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Stopper cylinders STA/STAF

FESTO



Stopper cylinders STA/STAF

Key features

At a glance

- Single-acting or double-acting
- Versions
  - Trunnion
  - Roller
  - Toggle lever
- Direct mounting of solenoid valves on flange plate
- Fast and simple set-up of conveyor lines
- Workpiece carriers, pallets and packages weighing up to 150 kg can be safely stopped
- Gentle stopping without impact vibrations or noise with toggle lever version
- Simple actuation via valve terminal (e.g. in combination with other cylinders at an assembly station)
- Flanged solenoid valve permits fast actuation even over long distances and with individual stopper cylinders
- Space-saving sensing via integrated proximity sensors

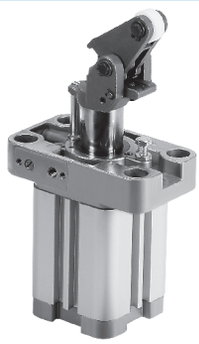
Trunnion version



Roller version

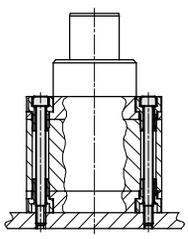


Toggle lever version

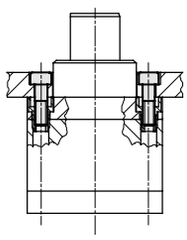


Mounting options

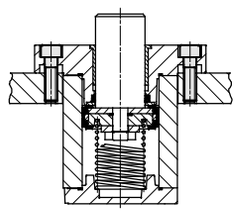
Through-hole mounting



Direct mounting

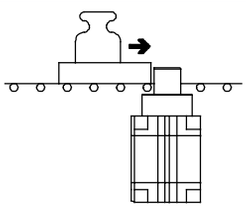


Flange mounting

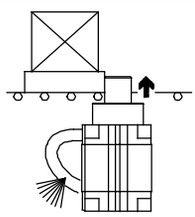


Application options and versions

For heavy masses



Safety



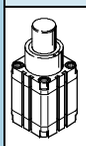
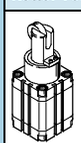
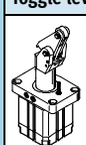
By means of spring return of the piston rod in the event of pressure failure.

Highly effective, low noise level

Toggle lever version with integrated shock absorber facilitates precise and gentle stopping of the workpiece carrier.

Stopper cylinders STA/STAF

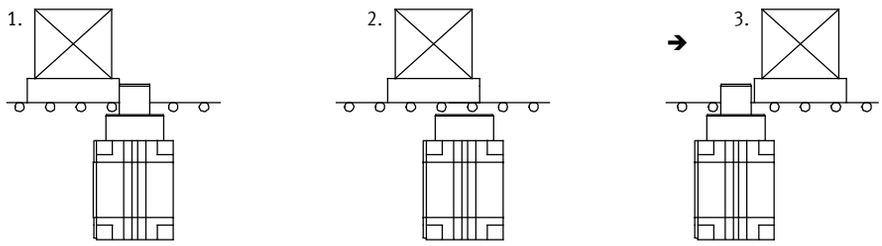
Product range overview

Function	Version	Type	Piston ∅ [mm]	Stroke [mm]	Type of mounting		Cushioning P	Position sensing A	➔ Page/Internet
					direct	via flange			
Single- or double-acting	**Trunnion version**								
		STA-...-P-A STAF-...-P-A	20	15	■	–	■	■	4
			32	20	■	■	■	■	
			50	30	■	■	■	■	
	Roller version								
		STA-...-P-A-R STAF-...-P-A-R	20	15	■	–	■	■	10
			32	20	■	■	■	■	
			50	30	■	■	■	■	
			80	30, 40	–	■	■	■	
	Toggle lever version								
		STAF-...-P-A-K	32	20	–	■	■	■	20

Stopper cylinders STA/STAF, trunnion

Functional sequence and type codes

Functional sequence



1. Sudden braking of the workpiece carrier via the piston rod.
2. The workpiece carrier is released by activating the cylinder.
   The control system must hold the piston down until the workpiece carrier has passed the stopper cylinder.
3. The piston rod then advances by means of spring force or compressed air. The next workpiece carrier can then be stopped.

Type codes

STA	–	20	–	15	–	P	–	A	

Type

Single-acting or double-acting	
STA	Stopper cylinder
STAF	Stopper cylinder with flange mounting

Piston ∅ [mm]

Stroke [mm]

Cushioning

P	Flexible cushioning rings/pads at both ends

Position sensing

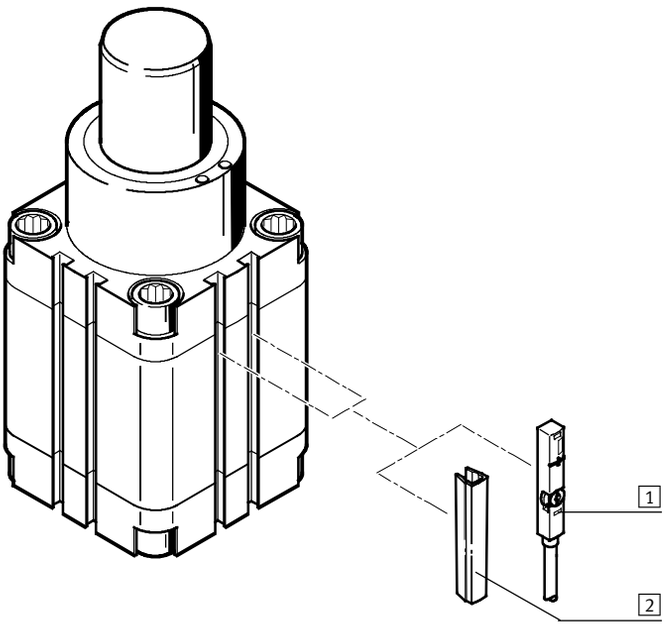
A	Via proximity sensor

Version

	Trunnion version

Stopper cylinders STA/STAF, trunnion

Peripherals overview



Accessories		
	Brief description	**➔ Page/Internet**
1 Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	28
2 Slot cover ABP	For protecting against ingress of dirt	28

Stopper cylinders STA/STAF, trunnion

Technical data

FESTO

Function



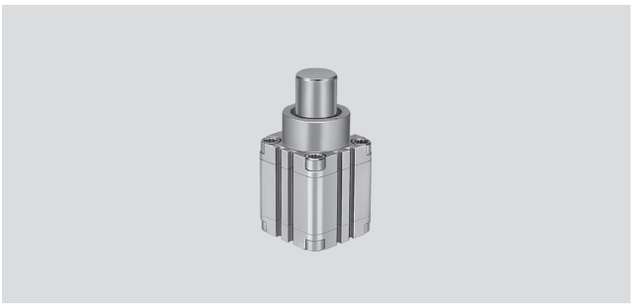
Diameter
20 ... 50 mm

Stroke length
15 ... 30 mm

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Note

Contact with liquids must be avoided during use.



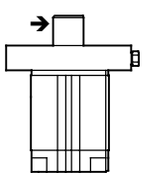
General technical data				
Piston ∅		20	32	50
Pneumatic connection	STA	M5	G1/8	G1/8
	STAF	–	M5	G1/8
Stroke	[mm]	15	20	30
Piston rod ∅	[mm]	12	20	32
Operating pressure	[bar]	10		
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:–:–]		
Constructional design		Piston cylinder with spring return		
Cushioning		Flexible cushioning rings/pads at both ends		
Position sensing		Via proximity sensor		
Type of mounting		Via through-holes		
		Via female thread		
Mounting position		Any		
Mode of operation		Single-acting or double-acting		
Protection against rotation		None		
Ambient temperature[1)]	[°C]	0 ... +60		

1) Note operating range of proximity sensors.

Note: This product conforms to ISO 1179-1 and to ISO 228-1

Forces [N]			
Piston ∅	20	32	50
Permissible impact force on the advanced piston rod	260	1,000	2,900
Spring force	13 ... 18	20 ... 42	43 ... 60

Under "impact force" we understand the maximum of a force-time curve during impact/braking of the moveable mass. It is effective vertical to the movement axis of the piston rod. If one regards the elastic components as linear springs, the permitted impact energy can be calculated from the permitted impact force. This serves for selecting the correct stopper.
The stopper must not switch under this force. Depending on the mass to be stopped, it may be advisable to provide an elastic buffer in order to cushion the impact, to reduce noise and to optimize the impact energy.



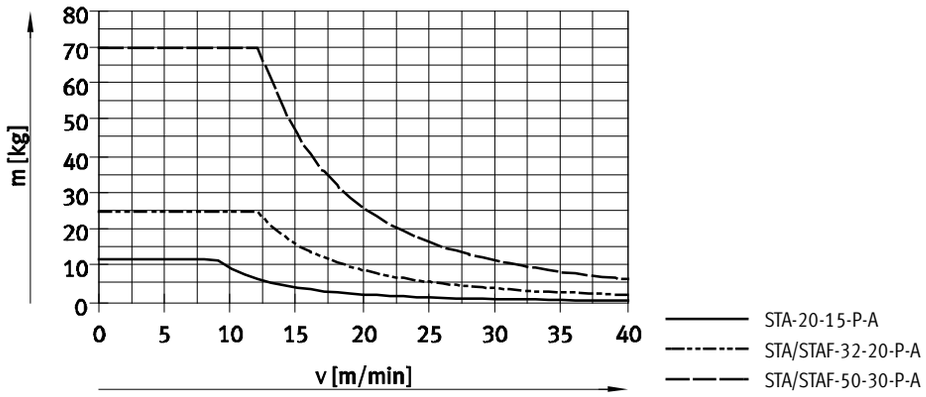
➔ = Direction of impact force

Stopper cylinders STA/STAF, trunnion

Technical data

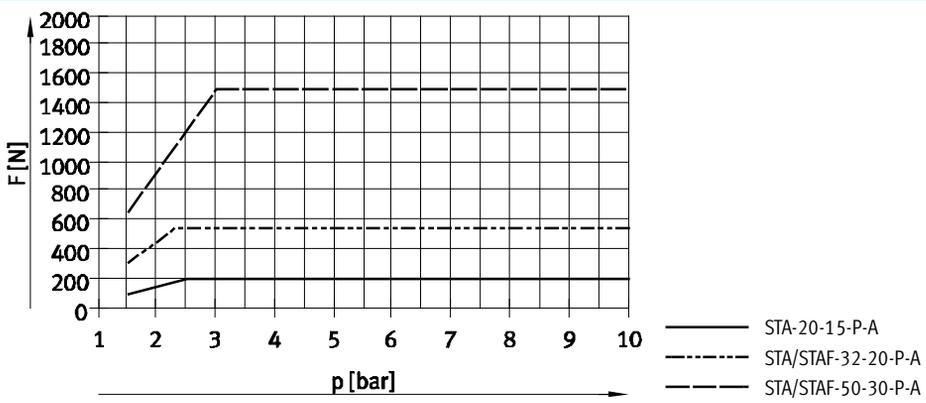
Permissible mass m as a function of the conveyor speed v

The values in the graph opposite are based on the assumption that the workpiece carrier is fitted with a flexible buffer with a deformation path of 1 mm.



Permissible transverse force F_Q during the switching operation as a function of the pressure p

Under "permitted lateral force" during the switching procedure, we understand the force which still exists vertical to the direction of movement of the piston rod after the impact or braking procedure, e.g. by bands still running or the slope power take-off force of an inclined rolling surface. The force is effective statically. The stopper must not switch under this force. In order that the functioning of the cylinder can be guaranteed, a certain minimum pressure must be applied.

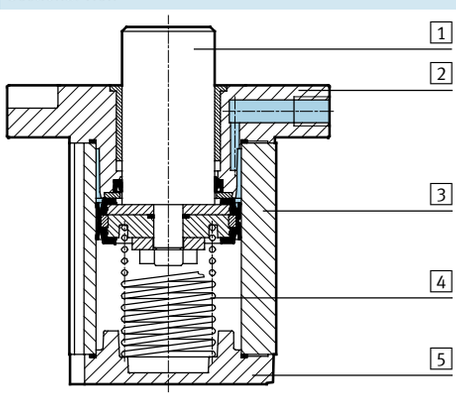


- Note

Selection aid ➔ 16

Materials

Sectional view



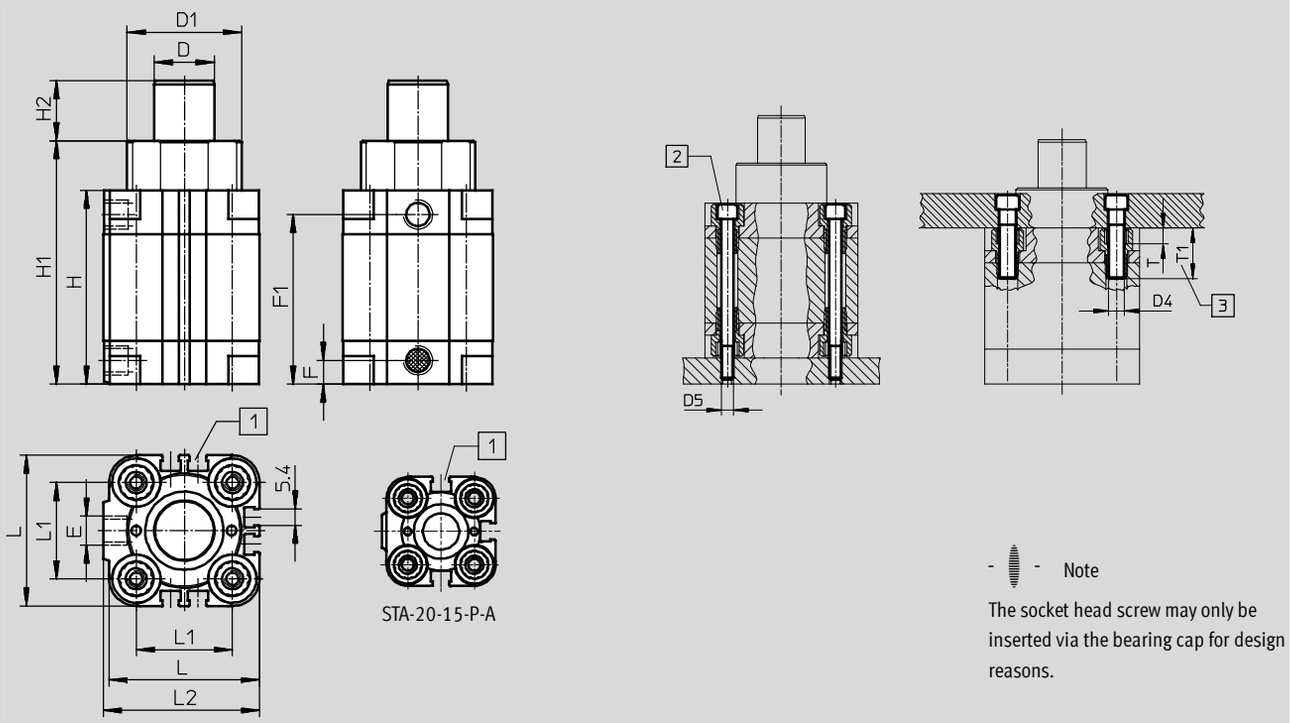
Stopper cylinder		
1	Piston rod	Stainless steel
2	Flange	Die-cast aluminium
3	Cylinder barrel	Anodised aluminium
4	Springs	Spring steel
5	End cap	Anodised aluminium
–	Seals	Polyurethane
–	Note on materials	Free of copper, PTFE and silicone

Stopper cylinders STA/STAF, trunnion

Technical data

Dimensions Download CAD data ➔ **www.festo.com**

Direct mounting



Note

The socket head screw may only be inserted via the bearing cap for design reasons.

1 Slot for proximity sensor SME/SMT-8

2 Socket head screw to DIN 912, screwed through

3 Recommended minimum screw-in depth

∅ [mm]	Stroke [mm]	D ∅	D1 ∅	D4	D5	E	F	F1	H	H1	H2	L	L1	L2	T	T1
20	15	12	26	M5	M4	M5	8	45	53	64.5	15	36	22	37.5	4	18
32	20	20	38	M6	M5	G1⁄8	8	56.5	64.5	80.5	20	50	32	52	5	20
50	30	32	53	M8	M6	G1⁄8	8	67.5	75.5	99.5	30	68	50	71	6	20

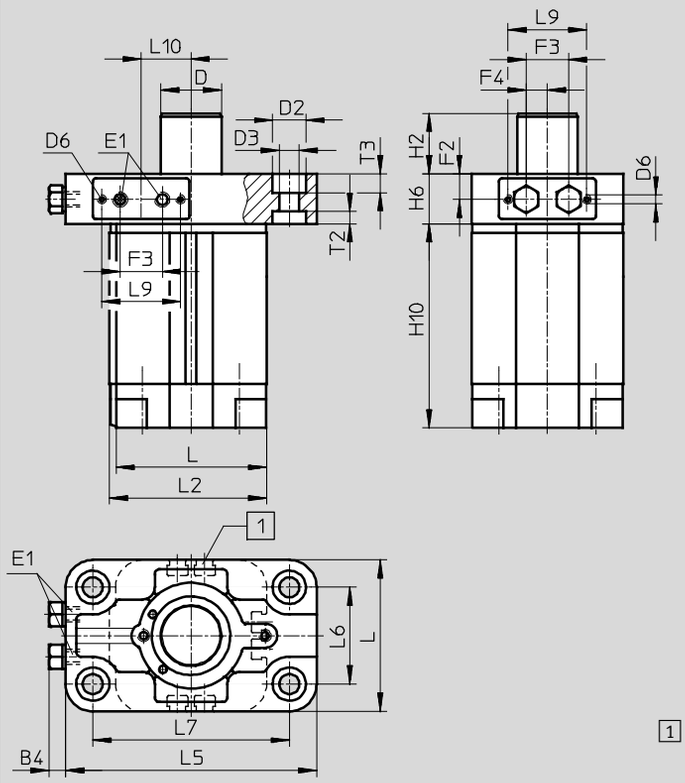
Note: This product conforms to ISO 1179-1 and to ISO 228-1

Stopper cylinders STA/STAF, trunnion

Technical data

Dimensions Download CAD data ➔ **www.festo.com**

Flange mounting



1 Slot for proximity sensor SME/SMT-8

∅ [mm]	Stroke [mm]	B4	D ∅	D2 ∅	D3 ∅	D6	E1	F2	F3	F4	H2
32	20	4.5	20	11	6.6	M3	M5	8.5	14	7	20
50	30	4.5	32	15	9	M4	G⅛	9	17	8	30

∅ [mm]	Stroke [mm]	H6	H10	L	L2	L5	L6	L7	L9	L10	T2	T2
32	20	16.5	67.5	50	52	83	32	65	26	16.5	4	6.2
50	30	18	85	68	71	111	45	90	36	7	5	5

Note: This product conforms to ISO 1179-1 and to ISO 228-1

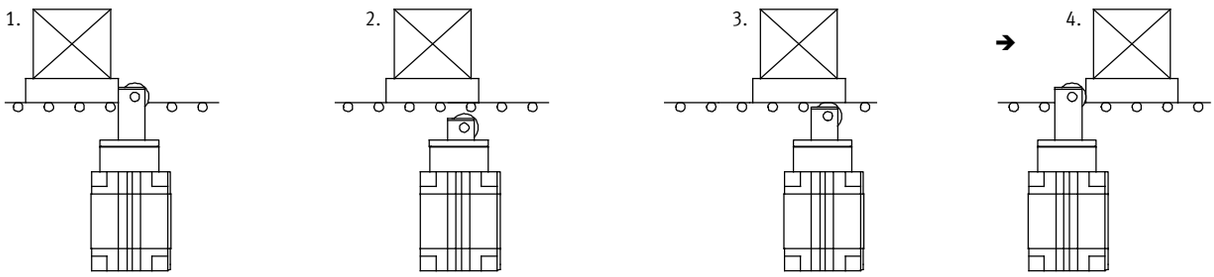
Ordering data

Piston ∅ [mm]	Stroke [mm]	Direct mounting Part No.	Type	Flange mounting Part No.	Type
20	15	**164 887**	**STA-20-15-P-A**	–	–
32	20	**164 888**	**STA-32-20-P-A**	**164 890**	**STAF-32-20-P-A**
50	30	**164 889**	**STA-50-30-P-A**	**164 891**	**STAF-50-30-P-A**

Stopper cylinders STA/STAF, roller

Functional sequence and type codes

Functional sequence



1. Sudden braking of the workpiece carrier via the piston rod.
2. The workpiece carrier is released by activating the cylinder.
3. The piston rod then advances by means of spring force or compressed air until the roller makes contact with the workpiece carrier. The workpiece carrier continues to move forward.
4. After the workpiece carrier has passed, the piston rod advances to the end position. The next workpiece carrier can then be stopped.

Type codes

STA – 20 – 15 – P – A – R

Type	
Single-acting or double-acting	
STA	Stopper cylinder
STAF	Stopper cylinder with flange mounting

Piston ∅ [mm]

Stroke [mm]

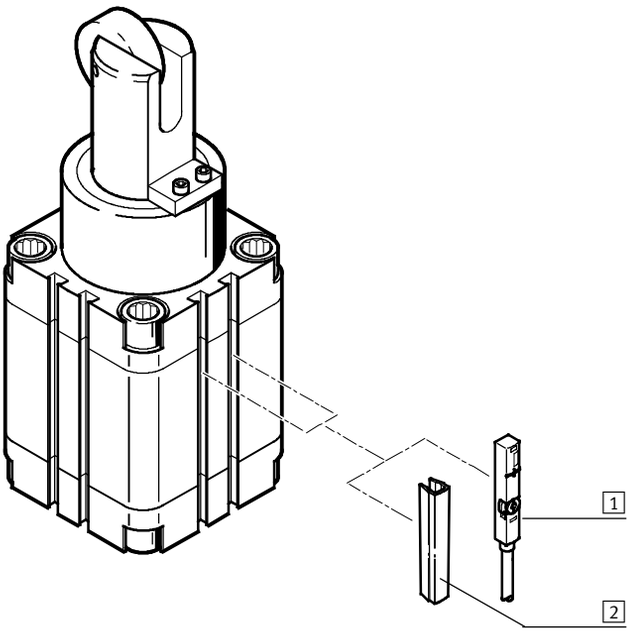
Cushioning	
P	Flexible cushioning rings/pads at both ends

Position sensing	
A	Via proximity sensor

Version	
R	Roller version

Stopper cylinders STA/STAF, roller

Peripherals overview



Accessories		
	Brief description	**➔ Page/Internet**
1 Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	28
2 Slot cover ABP	For protecting against ingress of dirt	28

Stopper cylinders STA/STAF, roller

Technical data

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Function



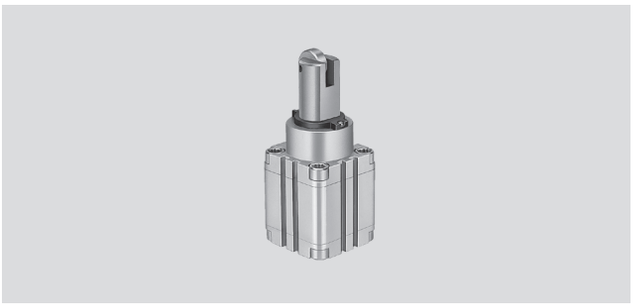
Diameter
20 ... 80 mm

Stroke length
15 ... 40 mm

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Note

Contact with liquids must be avoided during use.

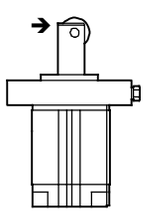


General technical data						
Piston ∅		20	32	50	80	
Pneumatic connection	STA	M5	G1⁄8	G1⁄8	–	
	STAF	–	M5	G1⁄8	G1⁄8	
Stroke	[mm]	15	20	30	30/40	
Piston rod ∅	[mm]	12	20	32	50	
Operating pressure	[bar]	10				
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:–:–]				
Constructional design		Piston cylinder with spring return				
Cushioning		Flexible cushioning rings/pads at both ends				
Position sensing		Via proximity sensor				
Type of mounting		Via through-holes				
		Via female thread				
Mounting position		Any				
Mode of operation		Single-acting or double-acting				
Protection against rotation		Flat-sided piston rod				
Ambient temperature[1)]	[°C]	0 ... +60				

1) Note operating range of proximity sensors.
Note: This product conforms to ISO 1179-1 and to ISO 228-1

Forces [N]					
Piston ∅	20	32	50	80	
Stroke	15	20	30	30	40
Permissible impact force on the advanced piston rod	170	830	2,300	14,600	13,300
Spring force	13 ... 18	20 ... 42	43 ... 60	79 ... 115	101 ... 170

Under "impact force" we understand the maximum of a force-time curve during impact/braking of the moveable mass. It is effective vertical to the movement axis of the piston rod. If one regards the elastic components as linear springs, the permitted impact energy can be calculated from the permitted impact force. This serves for selecting the correct stopper.
The stopper must not switch under this force. Depending on the mass to be stopped, it may be advisable to provide an elastic buffer in order to cushion the impact, to reduce noise and to optimize the impact energy.



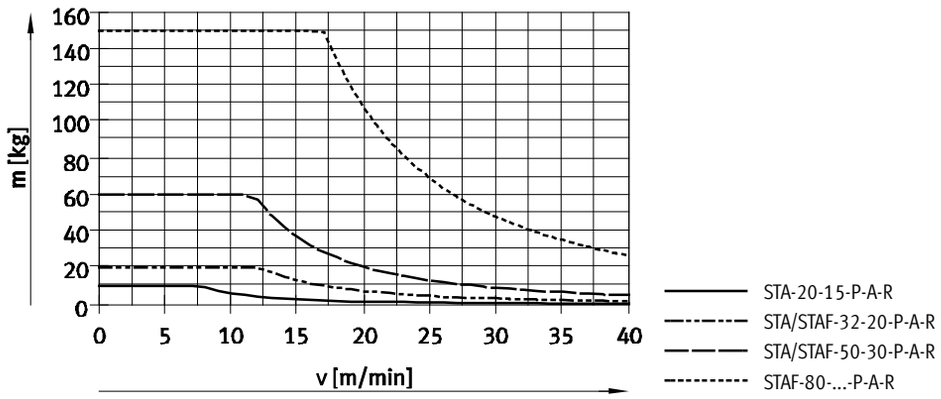
➔ = Direction of impact force

Stopper cylinders STA/STAF, roller

Technical data

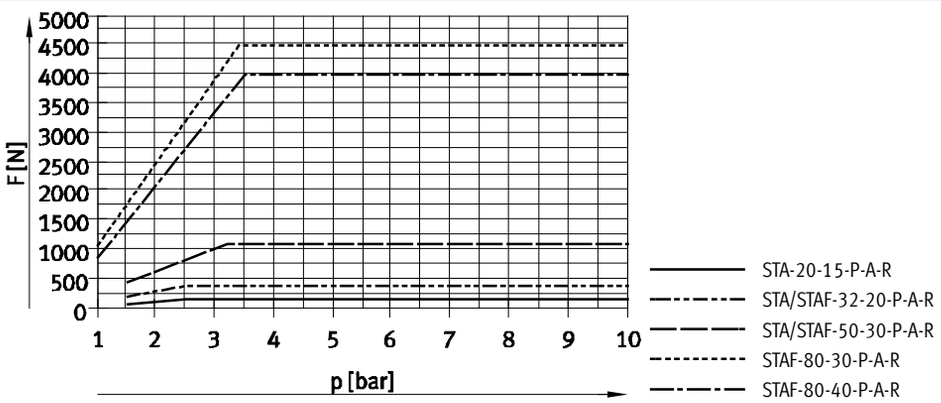
Permissible mass m as a function of the conveyor speed v

The values in the graph opposite are based on the assumption that the workpiece carrier is fitted with a flexible buffer with a deformation path of 1 mm.



Permissible transverse force F_Q during the switching operation as a function of the pressure p

Under "permitted lateral force" during the switching procedure, we understand the force which still exists vertical to the direction of movement of the piston rod after the impact or braking procedure, e.g. by bands still running or the slope power take-off force of an inclined rolling surface. The force is effective statically. The stopper must not switch under this force. In order that the functioning of the cylinder can be guaranteed, a certain minimum pressure must be applied.

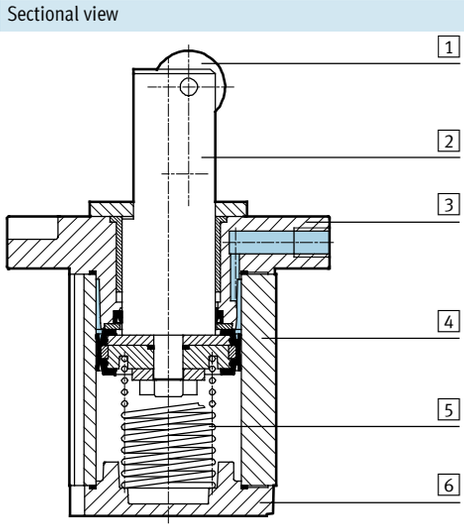


- Note

Selection aid ➔ 16

Materials

Sectional view



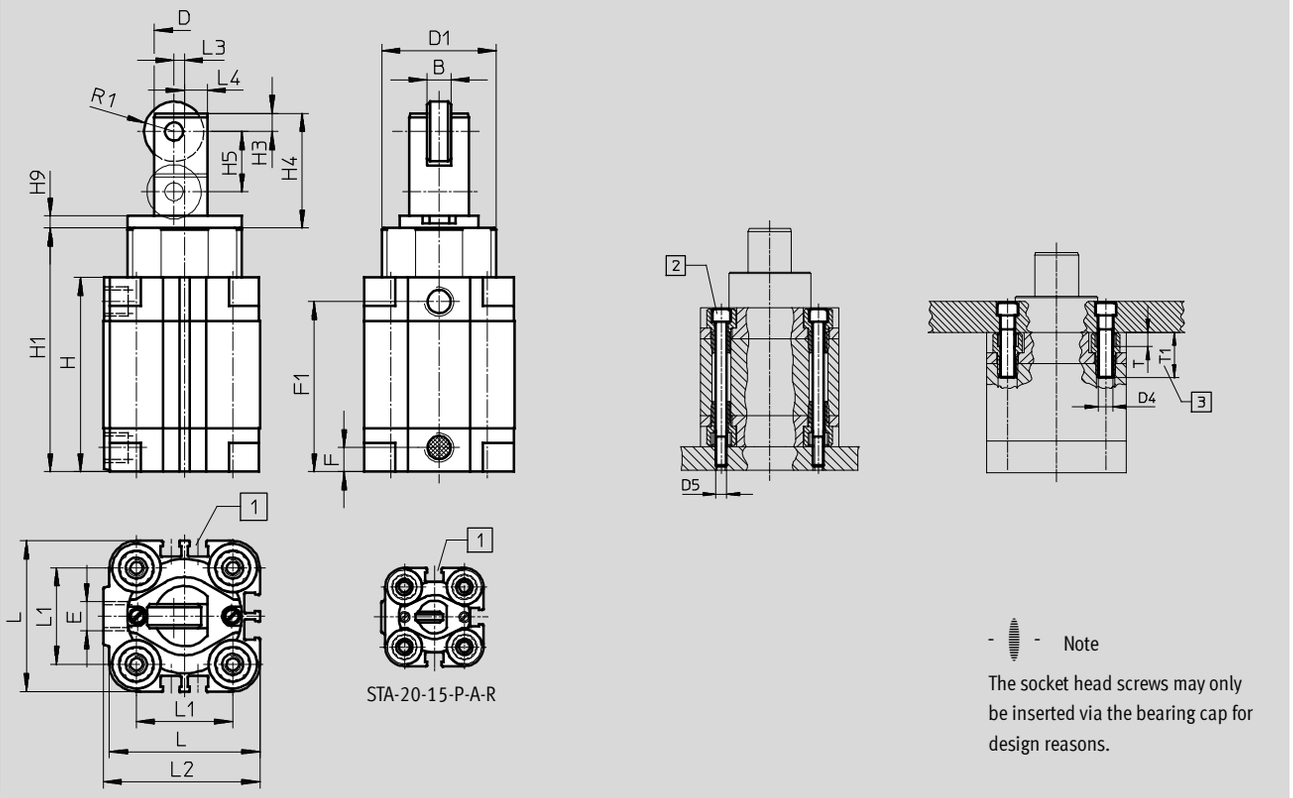
Stopper cylinder		
1	Roller	Steel
2	Piston rod	Stainless steel
3	Flange	Die-cast aluminium
4	Cylinder barrel	Anodised aluminium
5	Springs	Spring steel
6	End cap	Anodised aluminium
–	Seals	Polyurethane
–	Note on materials	Free of copper, PTFE and silicone

Stopper cylinders STA/STAF, roller

Technical data

Dimensions Download CAD data ➔ **www.festo.com**

Direct mounting



Note

The socket head screws may only be inserted via the bearing cap for design reasons.

1 Slot for proximity sensor SME/SMT-8

2 Socket head screw to DIN 912, screwed through

3 Recommended minimum screw-in depth

∅ [mm]	Stroke [mm]	B	D ∅	D1 ∅	D4	D5	E	F	F1	H	H1	H3
20	15	4	12	26	M5	M4	M5	8	45	53	64.5	3
32	20	8	20	38	M6	M5	G1⁄8	8	56.5	64.5	80.5	6
50	30	10	32	53	M8	M6	G1⁄8	8	67.5	75.5	99.5	6

∅ [mm]	Stroke [mm]	H4	H5	H9	L	L1	L2	L3	L4	R1	T	T1
20	15	24	15	4	36	22	37.5	2	4.5	5	4	18
32	20	38	20	4	50	32	52	3.5	7.5	9	5	20
50	30	50.5	30	5	68	50	71	7	12	12.5	6	20

Note: This product conforms to ISO 1179-1 and to ISO 228-1

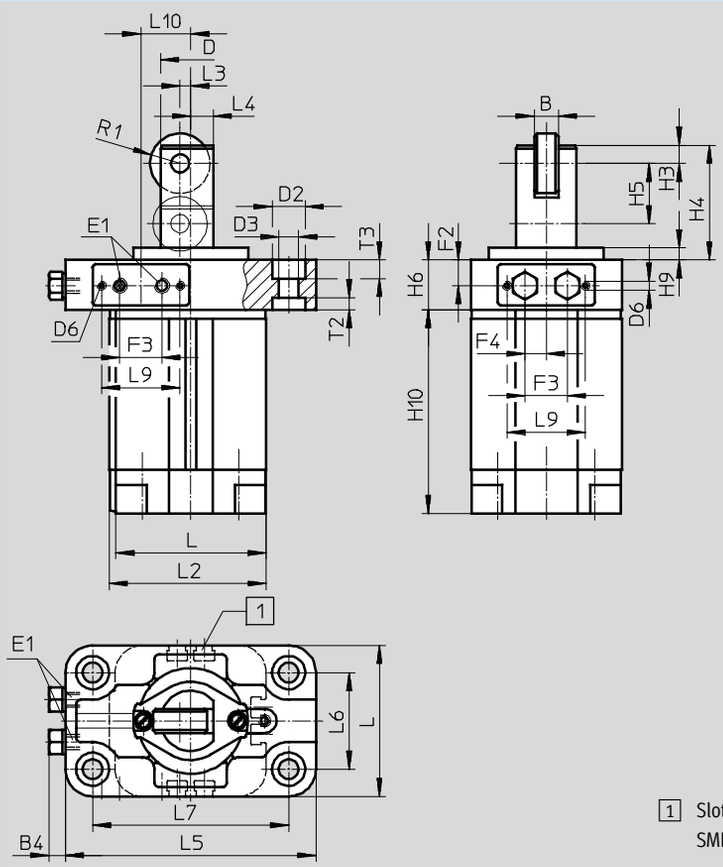
Stopper cylinders STA/STAF, roller

Technical data

FESTO

Dimensions Download CAD data ➔ **www.festo.com**

Flange mounting



1 Slot for proximity sensor SME/SMT-8

∅ [mm]	Stroke [mm]	B	B4	D ∅	D2 ∅	D3 ∅	D6	E1	F2	F3	F4	H3	H4	H5	H6
32	20	8	4.5	20	11	6.6	M3	M5	8.5	14	7	6	38	20	16.5
50	30	10	4.5	32	15	9	M4	G1⁄8	9	17	8	6	50.5	30	18
80	30	18	4.5	50	18	11	M4	G1⁄8	11	17	4.5	10	63	30	22
	40												73	40	

∅ [mm]	Stroke [mm]	H9	H10	L	L2	L3	L4	L5	L6	L7	L9	L10	R1	T2	T3
32	20	4	67.5	50	52	3.5	7.5	83	32	65	26	16.5	9	4	6.2
50	30	5	85	68	71	7	12	111	45	90	36	7	12.5	5	5
80	30	8	119	107	111	11	18	160	63	135	36	18.5	18	6	6
	40		129												

Note: This product conforms to ISO 1179-1 and to ISO 228-1

Ordering data

Piston ∅ [mm]	Stroke [mm]	Direct mounting Part No.	Type	Flange mounting Part No.	Type
20	15	**164 883**	**STA-20-15-P-A-R**	–	–
32	20	**164 884**	**STA-32-20-P-A-R**	**164 892**	**STAF-32-20-P-A-R**
50	30	**164 885**	**STA-50-30-P-A-R**	**164 893**	**STAF-50-30-P-A-R**
80	30	–	–	**164 886**	**STAF-80-30-P-A-R**
80	40	–	–	**164 894**	**STAF-80-40-P-A-R**

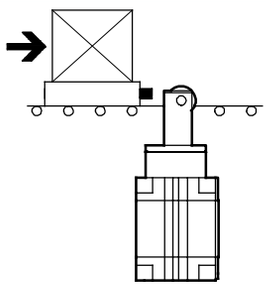
Stopper cylinders STA/STAF

Technical data

Selection aid

Stopping a workpiece carrier

The stopper cylinder is used to brake an individual workpiece carrier.



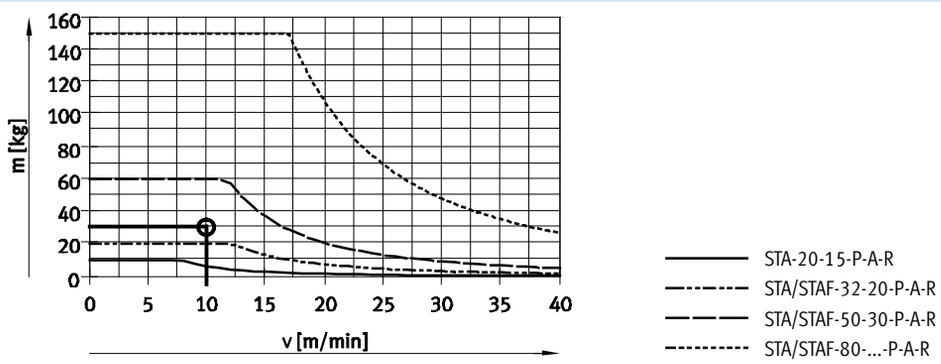
Example

Given:
Friction value μ = 0.1
Delivery speed v = 10 m/min
Workpiece carrier with workpiece m = 30 kg
Operating pressure p = 6 bar

Choice: Stopper cylinder STA...-50-...-R

1. Checking the permissible mass

The maximum permissible mass at a delivery speed of 10 m/min is 60 kg. This means that the total mass of the workpiece carrier and workpiece of 30 kg is permissible.

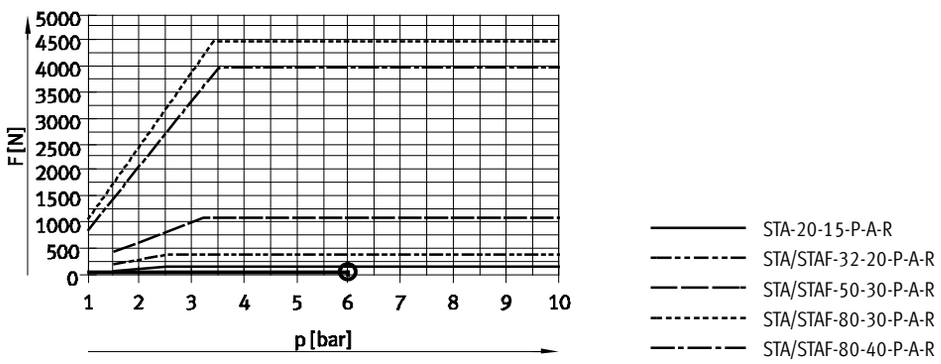


2. Checking the permissible transverse force during the switching operation

Transverse force F_Q = friction force $F_{Friction}$

$F_{Friction}$ = μ x m x g
= 0.1 x 30 kg x 9.81 m/s²
= approx. 30 N

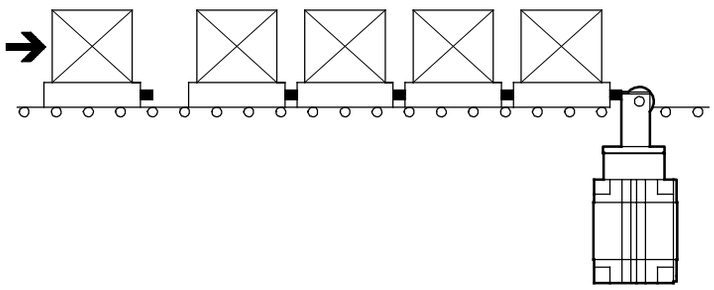
The maximum permissible transverse force at an operating pressure of 6 bar is 1,100 N.
This means that the transverse force of 30 N is permissible.



Selection aid

Stopping or separating several workpiece carriers

The stopper cylinder is used to separate workpiece carriers. Further workpiece carriers accumulate behind carriers already at the stopper cylinder. It is vital that a buffer is mounted between the workpiece carriers (e.g. elastomer elements).



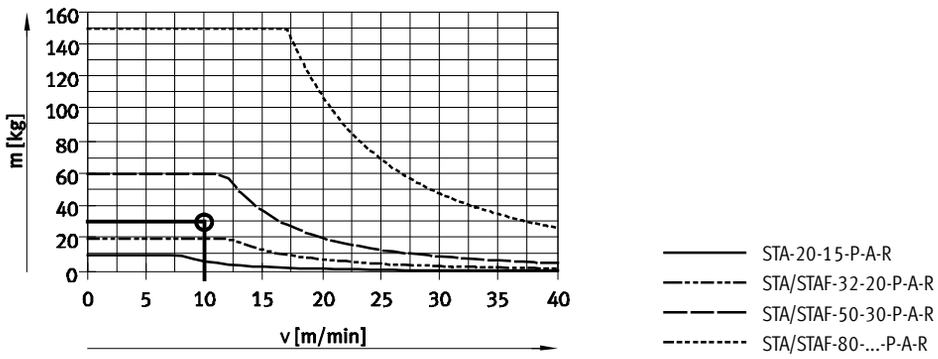
Example

Given:
Friction value $\mu = 0.1$
Delivery speed $v = 10$ m/min
Workpiece carrier with workpiece $m = 30$ kg
Operating pressure $p = 6$ bar
Maximum number of workpiece carriers accumulating simultaneously $n_{Group} = 1$
Maximum number of all queued workpiece carriers $n_{Queue} = 5$
Maximum number of all advancing workpiece carriers $n_{Queue-1} = 4$
Spring travel of the workpiece carrier buffer $s_F = 1$ mm

Choice: Stopper cylinder STA...-50-...-R

1. Checking the permissible mass of the first workpiece carrier

The maximum permissible mass at a delivery speed of 10 m/min is 60 kg. This means that the total mass of the workpiece carrier and workpiece of 30 kg is permissible.



2a. Calculation of the maximum permissible impact force when workpiece carriers accumulate behind a carrier at the stopper cylinder

With the STA...-50, the maximum permissible impact force is 2,300 N. This means that with a total force of 1,000 N, the number of workpiece carriers is permissible.

Impact force calculation:

$$F_{Impact} = \frac{(n_{Group} \times m) \times v^2}{s_F} = \frac{(1 \times 30kg) \times (10m/60s)^2}{0.001m} = ca.850N$$

Friction force:

$$F_{Friction} = \mu \times (n_{Queue} \times m) \times g = 0.1 \times (5 \times 30kg) \times 9.81m/s^2 = ca.150N$$

Max. total force:

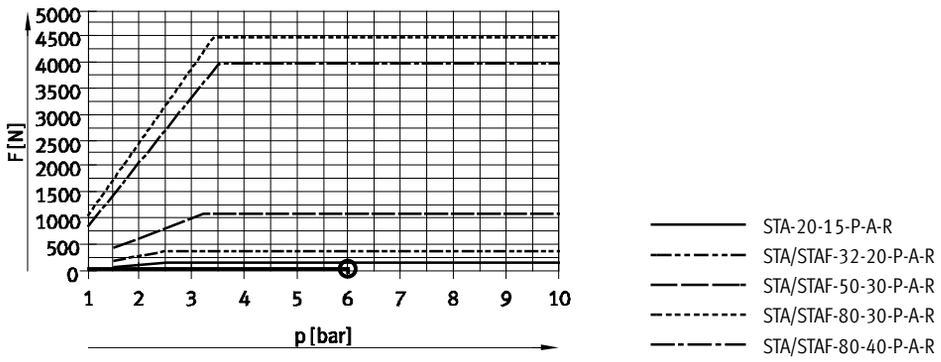
$$F_{Total\ force} = F_{Impact} + F_{Friction} = 850N + 150N = 1000N$$

Selection aid

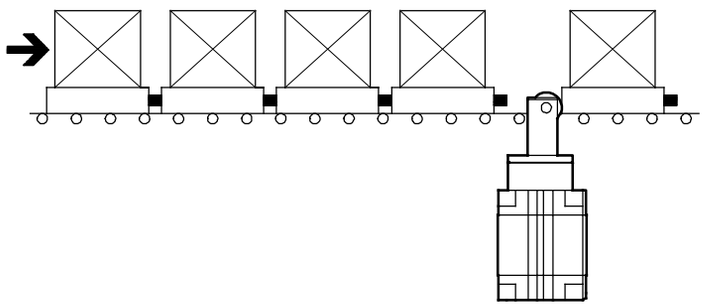
2b. Checking the permissible transverse force during the switching operation

Transverse force F_Q =
friction force $F_{Friction}$
$F_{Friction}$ = 150 N

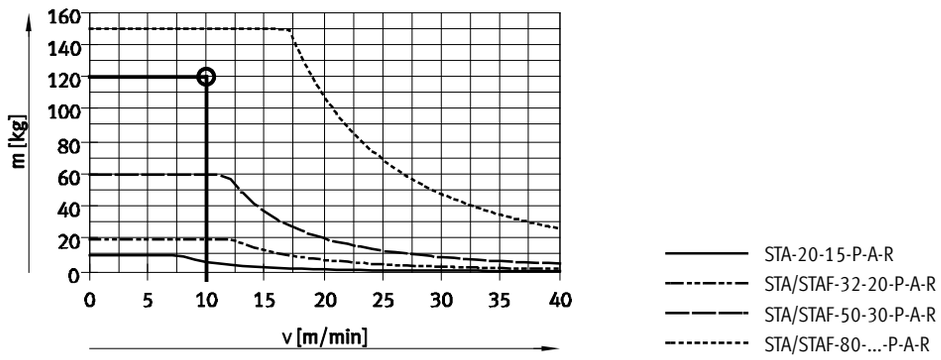
The maximum permissible transverse force at an operating pressure of 6 bar is 1,100 N.
This means that the transverse force of 150 N is permissible.



3. Separating and advancing the workpiece carriers



The maximum permissible mass with the STA...-50-...-R at a delivery speed of 10 m/min is 60 kg.
Since the total mass of the four workpiece carriers advancing on the stopper cylinder is 120 kg, the next largest stopper cylinder must be selected for separating.



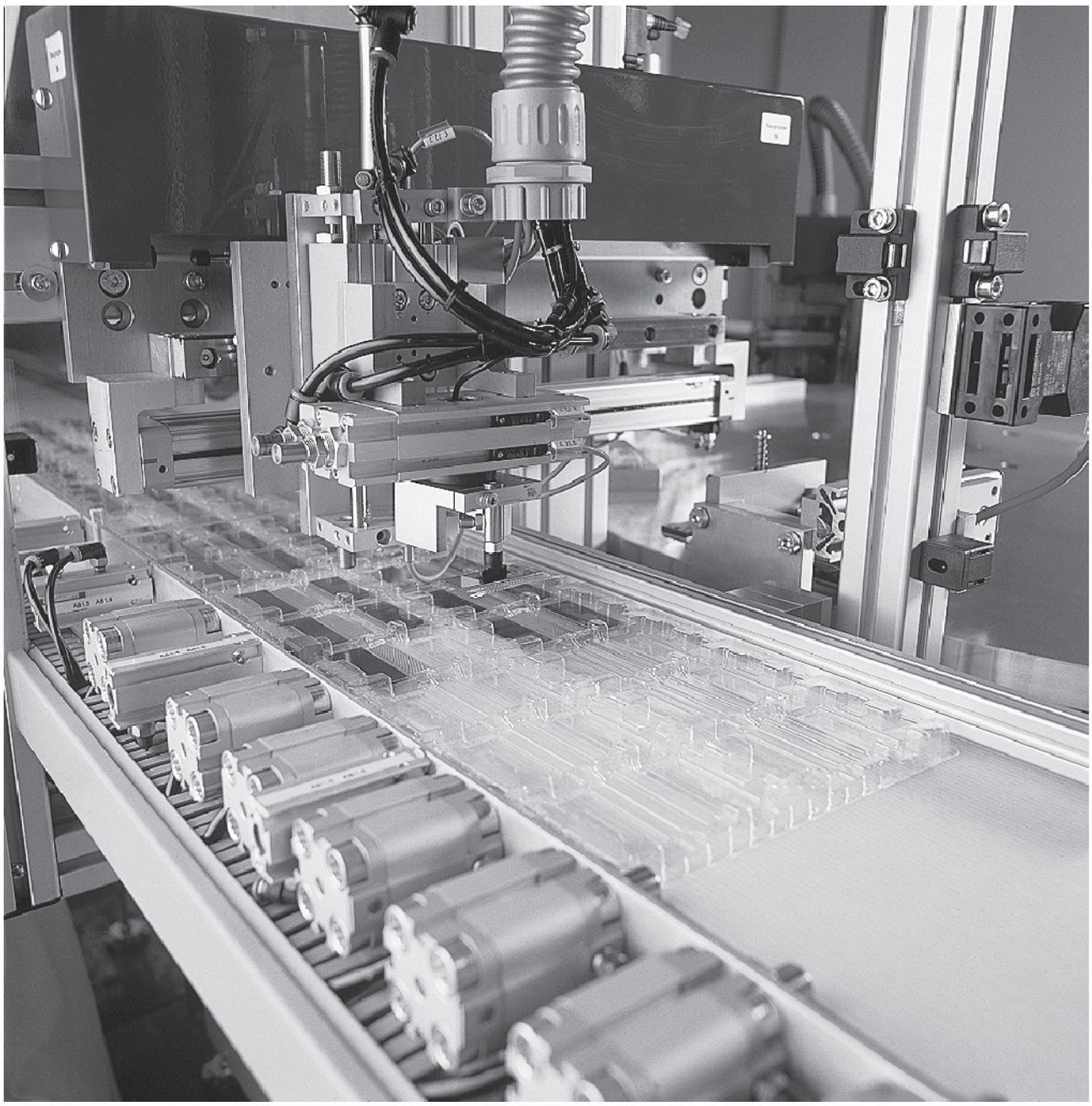
Max. total mass:

$m_{Total\ force} = n_{Queue-1} \times m = 4 \times 30kg = 120kg$

Result

The stopper cylinder STA...-80-...-R must be selected for separating five workpiece carriers.

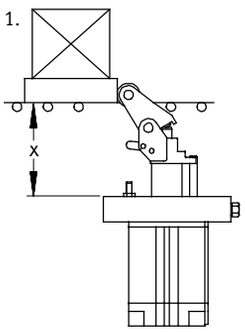
Application example



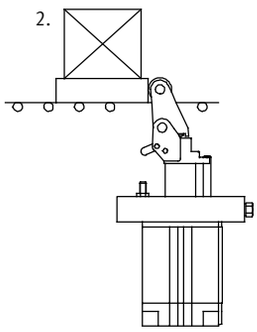
Stopper cylinders STAF, toggle lever

Functional sequence

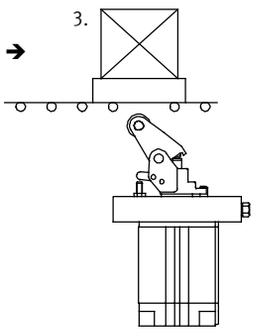
Functional sequence



1. Gentle stopping of heavy masses via a hydraulic shock absorber in the piston rod.

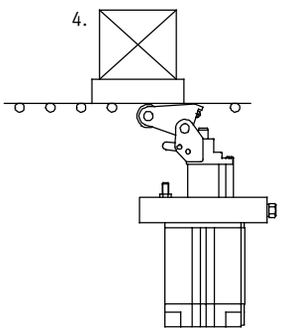


2. The toggle lever is locked into the retracted end position so that the workpiece carrier cannot be pushed back by the shock absorber.

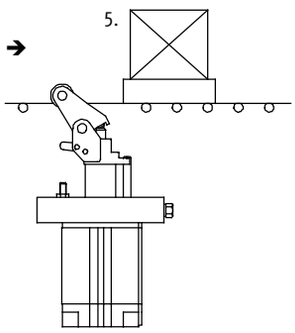


3. The workpiece carrier is released by means of compressed air, and the toggle lever is released simultaneously.

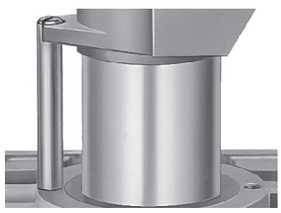
X = 62.8 ... 63.4 mm



4. The piston is advanced by means of spring force or compressed air. The toggle lever tips back which prevents the workpiece carrier from being pushed up.



5. The toggle lever is raised by means of spring force and stops the next workpiece carrier.



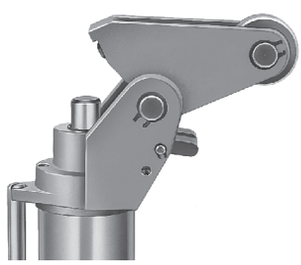
Protection against rotation:
The guide rod always aligns the toggle lever precisely to the approaching workpiece carrier.



Integrated shock absorber: absorbs impact energy and stops the workpiece carrier gently, and with low noise levels.
The impact energy can be adjusted using the regulating screw in the toggle lever.



Detenting roller lever: the workpiece carrier cannot be pushed back by the shock absorber.



Locking mechanism for disabling the stopper function: the workpiece carrier is able to pass the holding point without activating the cylinder.

Note

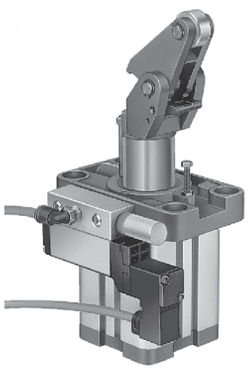
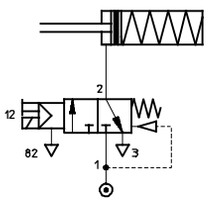
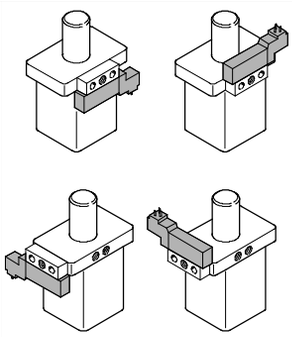
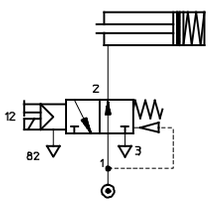
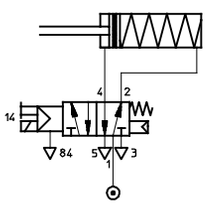
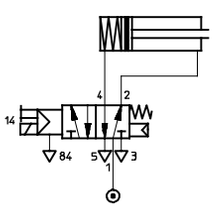
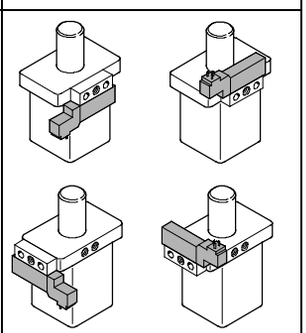
Trunnion or roller type stopper cylinders can be mounted in any position.
Stopper cylinders with toggle lever must be mounted in the vertical, upright position.

Stopper cylinders STAF, toggle lever

Key features

Mounting options for solenoid valves and valve functions

An MEH, MEBH, MOEH or MOEBH solenoid valve can be mounted on the stopper cylinder for quick, direct actuation of the cylinder. This type of actuation is only possible for stopper cylinders with flange mounting. The valve must be mounted on the flange plate via a valve sub-base ZVA. The position of the piston rod when the solenoid valve is in the normal position depends upon the valve type and the position of the valve on the cylinder.

Application	Piston rod in initial position	Required solenoid valve	Type of mounting for the solenoid valve with sub-base ZVA
	Single-acting		
		Normally advanced 173 125 MEH-3/2-5,0-B 172 999 MEBH-3/2-5,0-B	
		Normally retracted 173 429 MOEH-3/2-5,0-B 173 002 MOEBH-3/2-5,0-B	
	Double-acting		
		Normally advanced 173 128 MEH-5/2-5,0-B 173 005 MEBH-5/2-5,0-B	
		Normally retracted 173 128 MEH-5/2-5,0-B 173 005 MEBH-5/2-5,0-B	

Note

Cylinders are always supplied single-acting with spring. If a double-acting stopper cylinder is required, the filter nipple in the exhaust port must be removed. The exhaust port is then used as a supply port.

Solenoid valves MEH, MEBH
➔ Internet: solenoid valve

Stopper cylinders STAF, toggle lever

Type codes and peripherals overview

STAF	–	32	–	20	–	P	–	A	K

Type	
Single-acting or double-acting	
STAF	Stopper cylinder with flange mounting

Piston ∅ [mm]

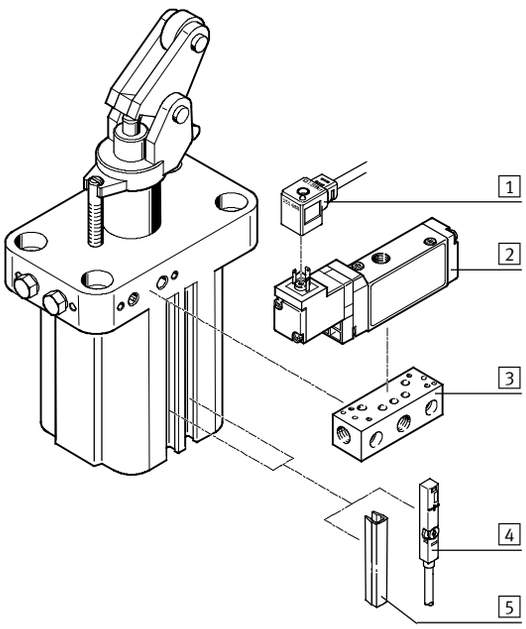
Stroke [mm]

Cushioning	
P	Flexible cushioning rings/pads at both ends

Position sensing	
A	Via proximity sensor

Version	
K	Toggle lever version

Peripherals overview



Accessories		
Brief description		**➔ Page/Internet**
1 Plug socket with cable KMEB	–	kmeb
2 3/2-way valve MEBH	For fast and direct actuation of the stopper cylinder	mebh
3 Sub-base ZVA	For stopper cylinder with flange	26
4 Proximity sensor SME/SMT-8	Can be integrated in the cylinder profile barrel	28
5 Slot cover ABP	For protecting against ingress of dirt	28

Stopper cylinders STAF, toggle lever

Technical data

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Function



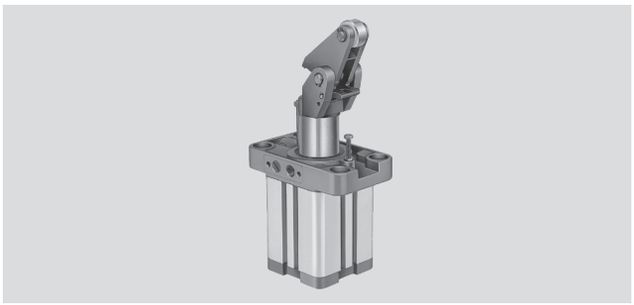
- Ø - Diameter 32 mm

- I - Stroke length 20 mm

- T - www.festo.com

- | - Note

Contact with liquids must be avoided during use.



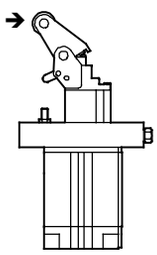
General technical data		
Pneumatic connection		M5
Stroke	[mm]	20
Piston rod ∅	[mm]	20
Operating pressure	[bar]	10
Operating medium		Compressed air in accordance with ISO 8573-1:2010 [7:–:–]
Constructional design		Piston cylinder with spring return
Cushioning		Flexible cushioning rings/pads at both ends
Position sensing		Via proximity sensor
Type of mounting		Via through-holes
Mounting position		Vertical, upright
Mode of operation		Single-acting or double-acting
Protection against rotation		Guide rod
Ambient temperature[1)]	[°C]	0 ... +60

1) Note operating range of proximity sensors.

- | - Note: This product conforms to ISO 1179-1 and to ISO 228-1

Forces [N]	
Permissible impact force on the rollers of the toggle lever when the piston rod is advanced and the toggle lever is pushed into its end position	480
Spring force	20 ... 42

Impact force is the basis for the calculation of permissible impact energy. Depending upon the type of load to be stopped, it is advisable to use a flexible buffer to cushion the impact, reduce noise levels and to optimise impact energy.



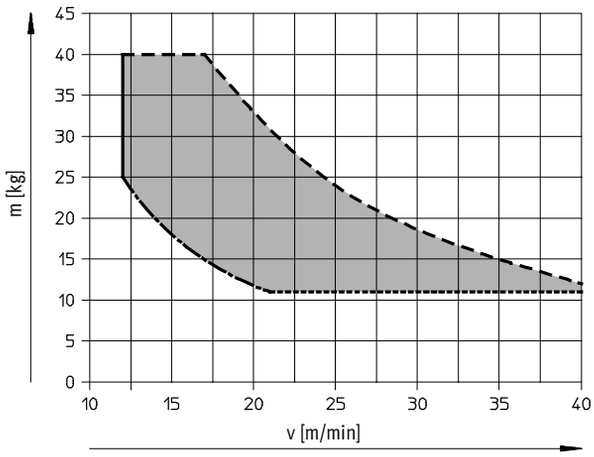
➔ = Direction of impact force

Stopper cylinders STAF, toggle lever

Technical data

Permissible mass m as a function of the conveyor speed v

With a friction value of μ = 0.1



Note

The required mass for reliable pushing into the end position is dependent on the friction pairing between the conveyor and conveyed goods, other friction values on request.

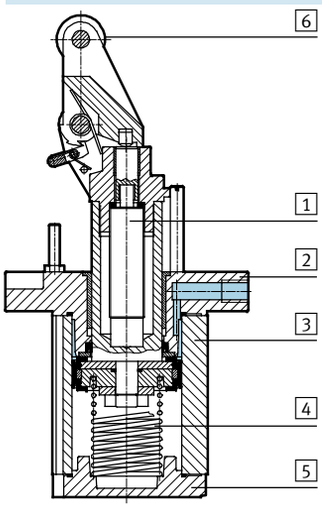
Cushioning time is increased for partial loads.
Energy values valid for ambient temperature T = 20 °C.

Operating range
Max. workload
Recommended minimum workload[1)]
Required mass[2)]

1) For optimum operation of the damper
2) Required mass for reliable pushing of the toggle lever into the end position with this friction value

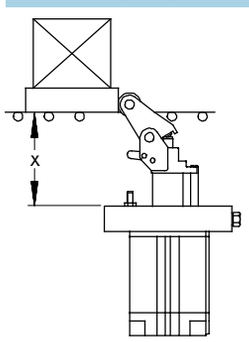
Materials

Sectional view



Stopper cylinder		
1	Piston rod	Stainless steel
2	Flange	Die-cast aluminium
3	Cylinder barrel	Anodised aluminium
4	Springs	Spring steel
5	End cap	Anodised aluminium
6	Roller	Polyacetate
–	Seals	Polyurethane
–	Note on materials	Free of copper, PTFE and silicone

Minimum distance to the conveyor



X = 62.8 ... 63.4 mm

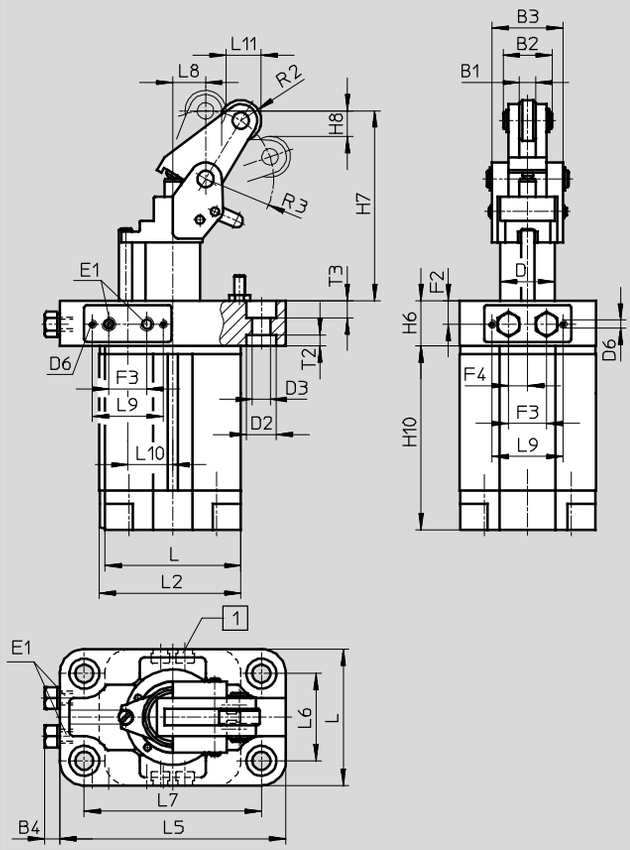
Stopper cylinders STAF, toggle lever

Technical data

FESTO

Dimensions Download CAD data ➔ **www.festo.com**

Flange mounting



1 Slot for proximity sensor SME/SMT-8

∅ [mm]	B1	B2	B3	B4	D ∅	D2 ∅	D3 ∅	D6	E1	F2	F3	F4	H6	H7	H8
32	6	18	26	4.5	20	11	6.6	M3	M5	8.5	14	7	16.5	70	9.5

∅ [mm]	H10	L	L2	L5	L6	L7	L8	L9	L10	L11	R2	R3	T2	T3
32	67.5	50	52	83	32	65	12	26	16.5	13	7.5	25	4	6.2

Note: This product conforms to ISO 1179-1 and to ISO 228-1

Ordering data

Piston ∅ [mm]	Stroke [mm]	Flange mounting Part No.	Type
32	20	**164 880**	**STAF-32-20-P-A-K**

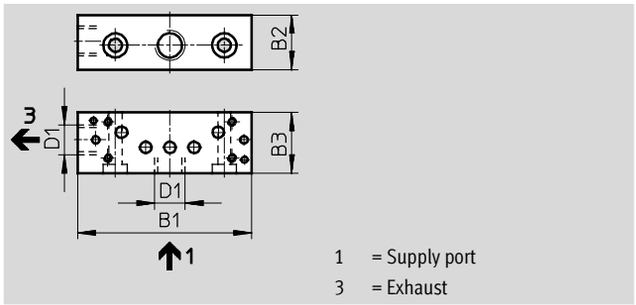
Stopper cylinders STA/STAF

Accessories

Sub-base ZVA
for stopper cylinder with flange

Material:
Wrought aluminium alloy
Free of copper, PTFE and silicone





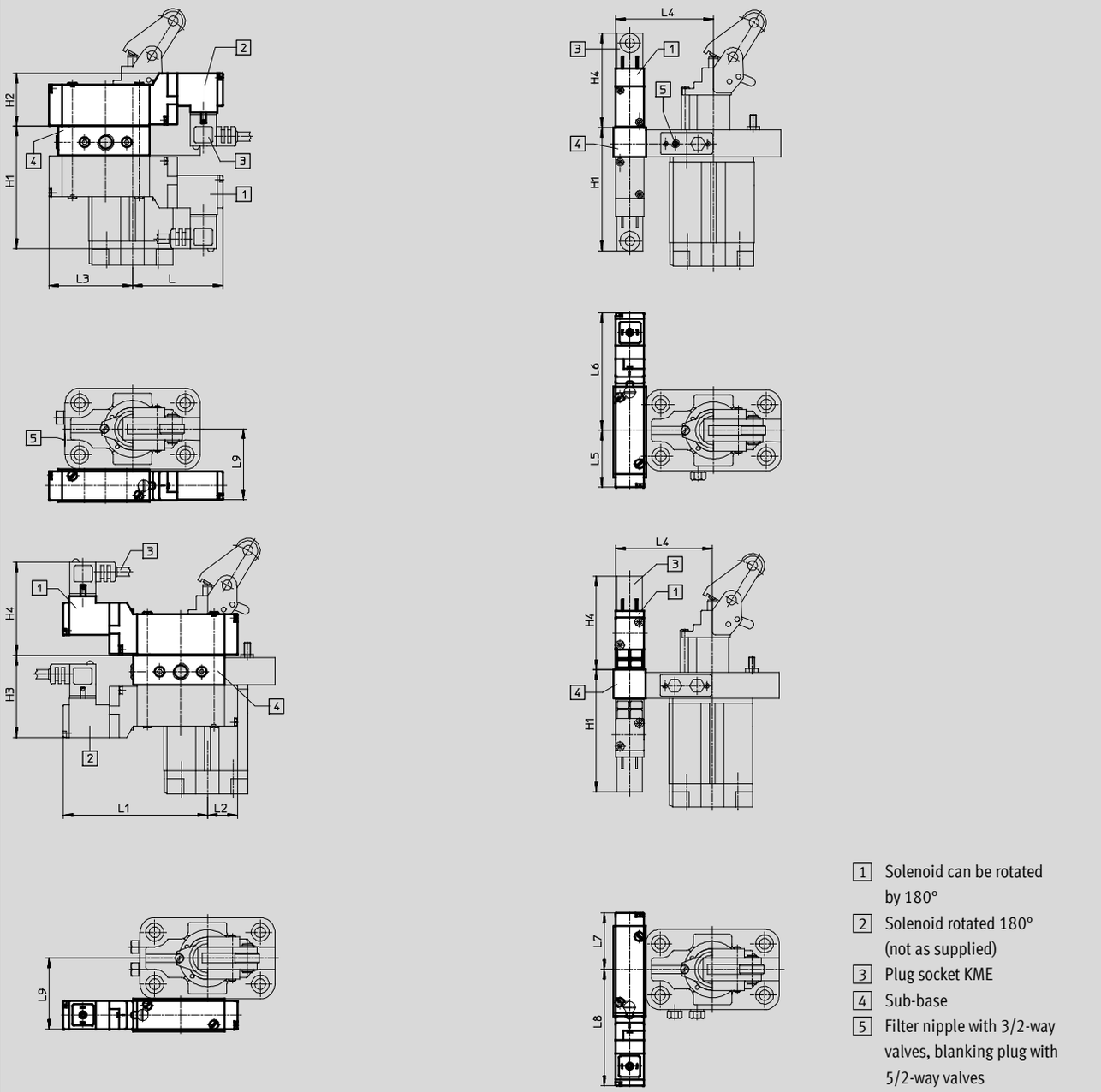
Dimensions and ordering data

For ∅ [mm]	B1	B2	B3	D1	CRC[1)]	Weight [g]	Part No.	Type
32	56	18	20	G1⁄8	2	50	**164 896**	**ZVA-1**
50/80	57.5	18	20	G1⁄8	2	52	**164 897**	**ZVA-2**

1) Corrosion resistance class 2 as per Festo standard 940 070
Components subject to moderate corrosion stress. Externally visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment or media such as coolants or lubricating agents.

Dimensions Download CAD data ➔ **www.festo.com**

Mounting dimensions for solenoid valves with sub-base ZVA on stopper cylinders

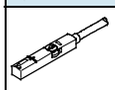
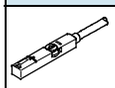


1 Solenoid can be rotated by 180°
2 Solenoid rotated 180° (not as supplied)
3 Plug socket KME
4 Sub-base
5 Filter nipple with 3/2-way valves, blanking plug with 5/2-way valves

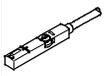
For ∅ [mm]	L	L1	L2	L3	L4	L5	L6
32	55.5	88.5	18.5	51.5	59	35	72
50	65	79	28	42	73	36	71
80	48.5	95.5	11.5	58.5	98	39	68

For ∅ [mm]	L7	L8	L9	H1	H2	H3	H4
32	35	72	42	74.5	33.5	48.5	59.5
50	34	73	52	77	31	31	57
80	31	76	71	79	29	53	56

Ordering data – Proximity sensors for T-slot, magneto-resistive — Technical data ➔ Internet: smt

	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile, short design	PNP	Cable, 3-wire	2.5	**574335**	**SMT-8M-A-PS-24V-E-2,5-OE**
			Plug M8x1, 3-pin	0.3	**574334**	**SMT-8M-A-PS-24V-E-0,3-M8D**
			Plug M12x1, 3-pin	0.3	**574337**	**SMT-8M-A-PS-24V-E-0,3-M12**
		NPN	Cable, 3-wire	2.5	**574338**	**SMT-8M-A-NS-24V-E-2,5-OE**
			Plug M8x1, 3-pin	0.3	**574339**	**SMT-8M-A-NS-24V-E-0,3-M8D**
N/C contact						
	Insertable in the slot from above, flush with cylinder profile, short design	PNP	Cable, 3-wire	7.5	**574340**	**SMT-8M-A-PO-24V-E-7,5-OE**

Ordering data – Proximity sensors for T-slot, magnetic reed — Technical data ➔ Internet: sme

	Type of mounting	Switch output	Electrical connection	Cable length [m]	Part No.	Type
N/O contact						
	Insertable in the slot from above, flush with cylinder profile	Contacting	Cable, 3-wire	2.5	**543 862**	**SME-8M-DS-24V-K-2,5-OE**
				5.0	**543 863**	**SME-8M-DS-24V-K-5,0-OE**
			Cable, 2-wire	2.5	**543 872**	**SME-8M-ZS-24V-K-2,5-OE**
			Plug M8x1, 3-pin	0.3	**543 861**	**SME-8M-DS-24V-K-0,3-M8D**
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	2.5	**150 855**	**SME-8-K-LED-24**
			Plug M8x1, 3-pin	0.3	**150 857**	**SME-8-S-LED-24**
N/C contact						
	Insertable in the slot lengthwise, flush with the cylinder profile	Contacting	Cable, 3-wire	7.5	**160 251**	**SME-8-O-K-LED-24**

Ordering data – Connecting cables — Technical data ➔ Internet: nebu

	Electrical connection, left	Electrical connection, right	Cable length [m]	Part No.	Type
	Straight socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	**541 333**	**NEBU-M8G3-K-2.5-LE3**
			5	**541 334**	**NEBU-M8G3-K-5-LE3**
	Angled socket, M8x1, 3-pin	Cable, open end, 3-wire	2.5	**541 338**	**NEBU-M8W3-K-2.5-LE3**
			5	**541 341**	**NEBU-M8W3-K-5-LE3**

Ordering data – Slot cover for T-slot

	Assembly	Length [m]	Part No.	Type
	Insertable from above	2x 0.5	**151 680**	**ABP-5-S**

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