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Find the *Galil Motion Control DMC-2210* at our website: *Click HERE*

Ethernet/RS232 & USB/RS232 Optima 1–8 axes

DMC-22x0 and -20x0 Series

Product Description

The DMC-20x0 and DMC-22x0 Optima Series are box-level, multi-axis motor controllers designed for stand-alone applications. The controllers differ only in their type of communication interface: the DMC-20x0 has USB and the DMC-22x0 has an Ethernet 10/100Base-T port. The controllers also include two RS232 serial ports. The DMC-20x0 and DMC-22x0 motion controllers are available for 1 through 8 axes.

The DMC-2xx0 controllers incorporate a 32-bit microcomputer and provide such advanced features as PID compensation with velocity and acceleration feedforward, programmable notch filter, program memory with multitasking for simultaneously running up to eight application programs, and uncommitted I/O for synchronizing motion with external events. They handle various modes of motion including point-to-point positioning, jogging, linear and circular interpolation, contouring, electronic gearing and ECAM. Additionally, the controllers are user-configurable for stepper or servo motor control on any combination of axes.

Like all Galil controllers, the DMC-2xx0 controllers use a simple, English-like command language which makes them very easy to program. Galil's WSDK servo design software further simplifies system set-up with "one-button" servo tuning and real-time display of position and velocity information. Communication drivers are available for Linux and Windows operating systems.

DMC-22x0 Stand-alone with Ethernet/RS232



Features

- *Box-level, stand-alone motion controllers*
- *Available in 1 through 8 axis versions: where x=1,2,3,4,5,6,7,8 axes*
- *Two RS232/422 ports up to 115 kbaud*
- *DMC-20x0: USB*
  DMC-22x0: Ethernet 10/100 Base-T
- *Ethernet supports multiple masters and slaves. TCP/IP, UDP and ModBus TCP master protocol for communication with I/O*
- *User-configurable for stepper or servo motors on any combination of axes. Optional firmware for piezo-ceramic motors. Sinusoidal commutation for brushless servo motors*
- *12 MHz encoder frequencies for servos; 3 MHz for steppers*
- *PID compensation with velocity and acceleration feedforward, integrator limit, notch filter and low-pass filter*
- *Modes of motion include jogging, point-to-point positioning, contouring, linear and circular interpolation, electronic gearing and ECAM. Features elliptical scaling, slow-down around corners, infinite segment feed and feedrate override*
- *Over 200 English-like commands directly executable by controller. Includes conditional statements and event triggers*
- *Non-volatile memory for programs, variables and arrays. Concurrent execution of up to eight application programs*
- *Dual encoders, isolated home and limits for each axis*
- *8 optoisolated uncommitted inputs and 8 outputs for 1- through 4-axis models, 16 in/16 out for 5- through 8-axis models*
- *High speed position latch for each axis and output compare*
- *8 uncommitted analog inputs*
- *Additional 64 configurable digital I/O*
- *Use Galil's IOC-7007 I/O controller for additional I/O*
- *100-pin SCSI connectors for each set of 4 axes. Galil's ICM-2900 interconnect module breaks-out 100-pin cable into screw terminals and attaches directly to DMC-2xx0 metal enclosure*
- *12.1" x 2.2" x 6.3" metal enclosure; Accepts 90-250V AC*
- *CE certified*
- *Custom hardware and firmware options available*

Ethernet/RS232 and USB/RS232 Optima 1–8 axes

DMC-22x0 and DMC-20x0 Series

Specifications

System Processor

- Motorola 32-bit microcomputer

Communications Interface

- DMC-2000: USB 1.1 or 12.5 Mb/sec, expansion hub with two ports. (2) RS232/422 ports up to 115 kb. RS485 option
- DMC-2200: Ethernet 10/100BASE-T. (2) RS232/422 ports up to 115 kb. RS485 option

Commands are sent in ASCII. A binary communication mode is also available as a standard feature

Modes of Motion:

- Point-to-point positioning
- Position Tracking
- Jogging
- 2D Linear and Circular Interpolation with feedrate override
- Linear Interpolation for up to 8 axes
- Tangential Following
- Helical
- Electronic Gearing with multiple masters
- Gantry Mode
- Electronic Cam
- Contouring
- Teach and playback

Memory

- Program memory size — 1000 lines × 80 characters
- 510 variables
- 8000 array elements in up to 30 arrays

Filter

- PID (proportional-integral-derivative) with velocity and acceleration feedforward
- Notch filter and low-pass filter
- Dual-loop control for backlash compensation
- Velocity smoothing to minimize jerk
- Integration limit
- Torque limit
- Offset adjustments
- Option for piezo-ceramic motors

Kinematic Ranges

- Position: 32 bit (±2.15 billion counts per move; automatic rollover; no limit in jog or vector modes)
- Velocity: Up to 12 million counts/sec for servo motors
- Acceleration: Up to 67 million counts/sec^2

Uncommitted Digital I/O

	DIGITAL INPUTS	DIGITAL OUTPUTS	CONFIGURABLE I/O
DMC-2x10 thru -2x40	8	8	64
DMC-2x50 thru -2x80	16	16	64

Uncommitted Analog Inputs

- 8 individual ±10 V analog inputs with 12-bit resolution (16-bit available as an option)

High Speed Position Latch

- Uncommitted inputs 1–4 latch X,Y,Z,W, and 9–12 latch E, F, G, H axes (latches within 40 microseconds with optoisolation)

Dedicated Inputs (per axis)

- Main encoder inputs — Channel A, A-, B,B-,I, I- (±12 V or TTL)
- Auxiliary encoder (for axes configured as servo) — Channel A, A-, B, B-
- Forward and reverse limit inputs — optoisolated
- Home input — optoisolated
- Selectable high-speed position latch input — optoisolated
- Selectable abort input — optoisolated

Dedicated Outputs (per axis)

- Analog motor command output with 16-bit DAC resolution
- Pulse and direction output for step motors
- PWM output also available for servo amplifiers
- Amplifier enable output
- Error output (one per controller)
- High-speed position compare output (1 output for each set of 4 axes)

Minimum Servo Loop Update Time

	STANDARD	*-FAST*†
1–2 axes:	250 µsec	125 µsec
3–4 axes:	375 µsec	250 µsec
5–6 axes:	500 µsec	375 µsec
7–8 axes:	625 µsec	500 µsec

Maximum Encoder Feedback Rate

- 12 MHz

Maximum Stepper Rate

- 3 MHz (Full, half or microstep)

Power Requirements

- *DMC-2xx0 series: accepts 90–250 V AC, 50–60 Hz*

Environmental

- Operating temperature: 0–70° C for card; 0–60° for box
- Humidity: 20–95% RH, non-condensing

Mechanical

- DMC-2xx0 series: 1–8 axes, 12.1" × 2.2" × 6.3" metal enclosure

†*Reduced feature set for -FAST.*

OTHER

Hardware Accessories

AMP-19540 Interconnect with Four 500 Watt Servo Drives

Galil's AMP-19540 is a 4-axis amplifier for driving brush or brushless servo motors up to 500 Watts. By interfacing directly to Galil's Optima controllers, it provides a cost-effective controller/drive solution for multi-axis applications. The AMP-19540 contains four transconductance, PWM amplifiers for driving brush or brushless motors. Each amplifier operates at 18V to 80V DC, up to 7 Amps continuous, 10 Amps peak. The AMP-19540 gain setting is easily configured with jumpers. The PWM switching frequency is 60 kHz. The AMP-19540 enclosure has dimensions of 6.8" x 8.75" x 1". It interfaces to the Optima controller with a single, 100-pin high density SCSI cable. Signals for each axis are brought out through D-type connectors located on the AMP-19540. For applications with less than three axes, the AMP-19520 two-axis model is available. A shunt regulator option is also available.



AMP-19540



Left: *ICM-2900 Interconnect Module*
Center: *DMC-2040 with attached ICM-2900*
Right: *ICM-2908*

ICM-2900 Interconnect Module for DMC-2xx0

The ICM-2900 interconnect module for the DMC-2xx0 mounts directly to the DMC-2xx0 enclosure. Use one for every four axes. The ICM-2900 accepts the 100-pin motion controller cable for break-out into screw terminals.

ICM-2908 Interconnect Module for Auxiliary Encoders

The ICM-2908 interconnect module for the DMC-2xx0 accepts the 36-pin cable for auxiliary encoders. One ICM-2908 may be used for up to eight axes.

Ethernet/RS232 and USB/RS232 Optima 1–8 axes

DMC-22x0 and DMC-20x0 Series

Ordering Information

PART NUMBER	DESCRIPTION	QUANTITY 1	QUANTITY 100
DMC-2010 (or 2210)	1-axis USB, RS232 (or 1-axis Ethernet 10/100BASE-T, RS232)	$1595	$ 995
DMC-2020 (or 2220)	2-axis USB, RS232 (or 2-axis Ethernet 10/100BASE-T, RS232)	$1995	$1145
DMC-2030 (or 2230)	3-axis USB, RS232 (or 3-axis Ethernet 10/100BASE-T, RS232)	$2395	$1195
DMC-2040 (or 2240)	4-axis USB, RS232 (or 4-axis Ethernet 10/100BASE-T, RS232)	$2595	$1295
DMC-2050 (or 2250)	5-axis USB, RS232 (or 5-axis Ethernet 10/100BASE-T, RS232)	$2895	$1445
DMC-2060 (or 2260)	6-axis USB, RS232 (or 6-axis Ethernet 10/100BASE-T, RS232)	$3095	$1545
DMC-2070 (or 2270)	7-axis USB, RS232 (or 7-axis Ethernet 10/100BASE-T, RS232)	$3295	$1645
DMC-2080 (or 2280)	8-axis USB, RS232 (or 8-axis Ethernet 10/100BASE-T, RS232)	$3495	$1745
FIBEROPTIC	Ethernet 10/100BASE-F, RS232 fiberoptic link	$ 200	$ 150
ICM-2900	Interconnect module (use 1 for every 4 axes). Specify -HAEN for high amp enable or -LAEN for low amp enable. Specify -FL for flange	$ 295	$ 195
ICM-2900-OPTO	ICM with optoisolated outputs	$ 345	$ 245
ICM-2908	Interconnect module for auxiliary encoders	$ 125	$ 95
CABLE-100-1M	100-pin HD cable in 1 meter length	$ 165	$ 125
CABLE-100-2M	100-pin HD cable in 2-meter length	$ 180	$ 135
CABLE-100-4M	100-pin HD cable in 4 meter length	$ 195	$ 145
CABLE-36-1M	36-pin HD cable in 1-meter length (for aux encoders)	$ 90	$ 75
CABLE-36-3M	36-pin HD cable in 3-meter length (for aux encoders)	$ 110	$ 90
CABLE-80-1M	80-pin HD cable in 1-meter length (for extended I/O)	$ 125	$ 95
CABLE-80-4M	80-pin HD cable in 4-meter length (for extended I/O)	$ 150	$ 105
AMP-19520	2-axis amplifier for 500 W servos	$ 595	$ 395
AMP-19540	4-axis amplifier for 500 W servos	$ 795	$ 495
-SR	Shunt regulator option for AMP-195x0	$ 50	$ 25

Galil offers additional quantity discounts for purchases between 1 and 100. Consult Galil for a quotation.

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