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Keysight E-Series E9300 Power Sensors

Operating and Service Guide

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NOTICE: This document contains references to Agilent Technologies. Agilent's former Test and Measurement business has become Keysight Technologies. For more information, go to **www.keysight.com.**

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The following general safety precautions must be observed during all phases of operation of this instrument. Failure to comply with these precautions or with specific warnings elsewhere in this manual violates safety standards of design, manufacture, and intended use of the instrument. Keysight Technologies assumes no liability for the customer's failure to comply with these requirements.

Safety Notices

WARNING

A WARNING notice denotes a hazard. It calls attention to an operating procedure, practice, or the like that, if not correctly performed or adhered to, could result in personal injury or loss of life. Do not proceed beyond a WARNING notice until the indicated conditions are fully understood and met.

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General Safety Information

The following general safety precautions must be observed during all phases of operation, service and repair of this sensor. Failure to comply with these precautions or specific warnings elsewhere in this manual violates safety standards of design manufacture and intended use of the sensor. Keysight Technologies assumes no liability for the customer's failure to comply with these requirements.

The Instruction Documentation Symbol. The product is marked with this symbol when it is necessary for the user to refer to the instructions in the supplied documentation.

WARNING **BEFORE CONNECTING THE POWER SENSOR TO OTHER INSTRUMENTS, ensure that all instruments are connected to the protective (earth) ground. Any interruption of the protective earth grounding will cause a potential shock hazard that could result in personal injury.**

Sound Emission

Herstellerbescheinigung

Diese Information steht im Zusammenhang mit den Anforderungen der Maschinenlarminformationsverordnung vom 18 Januar 1991.

- Sound Pressure LpA < 70 dB.
- Am Arbeitsplatz.
- Normaler Betrieb.
- Nach DIN 45635 T. 19 (Typprufung).

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Manufacturers Declaration

This statement is provided to comply with the requirements of the German Sound DIN 45635 T. 19 (Typprufung).

- Sound Pressure LpA < 70 dB.
- At operator position.
- Normal operation.
- According to ISO 7779 (Type Test).

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Power Meter Front Panel Operation

This guide uses the following symbols to denote power meter front panel keys and display legends.



A function name in a keycap symbol indicates the use of a key physically located on the power meter's front panel.



A function name in display-font indicates the use of a key down the right side of the power meter's display adjacent to the displayed text.

Display Text

Display TextText shown in this font indicates message text displayed by the power meter.

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Documentation

Sensors Covered by Manual

These sensors have a two-part serial number: the prefix (two letters and the first four numbers), and the suffix (the last four numbers). The two letters identify the country in which the unit was manufactured. The four numbers of the prefix are a code identifying the date of the last major design change incorporated in your sensor. The four-digit suffix is a sequential number and, coupled with the prefix, provides a unique identification for each unit produced. The contents of this manual apply directly to all serial numbers unless otherwise indicated.

Related Publications

The *Keysight E-Series E9300 Power Sensors Operating and Service Guide* is also available in the following languages:

- English Language *Operating and Service Guide* - Standard
- German Language *Operating and Service Guide* - Option ABD
- Spanish Language *Operating and Service Guide* - Option ABE
- French Language *Operating and Service Guide* - Option ABF
- Japanese Language *Operating and Service Guide* - Option ABJ
- Italian Language *Operating and Service Guide* - Option ABZ
- Korean Language *Operating and Service Guide* - Option AB1

Further useful information can be found in:

- *Application Note 64-1B, Fundamentals of RF and Microwave Power Measurements*, available by ordering through your local Keysight Technologies Sales Office.
- The Keysight EPM Series Power Meter *User's Guide and Programming Guide*.

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In This Guide ...

1 **Introduction** Chapter 1 introduces you to the general information about the E-Series E9300 power sensor.

2 **Making Measurements** Chapter 2 describes the general operation of the E-Series E9300 power sensor.

3 **Specifications and Characteristics** Chapter 3 describes the specifications and characteristics of your E-Series E9300 power sensor.

4 **Service** Chapter 4 describes the performance test, replaceable parts and service of the E-Series E9300 power sensor.

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What You'll Find In This Chapter

This Chapter introduces you to the Keysight E-Series E9300 power sensors, some detail on their operation, the minimum power meter requirements and connecting to your power meter. It contains the following sections:

"General Information" on page 3

"The Keysight E-Series E9300 Power Sensors in Detail" on page 4

"Getting Started" on page 6



Figure 1-1 Typical Keysight E-Series E9300 power sensors.

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General Information

Welcome to the Keysight E-Series E9300 power sensors Operating and Service Guide! This guide contains information about the initial inspection, operation, specifications and repair of the Keysight E-Series E9300 power sensors. Use this guide as a supplement to the Keysight EPM series power meters User's Guides. It is 3-hole drilled to allow you to retain it in the power meter's binder.

All power meter functions are detailed in the Keysight EPM series power meters User's Guide and Programming Guide, however, this guide contains information specific to the operation of Keysight E-Series E9300 power sensor.

Accessories Shipped with the Instrument

The following items are shipped with every purchase of E9300 Series power sensor:

- Certificate of Calibration
- E9300 Series Power Sensors Operating and Service Guide

Verify that any options ordered are included with the shipment by checking the packing list included with the shipment.

Power Meter Requirements

The Keysight E-Series E9300 power sensors are NOT compatible with the earlier Keysight 430-Series, Keysight E1416A, or Keysight 70100A power meters. They are compatible ONLY with the Keysight EPM series power meters. Also, not all Keysight EPM series power meters are immediately compatible - your power meter must use firmware and Digital Signal Processing (DSP) code from a specific release onwards. see "Checking Power Meter Firmware and DSP Revision" on page 6 tells you how to check your power meter and have it upgraded if required.

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The Keysight E-Series E9300 Power Sensors in Detail

Most power sensors used for measuring average power employ either thermocouple or diode technologies. Diode based sensors frequently rely on the application of correction factors to extend their dynamic range beyond their square law response region, typically –70 dBm to –20 dBm. However, while this technique achieves wide dynamic range capability, it is limited to continuous wave (CW) signals outside the square law region. Modulated signals must be padded down or at low levels, with their average and peak power levels within the diode square law region, to be measured accurately. Accurate, average power measurement of high level signals carrying modulation cannot be obtained using a CW correction factor technique. Specialized modulation sensors provide accurate measurements but are bandwidth limited.

The Keysight E-Series E9300 power sensors are true average, wide dynamic range RF microwave power sensors. They are based on a dual sensor diode pair/attenuator/diode pair proposed by Szente et. al. in 1990*. Figure 1-2 shows a block diagram of this technique.

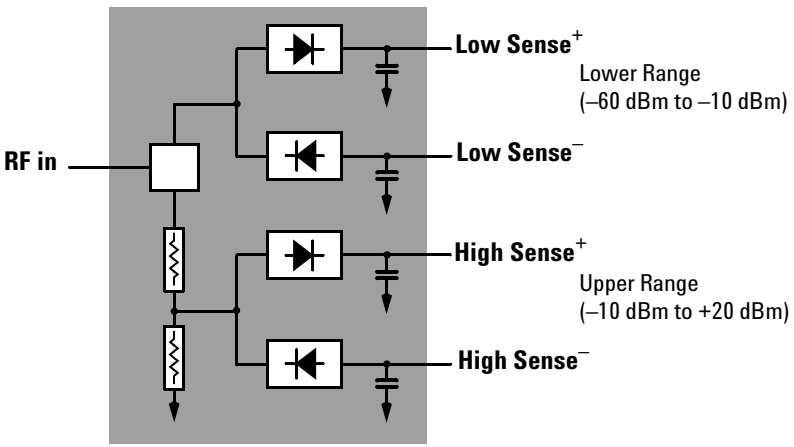


Figure 1-2 Simplified Block Diagram of Diode Pair/Attenuator/Diode Pair

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This technique ensures the diodes in the selected signal path are kept in their square law region, thus the output current (and voltage) is proportional to the input power. The diode pair/attenuator/diode pair assembly can yield the average of complex modulation formats across a wide dynamic range, irrespective of signal bandwidth.

The dual range Modified Barrier Integrated Diode (MBID)† package includes further refinements to improve power handling allowing accurate measurement of high level signals with high crest factors without incurring damage‡ to the sensor.

These sensors measure average RF power on a wide variety of modulated signals and are independent of the modulation bandwidth. They are ideally suited to the average power measurement of multi-tone and spread spectrum signals such as CDMA, W-CDMA and digital television formats. Also, pulsed, TDMA signals can be measured within the constraints detailed in Chapter 2, "Measuring TDMA Signals" on page 17.

The results are displayed on a compatible# power meter in logarithmic (dBm or dB) or linear (Watts or %) measurement units.

* US Patent #4943764, assigned to Keysight Technologies.

† November 1986 Hewlett-Packard Journal pages 14-2, "*Diode Integrated Circuits for Millimeter-Wave Applications*".

‡ Refer Chapter 3, Maximum Power on page 28 and page 41 to for maximum power handling specifications.

A Keysight EPM-Series power meter is required as specified in the section see "Checking Power Meter Firmware and DSP Revision" on page 6.

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Getting Started

Initial Inspection

Inspect the shipping container for damage. If the shipping container or packaging material is damaged, it should be kept until the contents of the shipment have been checked mechanically and electrically. If there is mechanical damage, notify the nearest Keysight Technologies office. Keep the damaged shipping materials (if any) for inspection by the carrier and a Keysight Technologies representative. If required, you can find a list of Keysight Technologies Sales and Service offices on page 63.

Checking Power Meter Firmware and DSP Revision

Before proceeding, first ensure your Keysight EPM series power meter has the required firmware and DSP revisions (E4418B and E4419B only) for the correct operation of your Keysight EPM series power meters.

On the power meter press System Inputs, More, Service, Version.

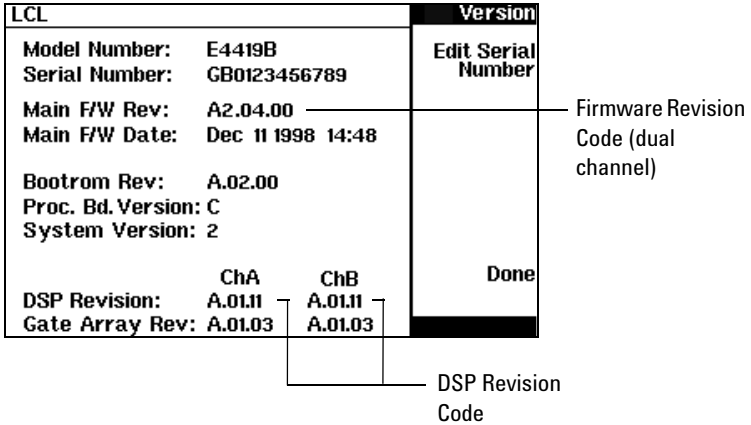


Figure 1-3 Power Meter Firmware Version Screen

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First check the section labelled **DSP Revision:**. Release A.01.11 or later is required. If your power meter has an earlier release, please contact your nearest Service Office (listed on page 63) to arrange an upgrade.

Next check the section labelled Main F/W Rev:. Release A1.04.00 or later is required for single channel meters; release A2.04.00 or later is required for dual channel meters. For E9300 power sensors with suffix 'B' or 'H', firmware revision A1.06.00 or later is required for single channel meters; revision A2.06.00 or later is required for dual channel meters. If your power meter has an earlier release, please contact your nearest Keysight Service Office (listed on page 63) to arrange an upgrade.

NOTE You can carry out the firmware upgrade yourself if your power meter has the required. Access **http://www.keysight.com/find/powermeters** and click on the link: "**EPM Series E4418B Single-Channel Power Meter**" or "**EPM Series E4419B Dual-Channel Power Meter**". Click the "**Software, Firmware and Drivers**" link and follow the downloading instructions.

Interconnections and Calibration

Connect one end of a Keysight 11730 series sensor cable to the Keysight E-series E9300 power sensor and connect the other end of the cable to the power meter's channel input. Allow a few seconds for the power meter to download the power sensor's calibration table.

CAUTION The Keysight 9304A Sensor is DC coupled. DC voltages in excess of the maximum value (5 Vdc) can damage the sensing diode.

NOTE Ensure power sensors and cables are attached and removed in an indoor environment.

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To carry out a zero and calibration cycle as requested by the power meter proceed as follows:

- Ensure the Keysight E-Series E9300 power sensor is disconnected from any signal source.
- When calibrating Keysight E-Series E9300B or E9301B sensors, first remove the attenuator.
- On the power meter, press Zero Cal, Zero (or Zero A/ Zero B). During zeroing the wait symbol is displayed.
- When the wait period is complete connect the Keysight E-Series power sensor to the power meter's POWER REF output.
- Press Cal (or Cal, Cal A/ Cal B). The wait symbol is again displayed during calibration.

On completion the power meter and sensor are ready to connect to the device under test (DUT). Ensure the attenuator is re-connected to the Keysight E-Series E9300B or E9301B sensors prior to making measurements.

CAUTION The Keysight E-Series E9300B or E9301B sensors should not be operated without the attenuator connected at any time other than for calibration. You must ensure the attenuator is reconnected following calibration.

WARNING **BEFORE CONNECTING THE POWER SENSOR TO OTHER INSTRUMENTS ensure that all instruments are connected to the protective (earth) ground. Any interruption of the protective earth grounding will cause a potential shock hazard that could result in personal injury.**

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The measurement connector (for connection to DUT) is Type-N (male) for all the Keysight E-Series E9300 power sensors. A torque wrench should be used to tighten these connectors. Use a 3/4-inch open-end wrench and torque to 12 in-lb (135 Ncm) for the Type-N connector.

Recommended Calibration Interval

Keysight Technologies recommends a one-year calibration cycle for the E9300 series power sensors.

Specifications

The specifications listed in Chapter 3, "Specifications and Characteristics", are the performance standards or limits against which the power sensor may be tested. These specifications are valid ONLY after proper calibration of the power meter. Refer to the "*Calibration Procedure Using Keysight E-Series Power Sensors*" in your Keysight EPM series power meter *User's Guide*.

Use the plastic flange cover to protect the waveguide connector from dirt and mechanical damage whenever it is not in use. Any burn, dents or dirt on the flange or waveguide surface will increase the SWR and change the Cal Factor.

Refer to the power meter operating and service manual for interconnecting instructions.

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What You'll Find In This Chapter

This Chapter shows you how to use the Keysight E-Series E9300 power sensors to make power measurements on signals with different modulation formats. For all other operations please refer to your Keysight EPM series power meter *User's Guide*.

This chapter contains the following sections:

- "Power Meter Configuration Changes" on page 13
- "Measuring Spread Spectrum and Multitone Signals" on page 14
- "Measuring TDMA Signals" on page 17
- "Electromagnetic Compatibility (EMC) Measurements" on page 19
- "Measurement Accuracy and Speed" on page 20

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Power Meter Configuration Changes

The Keysight EPM series power meter recognizes when a Keysight E-Series E9300 power sensor is connected. The sensor calibration data is automatically read by the power meter. In addition, the Keysight E-Series E9300 power sensors change the auto-averaging settings used by the power meter. These are also automatically configured.

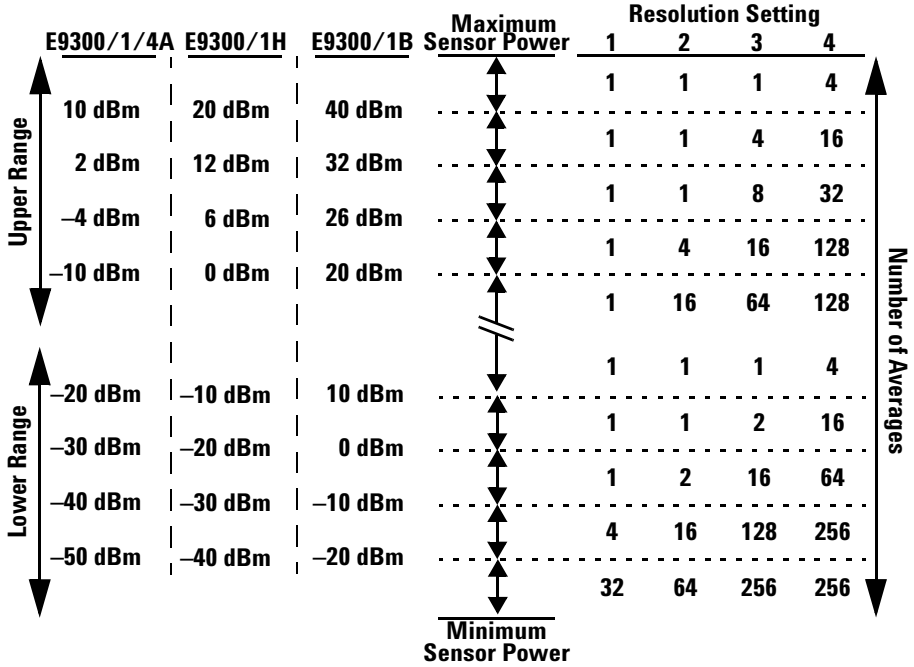


Figure 2-4 Auto-averaging Settings

NOTE

These values are valid only for the power meter channel connected to the Keysight E-Series E9300 power sensor and only while the sensor is connected. Averaging settings can also be manually configured. Refer to "Achieving Stable Results with TDMA Signals" on page 17 if required.

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Measuring Spread Spectrum and Multitone Signals

To achieve high data transfer rates within a given bandwidth, many transmission schemes are based around phase and amplitude (I and Q) modulation. These include CDMA, W-CDMA and digital television. These signals are characterized by their appearance on a spectrum analyzer display – a high amplitude noise-like signal of bandwidths up to 20 MHz. An 8 MHz bandwidth digital television signal is shown in Figure 2-5.

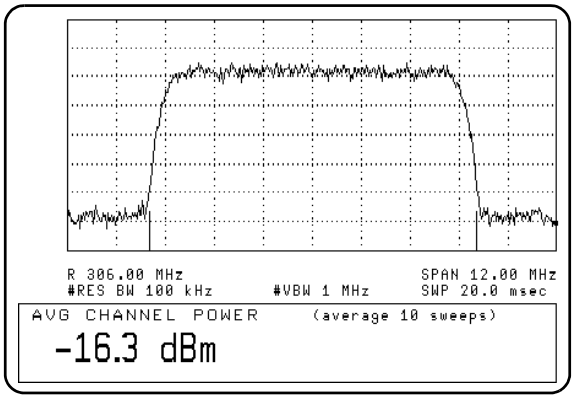


Figure 2-5 Example of an 8 MHz bandwidth digital television signal

Prior to the Keysight E-Series E9300 power sensors, average power measurement over a wide dynamic range of these signals required either tuned/swept signal analyzer methods or a dual channel power meter connected to power sensors, pads and a power splitter.

The diode pair/attenuator/diode pair architecture of the Keysight E-Series E9300 power sensors is ideally suited to the average power measurement of these signals. The sensors have wide dynamic range (80 dB max, sensor dependent) and are bandwidth independent.

Some signal modulation formats such as orthogonal-frequency-division multiplexing (OFDM) and CDMA have large crest factors. The Keysight E-Series E9300/1/4A power sensors can measure +20 dBm average power even in the presence of +13 dB peaks as long as the peak pulse duration is less than 10 microseconds. For high power applications, such as base-station testing the E9300/1B and E9300/1H are recommended.

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CDMA Signal Measurements

Figure 2-6 and Figure 2-7 show typical results obtained when measuring a CDMA signal. In these examples, the error is determined by measuring the source at the amplitude of interest, with and without CDMA modulation, adding attenuation until the difference between the two values stops changing. The CW sensor in Figure 2-6 uses correction factors to correct for power levels beyond its square law operating region.

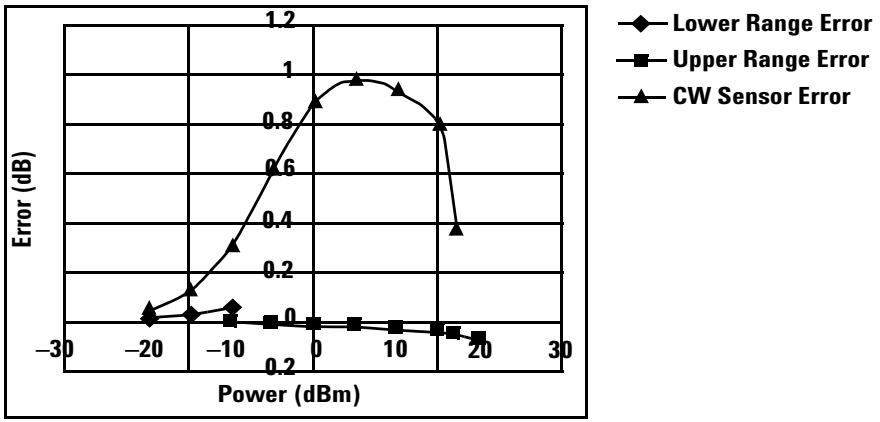


Figure 2-6 Wideband CDMA Error of Keysight E-Series E9300 power sensor versus corrected CW sensor

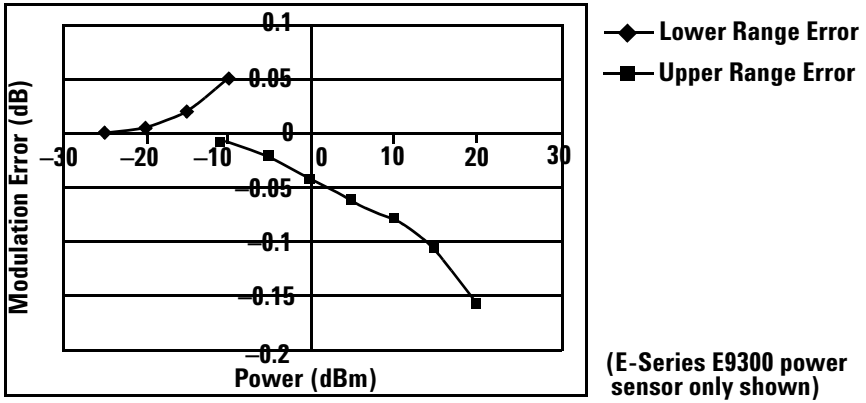


Figure 2-7 CDMA (IS-95A): 9Ch Fwd

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Multitone Signal Measurements

In addition to wide dynamic range, the Keysight E-Series E9300 power sensors also have an exceptionally flat calibration factor versus frequency response across the entire frequency range as shown in Figure 2-8. This is ideal for amplifier intermodulation distortion measurements where the components of the two-tone or multitone test signal can be separated by hundreds of MHz.

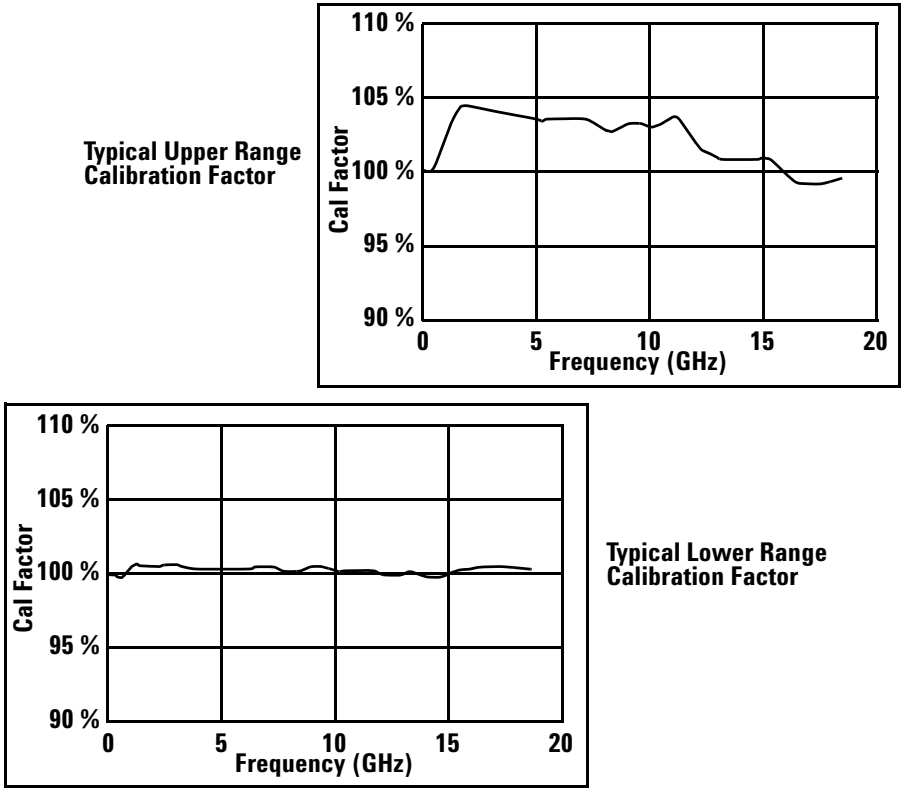


Figure 2-8 Calibration Factors versus Frequency

Simply select an suitable single calibration factor frequency for your measurement using the Frequency Cal Fac key on the power meter.

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Measuring TDMA Signals

Power Meter and Sensor Operation

The voltages generated by the diode detectors in the power sensor can be very small. Gain and signal conditioning are required to allow accurate measurement. This is achieved using a 220 Hz (440 Hz in fast mode) square wave output from the power meter to drive a chopper-amplifier in the power sensor. Digital Signal Processing (DSP) of the generated square wave is used by the power meter to recover the power sensor output and accurately calculate the power level.

The chopper-amplifier technique provides noise immunity and allows large physical distances between power sensor and power meter (Keysight 11730 series cables available up to 61 metres). Additional averaging helps reduce noise susceptibility.

Achieving Stable Results with TDMA Signals

The averaging settings in the power meter are designed to reduce noise when measuring continuous wave (CW) signals. Initial measurement of a pulsed signal may appear unstable with jitter on the less significant displayed digits. With pulsed signals the averaging period must be increased to allow measurement over many cycles of the pulsed signal.

To set the averaging proceed as follows:

NOTE The example shows the key labels for a single channel power meter. Dual channel meter are similar, adding only channel identification to the softkey labels.

1. Press System Inputs, Input Settings, More. Press the Filter softkey to access the filter menu.
2. The filter setting is displayed under the Length softkey label. To change this setting first set manual mode by pressing the Mode Man Auto softkey to highlight Man.
3. Press Length and use the ⇧, ⇩, ⇦ or ⇨ to set the averaging you require. Confirm your entry by pressing Enter.

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NOTE You should also ensure the filter is not reset when a step increase or decrease in power is detected by switching the step detection off.

Switch off step detection as follows:

1 Press System Inputs, Input Settings, More.

2 Press the Filter softkey to access the filter menu.

3 Press Step Det Off On to highlight Off.

The section "Setting the Range, Resolution and Accuracy" in the *Keysight EPM series power meters Programming Guide* shows you how to configure these parameters using the remote interface.

Achieving Stable Results with GSM Signals

Signals with a pulse repetition frequency (PRF) close to a multiple or sub-multiple of the 220 Hz chopper-amplifier signal generate a beat note at a frequency between the PRF and 220 Hz. Control over the filter settings is again required to obtain stable results.

The PRF of a GSM signal is approximately 217 Hz and thus requires more averaging than most other TDMA signals. To achieve a stable measurement use the filter setting procedures to set the Length. Experimentally, a Length setting of 148 gives optimum results although settings in the order of 31 or 32 give acceptable results if a faster measurement is required.

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Electromagnetic Compatibility (EMC) Measurements

The low frequency range of the Keysight 9304A make it the ideal choice for making EMC measurements to CISPR (Comite International Special Perturbations Radioelectriques) requirements, and electromagnetic interference (EMI) test applications such as the radiated immunity test (IEC61000-4-3).

DC coupling of the Keysight 9304A input allows excellent low frequency coverage. However, the presence of any dc voltages mixed with the signal will have an adverse effect on the accuracy of the power measurement - see Figure 3-3 on page 29.

The Keysight 9304A sensor is DC coupled. DC voltages in excess of the maximum value (5 Vdc) can damage the sensing diode.

CAUTION The Keysight 9304A Sensor is DC coupled. DC voltages in excess of the maximum value (5 Vdc) can damage the sensing diode.

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Measurement Accuracy and Speed

The power meter has no internal ranges. The only ranges you can set are those of the Keysight E-Series E9300 power sensors (and other Keysight E-series power sensors). With a Keysight E-Series E9300 power sensor the range can be set either automatically or manually. Use autoranging when you are not sure of the power level you are about to measure.

CAUTION

To prevent damage to your sensor do not exceed the power levels specified in the section "Maximum Power" on page 28.

The Keysight 9304A sensor is DC coupled. DC voltages in excess of the maximum value (5 Vdc) can damage the sensing diode

Setting the Range

There are two manual settings, "LOWER" and "UPPER". The LOWER range uses the more sensitive path and the UPPER range uses the attenuated path in the Keysight E-series E9300 power sensors (see Table 2-1).

Table 2-1 Sensor Ranges

Sensor	LOWER range	UPPER range
E9300/1/4A	–60 dBm to –10 dBm	–10 dBm to +20 dBm
E9300/1B	–30 dBm to +20 dBm	+20 dBm to +44 dBm
E9300/1H-50	–50 dBm to 0 dBm	0 dBm to +30 dBm

The default is "AUTO". In AUTO the range crossover value depends on the sensor model being used (see Table 2-2).

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Table 2-2 Range Crossover Values

E9300/1/4A	E9300/1B	E9300/1H
–10 dBm ± 0.5 dBm	+20 dBm ± 0.5 dBm	0 dBm ± 0.5 dBm

Configure the power meter as follows:

NOTE The example shows the key labels for a single channel power meter. Dual channel meters are similar, adding channel identification to the softkey labels.

1 Press System Inputs, Input Settings. The current setting is displayed under the Range softkey.

2 To change this press Range. A pop up window appears. Use ⇧ or ⇩ to highlight your choice.

To confirm your choice press Enter.

The section "Setting the Range, Resolution and Accuracy" in the Keysight EPM series power meters *Programming Guide* shows you how to configure these parameters using the remote interface.

Measurement Considerations

While autoranging is a good starting point, it is not ideal for all measurements. Signal conditions such as crest factor or duty cycle may cause the power meter to select a range which is not the optimum configuration for your specific measurement needs. Signals with average power levels close to the range switch point require you to consider your needs for measurement accuracy and speed. For example, using a Keysight E9300/1/4A sensor, where the range switch point is –10 ± 0.5 dBm in a pulsed signal configured as follows:

Characteristics	Value
Peak Amplitude	–6 dBm
Duty Cycle	25%

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the calculated average power is –12 dBm.

Accuracy

The value of –12 dBm lies in the lower range of the Keysight E-Series E9300 power sensor. In autoranging mode (“AUTO”) the Keysight EPM Series power meter determines the average power level is below –10 dBm and selects the low power path. However, the peak amplitude of –6 dBm is beyond the specified, square law response range of the low power path diodes.The high power path (–10 dBm to +20 dBm) should be used to ensure a more accurate measurement of this signal. However, range holding in “UPPER” (the high power path), for a more accurate measurement, results in considerably more filtering.

Speed and Averaging

The same signal also requires that consideration is given to measurement speed. As shown above, in autoranging mode the Keysight EPM series power meter selects the low power path in the Keysight E-series E9300 power sensor. With auto-averaging also configured, minimal filtering is applied. Values of 1 to 4 for average power levels above –20 dBm are used in the low power path. (Refer to “Auto-averaging Settings” on page 13.)

If the range is held in “UPPER” for more accuracy, the measurement is slower. More filtering is applied due to the increase in noise susceptibility at the less sensitive area of the high power path. Values of 1 to 128 for average power levels less than –10 dBm are used. (Again, refer to “Auto-averaging Settings” on page 13.) Manually lowering the filter settings speeds up the measurement but can result in an unwanted level of jitter.

Summary

Attention must be paid to signals whose average power levels are in the low power path range whilst their peaks are in the high power path range. You can achieve best accuracy by selecting the high power path or best speed by selecting the low power path.

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3
Specifications and Characteristics

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Introduction

The Keysight E-Series E9300 power sensors are average, wide dynamic range power sensors designed for use with the Keysight EPM Series power meters.

These specifications are valid ONLY after proper calibration of the power meter and apply for continuous wave (CW) signals unless otherwise stated. Specifications apply over the temperature range 0 °C to +55 °C unless otherwise stated.

Specifications quoted over the temperature range 25 °C ± 10 °C apply up to 75% relative humidity and conform to the standard environmental test conditions as defined in TIA/EIA/IS-97-A and TIA/EIA/IS-98-A[1].

The Keysight E-series E9300 power sensors have two independent measurement paths (high and low power paths):

Sensor	Low Power Path	High Power Path
E9300/1/4A	–60 dBm to –10 dBm	–10 dBm to +20 dBm
E9300/1B	–30 dBm to +20 dBm	+20 dBm to +44 dBm
E9300/1H	–50 dBm to 0 dBm	0 dBm to +30 dBm

Some specifications are detailed for individual measurement path, with the automatic switching point at –10 dBm for the E9300/1/4A, 20 dBm for the E9300/1B and 0 dBm for the E9300/1H.

Supplemental characteristics, which are shown in italics, are intended to provide information useful in applying the power sensors by giving typical, but nonwarranted performance parameters. These characteristics are shown in italics or denoted as "*typical*", "*nominal*" or "*approximate*".

1. TIA is the Telecommunications Industry Association; EIA is the Electronic Industries Association.

TIA/EIA/IS-97-A is the recommended Minimum Performance Standard for Base Stations Supporting Dual-Mode Wideband Spread Spectrum Cellular Mobile Stations.
TIA/EIA/IS-98-A is the recommended Minimum Performance Standard for Dual-Mode Wideband Spread Spectrum Cellular Mobile Stations.

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Specification definitions

There are two types of product specifications:

- Warranted specifications
- Characteristic specifications

Warranted specifications

Warranted specifications are covered by the product warranty, and they apply over 0 °C to 55 °C unless otherwise noted. Warranted specifications include measurement uncertainty calculated with a 95% confidence level.

Characteristic specifications

Characteristic specifications are not warranted. They describe product performance that is useful in the application of the power sensors by giving typical but non-warranted performance parameters. These characteristics are shown in *italics* or denoted as "*typical*", "*nominal*", or "*approximate*".

Characteristic information is representative of the product. In many cases, it may also be supplemental to a warranted specification. Characteristic specifications are not verified on all power sensors. The types of characteristic specifications can be placed in two groups:

- The first group of characteristic types describes 'attributes' common to all products of a given model or option.

  Examples of characteristics that describe 'attributes' are product weight and 50 Ω input Type-N connector. In these examples, product weight is an approximate value and a 50 Ω input is *nominal*. These two terms are most widely used when describing a product's 'attributes'.

- The second group of characteristic types describes 'statistically' the aggregate performance of the population of products.

  These characteristics describe the expected behavior of the population of products. They do not guarantee the performance of any individual product. No measurement uncertainty value is accounted for in the specifications. These specifications are referred to as *typical*.

- *Typical plots* are derived from a population mean from production testing. Plot shown may vary from unit to unit and is not warranted.

  For warranted specifications, refer to the individual tables.

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E9300/1/4/A Power Sensor Specifications

Frequency Range

	Frequency Range
E9300A	10 MHz to 18.0 GHz
E9301A	10 MHz to 6.0 GHz
E9304A	9 kHz to 6.0 GHz

Connector Type

Type-N (Male) 50 ohm

Maximum SWR (25 °C ± 10 °C)

	Frequency	SWR
E9300A	10 MHz to 30 MHz	1.15
	30 MHz to 2 GHz	1.13
	2 GHz to 14 GHz	1.19
	14 GHz to 16 GHz	1.22
	16 GHz to 18 GHz	1.26
E9301A	10 MHz to 30 MHz	1.15
	30 MHz to 2 GHz	1.13
	2 GHz to 6 GHz	1.19

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E9304A	9 kHz to 2 GHz	1.13
	2 GHz to 6 GHz	1.19

Maximum SWR (0 °C to +55 °C)

	Frequency	SWR
E9300A	10 MHz to 30 MHz	1.21
	30 MHz to 2 GHz	1.15
	2 GHz to 14 GHz	1.20
	14 GHz to 16 GHz	1.23
	16 GHz to 18 GHz	1.27
E9301A	10 MHz to 30 MHz	1.21
	30 MHz to 2 GHz	1.15
	2 GHz to 6 GHz	1.20
E9304A	9 kHz to 2 GHz	1.15
	2 GHz to 6 GHz	1.20

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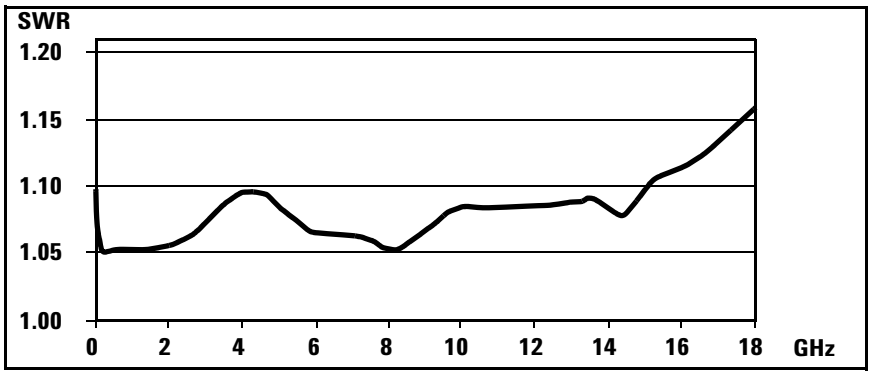


Figure 3-1 Typical SWR 10 MHz to 18 GHz (25 °C ± 10 °C)

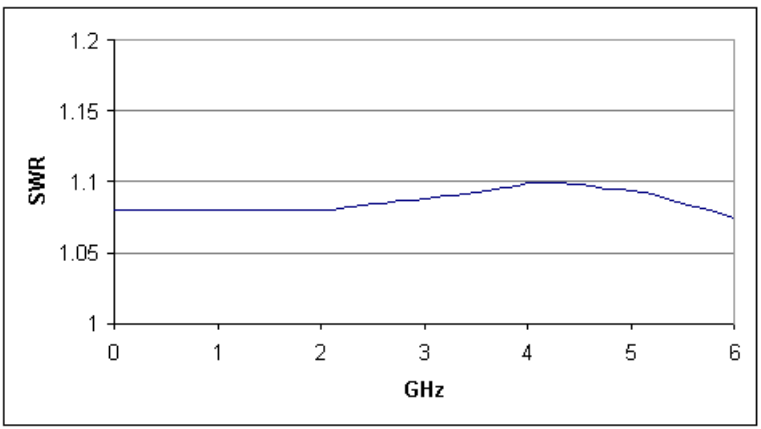


Figure 3-2 Typical SWR 9 kHz to 6 GHz (25 °C ±10 °C) E9304A

Maximum Power

+25 dBm (320 mW) average
+33 dBm peak (2 W) <10 µs

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Maximum DC Voltage

The Keysight E9304A sensor is dc coupled. DC coupling of the input allows excellent low frequency coverage. However, the presence of dc voltages mixed with the signal will have an effect on the accuracy of the power measurement (see Figure 3-3).

CAUTION DC voltages in excess of the maximum value (5 V) can damage the sensing diode.

Maximum dc voltage: 5 Vdc (E9304A only)

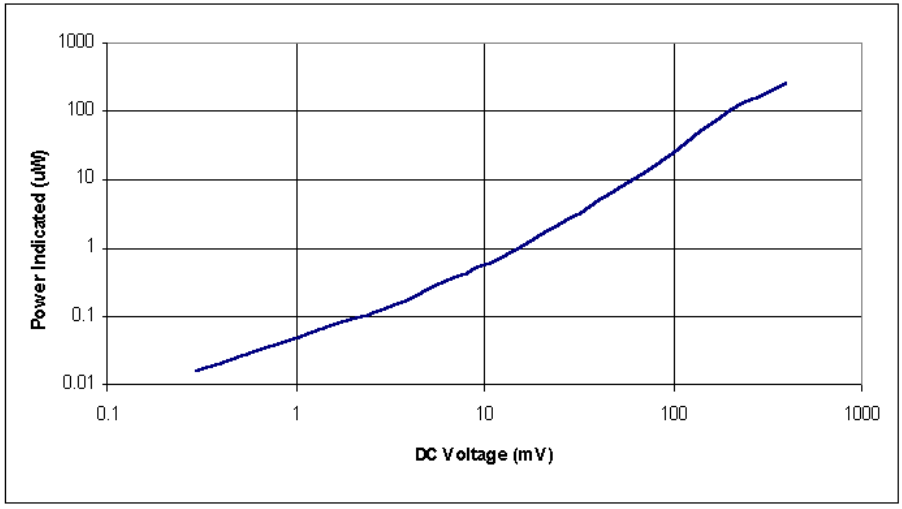


Figure 3-3 Typical Power Error Introduced in a Keysight E9304A power sensor by DC Voltage

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Power Linearity

After Zero and Calibration at ambient environmental conditions.

Power Level	Linearity 25 °C ± 10 °C	Linearity 0 °C to 55 °C
–60 dBm to –10 dBm	± 3.0%	± 3.5%
–10 dBm to 0 dBm	± 2.5%	± 3.0%
0 dBm to +20 dBm	± 2.0%	± 2.5%

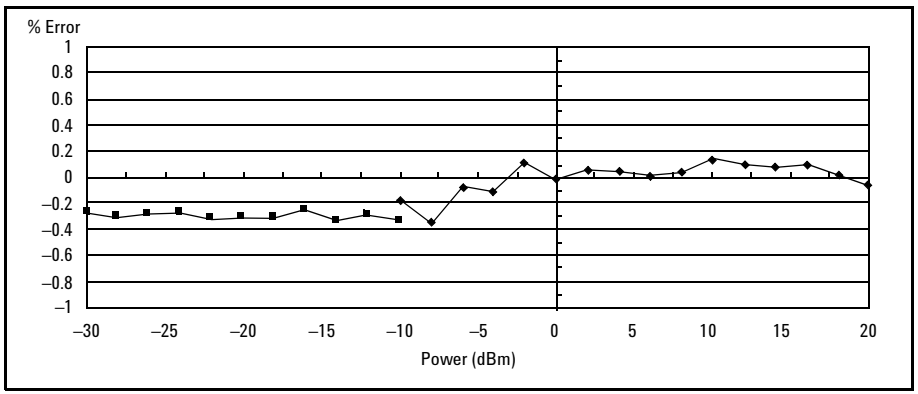


Figure 3-4 Typical Power Linearity at 25 °C, after zero and calibration, with associated Measurement Uncertainty

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	–30 to –20 dBm	–20 to –10 dBm	–10 to 0 dBm	0 to 10 dBm	10 to 20 dBm
Measurement Uncertainty	*±0.9%*	*±0.8%*	*±0.65%*	*±0.55%*	*±0.45%*

NOTE

If the temperature changes after calibration and you choose not to re-calibrate the sensor, Additional Power Linearity Error (next table) should be added to the Power Linearity specifications shown above. The typical maximum Additional Power Linearity error due to temperature change after calibration at 25 °C, for small changes in temperature, is ±0.15%/°C (valid after zeroing the sensor).

For larger changes refer to the following table.

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Additional Power Linearity Error Due to Change in Temperature

Power Level	Additional Power Linarity Error 25 °C ± 10 °C	Additional Power Linearity Error 0 °C to 55 °C
–60 dBm to –10 dBm	*±1.5%*	*±2.0%*
–10 dBm to +10 dBm	*±1.5%*	*±2.5%*
+10 dBm to +20 dBm	*±1.5%*	*±2.0%*

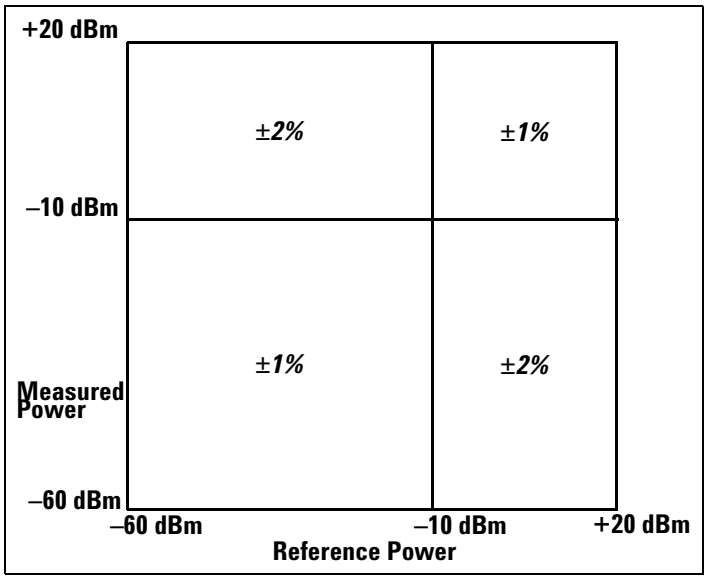


Figure 3-5 Relative Mode Power Measurement Linearity with Keysight EPM power meter at 25 °C ±10 °C (typical)

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Figure 3-5 shows the typical uncertainty in making a relative power measurement, using the same power meter channel and same power sensor to obtain the reference and the measured values. It assumes that negligible changes in frequency and mismatch error occur when transitioning from the power level used as the reference to the power level being measured.

Switching Point

The Keysight E-Series E9300 power sensors have two paths, a low power path covering –60 dBm to –10 dBm, and a high power path covering –10 dBm to +20 dBm. The power meter automatically selects the proper power level path. To avoid unnecessary switching when the power level is near the –10 dBm point, **Switching Point Hysteresis** has been added. This hysteresis causes the low power path to remain selected until approximately –9.5 dBm as the power level is increased, above this power the high power path is selected.The high power path remains selected until approximately –10.5 dBm as the signal level decreases, below this power the low power path is selected.

	Error
Offset at Switch Point	*≤±0.5% (≤±0.02 dB) typical*
Switching Point Hysteresis	*0.5 dB typical*

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Zero Set, Zero Drift and Measurement Noise

	Conditions (RH)[1]	Zero Set	Zero Drift[2]	Measurement Noise[3]
Lower Range	Up to 75%	500 pW	*150 pW*	*700 pW*
(–60 to –10 dBm)	75% to 95%	500 pW	*4,000 pW*	*700 pW*
Upper Range	Up to 75%	500 nW	*150 nW*	*500 nW*
(–10 to +20 dBm)	75% to 95%	500 nW	*3,000 nW*	*500 nW*

1. RH is the abbreviation for Relative Humidity.

2. Within 1 hour after zero set, at a constant temperature, after a 24 hour warm-up of the power meter with sensor connected.

3. The number of averages at 16 for **Normal** mode and 32 for **x2** mode, at a constant temperature, measured over a one minute interval and two standard deviations.

Settling Time

In **FAST** mode (using Free Run trigger), for a 10 dB decreasing power step, the settling time is:

	Time
E4418B	*10 ms*[1]
E4419B	*20 ms*[1]

1. When a power step crosses the auto-range switch point of the sensor, add 25 ms.

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Number of Averages	1	2	4	8	16	32	64	128	256	512	1,024
Settling Time[1] (s) (Normal Mode)	*0.07*	*0.12*	*0.21*	*0.4*	*1.0*	*1.8*	*3.3*	*6.5*	*13*	*27*	*57*
Settling Time[a] (s) (x2 Mode)	*0.04*	*0.07*	*0.12*	*0.21*	*0.4*	*1.0*	*1.8*	*3.4*	*6.8*	*14.2*	*32*

1. Manual filter, 10 dB decreasing power step (not across the switching point)

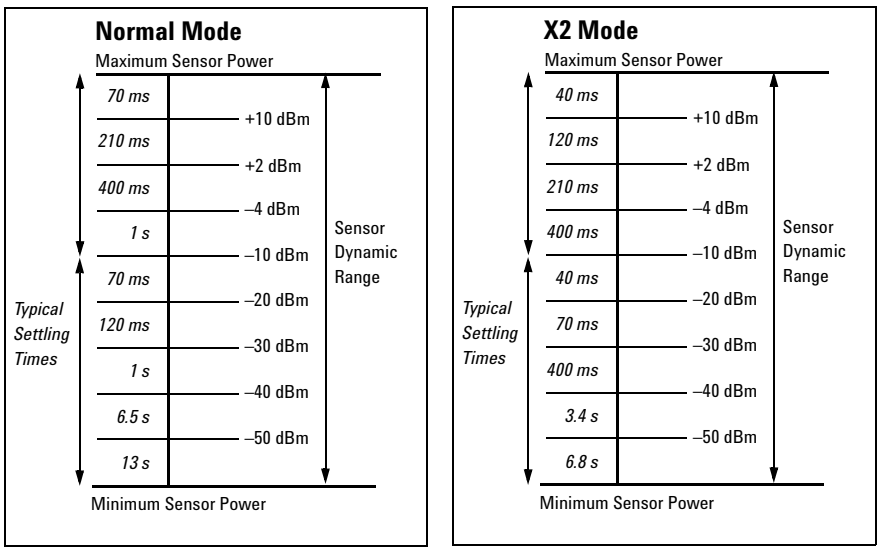


Figure 3-6 Autofilter, default resolution, 10 dB decreasing power step (not across the switching point)

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Calibration Factor and Reflection Coefficient

Calibration Factor (CF) and Reflection Coefficient (Rho) data are provided on a data sheet included with the power sensor. This data is unique to each sensor. If you have more than one sensor, match the serial number on the data sheet with the serial number on the power sensor you are using. The CF corrects for the frequency response of the sensor. Keysight EPM series power meters automatically read the CF data stored in the sensor and use it to make the corrections.

Reflection Coefficient (Rho, or ρ) relates to the SWR according to the following formula:

$$SWR = \frac{1+\rho}{1-\rho}$$

Typical CF data are listed in the following tables. As the Keysight E-Series E9300 power sensors have two independant measurement paths (high and low power paths), there are two calibration factor uncertainty tables for each sensor. The undertainty analysis for the calibration of the sensors was done in accordance with ISO Guide. The uncertainty data reported on the calibration cerfiticate is the expanded uncertainty with a 95% confidence level and a coverage factor of 2.

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Cal Factor Uncertainty (Lower Power Path, –60 to –10 dBm)

Frequency	Uncertainty (25 °C ± 10 °C)			Uncertainty (0 °C to 55 °C)		
	E9300A	E9301A	E9304A	E9300A	E9301A	E9304A
9 kHz to 10 MHz	-	-	±1.7%	-	-	±2.0%
10 MHz to 30 MHz	±1.8%	±1.8%	±1.7%	±2.2%	±2.2%	±2.0%
30 MHz to 500 MHz	±1.6%	±1.6%	±1.7%	±2.0%	±2.0%	±2.0%
500 MHz to 1.2GHz	±1.8%	±1.8%	±1.7%	±2.5%	±2.5%	±2.0%
1.2 GHz to 6 GHz	±1.7%	±1.7%	±1.7%	±2.0%	±2.0%	±2.0%
6 GHz to 14 GHz	±1.8%	-	-	±2.0%	-	-
14 GHz to 18 GHz	±2.0%	-	-	±2.2%	-	-

Cal Factor Uncertainty (High Power Path, –10 to +20 dBm)

Frequency	Uncertainty (25 °C ± 10 °C)			Uncertainty (0 °C to 55 °C)		
	E9300A	E9301A	E9304A	E9300A	E9301A	E9304A
9 kHz to 10 MHz	-	-	±2.0%	-	-	±3.4%
10 MHz to 30 MHz	±2.1%	±2.1%	±2.0%	±4.0%	±4.0%	±3.4%
30 MHz to 500 MHz	±1.8%	±1.8%	±2.0%	±3.0%	±3.0%	±3.4%
500 MHz to 1.2GHz	±2.3%	±2.3%	±2.2%	±4.0%	±4.0%	±3.4%
1.2 GHz to 6 GHz	±1.8%	±1.8%	±1.8%	±2.1%	±2.1%	±2.1%
6 GHz to 14 GHz	±1.9%	-	-	±2.3%	-	-
14 GHz to 18 GHz	±2.2%	-	-	±3.3%	-	-

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General

	Physical Characteristics
Net Weight	0.18 kg (0.4 lb)
Dimensions	Length: 130 mm (5.1 in) Width: 38 mm (1.5 in) Height: 30 mm (1.2 in)

	Storage and Shipment
Environment	The sensor should be stored in a clean, dry environment
Temperature	–55 °C to +75 °C
Relative Humidity	<95% at 40 °C
Altitude	<15,240 metres (50,000 feet)

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E9300/1B and H Power Sensor Specifications

Frequency Range

	Frequency Range
E9300B/H	10 MHz to 18.0 GHz
E9301B/H	10 MHz to 6.0 GHz

Connector Type

Type -N (Male) 50 ohm

Maximum SWR (25 °C ± 10 °C)

	Frequency	SWR
E9300B	10 MHz to 2 GHz	1.12
	2 GHz to 12.4 GHz	1.17
	12.4 GHz to 18 GHz	1.24
E9301B	10 MHz to 6 GHz	1.12
E9300H	10 MHz to 8 GHz	1.15
	8 GHz to 12.4 GHz	1.25
	12.4 GHz to 18 GHz	1.28
E9301H	10 MHz to 6 GHz	1.15

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Maximum SWR (0 °C to +55 °C)

	Frequency	SWR
E9300B	10 MHz to 2 GHz	1.14
	2 GHz to 12.4 GHz	1.18
	12.4 GHz to 18 GHz	1.25
E9301B	10 MHz to 6 GHz	1.14
E9300H	10 MHz to 8 GHz	1.17
	8 GHz to 12.4 GHz	1.26
	12.4 GHz to 18 GHz	1.29
E9301H	10 MHz to 6 GHz	1.17

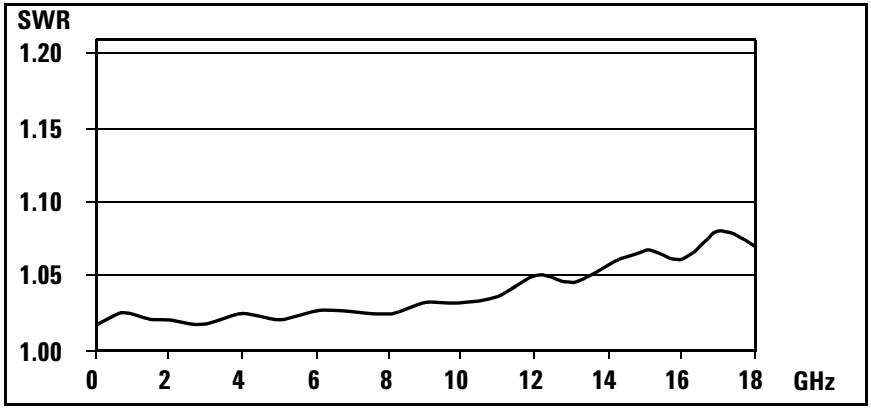


Figure 3-7 E9300B Typical SWR (25 °C ± 10 °C)

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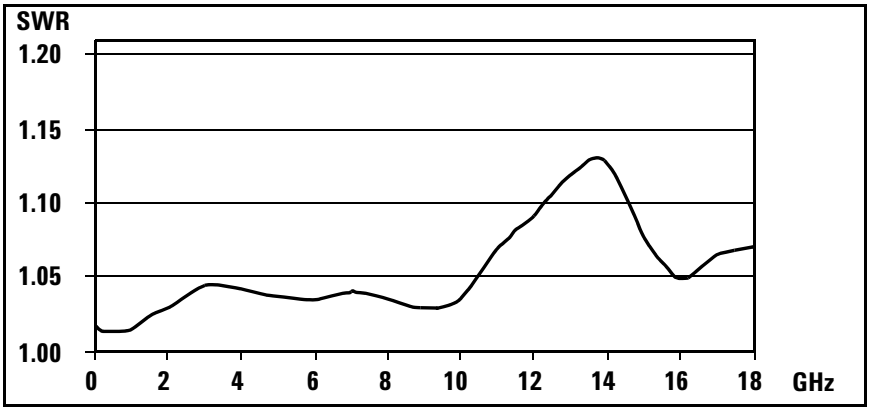


Figure 3-8 E9300H Typical SWR 10 MHz to 18 GHz (25 °C ± 10 °C)

Maximum Power

	Maximum Power			
Sensor	**0 °C to 35 °C**	**35 °C to 55 °C**	**<6.0 GHz**	**>6.0 GHz**
E9300/1B	30 W average 500 Wµs per pulse	25 W average 500 Wµs per pulse	500 W Peak 500 Wµs per pulse	125 W Peak 500 Wµs per pulse
E9300/1H	3.16 W average 100 Wµs per pulse	3.16 W average 100 Wµs per pulse	100 W Peak 100 Wµs per pulse	100 W Peak 100 Wµs per pulse

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Power Linearity

After Zero and Calibration at ambient environmental conditions.

Sensor	Power Level	Linearity 25 °C ± 10 °C	Linearity 0 °C to 55 °C
E9300/1B	–30 dBm to +20 dBm	±3.5%	±4.0%
	+20 dBm to +30 dBm	±3.0%	±3.5%
	+30 dBm to +44 dBm	±2.5%	±3.0%
E9300/1H	–50 dBm to 0 dBm	±4.0%	±5.0%
	0 dBm to +10 dBm	±3.5%	±4.0%
	+10 dBm to +30 dBm	±3.0%	±3.5%

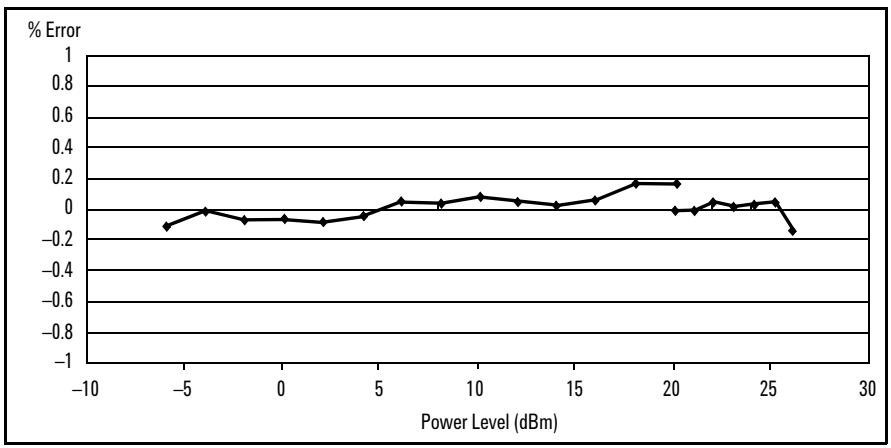


Figure 3-9 E9300B Typical Power Linearity at 25 °C, after zero and calibration with associated Measurement Uncertainty

E9300/1B	–6 to 0 dBm	0 to 10 dBm	10 to 20 dBm	20 to 26 dBm
Measurement Uncertainty	*±0.65%*	*±0.55%*	*±0.45%*	*±0.31%*

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See Note on page 44.

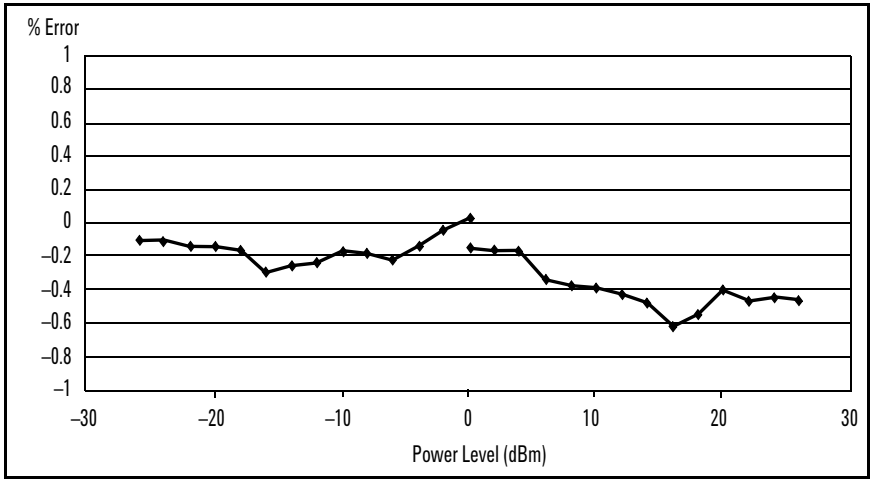


Figure 3-10 E9300H Typical Power Linearity at 25 °C, after zero and calibration with associated Measurement Uncertainty

E9300/1H	–26 to –20 dBm	–20 to –10 dBm	–10 to 0 dBm	0 to 10 dBm	10 to 20 dBm	20 to 26 dBm
Measurement Uncertainty	*±0.9%*	*±0.8%*	*±0.65%*	*±0.55%*	*±0.45%*	*±0.31%*

NOTE

If the temperature changes after calibration and you choose not to re-calibrate the sensor, Additional Power Linearity Error (next table) should be added to the Power Linearity specifications shown above. The typical maximum Additional Power Linearity error due to temperature change after calibration at 25 °C, for small changes in temperature, is ±0.2%/°C (valid after zeroing the sensor).

For larger changes refer to the following table.

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Additional Power Linearity Error due to Change in Temperature

Sensor	Power Level	Additional Power Linearity Error 25 °C ± 10 °C	Additional Power Linearity Error 0 °C to 55 °C
E9300/1B	–30 dBm to +20 dBm	*±1.5%*	*±2.0%*
	+20 dBm to +30 dBm	*±1.5%*	*±2.5%*
	+30 dBm to +44 dBm	*±1.5%*	*±2.0%*
E9300/1H	–50 dBm to 0 dBm	*±1.5%*	*±2.0%*
	0 dBm to +10 dBm	*±1.5%*	*±2.5%*
	+10 dBm to +30 dBm	*±1.5%*	*±2.0%*

Figure 3-11 shows the typical uncertainty in making a relative power measurement, using the same power meter channel and same power sensor to obtain the reference and measured values. It assumes that negligible changes in frequencies and mismatch error occur when transitioning from the power level used as the reference to the power level being measured.

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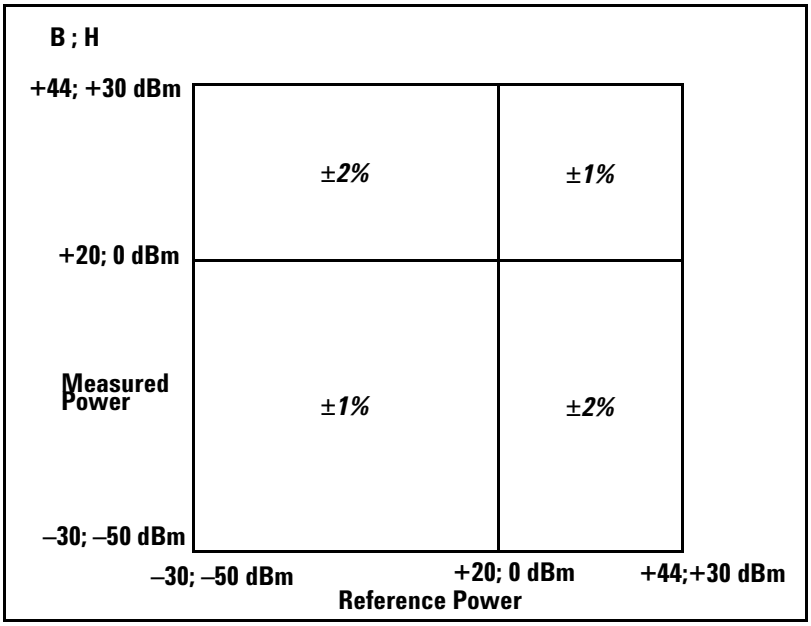


Figure 3-11 Relative Mode Power Measurement Linearity with Keysight EPM power meter at 25 °C ± 10 °C (typical)

Switching Point

The Keysight E-Series E9300 power sensors have two paths, a lower path and a higher path. The power meter automatically selects the proper power level path. To avoid unnecessary switching when the power level is near the switch point, **Switching Point Hysteresis** has been added. This hysteresis causes the low power path to remain selected until approximately 0.5 dB above the switch point as the power level is increased. Above this power, the high power path is selected. The high power path remains selected until approximately 0.5 dB below the switch point as the signal level decreases. Below this power, the lower path is selected. 0 dBm is the switch point for the E9300/01B sensors while the E9300/01H sensors switch at 20 dBm.

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	Error
Offset at Switch Point	*≤±0.5% (≤±0.02 dB) typical*
Switching Point Hysteresis	*0.5 dB typical*

E9300/1B	Conditions (RH)[1]	Zero Set	Zero drift[2]	Measurement Noise[3]
Lower Range	Up to 75%	500 nW	*150 nW*	*700 nW*
(–30 to +20 dBm)	75% to 95%	500 nW	*4 µW*	*700 nW*
Upper Range	Up to 75%	500 µW	*150 µW*	*500 µW*
(+20 to +44 dBm)	75% to 95%	500 µW	*3000 mW*	*500 µW*
E9300/1H				
Lower Range	Up to 75%	5 nW	*1.5 nW*	*7 nW*
(–50 to 0 dBm)	75% to 95%	5 nW	*40 µW*	*7 nW*
Upper Range	Up to 75%	5 µW	*1.5 µW*	*5 µW*
(0 to +30 dBm)	75% to 95%	5 µW	*30 mW*	*5 µW*

1 RH is the abbreviation for Relative Humidity.
2 Within 1 hour after zero set, at a constant temperature, after a 24 hour warm-up of the power meter with sensor connected.
3 The number of averages at 16 for **Normal** mode and 32 for **x2** mode, at a constant temperature, measured over a one minute interval and two standard deviations.

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Settling Time

In **FAST** mode (using Free Run trigger), for a 10 dB decreasing power step, the settling time is:

	Time
E4418B	*10 ms*[1]
E4419B	*20 ms*[1]

1. When a power step crosses the auto-range switch point of the sensor, add 25 ms.

Number of Averages	1	2	4	8	16	32	64	128	256	512	1,024
Settling Time(s) (Normal Mode)	*0.07*	*0.12*	*0.21*	*0.4*	*1.0*	*1.8*	*3.3*	*6.5*	*13*	*27*	*57*
Settling Time[a] (s) (x2 Mode)	*0.04*	*0.07*	*0.12*	*0.21*	*0.4*	*1.0*	*1.8*	*3.4*	*6.8*	*14.2*	*32*

1. Manual filter, 10 dB decreasing power step (not across the switching point)

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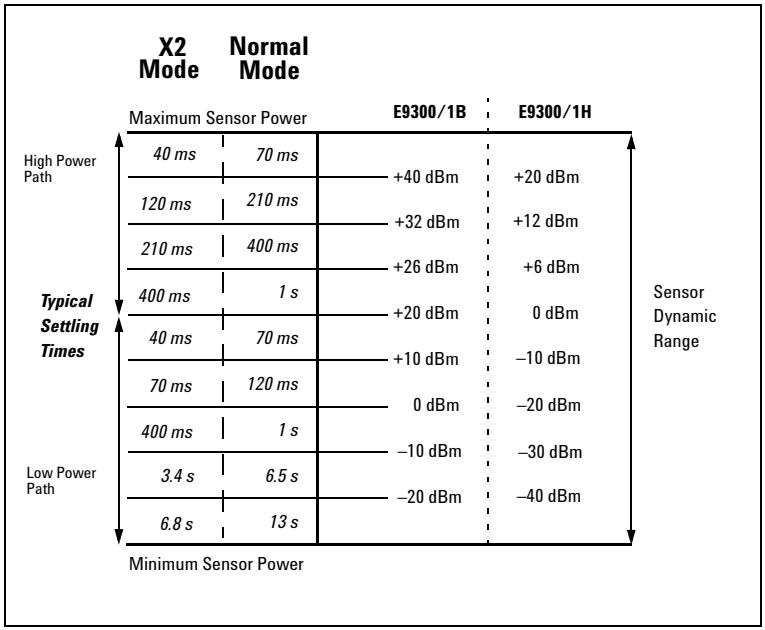


Figure 3-12 E9300/1B & H Autofilter, default resolution, 10 dB decreasing power step (not across the switching point)

Calibration Factor and Reflection Coefficient

Calibration Factor (CF) and Reflection Coefficient (Rho) data are provided on a data sheet included with the power sensor. This data is unique to each sensor. If you have more than one sensor, match the serial number on the data sheet with the serial number on the power sensor you are using. The CF corrects for the frequency response of the sensor. The Keysight EPM Series power meters automatically read the CF data stored in the sensor and use it to make the corrections.

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Reflection Coefficient (Rho, or ρ) relates to the SWR according to the following formula:

$$SWR = \frac{1+\rho}{1-\rho}$$

Typical CF data are listed in the following tables. As the Keysight E-Series E9300 power sensors have two independent measurement paths (high and low power paths), there are two calibration factor uncertainty tables for each sensor. The uncertainty analysis for the calibration of the sensors was done in accordance with ISO Guide. The uncertainty data reported on the calibration certificate is the expanded uncertainty with a 95% confidence level and coverage factor of two.

Cal Factor Uncertainty (Low Power Path)

Frequency	Uncertainty (25 °C ± 10 °C)				Uncertainty (0 °C to 55 °C)			
	E9300B	E9301B	E9300H	E9301H	E9300B	E9301B	E9300H	E9301H
10 MHz to 30 MHz	±1.8%	±1.8%	±1.8%	±1.8%	±2.2%	±2.2%	±2.2%	±2.2%
30 MHz to 500 MHz	±1.6%	±1.6%	±1.6%	±1.6%	±2.0%	±2.0%	±2.0%	±2.0%
500 MHz to 1.2 GHz	±1.8%	±1.8%	±1.8%	±1.8%	±2.5%	±2.5%	±2.5%	±2.5%
1.2 GHz to 6 GHz	±1.7%	±1.7%	±1.7%	±1.7%	±2.0%	±2.0%	±2.0%	±2.0%
6 GHz to 14 GHz	±1.8%	-	±1.8%		±2.0%	-	±2.0	-
14 GHz to 18 GHz	±2.0%	-	±2.0%		±2.2%	-	±2.2	-

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Cal Factor Uncertainty (High Power Path)

Frequency	Uncertainty (25 °C ± 10 °C)				Uncertainty (0 °C to 55 °C)			
	E9300B	E9301B	E9300H	E9301H	E9300B	E9301B	E9300H	E9301H
10 MHz to 30 MHz	±2.1%	±2.1%	±2.6%	±2.6%	±4.0%	±4.0%	±5.0%	±5.0%
30 MHz to 500 MHz	±1.8%	±1.8%	±2.3%	±2.3%	±3.0%	±2.0%	±3.5%	±3.5%
500 MHz to 1.2 GHz	±2.3%	±2.3%	±2.8%	±2.8%	±4.0%	±4.0%	±4.5%	±4.5%
1.2 GHz to 6 GHz	±1.8%	±1.8%	±2.3%	±2.3%	±2.1%	±2.1%	±2.6%	±2.6%
6 GHz to 14 GHz	±1.9%	-	±2.4%		±2.3%	-	±2.8	-
14 GHz to 18 GHz	±2.2%	-	±2.7%		±3.3%	-	±3.8	-

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General Characteristics

	Physical Characteristics	
	E9300/1B	E9300/1H
Net Weight	0.8 kg (1.74 lb)	0.2 kg (0.5 lb)
Dimensions	Length: 275 mm (10.8 in) Width: 115 mm (4.5 in) Height: 82 mm (3.2 in)	Length: 172 mm (6.8 in) Width: 38 mm (1.5 in) Height: 30 mm (1.2 in)

	Storage and Shipment
Environment	The sensor should be stored in a clean, dry environment
Temperature	–55 °C to +75 °C
Relative Humidity	<95% at 40 °C
Altitude	<15,240 metres (50,000 feet)

References

TIA is the Telecommunications Industry Association; EIA is the Electronic Industries Association.

TIA/EIA/IS-97-A is the Recommended Minimum Performance Standards for Base Stations Supporting Dual-Mode Wideband Spread Spectrum Cellular Mobile Stations.

TIA/EIA/IS-98-A is the Recommended Minimum Performance Standards for Dual-Mode Wideband Spread Spectrum Cellular Mobile Stations.

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4
Service

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Performance Test 53
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General Information

This chapter contains information about general maintenance, performance tests, troubleshooting and repair of Keysight E-Series E9300 power sensors.

Cleaning

Use a clean, damp cloth to clean the body of the Keysight E-Series E9300 power sensor.

Connector Cleaning

CAUTION The RF connector beads deteriorate when contacted by hydrocarbon compounds such as acetone, trichloroethylene, carbon tetrachloride, and benzene.

CAUTION Clean the connector only at a static free workstation. Electrostatic discharge to the center pin of the connector will render the power sensor inoperative.

Keeping in mind its flammable nature; a solution of pure isopropyl or ethyl alcohol can be used to clean the connector.

Clean the connector face using a cotton swab dipped in isopropyl alcohol. If the swab is too big use a round wooden toothpick wrapped in a lint free cotton cloth dipped in isopropyl alcohol. Refer to Keysight Application Note 326, *Principles of Microwave Connector Care (5954- 1566)* or *Microwave Connector Care (08510- 90064)* for proper cleaning methods.

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Performance Test

Standing Wave Ratio (SWR) and Reflection Coefficient (Rho) Performance Test

This section does not establish preset SWR test procedures since there are several test methods and different equipment available for testing the SWR or reflection coefficient. Therefore, the actual accuracy of the test equipment must be accounted for when measuring against instrument specifications to determine a pass or fail condition. The test system used must not exceed the system Rho uncertainties shown in the following tables when testing the Keysight E-Series E9300 power sensors.

Table 4-3 Power Sensor SWR and Reflection Coefficient for the E9300A

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
10 MHz to 30 MHz	±0.010		0.070
30 MHz to 2 GHz	±0.010		0.061
2 GHz to 14 GHz	±0.010		0.087
14 GHz to 16 GHz	±0.010		0.099
16 GHz to 18 GHz	±0.010		0.115

Table 4-4 Power Sensor SWR and Reflection Coefficient for the E9301A

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
10 MHz to 30 MHz	±0.010		0.070
30 MHz to 2 GHz	±0.010		0.061
2 GHz to 6 GHz	±0.010		0.087

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CAUTION DC voltages in excess of the maximum value (5 Vdc) can damage the sensing diode.

Table 4-5 Power Sensor SWR and Reflection Coefficient for the E9304A

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
9 kHz to 2 GHz	±0.010		0.061
2 GHz to 6 GHz	±0.010		0.087

Table 4-6 Power Sensor SWR and Reflection Coefficient for the E9300A

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
10 MHz to 8 GHz	±0.010		0.057
8 GHz to 12.4GHz	±0.010		0.078
12.4 GHz to 18 GHz	±0.010		0.107

Table 4-7 Power Sensor SWR and Reflection Coefficient for the E9301B

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
10 MHz to 6 GHz	±0.010		0.057

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Table 4-8 Power Sensor SWR and Reflection Coefficient for the E9300H

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
10 MHz to 8 GHz	±0.010		0.070
8 GHz to 12.4GHz	±0.010		0.111
12.4 GHz to 18 GHz	±0.010		0.123

Table 4-9 Power Sensor SWR and Reflection Coefficient for the Keysight E9301H

Frequency	System Rho Uncertainty	Actual Measurement	Maximum Rho
10 MHz to 6 GHz	±0.010		0.070

Replaceable Parts

Figure 4-1 is the illustrated parts breakdown (IPB) that identifies all of the replaceable parts. To order a part, quote the Keysight part number, specify the quantity required, and address the order to the nearest Keysight office.

Within the USA, it is better to order directly from the Keysight Parts Center in Roseville, California. Ask your nearest Keysight office for information and forms for the “Direct Mail Order System.” Also your nearest Keysight office can supply toll free telephone numbers for ordering parts and supplies.

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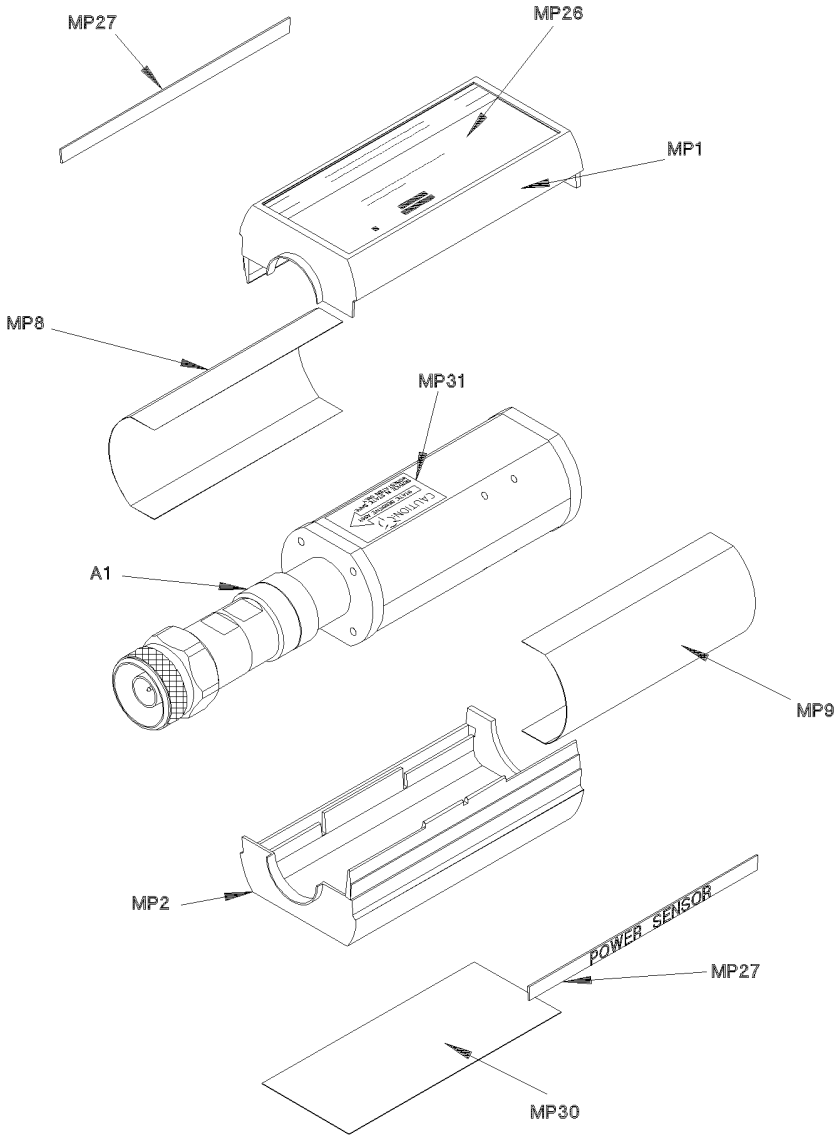


Figure 4-1 Illustrated Parts Break down

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NOTE The A1/A2 parts are applicable only for Keysight Service Center as calibration is required.

Reference Designation	Keysight Part Number	Qty	Description
A1/A2			
E9300A	E9300-60006	1	SENSOR MODULE
E9300B	E9300-60017	1	SENSOR MODULE
E9300H	E9300-60018	1	SENSOR MODULE
E9301A	E9301-60007	1	SENSOR MODULE
E9301B	E9301-60001	1	SENSOR MODULE
E9301H	E9301-60002	1	SENSOR MODULE
E9304A	E9304-60003	1	SENSOR MODULE
A1/A2			
E9300A	E9300-69006	1	RESTORED SENSOR MODULE
E9300B	E9300-69017	1	RESTORED SENSOR MODULE[1]
E9300H	E9300-69018	1	RESTORED SENSOR MODULE
E9301A	E9301-69007	1	RESTORED SENSOR MODULE
E9301B	E9301-69001	1	RESTORED SENSOR MODULE[1]
E9301H	E9301-69002	1	RESTORED SENSOR MODULE
E9304A	E9304-69003	1	RESTORED SENSOR MODULE
CHASSIS PARTS			
MP1	5041-9160	2	SHELL-PLASTIC
MP2	5041-9160		SHELL-PLASTIC
MP3	08481-20011	2	CHASSIS
MP4	08481-20011		CHASSIS
MP8	08481-00002	2	SHIELD
MP9	08481-00002		SHIELD
MP26	E9300-80001	1	LABEL, ID E9300A
MP26	E9300-80002	1	LABEL, ID E9300B

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Reference Designation	Keysight Part Number	Qty	Description
MP26	E9300-80003	1	LABEL, ID E9300H
MP26	E9301-80001	1	LABEL, ID E9301A
MP26	E9301-80003	1	LABEL, ID E9301B
MP26	E9301-80002	1	LABEL, ID E9301H
MP26	E9304-80001	1	LABEL, ID E9304A
MP27	7121-7389	2	LABEL, POWER SENSOR
MP30	7121-7388	1	LABEL, CAL/ESD
MP30	E9304-80002	1	LABEL, CAUTION E9304A
MP31	00346-80011	1	LABEL, CAUTION

[1] Includes attenuator assembly

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Service

Service instructions consist of principles of operation, troubleshooting, and repairs.

Principles of Operation

The A1 Bulkhead assembly on the Keysight E-Series E9300 power sensors provides a 50 ohm load to the RF signal applied to the power sensor. The A1 Bulkhead assembly on the E9300/1B sensors includes a 30 dB attenuator that can be disconnected by means of a Type-N connector. The A1 Bulkhead assembly on the E9300/1H sensors includes a 10 dB attenuator in the front end. A dual range GaAs diode pair/attenuator/diode pair assembly in the bulkhead rectifies the applied RF to produce dc voltages (high and low ranges) which vary with the RF power across the 50 Ω load. Thus the voltage varies with the RF power dissipated in the load.

The low-level dc voltages from the bulkhead assembly are amplified before they are transferred on standard cables to the power meter. The amplification is provided by an input amplifier assembly which consists of a chopper (sampling gate) and an input amplifier. The chopper circuit converts the dc voltages to ac voltages. The chopper is controlled by a 220 Hz square wave generated by the power meter. The amplitude of the sampling gate output is a 220 Hz square wave which varies with the RF power input. The 220 Hz ac output is applied to an amplifier which provides the input to the power meter.

The Keysight EPM series power meter automatically detects when a Keysight E-Series E9300 power sensor is connected and downloads the correction data from the sensor's EEPROM. In the E9300/1B/H the EEPROM contains an offset value for the measured attenuation value of the attenuator used in the bulkhead assembly. Thus, the attenuator is matched to a particular sensor. The auto-averaging settings are also configured automatically for use with Keysight E-Series E9300 power sensors. This configures the power meter to operate over the range with that particular sensor's unique correction data applied.

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Troubleshooting

Troubleshooting information is intended to first isolate the power sensor, the cable, or the power meter as the defective component. When the power sensor is isolated, an appropriate Sensor Module must be used for repair.

If error message 241 or 310 is indicated on the power meter, suspect a failed power sensor. If no error message is displayed, but a problem occurs when making a measurement, try replacing the cable from the power meter to the power sensor. If the problem still exists, try using a different power sensor to determine if the problem is in the power meter or in the power sensor.

CAUTION Electrostatic discharge will render the power sensor inoperative. Do not, under any circumstances, open the power sensor unless you and the power sensor are in a static free environment.

Repair of Defective Sensor

There are no serviceable parts inside the Keysight E-Series E9300 power sensors. If the sensor is defective, replace the entire “module” with the appropriate “Restored Sensor Module.”

Disassembly Procedure

Disassemble the power sensor by performing the following steps:

CAUTION Disassemble the power sensor only in a static free workstation. Electrostatic discharge will render the power sensor inoperative.

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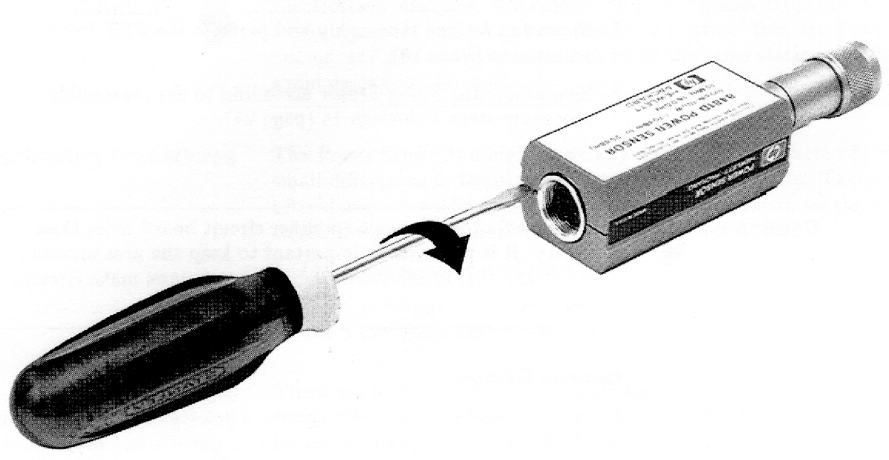


Figure 4-2 Removing Power Sensor Shell

1 At the rear of the power sensor, insert the blade of a screwdriver between the plastic shells (See Figure 4-2). To prevent damage to the plastic shells use a screwdriver blade as wide as the slot between the two shells.

2 Pry alternately at both sides of the connector J1 until the plastic shells are apart. Remove the shells and the magnetic shields.

Reassembly Procedure

Replace the magnetic shields and the plastic shells as shown in Figure 4-1. Snap the plastic shells together.

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