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Find the *Ametek / Haydon Kerk 35F4N-05-040* at our website: ***Click HERE***

35000 Series
Size 14 Hybrid Linear Actuators

Higher force, longer life and improved performance

The various patented designs deliver exceptional performance and new linear motion design opportunities.

3 Available Designs

– Captive
– Non-Captive
– External Linear

The 35000 Series is available in a wide variety of resolutions - from 0.00012-in (.003048 mm) per step to 0.00192-in (.048768 mm) per step. The motors can also be microstepped for even finer resolutions.

The Size 14 actuator delivers thrust of -up to 50 lbs. (222 N).



Size 14
Captive Shaft

Size 14
External Linear

Size 14
Non-Captive Shaft

Size 14: 35 mm (1.1-in) Hybrid Linear Actuator (1.8° Step Angle)						
Part No.	Captive	35H4 – – – †			35H6 – – – †	
	Non-Captive	35F4 – – – †			35F4 – – – †	
	External Linear	E35H4 – – – †			E35H6 – – – †	
Wiring		Bipolar			Unipolar**	
Winding Voltage		2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase		1.25 A	0.57 A	0.24 A	0.57 A	0.24 A
Resistance/phase		1.86 Ω	8.8 Ω	50.5 Ω	8.8 Ω	50.5 Ω
Inductance/phase		2.8 mH	13 mH	60 mH	6.5 mH	30 mH
Power Consumption		5.7 W				
Rotor Inertia		16.0 gcm^2				
Insulation Class		Class B (Class F available)				
Weight		5.7 oz (162 g)				
Insulation Resistance		20 MΩ				

†Part numbering information on page 5. ** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Linear Travel / Step Screw Ø .218" (5.54 mm)		Order Code I.D.
inches	mm	
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q
.00192	.0487*	R

Linear Travel / Step Screw Ø .250" (6.35 mm)		Order Code I.D.
inches	mm	
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B
.00125	.0317*	C

*Values truncated.

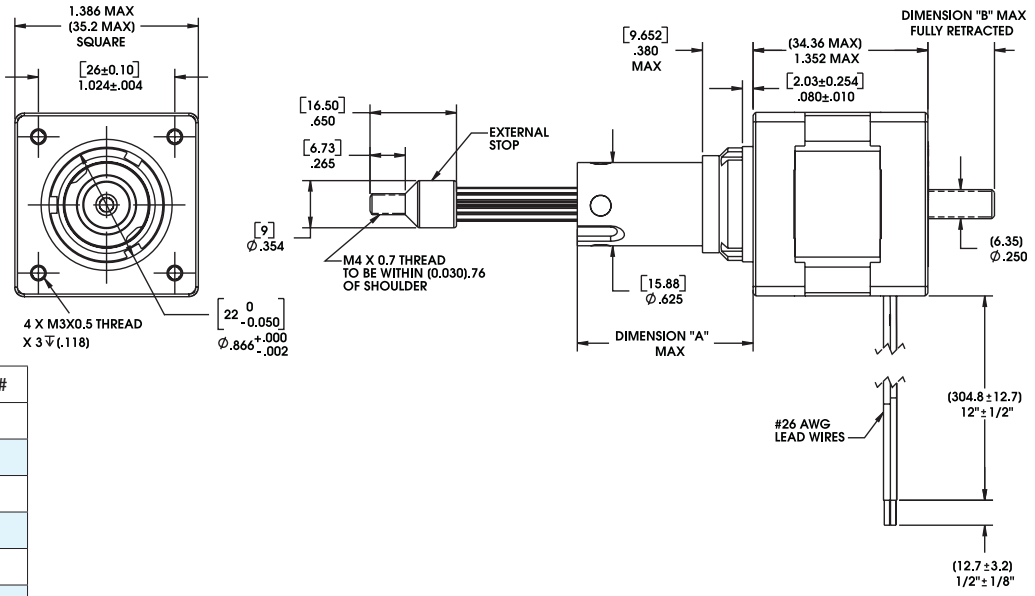
Standard motors are Class B rated for maximum temperature of 130°C.

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available



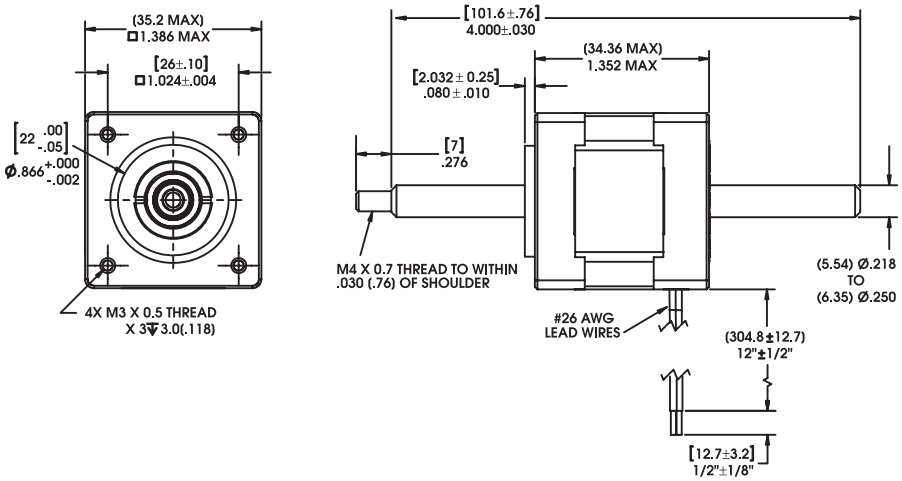
Stroke	Dim. "A"	Dim. "B"	Suffix #
0.500 (12.7)	0.82 (20.8)	0.04 (1.0)	–905
0.750 (19.05)	1.07 (27.2)	0.29 (7.4)	–907
1.000 (25.4)	1.32 (33.5)	0.54 (13.7)	–910
1.250 (31.8)	1.57 (39.9)	0.79 (20.1)	–912
1.500 (38.1)	1.82 (46.2)	1.04 (26.4)	–915
2.00 (50.8)	2.32 (58.9)	1.54 (39.1)	–920
2.500 (63.5)	2.82 (71.6)	2.04 (51.8)	–925

Non-Captive Lead Screw

Dimensions = (mm) inches

Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.

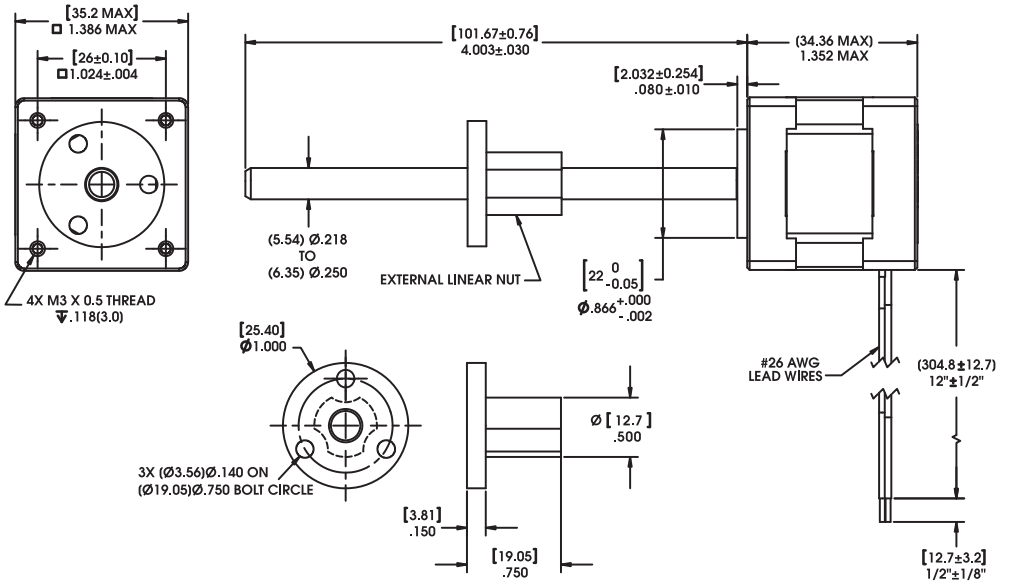


External Linear

Dimensions = (mm) inches

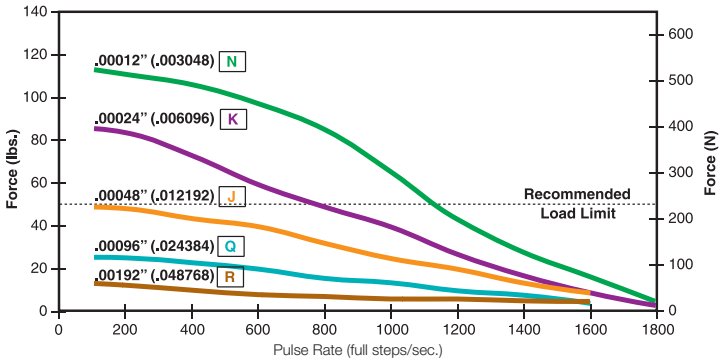
Integrated connector option available

4-in [101.6 mm]
standard screw lengths.
Longer screw lengths are available.

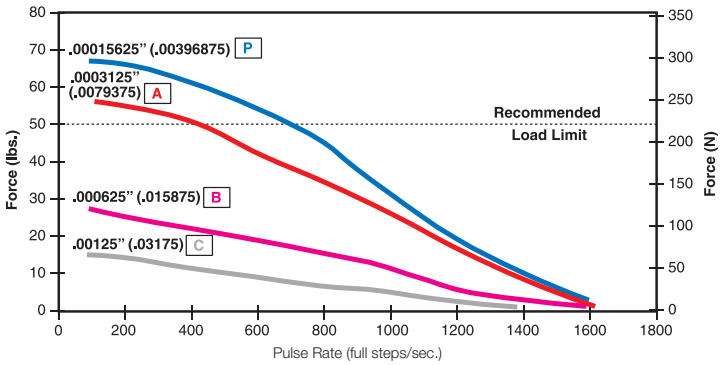


FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle

– Ø .218 (5.54) Lead Screw

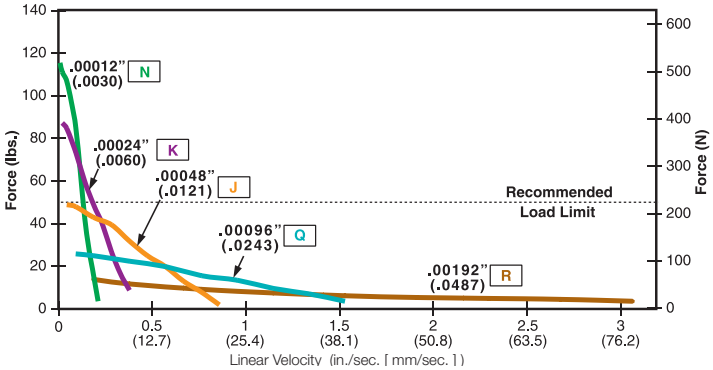


– Ø .250 (6.35) Lead Screw

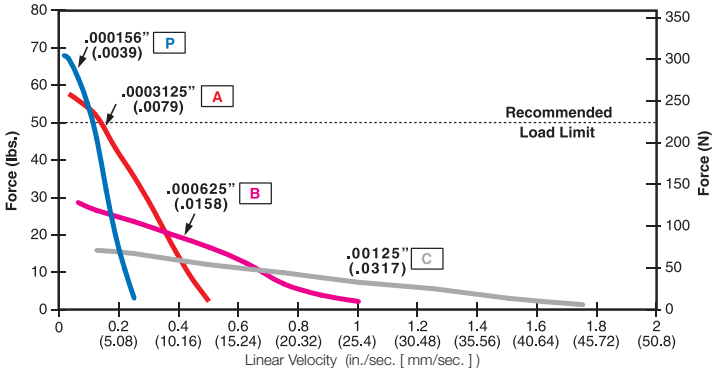


FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle

– Ø .218 (5.54) Lead Screw



– Ø .250 (6.35) Lead Screw



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

35000 Series
Size 14, 0.9° High Resolution Motor

Compared to the standard resolution (1.8°) this motor has been engineered to precisely deliver reliable high speed, force, up to 50 lbs (222 N), as well as a full step movement as low as 1.5 microns.

Size 14: 35 mm (1.1-in) Hybrid Linear Actuator (0.9° Step Angle)						
Part No.	Captive	35K4 □ – □ □ – □ □ □ †			35K6 □ – □ □ – □ □ □ †	
	Non-Captive	35J4 □ – □ □ – □ □ □ †			35J4 □ – □ □ – □ □ □ †	
	External Linear	E35K4 □ – □ □ – □ □ □ †			E35K6 □ – □ □ – □ □ □ †	
Wiring		Bipolar			Unipolar**	
Winding Voltage		2.33 VDC	5 VDC	12 VDC	5 VDC	12 VDC
Current (RMS)/phase		1.25 A	0.57 A	0.24 A	0.57 A	0.24 A
Resistance/phase		1.86 Ω	8.8 Ω	50.5 Ω	8.8 Ω	50.5 Ω
Inductance/phase		2.8 mH	13 mH	60 mH	6.5 mH	30 mH
Power Consumption		5.7 W				
Rotor Inertia		16.0 gcm^2				
Insulation Class		Class B (Class F available)				
Weight		5.7 oz (162 g)				
Insulation Resistance		20 MΩ				

** Unipolar drive gives approximately 30% less thrust than bipolar drive.

Linear Travel / Step Screw Ø .218" (5.54 mm)		Order Code I.D.
inches	mm	
.00006	.0015*	U
.00012	.0030*	N
.00024	.0060*	K
.00048	.0121*	J
.00096	.0243*	Q

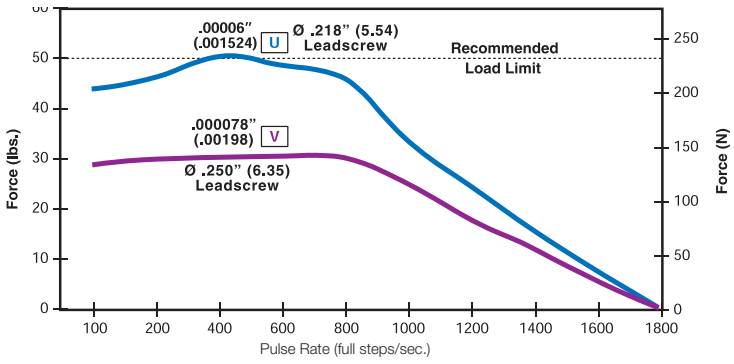
Linear Travel / Step Screw Ø .250" (6.35 mm)		Order Code I.D.
inches	mm	
.000078*	.00198*	V
.00015625	.0039*	P
.0003125	.0079*	A
.000625	.0158*	B

*Values truncated.

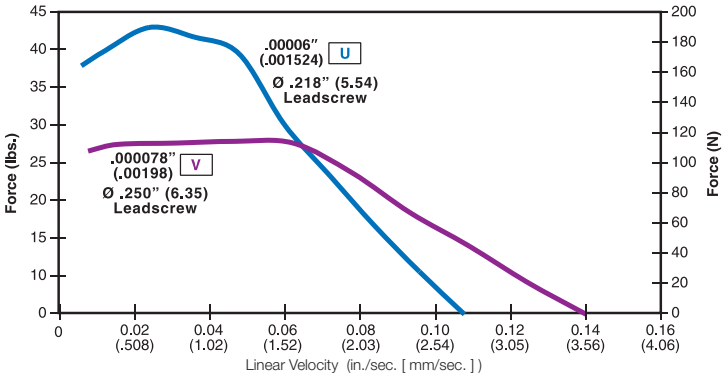
Standard motors are Class B rated for maximum temperature of 130°C.
NOTE: Refer to performance curves on page 3 for codes N, K, J, Q, P, A, B

Special drive considerations may be necessary when leaving shaft fully extended or fully retracted.

FORCE vs. PULSE RATE – Chopper – Bipolar – 100% Duty Cycle
with two available lead screw diameters



FORCE vs. LINEAR VELOCITY – Chopper – Bipolar – 100% Duty Cycle
with two available lead screw diameters



NOTE: All chopper drive curves were created with a 5 volt motor and a 40 volt power supply.

Ramping can increase the performance of a motor either by increasing the top speed or getting a heavier load accelerated up to speed faster. Also, deceleration can be used to stop the motor without overshoot.

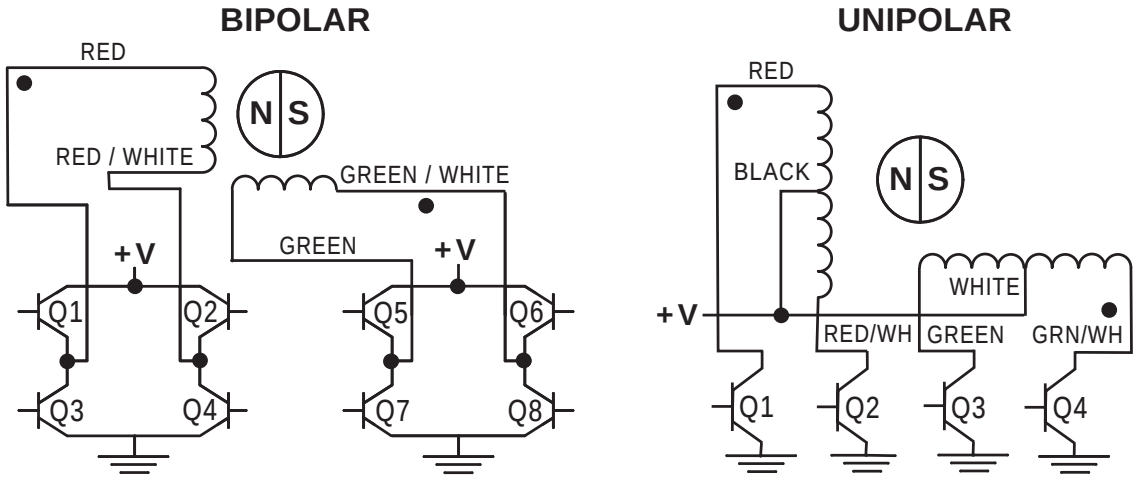
With L/R drives peak force and speeds are reduced, using a unipolar drive will yield a further 30% force reduction.

Identifying the Hybrid Part Number Codes when Ordering

E	35	H	4	7	—	2.33	—	910
Prefix (include only when using the following) **A =** A Coil (See AC Synchronous Data Sheet) **E** = External **K** = External with 40° thread form **P** = Proximity Sensor **S** = Home Position Switch	**Series Number Designation** **35 = 35000** (Series numbers represent approximate width of motor body)	**Style** **F** = 1.8° Non-captive **H** = 1.8° Captive or External (use "E" or "K" Prefix for External version) **J** = 0.9° Non-captive **K** = 0.9° Captive or External (use "E" or "K" Prefix for External version)	**Coils** **4** = Bipolar (4 wire) **6** = Unipolar (6 wire)	**Code ID Resolution Travel/Step** **N** = .00012-in (.0030) **K** = .00024-in (.0060) **J** = .00048-in (.0121) **Q** = .00096-in (.0243) **P** = .00015625-in (.0039) **A** = .0003125-in (.0079) **B** = .000625-in (.0158) **C** = .00125-in (.0317) **R** = .00192-in (.0478) **High Resolution** **U** = .00006-in (.0015) **V** = .000078-in (.00198)		**Voltage** **2.33** = 2.33 VDC **05** = 5 VDC **12** = 12 VDC Custom V available		**Suffix** **Stroke** Example: –910 = 1-in (Refer to Stroke chart on Captive motor series product page.) **Suffix also represents**: –800 = Metric –900 = External Linear with grease and flanged nut –XXX = Proprietary suffix assigned to a specific customer application. The identifier can apply to either a standard or custom part.

NOTE: Dashes must be included in Part Number (–) as shown above. For assistance call our Engineering Team at 203 756 7441.

Hybrids: **Wiring**



Hybrids: **Stepping Sequence**

Bipolar	Q2-Q3	Q1-Q4	Q6-Q7	Q5-Q8
Step				
1	ON	OFF	ON	OFF
2	OFF	ON	ON	OFF
3	OFF	ON	OFF	ON
4	ON	OFF	OFF	ON
1	ON	OFF	ON	OFF

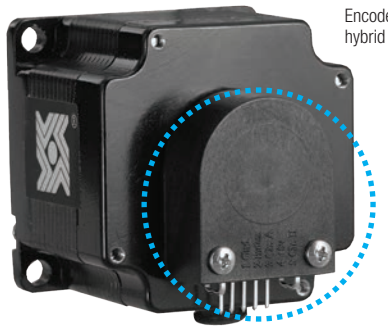
EXTEND CW ↓ ↑ RETRACT CCW

Note: Half stepping is accomplished by inserting an off state between transitioning phases.

Encoders Designed for All Sizes of Hybrid Linear Actuators

All Haydon Hybrid Linear Actuators are available with specifically designed encoders for applications that require feedback. The compact optical incremental encoder design is available with two channel quadrature TTL squarewave outputs. An optional index is also available as a 3rd channel. The Size 14 Encoder provides resolutions for applications that require 200, 400 and 1,000 counts per revolution. Encoders are available for all motor configurations.

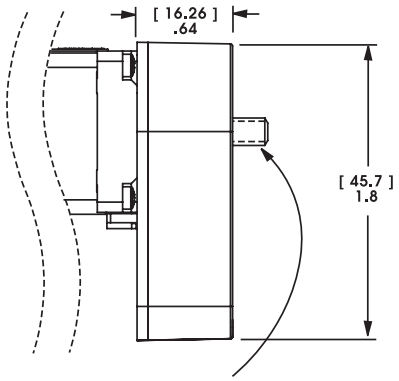
Simplicity and low cost make the encoders ideal for both high and low volume motion control applications. The internal monolithic electronic module converts the real-time shaft angle, speed, and direction into TTL compatible outputs. The encoder module incorporates a lensed LED light source and monolithic photodetector array with signal shaping electronics to produce the two channel bounceless TTL outputs.



Encoder on Size 23 hybrid motor

30 mm 35000 Series Size 14

NOTE: Lead Screw extends beyond encoder on specific captive and non-captive motors. External linear shaft extension is available upon request.



Electrical Specifications				
	Minimum	Typical	Maximum	Units
Input Voltage	4.5	5.0	5.5	VDC
Output Signals	4.5	5.0	5.5	VDC

2 channel quadrature TTL squarewave outputs.
Channel B leads A for a clockwise rotation of the rotor viewed from the encoder cover.
Tracks at speeds of 0 to 100,000 cycles/sec.
Optional index available as a 3rd channel (one pulse per revolution).

Operating Temperature		
	Minimum	Maximum
Size 14	- 40°C (- 40°F)	100°C (212°F)

Differential Ended Encoder - Pinout - Size 14	
Connector Pin #	Description
1	Ground
2	Ground
3	– Index
4	+ Index
5	Channel A –
6	Channel A +
7	+5 VDC Power
8	+5 VDC Power
9	Channel B –
10	Channel B +

Mechanical Specifications	
	Maximum
Acceleration	250,000 rad/sec2
Vibration (5 Hz to 2 kHz)	20 g

Resolution				
4 Standard Cycles Per Revolution (CPR) or Pulses Per Revolution (PPR)				
Size 14	CPR	200	400	1000*
	PPR	800	1600	4000*

*Index Pulse Channel not available.

Single Ended Encoder - Pinout - Size 14			
Connector Pin #	Description	Connector Pin #	Description
1	Ground	4	+5 VDC Power
2	Index (optional)	5	Channel B
3	Channel A		

Integrated Connector for Hybrid Size 14

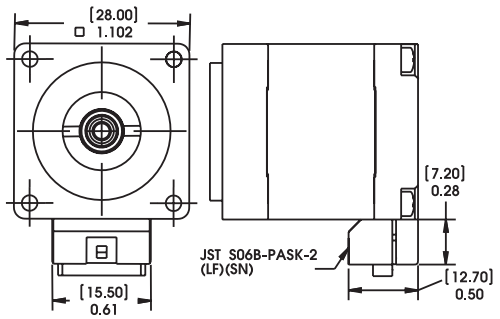
Offered alone or with a harness assembly, this connector is RoHS compliant and features a positive latch in order for high connection integrity. The connector is rated up to 3 amps and the mating connector will handle a range of wire gauges from 22 to 28. Ideal for those that want to plug in directly to pre-existing harnesses.

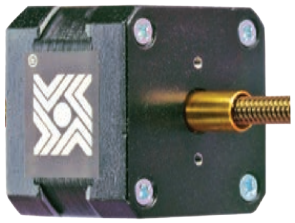
Motor Connector:
JST part # S06B-PASK-2

Mating Connector:
JST part # PAP-06V-S
Haydon Kerk Part #56-1210-5 (12 in. Leads)

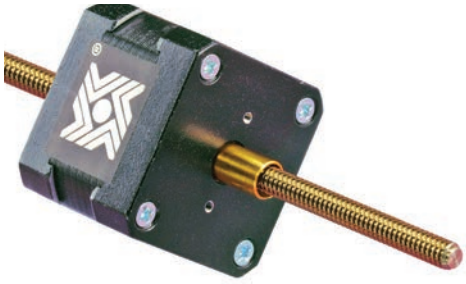
Wire to Board Connector:
JST part number SPHD-001T-P0.5

Pin #	Bipolar	Unipolar	Color
1	Phase 2 Start	Phase 2 Start	G/W
2	Open	Phase 2 Common	–
3	Phase 2 Finish	Phase 2 Finish	Green
4	Phase 1 Finish	Phase 1 Finish	R/W
5	Open	Phase 1 Common	–
6	Phase 1 Start	Phase 1 Start	Red

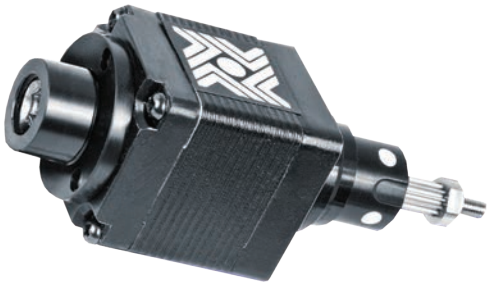




Encoder Ready Option Shown 34000 Series Size 17



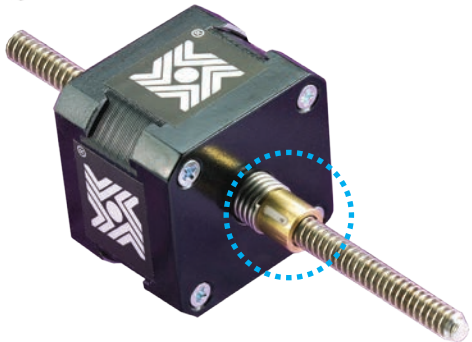
Extended Rotor Journal Shown 34000 Series Size 17



End of Stroke Proximity Sensor



TFE Coated Lead Screw



Integrated Anti-Backlash Nut

Encoder Ready Option for all Hybrid Sizes

Our Hybrid Linear Actuators can now be manufactured as an Encoder Ready Actuator. Encoder Ready Actuators can be used to install several popular hollow shaft encoders. Available with an extended rotor journal and a threaded rear housing. The motor uses a proprietary manufacturing process which incorporates engineering thermoplastics in the rotor drive nut and a stainless steel Acme Lead Screw that allows the motor to be much more efficient and durable than today's more commonly used V-thread bronze nut configurations.

Extended Rotor Journal for all Hybrid Sizes

Available with an extended rotor journal. The extended rotor journal can be used for encoder installation, manual adjustment, or flag installation for a positioning sensor.

Home Position Switch for Hybrids

A miniature electronic Home Position Switch capable of monitoring the home positions of linear actuators. The switch mounts on the rear sleeve of captive linear motors and allows the user to identify start, stop or home positions.

When ordering motors with the home position switch the part number should be preceded by an "S" prefix.

End of Stroke Proximity Sensor for all Hybrid Sized

The Sensor incorporates a hall effect device, which is activated by a rare earth magnet embedded in the end of the internal screw. The compact profile of the sensor allows for installation in limited space applications. The sensor has a virtually unlimited cycle life. Special cabling and connectors can also be provided.

When ordering motors with the proximity sensor, the part number should be preceded by a "P" prefix.

Black Ice® and Kerkote® TFE Coated Lead Screws*

TFE Coated Lead Screws for applications that require a *greaseless* screw and nut interface.

A *dry* (non-lubricated) TFE coated lead screw provides improved performance in both life and thrust as compared to a conventional stainless steel lead-screw. TFE can be applied to a wide variety of lead-screw pitches and is available for our brand captive, non-captive and external linear actuators. Not available for 0.00006-in (.0015 mm) and 0.000098-in (.0025 mm) resolutions.

*Certain conditions apply.

Integrated Anti-Backlash Nut for Hybrids*

Most sizes (except Size 34) of our captive and non-captive hybrid stepper motors can be equipped with an integral anti-backlash feature. There is a normal backlash between the lead screw and integral rotor nut.

Our actuators are designed for millions of cycles. However over time, additional backlash could increase and eventually double. Haydon Kerk Integrated Anti-Backlash Nut can eliminate all backlash. Designed specifically for our captive and non-captive hybrid motors, nuts use an opposing spring force to eliminate backlash between the screw and the nut interface. The nuts will self-compensate and accommodate any wear. Haydon Kerk Motion Solutions application engineers can help you select the appropriate preload for your application

*Except Size 34.

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