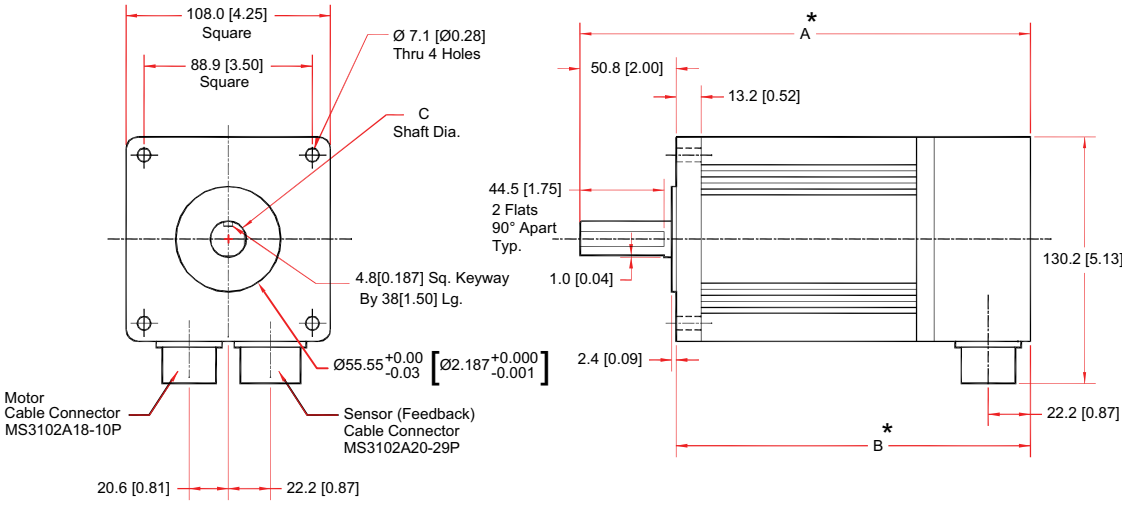
Notes:
1. Performance is dependent upon heat sink configuration, system cooling conditions, and ambient temperature.
2. All performance and electrical specifications ±10%.
3. Values shown @ 105°C rise above a 25°C ambient temperature, with motor mounted to a 250 mm x 250 mm x 6 mm aluminum heat sink.
4. Peak torque assumes correct rms current; consult Aerotech.
5. Torque constant and motor constant specified at stall.
6. De-rate continuous torque an continuous current by 10% when using an encoder (does not apply to BM22).
7. Maximum winding temperature is 130°C.
8. Ambient operating temperature range 0°C - 25°C; consult Aerotech for performance in elevated ambient temperatures.
9. All Aerotech amplifiers are rated $A_{pk}$; use torque constant in N-m/$A_{pk}$ when sizing.



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## BM Series DIMENSIONS

### NEMA 42




Dimensions - millimeters [inches]

| Motor Model No. | A* | B* | C |
|---|---|---|---|
| BM800 | 238<br>9.37" | 187<br>7.37" | Ø 19.04 +0.000, -0.013<br>0.7497" +0.0000", -0.0005" |
| BM1400 | 318<br>12.52" | 267.2<br>10.52" | Ø 19.04 +0.000, -0.013<br>0.7497" +0.0000", -0.0005" |

*Add 68.9[2.71 IN.] To Length For Optional Brake.



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## BM Series SPECIFICATIONS

| Model | | BM2000 | BM3400 | BM4500 |
|---|---|---|---|---|
| **Performance Specifications[1,5]** | | | | |
| **Stall Torque, Continuous[2]** | N·m(lb·in) | 14.7 (130) | 23.7 (210) | 31.6 (280) |
| **Peak Torque[3]** | N·m(lb·in) | 44.1 (390) | 71.2 (630) | 94.9 (840) |
| **Rated Speed** | rpm | 2,400 | 2,400 | 2,400 |
| **Rated Power Output, Continuous** | watts | 3282 | 5073 | 6789 |
| **Electrical Specifications[5]** | | | | |
| **BEMF Constant (line to line, max)** | $Volts_{pk}$/krpm | 99.0 | 99.0 | 113.1 |
| **Continuous Current, Stall[2]** | $Amp_{pk}$ | 16.5 | 26.7 | 31.1 |
| | $Amp_{rms}$ | 11.7 | 18.9 | 22.0 |
| **Peak Current, Stall[3]** | $Amp_{pk}$ | 49.7 | 80.3 | 93.5 |
| | $Amp_{rms}$ | 35.1 | 56.7 | 66.1 |
| **Torque Constant[4,8]** | N·m/$Amp_{pk}$ | 0.89 | 0.89 | 1.01 |
| | lb·in/$Amp_{pk}$ | 7.9 | 7.9 | 9.0 |
| | N·m/$Amp_{rms}$ | 1.25 | 1.25 | 1.43 |
| | lb·in/$Amp_{rms}$ | 11.1 | 11.1 | 12.7 |
| **Motor Constant[2,4]** | N·m/√W | 1.13 | 1.86 | 2.31 |
| | lb·in/√W | 10.0 | 16.5 | 20.5 |
| **Resistance, 25°C (line-line)** | ohms | 0.54 | 0.20 | 0.17 |
| **Inductance (line-line)** | mH | 3.50 | 1.60 | 1.50 |
| **Maximum Bus Voltage** | VDC | 340 | 340 | 340 |
| **Thermal Resistance** | C/W | 0.78 | 0.80 | 0.69 |
| **Number of Poles** | P | 6 | 6 | 6 |
| **Encoder Options** | Quadrature or Amplified Sine | | | |
| **Mechanical Specifications** | | | | |
| **Frame Size** | NEMA | 56 | 56 | 56 |
| **Motor Weight** | kg (lb) | 15 (33.0) | 23 (49.9) | 30 (66.9) |
| **Rotor Moment of Inertia** | kg·$m^2$ | $1.25x10^{-3}$ | $2.23x10^{-3}$ | $3.24x10^{-3}$ |
| | lb·in·$s^2$ | 0.0111 | 0.0197 | 0.0287 |
| **Max. Radial Load** | N (lb) | 668 (150) | 668 (150) | 668 (150) |
| **Max. Axial Load** | N (lb) | 223 (50) | 223 (50) | 223 (50) |

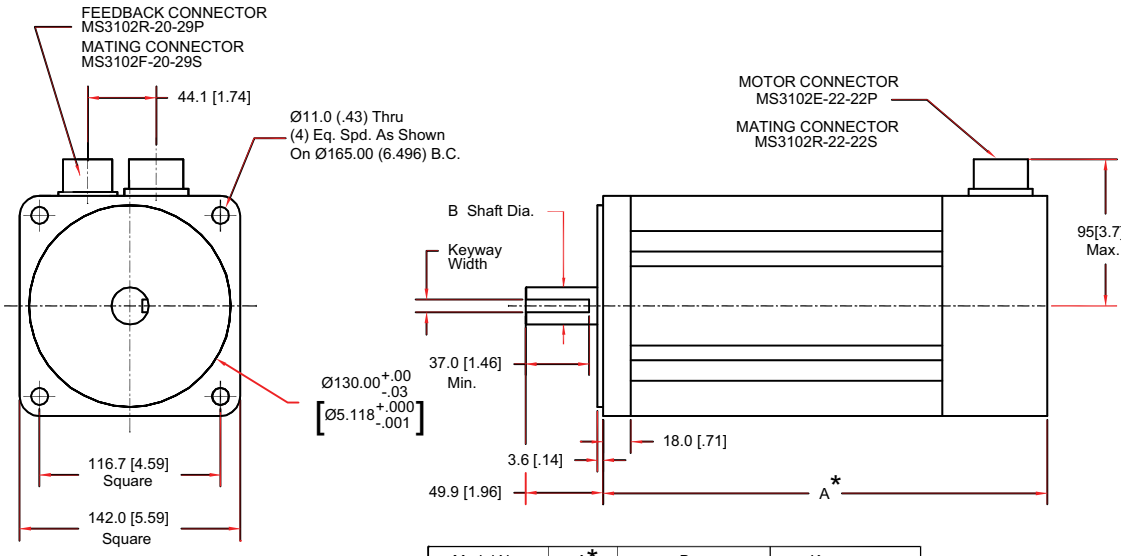
Notes:
1. Performance is dependent upon heat sink configuration, system cooling conditions, and ambient temperature.
2. All performance and electrical specifications ±10%.
3. Values shown @ 130°C rise above a 25°C ambient temperature, with motor mounted to a 250 mm x 250 mm x 6 mm aluminum heat sink.
4. Peak torque assumes correct rms current; consult Aerotech.
5. Torque constant and motor constant specified at stall.
6. De-rate continuous torque an continuous current by 10% when using an encoder (does not apply to BM22).
7. Maximum winding temperature is 155°C.
8. Ambient operating temperature range 0°C - 25°C; consult Aerotech for performance in elevated ambient temperatures.
9. All Aerotech amplifiers are rated $A_{pk}$; use torque constant in N-m/$A_{pk}$ when sizing.



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## BM Series DIMENSIONS

### NEMA 56

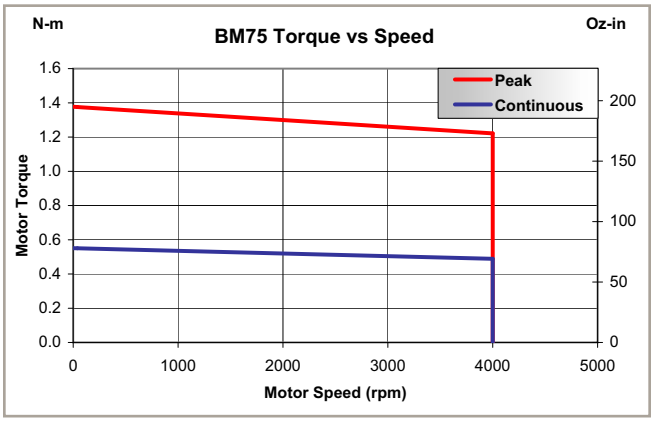


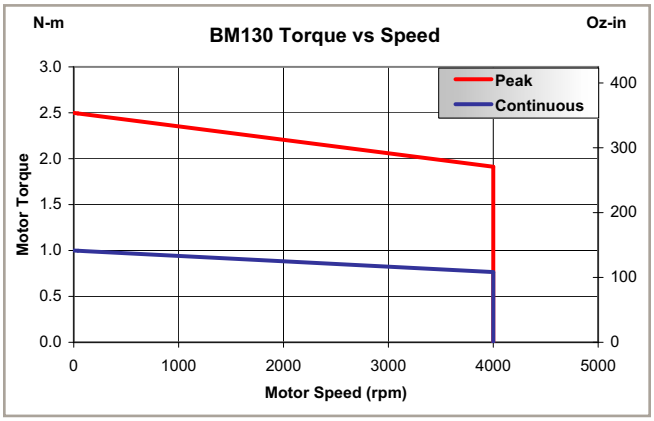

Dimensions - millimeters [inches]

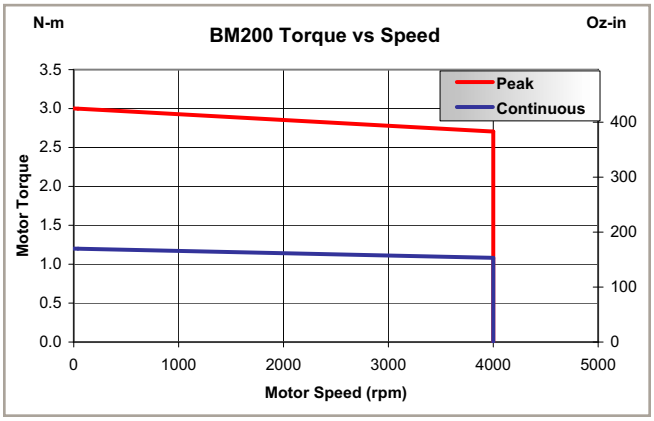
| Model No. | A* | B | Keyway |
|---|---|---|---|
| BM2000 | 286.8 / 11.29" | 24.000 / 23.988 / 0.9449" / 0.9444" | 7.998 / 7.963 / 0.3135" / 0.3149" |
| BM3400 | 355.3 / 13.99" | 24.000 / 23.988 / 0.9449" / 0.9444" | 7.998 / 7.963 / 0.3135" / 0.3149" |
| BM4500 | 423.9 / 16.69" | 32.000 / 31.984 / 1.2598" / 1.2593" | 9.975 / 10.000 / 0.3927" / 0.3937" |

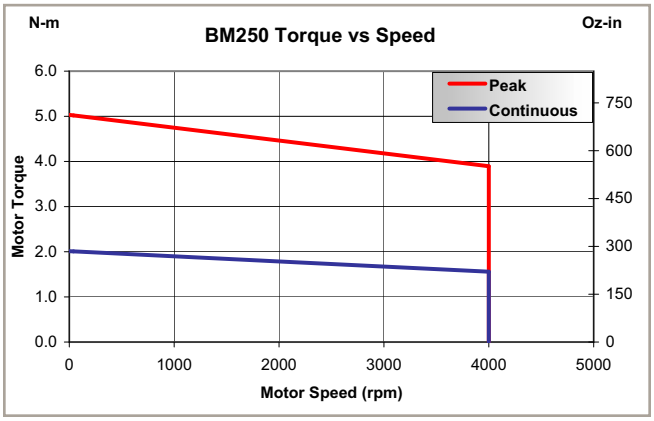
*Add 69[2.7] To Length For Optional Brake.

## BM Series MOTOR PERFORMANCE



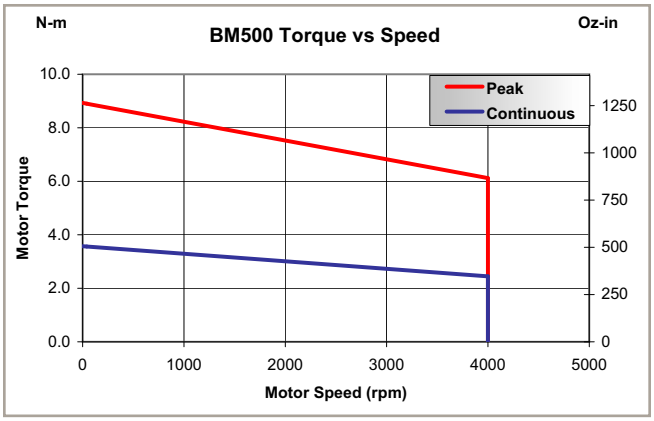



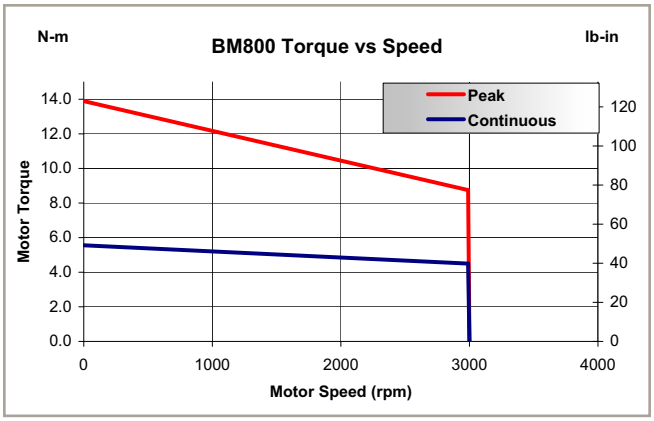



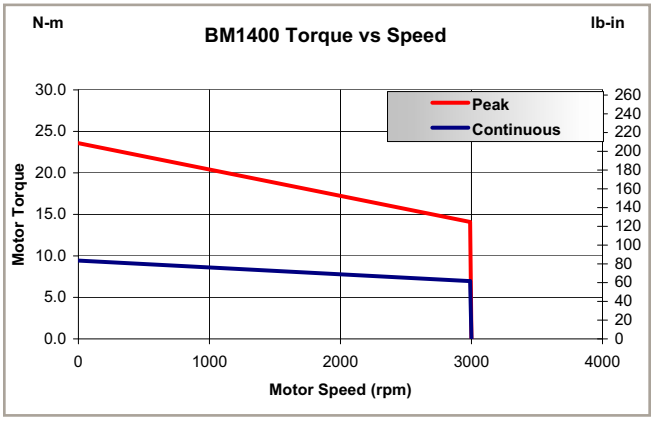


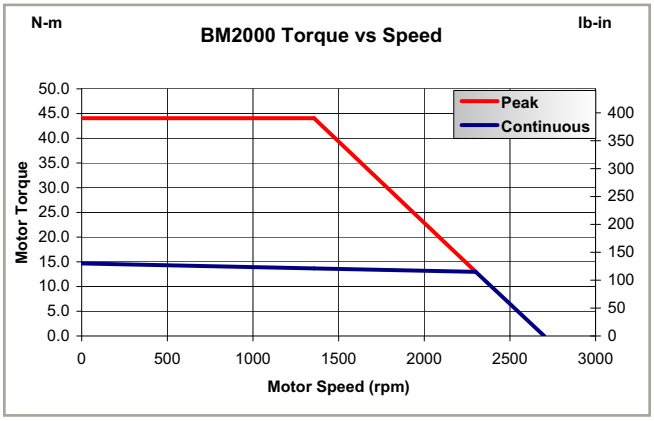

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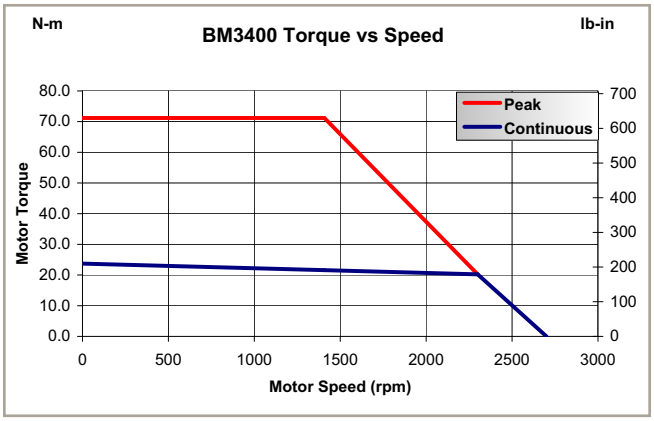
## BM Series MOTOR PERFORMANCE

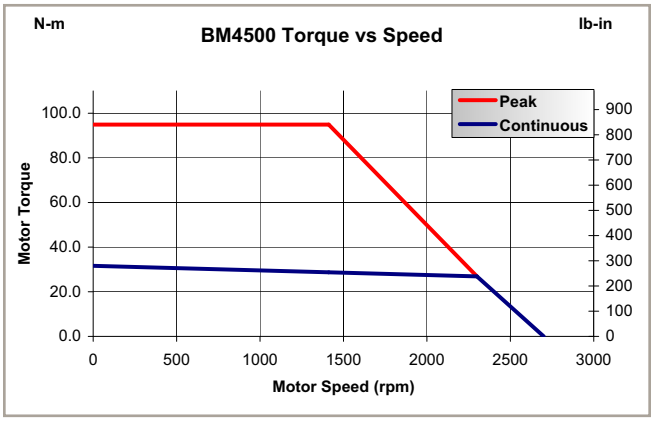





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## BM Series ORDERING INFORMATION

### Ordering Example

| BM | 130 | -MS | -E2000H | -BK1 |
|---|---|---|---|---|
| Motor Series | Motor Torque Code | Connector Options | Encoder Resolution with Hall Tracks | Motor Options |
| | 22<br>75<br>130<br>200<br>250<br>500<br>800<br>1400<br>2000<br>3400<br>4500 | -MS<br>-D25 | -E1000H<br>-E2000H<br>-E2500H<br>-E5000H<br>-E1000ASH | -BK1<br>-BK2<br>-BK3<br>-BK5<br>-NS<br>-VAC6 |

Standard motor/encode = BM130E (MS connectors; E1000H encoder)

### Brushless Rotary Servomotors

| | |
|---|---|
| BM22 | NEMA 17 brushless servomotor; 22.5 oz-in continuous torque |
| BM75 | NEMA 23 brushless servomotor; 78.3 oz-in continuous torque |
| BM130 | NEMA 23 brushless servomotor; 141.5 oz-in continuous torque |
| BM200 | NEMA 23 brushless servomotor; 170.0 oz-in continuous torque |
| BM250 | NEMA 34 brushless servomotor; 285 oz-in continuous torque |
| BM500 | NEMA 34 brushless servomotor; 506 oz-in continuous torque |
| BM800 | NEMA 42 brushless servomotor; 787 oz-in continuous torque |
| BM1400 | NEMA 42 brushless servomotor; 1336 oz-in continuous torque |
| BM2000 | NEMA 56 brushless servomotor; 130 lb-in continuous torque |
| BM3400 | NEMA 56 brushless servomotor; 210 lb-in continuous torque |
| BM4500 | NEMA 56 brushless servomotor; 280 lb-in continuous torque |

### Connectors

| | |
|---|---|
| -MS | MS connectors for feedback and motor power (not available on BM22) |
| -D25 | D-shell for feedback and motor power (not available on BM250, BM500, BM800, BM1400, BM2000, BM3400, and BM4500) |

### Feedback Options

| | |
|---|---|
| -E1000H | Encoder, A quad B with marker, 5 VDC, 1000 line, line-driver output |
| -E2000H | Encoder, A quad B with marker, 5 VDC, 2000 line, line-driver output (only option for BM22) |
| -E2500H | Encoder, A quad B with marker, 5 VDC, 2500 line, line-driver output |
| -E5000H | Encoder, A quad B with marker, 5 VDC, 5000 line, line-driver output |
| -E1000ASH | Encoder, amplified sine, 5 VDC, 1000 line with integral hall sensors |

### Options (Brushless Rotary Motors)

| | |
|---|---|
| -BK1 | Brake; holding torque = 0.8 N-m (112 oz-in), 24 VDC, 0.3 A for BM75, BM130, and BM200 |
| -BK2 | Brake; holding torque = 1.7 N-m (240 oz-in), 24 VDC, 0.4 A for BM250, BM500 |
| -BK3 | Brake; holding torque = 5.6 N-m (800 oz-in), 24 VDC, 0.7 A for BM800, BM1400 |
| -BK5 | Brake; holding torque = 40.7 N-m (360 lb-in), 24 VDC, 0.7 A for BM2000, BM3400, BM4500 |
| -NS | IP65 rated Nitrile front shaft seal (not available for BM75, BM130, BM200) |
| -VAC6 | Vacuum prep for up to $10^{-6}$ torr |

Example: Motor with 2000 line encoder and Nitrile shaft seal: BM250-MS-E2000H-NS

### Accessories

| | |
|---|---|
| MCM1-3 | Connector, MS motor power mate (BM2000, BM3400, BM4500) |
| MCM-3 | Connector, MS motor power mate (BM75, BM130, BM200, BM250, BM500, BM800, BM1400) |
| MCF-3 | Connector, MS motor feedback mate for all BM motors |



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