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PXI

NI PXI-6682 User Manual

Timing and Synchronization Module for PXI

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Compliance with FCC/Canada Radio Frequency Interference Regulations

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All Class A products display a simple warning statement of one paragraph in length regarding interference and undesired operation. The FCC rules have restrictions regarding the locations where FCC Class A products can be operated.

Consult the FCC Web site at `www.fcc.gov` for more information.

FCC/DOC Warnings

This equipment generates and uses radio frequency energy and, if not installed and used in strict accordance with the instructions in this manual and the CE marking Declaration of Conformity*, may cause interference to radio and television reception. Classification requirements are the same for the Federal Communications Commission (FCC) and the Canadian Department of Communications (DOC).

Changes or modifications not expressly approved by NI could void the user's authority to operate the equipment under the FCC Rules.

Class A

Federal Communications Commission

This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference when the equipment is operated in a commercial environment. This equipment generates, uses, and can radiate radio frequency energy and, if not installed and used in accordance with the instruction manual, may cause harmful interference to radio communications. Operation of this equipment in a residential area is likely to cause harmful interference in which case the user is required to correct the interference at their own expense.

Canadian Department of Communications

This Class A digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations.

Cet appareil numérique de la classe A respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada.

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Users in the European Union (EU) should refer to the Declaration of Conformity (DoC) for information* pertaining to the CE marking. Refer to the Declaration of Conformity (DoC) for this product for any additional regulatory compliance information. To obtain the DoC for this product, visit `ni.com/certification`, search by model number or product line, and click the appropriate link in the Certification column.

* The CE marking Declaration of Conformity contains important supplementary information and instructions for the user or installer.

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About This Manual

This manual describes the electrical and mechanical aspects of the NI PXI-6682, and contains information concerning its operation and programming.

Conventions

The following conventions appear in this manual:

<> — Angle brackets that contain numbers separated by an ellipsis represent a range of values associated with a bit or signal name—for example, DIO<3..0>.

» — The » symbol leads you through nested menu items and dialog box options to a final action. The sequence **File»Page Setup»Options** directs you to pull down the **File** menu, select the **Page Setup** item, and select **Options** from the last dialog box.

 This icon denotes a tip, which alerts you to advisory information.

 This icon denotes a note, which alerts you to important information.

 This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash. When this symbol is marked on the product, refer to the *Safety Information* section of Chapter 1, *Introduction*, for precautions to take.

bold — Bold text denotes items that you must select or click in the software, such as menu items and dialog box options. Bold text also denotes parameter names and hardware labels.

italic — Italic text denotes variables, emphasis, a cross reference, or an introduction to a key concept. This font also denotes text that is a placeholder for a word or value that you must supply.

`monospace` — Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, variables, filenames, and extensions.

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National Instruments Documentation

The *NI PXI-6682 User Manual* is one piece of the documentation set for your measurement system. You could have any of several other documents describing your hardware and software. Use the documentation you have as follows:

- Measurement hardware documentation—This documentation contains detailed information about the measurement hardware that plugs into or is connected to the computer. Use this documentation for hardware installation and configuration instructions, specifications about the measurement hardware, and application hints.
- Software documentation—Refer to the *NI-Sync User Manual*, available at `ni.com/manuals`.

You can download NI documentation from `ni.com/manuals`.

Related Documentation

The following documents contain information that you might find helpful as you read this manual:

- *PICMG 2.0 R3.0, CompactPCI Core Specification*, available from PICMG at `www.picmg.org`
- *PXI Specification*, Revision 2.1, available from `www.pxisa.org`
- *NI-VISA User Manual*, available from `ni.com/manuals`
- *NI-VISA Help*, included with the NI-VISA software
- *NI-Sync User Manual*, available from `ni.com/manuals`

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1 Introduction

The NI PXI-6682 enables you to synchronize PXI systems using GPS, IEEE 1588, IRIG-B or PPS to perform synchronized events. The NI PXI-6682 can generate events and clock signals at specified synchronized future times and timestamp input events with the synchronized system time. The PXI-6682 also allows you to route clock signals and triggers with low skew within a PXI chassis or between multiple chassis, providing a method for synchronizing multiple devices in a PXI system.

What You Need to Get Started

To set up and use the NI PXI-6682, you need the following items:

- ❑ NI PXI-6682 Timing and Triggering Module
- ❑ *NI PXI-6682 User Manual*
- ❑ NI-VISA
- ❑ *NI-Sync* CD
- ❑ One of the following software packages and documentation:
  - LabVIEW
  - LabWindows/CVI™
  - Microsoft Visual C++ (MSVC)
- ❑ PXI chassis
- ❑ PXI embedded controller or a desktop computer connected to the PXI chassis using MXI hardware

If you are using the NI PXI-6682 in a system to synchronize NI PXI-4472, NI PXI-5112, NI PXI-5411, NI PXI-6115, or E Series DAQ modules, you can refer to the *NI-Sync User Manual*, which you can find on the *NI-Sync* CD or download from `ni.com/manuals`.

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Unpacking

The NI PXI-6682 is shipped in an antistatic package to prevent electrostatic damage to the module. Electrostatic discharge (ESD) can damage several components on the module.

Caution *Never* touch the exposed pins of connectors.

To avoid such damage in handling the module, take the following precautions:

- Ground yourself using a grounding strap or by touching a grounded object.
- Touch the antistatic package to a metal part of the computer chassis before removing the module from the package.

Remove the module from the package and inspect the module for loose components or any sign of damage. Notify NI if the module appears damaged in any way. Do *not* install a damaged module into the computer.

Store the NI PXI-6682 in the antistatic envelope when not in use.

Software Programming Choices

The NI PXI-6682 uses NI Sync software as its driver.

When programming the NI PXI-6682, you can use NI application development environment (ADE) software such as LabVIEW or LabWindows/CVI, or you can use other ADEs such as Visual C/C++ to interface with the NI Sync software.

LabVIEW features interactive graphics, a state-of-the-art interface, and a powerful graphical programming language. The LabVIEW Data Acquisition VI Library, a series of virtual instruments for using LabVIEW with National Instruments DAQ hardware, is included with LabVIEW.

LabWindows/CVI is a complete ANSI C ADE that features an interactive user interface, code generation tools, and the LabWindows/CVI Data Acquisition and Easy I/O libraries.

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Safety Information

The following section contains important safety information that you *must* follow when installing and using the product.

Do *not* operate the product in a manner not specified in this document. Misuse of the product can result in a hazard. You can compromise the safety protection built into the product if the product is damaged in any way. If the product is damaged, return it to National Instruments for repair.

Do *not* substitute parts or modify the product except as described in this document. Use the product only with the chassis, modules, accessories, and cables specified in the installation instructions. You *must* have all covers and filler panels installed during operation of the product.

Do *not* operate the product in an explosive atmosphere or where there may be flammable gases or fumes. If you must operate the product in such an environment, it must be in a suitably rated enclosure.

If you need to clean the product, use a soft, nonmetallic brush. The product *must* be completely dry and free from contaminants before you return it to service.

Operate the product only at or below Pollution Degree 2. Pollution is foreign matter in a solid, liquid, or gaseous state that can reduce dielectric strength or surface resistivity. The following is a description of pollution degrees:

- Pollution Degree 1 means no pollution or only dry, nonconductive pollution occurs. The pollution has no influence.
- Pollution Degree 2 means that only nonconductive pollution occurs in most cases. Occasionally, however, a temporary conductivity caused by condensation must be expected.
- Pollution Degree 3 means that conductive pollution occurs, or dry, nonconductive pollution occurs that becomes conductive due to condensation.

You *must* insulate signal connections for the maximum voltage for which the product is rated. Do *not* exceed the maximum ratings for the product. Do not install wiring while the product is live with electrical signals. Do not remove or add connector blocks when power is connected to the system. Avoid contact between your body and the connector block signal when hot swapping modules. Remove power from signal lines before connecting them to or disconnecting them from the product.

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Operate the product at or below the *installation category*[1] marked on the hardware label. Measurement circuits are subjected to *working voltages*[2] and transient stresses (overvoltage) from the circuit to which they are connected during measurement or test. Installation categories establish standard impulse withstand voltage levels that commonly occur in electrical distribution systems. The following is a description of installation categories:

- Installation Category I is for measurements performed on circuits not directly connected to the electrical distribution system referred to as MAINS[3] voltage. This category is for measurements of voltages from specially protected secondary circuits. Such voltage measurements include signal levels, special equipment, limited-energy parts of equipment, circuits powered by regulated low-voltage sources, and electronics.
- Installation Category II is for measurements performed on circuits directly connected to the electrical distribution system. This category refers to local-level electrical distribution, such as that provided by a standard wall outlet (for example, 115 V for U.S. or 230 V for Europe). Examples of Installation Category II are measurements performed on household appliances, portable tools, and similar products.
- Installation Category III is for measurements performed in the building installation at the distribution level. This category refers to measurements on hard-wired equipment such as equipment in fixed installations, distribution boards, and circuit breakers. Other examples are wiring, including cables, bus-bars, junction boxes, switches, socket-outlets in the fixed installation, and stationary motors with permanent connections to fixed installations.
- Installation Category IV is for measurements performed at the primary electrical supply installation (<1,000 V). Examples include electricity meters and measurements on primary overcurrent protection devices and on ripple control units.

---

[1] Installation categories, also referred to as *measurement categories*, are defined in electrical safety standard IEC 61010-1.

[2] Working voltage is the highest rms value of an AC or DC voltage that can occur across any particular insulation.

[3] MAINS is defined as a hazardous live electrical supply system that powers equipment. Suitably rated measuring circuits may be connected to the MAINS for measuring purposes.

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2

Installing and Configuring

This chapter describes how to install the NI PXI-6682 hardware and software and how to configure the device.

Installing the Software

Refer to the `readme.htm` file that accompanies the *NI-Sync* CD for software installation directions.

Note Be sure to install the driver software *before* installing the NI PXI-6682 hardware.

Installing the Hardware

The following are general installation instructions. Consult the chassis user manual or technical reference manual for specific instructions and warnings about installing new modules.

1. Power off and unplug the chassis.
2. Choose an available PXI slot in the PXI chassis.

Note The NI PXI-6682 is usually installed in Slot 2.

3. Remove the filler panel for the PXI slot you chose in step 2.
4. Ground yourself using a grounding strap or by touching a grounded object. Follow the ESD protection precautions described in the *Unpacking* section of Chapter 1, *Introduction*.
5. Insert the NI PXI-6682 into the PXI slot. Use the injector/ejector handle to fully insert the module into the chassis.
6. Screw the front panel of the device to the front panel mounting rail of the chassis.
7. Visually verify the installation. Make sure the module is not touching other modules or components and is fully inserted into the slot.
8. Plug in and power on the chassis.

The NI PXI-6682 is now installed.

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Configuring the Module

The NI PXI-6682 is completely software configurable. The system software automatically allocates all module resources.

The two LEDs on the front panel provide information about module status. The front panel description sections of Chapter 3, *Hardware Overview*, describe the LEDs in greater detail.

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3

Hardware Overview

This chapter presents an overview of the hardware functions of the NI PXI-6682, shown in Figure 3-1.

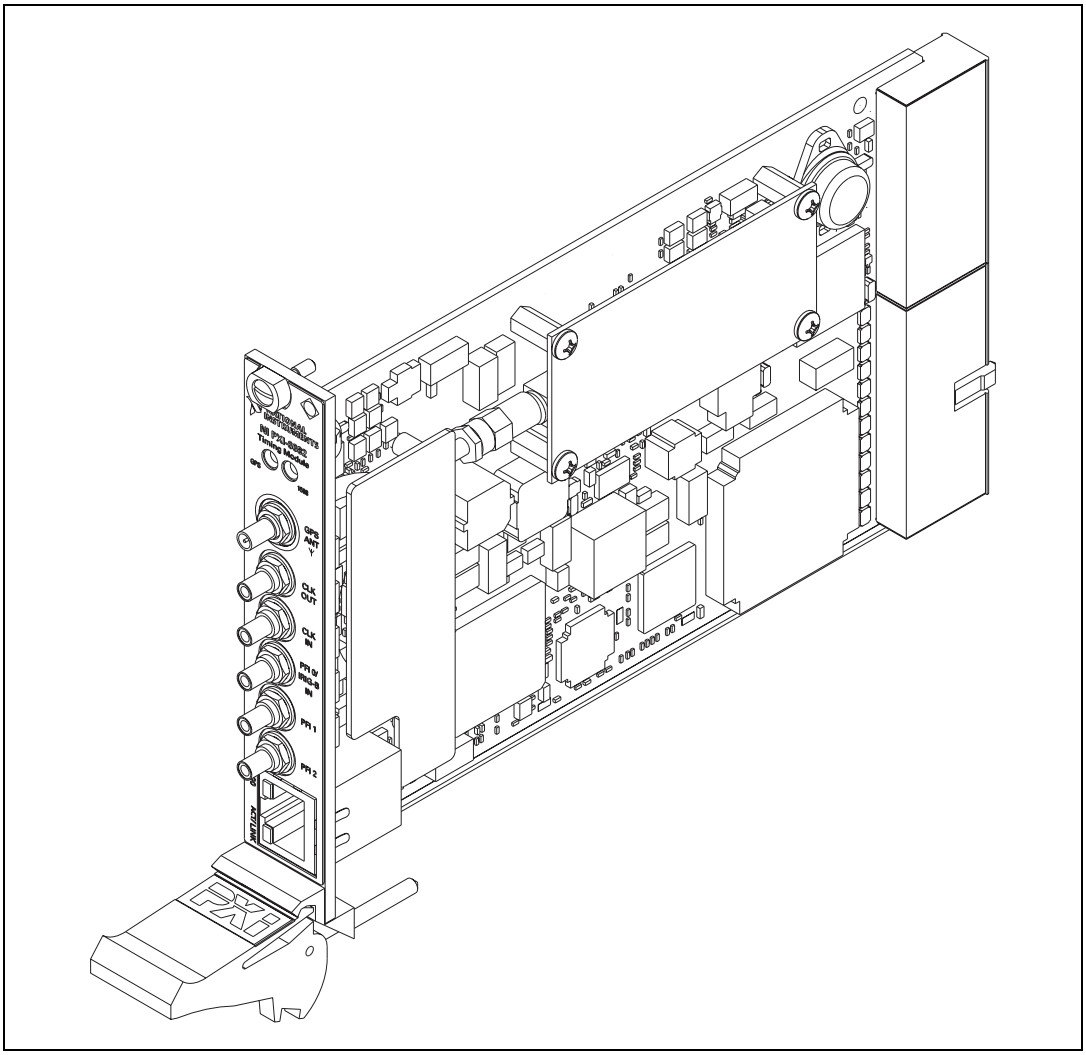


Figure 3-1. Isometric View of the NI PXI-6682

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Figure 3-2 provides a functional overview of the NI PXI-6682.

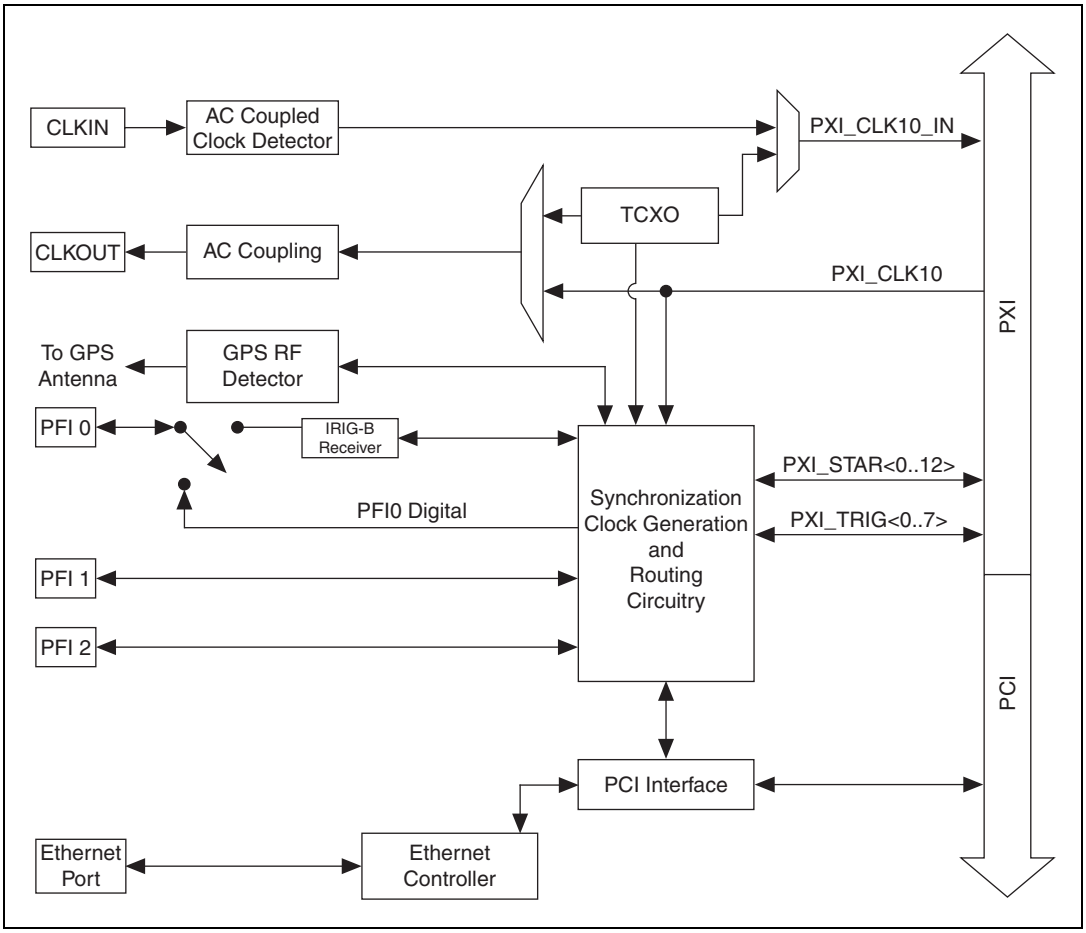
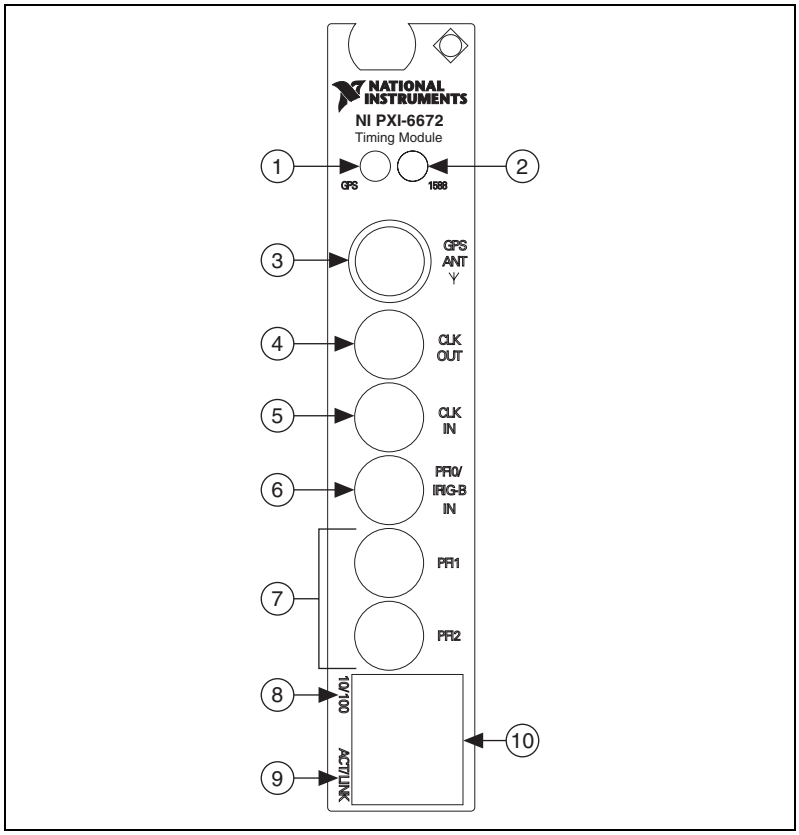


Figure 3-2. Functional Overview of the NI PXI-6682

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NI PXI-6682 Front Panel

Figure 3-3 shows the connectors and LEDs on the front panel of the NI PXI-6682.



1	GPS LED	6	PFI0/IRIG-B Input Connector
2	1588 LED	7	PFI <1..2> Connectors
3	GPS Antenna Connector	8	Ethernet Speed LED
4	CLKOUT Connector	9	Ethernet ACT/LINK LED
5	CLKIN Connector	10	Ethernet Connector

Figure 3-3. NI PXI-6682 Front Panel

GPS LED

The GPS LED indicates the status of the GPS hardware. Refer to Figure 3-3 for the GPS LED location.

Table 3-1 summarizes what the GPS LED colors represent.

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Table 3-1. GPS LED Color Description

Color	Status
Off	Not using GPS*
Amber	Attempting to start self survey
Blinking Amber	Self survey in progress
Blinking Green	Self survey complete (normal operation)
Red	Error**
* The GPS LED is turned off if GPS is not set as the time reference. ** An error is generated when the antenna is disconnected, when there is an antenna malfunction, or when there is a hardware malfunction.	

1588 LED

The 1588 LED indicates the status of the 1588 synchronization protocol. Refer to Figure 3-3 for the 1588 LED location.

Table 3-2 summarizes what the 1588 LED colors represent.

Table 3-2. 1588 LED Color Description

Color	Status
Off	Not using 1588*
Amber	Initializing
Blinking Amber (2 seconds)	Listening or Passive
Green	Uncalibrated or Slave
Blinking Green (2 seconds)	Master or Premaster
Red	Faulty
* 1588 has been disabled or stopped.	

Speed LED

The Speed LED indicates the NI PXI-6682 Ethernet link speed. Refer to Figure 3-3 for the Speed LED location.

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Table 3-3 summarizes what the Speed LED colors represent.

Table 3-3. Speed LED Description

Color	Status
Off	10 Mbps
Green	100 Mbps

Note When there is no Ethernet link the Speed LED is off.

ACT/LINK LED

The ACT/LINK LED indicates the NI PXI-6682 Ethernet link condition. Refer to Figure 3-3 for the ACT/LINK LED location.

Table 3-4 summarizes what the ACT/LINK LED colors represent.

Table 3-4. ACT/LINK LED Color Description

Color	Status
Off	No Ethernet link
Green	Ethernet link established
Blink	Ethernet activity occurring

Connectors

This section describes the connectors on the front panel of the NI PXI-6682.

- **GPS ANT**—GPS antenna RF input and DC power output for active GPS antenna. This connector provides 5 VDC for an active antenna. This connector also serves as the input for the RF signal coming in from the GPS antenna.
- **CLKOUT**—Clock Output. This connector is used to source a 10 MHz clock that can be routed programmatically from the temperature-compensated crystal oscillator (TCXO) or backplane clock (PXI_CLK10).
- **CLKIN**—Clock Input. This connector supplies the module with a clock that can be programmatically routed to the PXI backplane (PXI_CLK10_IN) for distribution to the other modules in the chassis.

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- **PFI <0..2>**—Programmable Function Interface <0..2>. These connectors can be used for either input or output. You can program the behavior of these PFI connections individually.

  Additionally, PFI0 can function as an input for IRIG-B DC or AM.

Caution Do not connect an AM signal to PFI0 when the PFI line is configured for digital operations. This could cause damage to the digital circuitry, the device driving the AM signal, or both. Always ensure the line is configured for IRIG-B AM operation before connecting an IRIG-B AM signal.

- **RJ-45 Ethernet**—10/100 Mbit Ethernet connection. This connector allows the module to communicate via standard Ethernet cabling.

Refer to Figure 3-3 for the location of these connections on the NI PXI-6682 front panel.

Caution Connections that exceed any of the maximum ratings of input or output signals on the NI PXI-6682 can damage the module, the computer, or other devices connected to the PXI-6682. NI is *not* liable for any damage resulting from such signal connections.

Hardware Features

The NI PXI-6682 performs the following functions:

- Synchronization using GPS, IRIG-B, PPS, or IEEE 1588.
- Generation of future time events and clock signals.
- Timestamping incoming signals with the synchronized time.
- Routing internally or externally generated signals from one location to another.

Table 3-5 outlines the function and direction of the signals discussed in detail in the remainder of this chapter. These signals are also identified in Figure 3-2.

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Table 3-5. NI PXI-6682 I/O Terminals

Signal Name	Direction	Description
PXI_CLK10_IN	Out	This is a signal that can replace the native 10 MHz oscillator on the PXI backplane. PXI_CLK10_IN may originate from the onboard TCXO or from an external source.
PXI_CLK10	In	This signal is the PXI 10 MHz backplane clock. By default, this signal is the output of the native 10 MHz oscillator in the chassis. An NI PXI-6682 in Slot 2 can replace this signal with PXI_CLK10_IN.
Oscillator	Out	This is the output of the 10 MHz TCXO. The TCXO is a very stable and accurate frequency source.
CLKIN	In	CLKIN is a signal connected to the SMB input pin of the same name. CLKIN can be routed to PXI_CLK10_IN.
CLKOUT	Out	CLKOUT is the signal on the SMB output pin of the same name. Either the TCXO clock or PXI_CLK10 may be routed to this location.
PXI_STAR <0..12>	In/Out	The PXI star trigger bus connects Slot 2 to Slot <3..15> in a star configuration. The electrical paths of each star line are closely matched to minimize intermodule skew. An NI PXI-6682 in Slot 2 can route signals to Slots <3..15> using the star trigger bus.
PFI <0..2>	In/Out	The Programmable Function Interface pins on the NI PXI-6682 route timing and triggering signals between multiple PXI chassis. A wide variety of input and output signals can be routed to or from the PFI lines. PFI<0> also can function as an input for IRIG-B DC or AM.
PXI_TRIG <0..7>	In/Out	The PXI trigger bus consists of eight digital lines shared among all slots in the PXI chassis. The NI PXI-6682 can route a wide variety of signals to and from these lines.

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The remainder of this chapter describes how these signals are used, acquired, and generated by the NI PXI-6682 hardware, and explains how you can use the signals between various locations to synchronize events in your system.

Clock and Event Generation

The NI PXI-6682 can generate two types of clock signals. The first type is generated with a precise 10 MHz oscillator, and the second is generated with the synchronized timebase. The following sections describe the two types of clock generation and explain the considerations for choosing either type. In addition to time-synchronized clock signals, the NI PXI-6682 is also capable of generating arbitrary digital events, to be used as triggers.

PXI_CLK10 and TCXO

The NI PXI-6682 features a precision 10 MHz TCXO. The frequency accuracy and stability of this clock is greater than the frequency accuracy and stability of the native 10 MHz PXI backplane clock (PXI_CLK10).

The main source of error in most frequency reference oscillators is temperature variation. The TCXO contains circuitry to measure the temperature of the oscillator. It uses the temperature to adjust its frequency output according to the crystal's known frequency variation across its operating temperature range.

An NI PXI-6682 module in Slot 2 of a PXI chassis can replace the native PXI 10 MHz backplane frequency reference clock (PXI_CLK10) with the more stable and accurate output of the TCXO. All other PXI modules in the chassis that reference the 10 MHz backplane clock benefit from this improved reference. The TCXO does not automatically replace the native 10 MHz clock; this feature must be explicitly enabled in software. The TCXO output also can be routed out to the **CLKOUT** connector.

Note The 10 MHz TCXO signal is freerunning. It is not disciplined to the board's time reference.

Time-Synchronized Clock and Event Generation

The NI PXI-6682 is capable of generating clock signals and triggers based on the synchronized time base. The NI PXI-6682 keeps an internal time base with 10 ns resolution that can be synchronized to GPS, IRIG-B, PPS, IEEE 1588, or freerunning. The NI Sync API allows you to schedule

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triggers to occur at an arbitrary future time (future time events), or clocks of arbitrary frequencies (with high and low times in multiples of 10ns). It is also possible to program the start and ending time of a clock generated in this way.

Refer to Table 3-6 for a list of destinations for synchronized time clocks and future-time events.

Routing Signals

The NI PXI-6682 has versatile trigger routing capabilities. It can route signals to and from the front panel, the PXI star triggers, and the PXI triggers. In addition, the polarity of the destination signal can be inverted, which is useful when handling active-low digital signals.

The NI PXI-6682 also can route a 10 MHz clock from **CLKIN** to the PXI 10 MHz reference clock. The NI PXI-6682 can route the TCXO, or PXI 10 MHz reference clock to **CLKOUT**.

Figure 3-4 summarizes the routing features of the NI PXI-6682. The remainder of this chapter details the capabilities and constraints of the routing architecture.

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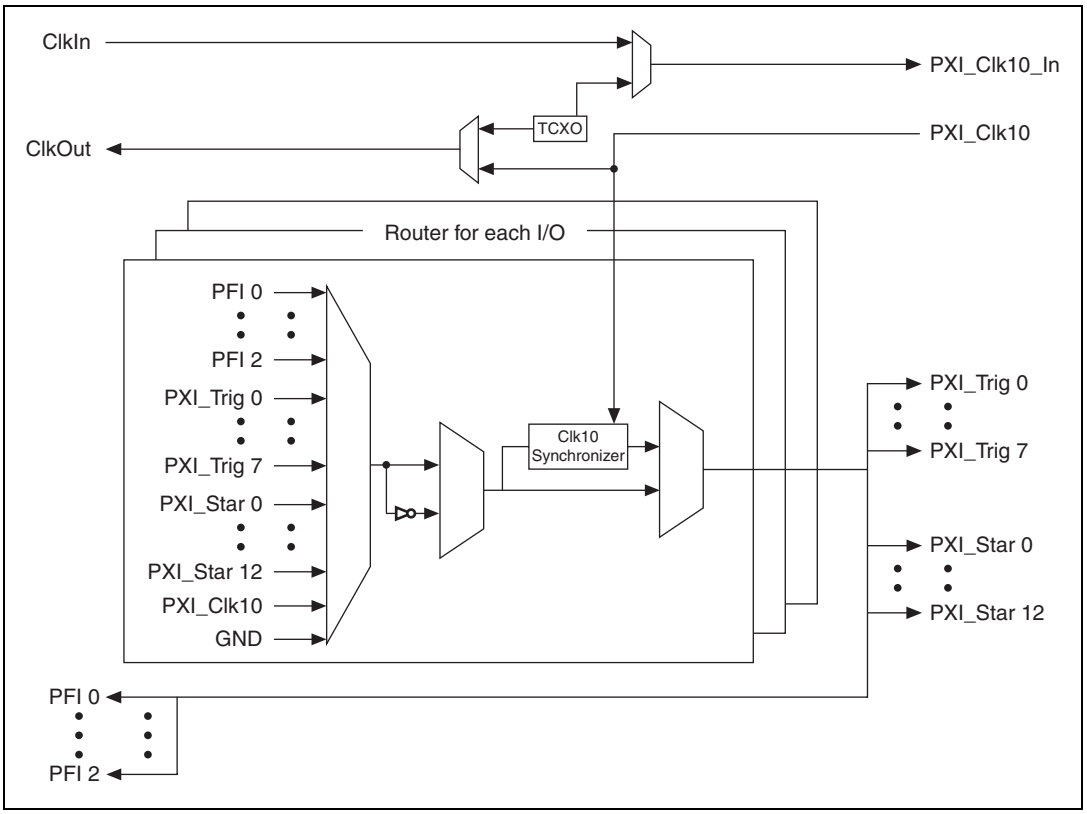


Figure 3-4. High-Level Schematic of NI PXI-6682 Signal Routing Architecture

Determining Sources and Destinations

All signal routing operations can be characterized by a *source* (input) and a *destination*. In addition, synchronous routing operations must also define a third signal known as the *synchronization clock*. Refer to the *Choosing the Type of Routing* section for more information on synchronous versus asynchronous routing.

Table 3-6 summarizes the sources and destinations of the NI PXI-6682. The destinations are listed in the horizontal heading row, and the sources are listed in the column at the far left. A ✓ in a cell indicates that the source and destination combination defined by that cell is a valid routing combination.

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Table 3-6. Sources and Destinations for NI PXI-6682 Signal Routing Operations

Sources		Destinations					
			Front Panel		Backplane		
Front Panel			CLKOUT	PFI <0..2>	PXI_ CLK10_IN	PXI_Star Trigger <0..12>	PXI TRIG <0..7>
Front Panel	CLKIN		✓[a]	✓[a]	✓	✓[a]	✓[a]
Front Panel	PFI <0..2>			✓		✓[b]	✓
Backplane	PXI_ CLK10		✓	✓		✓	✓
Backplane	PXI_STAR <0..12>			✓[b]		✓	✓
Backplane	PXI TRIG <0..7>			✓		✓	✓
Onboard	TCXO		✓	✓[a]	✓	✓[a]	✓[a]
	Time-synchronized events and clocks			✓		✓	✓

[a] Can be accomplished in two stages by routing source to PXI_CLK10_IN, replacing PXI_CLK10 with PXI_CLK10_IN (occurs automatically in most chassis), and then routing PXI_CLK10 to the destination. The source must be 10 MHz.
[b] Asynchronous routes between a single source and multiple destinations are very low skew. See Appendix A, *Specifications*, for details.

I/O Considerations

Using the Ethernet Port

The NI PXI-6682 provides one standard RJ-45 connection for Ethernet communication. This port auto negotiates to the best possible speed—10 Mbps or 100 Mbps. The Ethernet port is auto-MDI capable, which means crossover cabling is not necessary when connecting the NI PXI-6682 to another network card. The NI PXI-6682 senses whether a crossed connection is needed and performs the action internally. The Ethernet port also allows for full duplex operation, so traffic can be sent and received at the same time.

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Using Front Panel PFI Terminals as Outputs

The front panel PFI output signals use +3.3 V signaling for high-impedance loads. You can use the PFI terminals to generate future time events and clock signals up to 1.5 MHz. PFI output signals are suitable for driving most LEDs. To ensure proper signaling for fast edge rate signals, ensure that the system terminates to 50 Ω on the receiving end. Cabling should also be 50 Ω impedance. In a 50 Ω environment, the PFI terminals will output less than +3.3 V in the high state. Refer to Appendix A, *Specifications*, for more information. Refer to the *NI-Sync User Manual* for information on how to set up the PFI lines for output.

Caution Do not attempt to drive signals into PFI terminals set up as outputs. Doing so can damage the NI PXI-6682 or the device driving the PFI terminal.

You can independently select the output signal source for each PFI trigger line from one of the following sources:

- Another PFI <0..2>
- PXI_TRIG <0..7>
- PXI_STAR <0..12>
- Future time events
- PXI_CLK10
- Ground

The PFI trigger outputs may be synchronized to CLK10 except when routing future time events. Refer to the *Choosing the Type of Routing* section for more information about the synchronization clock.

Using Front Panel PFI Terminals as Inputs

The front panel PFI terminals can be configured by software to accept input signals. Refer to the *NI-Sync User Manual* for information on how to set up the PFI terminals to accept input signals. You can use these terminals to timestamp triggers with the synchronized system time or to route signals to other destinations (refer to Table 3-6). The input terminals accept native +3.3 V signaling, but are +5 V tolerant. Use 50 Ω source termination when driving signals into PFI terminals.

The voltage thresholds for the front-panel PFI input signals are fixed. Refer to Appendix A, *Specifications*, for the actual voltage thresholds. The front-panel PFI input signals can be timestamped on rising, falling, or both edges of an input signal.

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Note Regarding PFI0

Since PFI0 is a dual-purpose terminal capable of performing digital I/O like the other PFI lines while also being capable of receiving IRIG-B AM and DC inputs, care is taken to protect the digital circuitry when PFI0 is being used as an IRIG-B AM input. This is achieved with a normally-open solid-state relay (SSR), which is closed only when digital operations for the line are enabled through the API. Digital operations include setting up routes in which PFI0 is the source or the destination, enabling timestamping for PFI0, and scheduling future time events or clocks for PFI0.

The SSR has a 5 ms open and close time. Therefore, care must be taken when using PFI0 to ensure correct operation when the SSR is switching.

To avoid issues due to the SSR switching, follow these guidelines:

- Whenever timestamping begins on PFI0, either ensure the input will remain at a logic low state for at least 5 ms or disregard timestamps for at least 5 ms.
- When setting up PFI0 as an output (future time events or clocks), ensure that PFI0 is driven low for at least 5 ms after the line is set up. Alternately, ensure that the external receiver can tolerate a slow rising edge.
- Before disabling PFI0 set up as an output, drive the output low to avoid a very slow ramp down.
- Any time a route is set up or changed where PFI0 is the source or the destination, allow for a 5 ms settling time.

For more information, refer to KnowledgeBase **4E9BT88P** at `ni.com/support`.

Using the PXI Triggers

The PXI Triggers go to all the slots in the chassis. All modules receive the same PXI Triggers, so PXI Trigger 0 is the same for Slot 2 as it is for Slot 3, and so on. This feature makes the PXI Triggers convenient in situations where you want, for instance, to start an acquisition on several devices at the same time because all modules will receive the same trigger.

NI recommends transmitting clocks using the PXI_STAR triggers. However, if you must use the PXI Triggers, the frequency on the PXI Triggers should not exceed 20 MHz to preserve signal integrity.

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PXI Trigger signals do not reach each slot at precisely the same time. A difference of several nanoseconds between slots can occur in an eight-slot chassis. However, this delay is not a problem for many applications. If your application requires tighter synchronization, use the PXI_STAR triggers.

You can independently select the output signal source for each PXI trigger line from one of the following sources:

- PFI <0..2>
- PXI_TRIG <0..7>
- PXI_STAR <0..12>
- Future time events
- PXI_CLK10
- Ground

The PXI Trigger outputs may be synchronized to CLK10 except when routing future time events. Refer to the *Choosing the Type of Routing* section for more information about the synchronization clock.

Using the PXI Star Triggers

There are up to 13 PXI star triggers per chassis. Each trigger line is a dedicated connection between Slot 2 and one other slot. The *PXI Specification*, Revision 2.1, requires that the propagation delay along each star trigger line be matched to within 1 ns. A typical upper limit for the skew in most NI PXI chassis is 500 ps. The low skew of the PXI star trigger bus is useful for applications that require triggers to arrive at several modules nearly simultaneously. The NI PXI-6682 is able to route low skew triggers to the PXI_Star lines from any PFI line.

The star trigger lines are bidirectional, so signals can be sent to Slot 2 from a module in another slot or from Slot 2 to the other module.

You can independently select the output signal source for each PXI star trigger line from one of the following sources:

- PFI <0..2> (low skew)
- PXI_TRIG <0..7>
- Another PXI star trigger line (PXI_STAR <0..12>)
- Synchronized time event
- PXI_CLK10
- Ground

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The PXI star trigger outputs may be synchronized to CLK10 except when routing future time events. Refer to the *Choosing the Type of Routing* section for more information about the synchronization clock.

Choosing the Type of Routing

The NI PXI-6682 routes signals in one of two ways: asynchronously or synchronously. The following sections describe the two routing types and the considerations for choosing each type.

Asynchronous Routing

Asynchronous routing is the most straightforward method of routing signals. Any asynchronous route can be defined in terms of two signal locations: a source and a destination. A digital pulse or train comes in on the source and is propagated to the destination. When the source signal goes from low to high, this rising edge is transferred to the destination after a propagation delay through the module. Figure 3-5 illustrates an asynchronous routing operation.

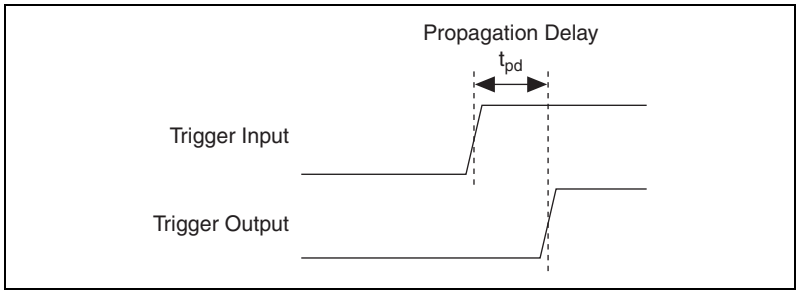


Figure 3-5. Asynchronous Routing Operation

Some delay is always associated with an asynchronous route, and this delay varies among NI PXI-6682 modules, depending on variations in temperature and chassis voltage. Typical delay times in the NI PXI-6682 for asynchronous routes between various sources and destinations are given in Appendix A, *Specifications*.

Asynchronous routing works well if the total system delays are not too long for the application. Propagation delay could be caused by the following reasons:

- Output delay on the source
- Propagation delay of the signal across the backplane(s) and cable(s)
- Propagation delay of the signal through the NI PXI-6682

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- Time for the receiver to recognize the signal

The source of an asynchronous routing operation on the NI PXI-6682 can be any of the following lines:

- Any front panel PFI pin (PFI<0..2>)
- Any PXI Star trigger line (PXI_STAR<0..12>)
- Any PXI Trigger line (PXI_TRIG<0..7>)
- Synchronized time events
- PXI_CLK10
- Ground

The destination of an asynchronous routing operation on the NI PXI-6682 can be any of the following lines:

- Any front panel PFI pin (PFI <0..2)
- Any PXI star trigger line (PXI_STAR <0..12>)
- Any PXI Trigger line (PXI_TRIG <0..7>)

Synchronous Routing

A synchronous routing operation is defined in terms of three signals: a source, a destination, and a *synchronization clock*. A digital signal comes in on the source and is propagated to the destination after the edge has been realigned with the synchronization clock.

Unlike asynchronous routing, the output of a synchronous routing operation does not directly follow the input after a propagation delay. Instead, the output waits for the next rising edge of the clock before it follows the input. Thus, the output is said to be “synchronous” with this clock.

Synchronous routing can send triggers to several places in the same clock cycle or send the trigger to those same places after a deterministic skew of a known number of clock cycles. If a signal arrives at two chassis within the same clock cycle, each NI PXI-6682 realigns the signal with the synchronization clock and distributes it to the modules in each chassis at the same time. Synchronous routing can thus remove uncertainty about when triggers are received. If the delays through the system are such that an asynchronous trigger might arrive near the edge of the receiver clock, the receiver might see the signal in the first clock cycle, or it might see it in the second clock cycle. However, by synchronizing the signal, you can eliminate the ambiguity, and the signal will always be seen in the second clock cycle.

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Figure 3-6 shows a timing diagram that illustrates synchronous routing.

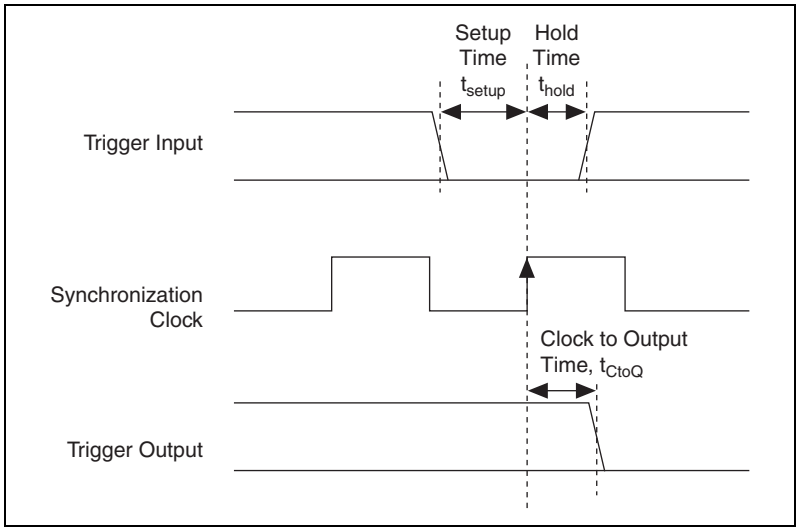


Figure 3-6. Synchronous Routing Operation

Possible sources and destinations for synchronous routing include the following:

- Any front panel PFI pin (PFI <0..2>)
- Any PXI star trigger line (PXI_STAR <0..12>)
- Any PXI Trigger line (PXI_TRIG <0..7>)

In the NI PXI-6682 the synchronization clock for synchronous routes is always PXI_CLK10.

Note The possible destinations for a synchronous route are identical to those for an asynchronous route. The destinations include any front panel PFI pin, any PXI star trigger line, or any PXI Trigger line.

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4

Synchronization

The NI PXI-6682 is capable is achieving tight synchronization with various other devices using GPS, IRIG-B, PPS, or IEEE 1588. When GPS or IRIG-B are selected as the synchronization source, the NI PXI-6682 can also serve as an IEEE 1588 grandmaster. The following sections describe the synchronization capabilities of the NI PXI-6682.

GPS

GPS stands for Global Positioning System, and it is a system of over 2 dozen satellites in medium Earth orbit that are constantly transmitting signals down to Earth. GPS receivers are able to detect these signals and determine location, speed, direction and time very precisely. GPS satellites are fitted with atomic clocks, and the signals they transmit to Earth contain timing information. This makes the GPS system a precise timing and synchronization source.

The NI PXI-6682 has a GPS receiver which powers an active GPS antenna and receives and processes the RF signals (1.575 GHz) from the satellites. The GPS receiver then generates a very precise pulse-per-second (PPS) that the NI PXI-6682 uses to achieve sub-microsecond synchronization.

GPS enables the NI PXI-6682 to synchronize PXI systems located far away from each other, as long as GPS satellites are visible to the antenna from each location. Furthermore, once the NI PXI-6682 is synchronized to GPS, it can function as an IEEE 1588 grandmaster to enable synchronization of external 1588 devices.

IRIG-B

IRIG is a standard used to transmit precise timing information between instruments to achieve synchronization. IRIG-B is a particular application of the IRIG standard, in which 100 bits of data are sent every second. Embedded in the data is a seconds' boundary marker that the receiving

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instrument uses to synchronize its timebase to the IRIG source. The rest of the data contains information such as the time of day, days since the beginning of the year, and optionally, control functions and the number of seconds since the start of the day, encoded as a straight binary number.

Refer to Appendix B, *IRIG Protocol Overview*, for more information about the IRIG standard.

The NI PXI-6682 can function as an IRIG-B receiver, supporting synchronization to sources outputting IRIG-B 12X (AM) and IRIG-B 00X (DC).

When configured to synchronize to an IRIG-B AM source, the NI PXI-6682 will be able to accept a 1kHz AM modulated IRIG-B 12X signal on its PFI0 input. When configured to synchronize to an IRIG-B DC source, the NI PXI-6682 will be able to accept an IRIG-B 00X DC encoded signal on its PFI0 input.

Caution Do not connect an AM signal to PFI0 when the PFI line is configured for digital operations. This could cause damage to the digital circuitry, the device driving the AM signal, or both. Always ensure the line is configured for IRIG-B AM operation before connecting an IRIG-B AM signal.

Furthermore, once the NI PXI-6682 is synchronized to IRIG-B, it can function as an IEEE 1588 grandmaster to synchronize of external 1588 devices.

The following assumptions are made regarding the received IRIG-B signal. All conditions must be met for the NI PXI-6682 to be able to synchronize accurately:

- Seconds begin every minute at 0, increment to 59, and then roll-over to 0.
- Minutes begin every hour at 0, increment to 59, and then roll-over to 0.
- Hours begin every day at 0, increment to 23, and then roll-over to 0.
- Days begin every year at 1. Days increment to 365 in non-leap years, or to 366 in leap years, and then roll-over to 1. Leap years must be supported. Valid values for year are 01–99, inclusive. Years are assumed to be in the XXI Century. For instance, year *07* represents 2007. If the year is not supplied (sent as *00*), the OS system time is read and the year is derived from it.

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To achieve proper synchronization of the NI PXI-6682 ensure that the IRIG-B source used conforms to the requirements listed above. Note that most IRIG-B sources conform to these requirements.

IEEE 1588

The NI PXI-6682 is capable of performing synchronization over Ethernet using IEEE 1588. It is possible to configure the NI PXI-6682 to synchronize to GPS or IRIG-B and then function as an IEEE 1588 grandmaster. It is also possible to configure the NI PXI-6682 to synchronize to IEEE 1588, in which case, the standard defines how the master will be selected. If the NI PXI-6682 is selected as IEEE 1588 master, and it is not configured to synchronize to GPS or IRIG-B, it will use its internal free-running timebase, which will be updated to the host computer's system time during power up.

PPS

The NI PXI-6682 is capable of using a PPS (pulse per second) signal for synchronization. Any PFI, PXI_Trigger or PXI_Star line can be configured as the PPS input terminal. When synchronizing based on a PPS, the first pulse received will set the NI PXI-6682 internal timebase to either an arbitrary time supplied by the user, or the host computer's system time. Each subsequent pulse received will be interpreted as a second's boundary (the pulse occurring exactly 1 second after the previous pulse). As each pulse is received, the NI PXI-6682 will adjust its internal timebase to match the frequency of the PPS source.

For best results when using PPS Time Reference, ensure that the device supplying the PPS signal is capable of providing a stable, consistent 1Hz signal. Error can be induced into the system if the reference signal contains significant jitter, or if the reference frequency strays from 1 Hz.

Synchronization Best Practices

The NI PXI-6682 can achieve sub-microsecond synchronization. The following section describes some guidelines for achieving the best possible performance from your NI PXI-6682. While the NI PXI-6682 will function properly if you follow the specifications, the following guidelines may increase the synchronization performance.

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Operating Environment

For best synchronization performance, follow these operating environment guidelines, while taking care to remain within the specified operating temperature limits:

- Ensure the PXI filler panels are properly installed for unused PXI slots. Airflow can degrade the NI PXI-6682 performance because it tends to cause rapid changes in temperature. The NI PXI-6682 has precision thermally compensated components, but limiting direct airflow helps achieve the best performance. Consider placing the PXI chassis containing the NI PXI-6682 in an environment free of rapid temperature transitions.
- Perform the same steps as above to ensure that all other synchronization partners also have a thermally stable environment.

Timing System Performance

The NI PXI-6682 can generate or receive a 1 Hz pulse per second signal on any PFI or PXI Trigger terminal. You can set up this signal to transition on the seconds boundary of the synchronized system time. You can then use this signal to analyze system performance by connecting two or more pulse per second signals to an oscilloscope and measuring the latency between them. Adjustments can be made to account for deterministic latency. Refer to the *NI-Sync API Reference Help* for more information. The NI PXI-6682 can also timestamp an incoming pulse per second signal. The NI PXI-6682 will timestamp the externally generated pulse per second with its internal timebase. By comparing this timestamp with the nearest seconds boundary, you can quickly determine the synchronization performance.

IEEE 1588 Synchronization Best Practices

Network Topology

To obtain the best NI PXI-6682 performance, follow these guidelines to set up the Ethernet network topology:

- Use short cabling when possible. Ethernet cabling is inherently asymmetric; the longer the cabling, the higher the asymmetry. This impacts synchronization performance, because the IEEE 1588 protocol assumes a symmetric network path.
- Use hubs when connecting to multiple IEEE 1588-capable devices. Hubs offer low latency and close to deterministic performance for transporting Ethernet traffic. This latency is on the order of hundreds of nanoseconds. Using switches degrades performance due to

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increased latency and indeterminate performance from the onboard buffers. Synchronization performance across switches can be in the tens of microseconds. If a switch must be used, obtain a 1588 boundary clock or transparent switch to achieve the best performance. These devices allow traffic to cross Ethernet collision domains without the inherent loss in performance from a switch.

- Ensure that the network is running at 100 Mbps by noting the Speed LED status. Synchronization performance is degraded when running at 10 Mbps.

Note If it is impossible to use a 100 Mbps network and you must run IEEE 1588 synchronization using a 10 Mbps network, ensure the network interface of the NI PXI-6682 is explicitly configured for 10 Mbps Full Duplex operation using the Windows configuration panels.

GPS Synchronization Best Practices

The embedded GPS receiver in the NI PXI-6682 requires signals from several satellites to be able to compute precise timing and location. The more satellites available to the receiver, the more precisely it can determine time and location. Therefore, the location of the antenna should be such that it will receive signals from the greatest number of satellites possible. As the number of satellites visible to the antenna decreases, the synchronization performance may also decrease. The antenna location should be chosen so that the antenna has a *clear view of the sky*. There is no strict definition for *clear view of the sky*, but a suitable guideline is that the GPS antenna should have a straight line of sight to the sky in all directions (360°) down to an imaginary line making a 30° angle with the ground. Locations far from trees and tall buildings which could reflect GPS satellite signals are best.

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A

Specifications

CLKOUT Characteristics

Output frequency..... 10 MHz

Duty cycle ..... 45 to 55%

Output impedance ..... 50 Ω, nominal

Output coupling..... AC

Load	Square Wave
Open Load	5 V_{p-p}, typical
50 Ω Load	2.5 V_{p-p}, typical

Square wave rise/fall time (10 to 90%).. 0.5 ns min,
2.5 ns max

CLKIN Characteristics

CLKIN fundamental frequency ..... 10 MHz, sine or square wave

Input impedance..... 50 Ω, nominal

Input coupling ..... AC

Voltage range ..... 400 mV_{p-p} to 5 V_{p-p}

Absolute maximum input voltage[1]..... 6 V_{p-p}, max

CLKIN to PXI_CLK10_IN delay ..... 13 ns, typical
± 1.0 ns, max

[1] Stresses beyond those listed can cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods of time can affect device reliability. Functional operation of the device outside the conditions indicated in the operational parts of the specification is not implied.

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CLKIN frequency accuracy requirement
For replacing PXI_CLK10 .....±100 ppm[1]

Jitter added to CLKIN .....1.3 ps_{rms}, 10 Hz to 100 kHz, typical

Duty cycle distortion of CLKIN to PXI_CLK10_IN .....±1%, max

Required input duty cycle.....45 to 55%

PFI <0..2>

Output Characteristics

Frequency range .....DC to 30 MHz

Output impedance.....50 Ω, nominal

Output coupling .....DC

Output voltage levels

Output high.....1.1 V min, 1.6 V typical for 50 Ω load;
2.4 V min, 3.3 V typical for 1 MΩ load

Output low.....0.3 V max, 0 V typical for 50 Ω load;
0.7 V max, 0 V typical for 1 MΩ load

Absolute maximum applied voltage[2].....0 to 5 V

Output-to-output skew, asynchronous....< 1.5 ns, typical

Output-to-output skew, synchronous.....< 2 ns, typical

Synchronized trigger clock to out time, t_{co} .....10 ns, typical[3]

[1] This is a requirement of the PXI specification.

[2] Stresses beyond those listed can cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods of time can affect device reliability. Functional operation of the device outside the conditions indicated in the operational parts of the specifications is not implied.

[3] Relative to CLKOUT when set up to route PXI_CLK10.

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Output current ..... ±48 mA, max

Square wave rise/fall time
(10 to 90%) for 50 Ω load..... 0.5 ns min,
2.5 ns max

Input Characteristics[1]

Frequency range..... DC to 30 MHz

Input impedance..... 1 kΩ, nominal

Input coupling ..... DC

Voltage level ..... 0 to +3.3 V, +5 V tolerant

Absolute maximum input voltage[2]..... –0.5 V to 6.0 V

Input threshold

Voltage threshold high..... +2.3 V

Voltage threshold low ..... +0.8 V

Asynchronous delay, t_{pd}

PFI <0..2> to
PXI_TRIG <0..7> output..... 20 to 31 ns, typical

PFI <0..2> to
PXI_STAR <0..12> output ..... 10 ns, typical

Synchronized trigger
input setup time, t_{setup}[1] ..... 12 ns

Synchronized trigger
input hold time, t_{hold}[1]..... 0 ns

IRIG-B Input Characteristics (PFI0)

IRIG-B AM compatibility..... IRIG-B 12X

Maximum Input voltage range ..... –5 V to +5 V

---

[1] For PFI 0 these characteristics apply when the line is configured as a digital input. They do not apply when configured as an IRIG-B AM input.

[2] Stresses beyond those listed can cause permanent damage to the device. Exposure to absolute maximum rated conditions for extended periods of time can affect device reliability. Functional operation of the device outside the conditions indicated in the operational parts of the specifications is not implied.

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Decode Input voltage range .....1.5 V to 10 V peak-peak mark
(3:1 ratio mark:space)

Input carrier frequency .....1 kHz

Caution Do not connect an IRIG-B AM signal to PFI 0 when the input is configured for digital operation, as this can result in damage of the digital input circuitry.

IRIG-B DC compatibility .....IRIG-B 00X

Input characteristics for IRIG-B DC.....same as PFI digital input characteristics listed above

The following assumptions are made regarding the received IRIG-B signal. All conditions must be met for the NI PXI-6682 to be able to synchronize accurately:

- Seconds begin every minute at 0, increment to 59, and then roll-over to 0.
- Minutes begin every hour at 0, increment to 59, and then roll-over to 0.
- Hours begin every day at 0, increment to 23, and then roll-over to 0.
- Days begin every year at 1. Days increment to 365 in non-leap years, or to 366 in leap years, and then roll-over to 1. Leap years must be supported. Valid values for year are 01–99, inclusive. Years are assumed to be in the XXI Century. For instance, year *07* represents 2007. If the year is not supplied (sent as *00*), the OS system time is read and the year is derived from it.

To achieve proper synchronization of the NI PXI-6682 ensure that the IRIG-B source used conforms to the requirements listed above. Note that most IRIG-B sources conform to these requirements.

PXI_STAR Trigger Characteristics

PXI_STAR <0..12> to
PXI_STAR <0..12> output skew
at NI PXI-6682 backplane connector .....< 400 ps[1]

Asynchronous delays, t_{pd}

PXI_STAR <0..12> to
PFI <0..2> output.....11 ns, typical

[1] This specification applies to all asynchronous routes from the PFI inputs to the PXI_Star lines.

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PXI_STAR <0..12> to
PXI_TRIG <0..7> output ..... 22 to 36 ns, typical

PXI Trigger Characteristics

PXI_TRIG <0..7> to
PXI_TRIG <0..7> output skew
at NI PXI-6682 backplane connector ..... < 5 ns, typical

Asynchronous delay, t_{pd}

PXI_TRIG <0..7> to
PFI <0..2> output ..... 18 to 34 ns, typical

Timestamping and Time-Synchronized Clock Generation

Time-sychronized
clock frequency range ..... DC to 1.5 MHz

Duty cycle ..... Programmable

Note Clock signals generated on PFI, PXI_STAR, or PXI Trigger lines must have a period and duty cycle that is a multiple of 10 ns.

Minimum pulse width
for timestamping ..... 36 ns

TCXO Characteristics

Frequency ..... 10 MHz

Initial accuracy ..... ±1 ppm

Temperature stability (0 to 55 °C) ..... ±1 ppm

Aging per year ..... ±1 ppm

GPS

Recommended GPS antenna ..... Trimble Bullet III

DC voltage output for antenna ..... 5 V

RF GPS signal frequency ..... 1575.42 MHz ± 1.023 MHz

Input impedance ..... 50 Ω, nominal

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Accuracy

PPS .....Within 15 ns to GPS/UTC (1 Sigma)

Horizontal position .....< 6 m (50%)
< 9 m (90%)

Altitude position .....< 11 m (50%)
< 18 m (90%)

Velocity .....0.06 m/s

Trimble Bullet III gain
at 1575.42 MHz .....35 dB

Signal strength required at PXI-6682 .....18 dB

Maximum signal loss at 1575.42 MHz...17 dB

Note The GPS antenna kit offered by National Instruments comes with a 30 m cable which has a loss of 15 dB/100 ft, making the total loss in the cable approximately 14.8 dB. If your GPS antenna installation requires a longer cable, ensure that the loss per unit of distance is lower, such that the total signal loss is under 17 dB.

Physical

Chassis requirement.....One 3U CompactPCI or PXI slot (PXI Slot 2 for full functionality)

Weight .....235 g

Front panel connectors.....Six SMB male, 50 Ω; one standard RJ-45 Ethernet connector

Front panel indicators .....Two tricolor LEDs (green, red, and amber) for GPS and IEEE 1588 status, and two green LEDs for Ethernet link status and speed

Recommended maximum cable lengths

PFI, DC to 1.5 MHz .....200 m

CLKOUT to CLKIN.....200 m

Ethernet CAT5.....100 m

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Power Requirements

Voltage (V)	Typical	Maximum
+3.3 V	450 mA	700 mA
+5 V	170 mA	235 mA
+12 V	135 mA	180 mA
–12 V	0 A	0 A

Synchronization Accuracy

Test[1]	Specification
GPS[2]	±100 ns, < 13 ns standard deviation
IEEE 1588 3 m Ethernet direct connection[3]	±47 ns, < 10 ns standard deviation
IEEE 1588 through a hub[3,4]	±210 ns, < 35 ns standard deviation
IEEE 1588 through a switch[3,5]	±25 µs, < 150 ns standard deviation
IRIG-B DC	±55 ns, < 13 ns standard deviation
IRIG-B AM matching[6,7]	±1 µs, < 220 ns standard deviation
IRIG-B AM to source[7]	±5 µs, < 500 ns standard deviation
PPS	±47 ns, < 10 ns standard deviation

1. All synchronization measurements were done by recording the offset between PPS signals generated by two PXI-6682 boards inside closed PXI-1031 chassis, at ambient room temperature conditions. Synchronization was performed for 15 minutes before testing began. All test durations were 12 hours.
2. For the GPS test, two PXI-6682 boards were independently synchronizing to GPS and configured to generate a PPS. The specification above represents empirical results. Please note that GPS satellites are only guaranteed to be within 100ns of UTC. Therefore, the offset between any two devices synchronizing can be as high as 200 ns plus the offset of that device to GPS.
3. Sync interval of 1 second was used for IEEE 1588 tests, and all Ethernet connections were 100 Mbps.
4. Netgear DS104 Hub used.
5. Airlink 101 Gigabit over copper switch used. For this test, a moderate amount of non-1588 Ethernet traffic was present on the switch.
6. IRIG-B AM matching specification was obtained by setting two PXI-6682 boards to synchronize independently to the same IRIG-B AM source and generate a PPS. The offset between their PPS signals was then measured over a 12 hour period.
7. IRIG-B performance depends on IRIG-B source stability and quality.

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Environmental

Operating Environment

Ambient temperature range .....0 to 55 °C (Tested in accordance with IEC-60068-2-1 and IEC-60068-2-2.)

Relative humidity range.....10% to 90%, noncondensing (Tested in accordance with IEC-60068-2-56.)

Maximum altitude.....2,000 m (at 25 °C ambient temperature)

Pollution Degree 2

Indoor use only.

Storage Environment

Ambient temperature range .....–20 to 70 °C (Tested in accordance with IEC-60068-2-1 and IEC-60068-2-2.)

Relative humidity range.....5% to 95% noncondensing (Tested in accordance with IEC-60068-2-56.)

Shock and Vibration

Operational Shock .....30 g peak, half-sine, 11 ms pulse (Tested in accordance with IEC-60068-2-27. Test profile developed in accordance with MIL-PRF-28800F.)

Random Vibration

- Operating .....5 to 500 Hz, 0.3 g_{rms}
- Nonoperating .....5 to 500 Hz, 2.4 g_{rms}

(Tested in accordance with IEC-60068-2-64. Nonoperating test profile exceeds the requirements of MIL-PRF-28800F, Class 3.)

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Safety

This product is designed to meet the requirements of the following standards of safety for electrical equipment for measurement, control, and laboratory use:

- IEC 61010-1, EN-61010-1
- UL 61010-1, CSA 61010-1

Note For UL and other safety certifications, refer to the product label or visit `ni.com/certification`, search by model number or product line, and click the appropriate link in the Certification column.

Electromagnetic Compatibility

This product is designed to meet the requirements of the following standards of EMC for electrical equipment for measurement, control, and laboratory use:

- EN 61326 EMC requirements; Minimum Immunity
- EN 55011 Emissions; Group 1, Class A
- CE, C-Tick, ICES, and FCC Part 15 Emissions; Class A

Note For EMC compliance, operate this device according to product documentation.

CE Compliance

This product meets the essential requirements of applicable European Directives, as amended for CE marking, as follows:

- 2006/95/EC; Low-Voltage Directive (safety)
- 2004/108/EEC; Electromagnetic Compatibility Directive (EMC)

Note Refer to the Declaration of Conformity (DoC) for this product for any additional regulatory compliance information. To obtain the DoC for this product, visit `ni.com/certification`, search by model number or product line, and click the appropriate link in the Certification column.

Environmental Management

National Instruments is committed to designing and manufacturing products in an environmentally responsible manner. NI recognizes that eliminating certain hazardous substances from our products is beneficial not only to the environment but also to NI customers.

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For additional environmental information, refer to the *NI and the Environment* Web page at ni.com/environment. This page contains the environmental regulations and directives with which NI complies, as well as any other environmental information not included in this document.

Waste Electrical and Electronic Equipment (WEEE)



EU Customers At the end of their life cycle, all products *must* be sent to a WEEE recycling center. For more information about WEEE recycling centers and National Instruments WEEE initiatives, visit ni.com/environment/weee.htm.

电子信息产品污染控制管理办法 （中国 RoHS）



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B

IRIG Protocol Overview

IRIG (Inter Range Instrumentation Group) is a standard used to transmit precise timing information between instruments to achieve synchronization. There are 6 different IRIG standards defined (A,B,D,E,G and H). The main difference between the standards is the rate with which the synchronization pulses and the information bits are sent. The standards also differ slightly in the content of the information transmitted. Table B-1 summarizes the characteristics of each IRIG standard

Table B-1. IRIG Standard Definitions

IRIG Standard	Bit rate (bit duration)	Frame rate (frame duration)	Information sent
IRIG-A	1 Kbps (1ms)	10 fps (100ms)	TOY & Y (BCD) SOD (SBS)
IRIG-B	100 bps (10ms)	1 fps (1s)	TOY & Y (BCD) SOD (SBS)
IRIG-D	1 bpm (60s)	1 fpm (1 hour)	TOY (BCD) days and hours only
IRIG-E	10 bps (100ms)	6 fpm (10s)	TOY & Y (BCD)
IRIG-G	10 kbps (0.1ms)	100 fps (10ms)	TOY & Y (BCD) Includes fractions of seconds
IRIG-H	1 bps (1s)	1fpm (60s)	TOY (BCD) Days, hours and minutes only
	bps—bits per second fps—frames per second TOY—time of year SOD—seconds of day	bpm—bits per minute fpm—frames per minute Y—year SBS—straight binary seconds BCD—binary-coded decimal	

In addition to the characteristics of each standard described in the table above, each of those is subdivided further depending on the electrical characteristics of the signal used to transmit the data, and the actual data

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transmitted. This is usually specified by 3 digits that follow the IRIG standard name (for instance, IRIG-B 120). Table B-2 details the different characteristics of each IRIG option.

Table B-2. IRIG Option Characteristics

Modulation type		Frequency		Information sent	
0	Pulse width modulated	0	DC	0	TOY (BCD), CB, SBS
1	Amplitude modulated (sine wave)	1	100Hz	1	TOY (BCD), CB
2	Manchester modulated	2	1kHz	2	TOY (BCD)
		3	10kHz	3	TOY (BCD), SBS
		4	100kHz	4	TOY (BCD), Year (BCD), CB, SBS
		5	1MHz	5	TOY (BCD), Year (BCD), CB
				6	TOY (BCD), Year (BCD)
				7	TOY (BCD), Year (BCD), SBS
CB = control bits					

For example, IRIG-B 120 indicates that the information is sent once per second, 100 bits per second, on a 1kHz amplitude modulated sine wave, and that the information sent is the time of year in BCD, control bits, and the seconds of day in straight binary seconds.

There are 3 types of “bits” sent in the IRIG standard: binary zeroes, binary ones and position identifiers. To transmit a binary zero, the source must keep the signal at mark for 20% of the bit duration and at space for the remaining 80%; to transmit a binary one the source must keep the signal at mark for 50% of the bit duration and at space for the remaining 50%; to transmit a position identifier, the source must keep the signal at mark for 80% of the bit duration, and at space for the remaining 20%. Binary bits are used to transmit information such as time of year, straight binary seconds, and so on, and position identifiers are used to separate the different pieces of data transmitted. The second’s boundary is embedded into the transmission by sending two consecutive position identifiers; the beginning of the second position identifier is the second’s boundary.

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For pulse width modulated systems, conventional digital binary signaling is used, and mark is defined as the logic high state, while space is defined as the logic low state.

For amplitude modulated systems, the source must generate sinusoidal signaling modulating the amplitude such that it has a 10:3 mark:space amplitude ratio (the range of allowable mark to space ratios is 3:1 to 6:1). The source must phase align the generated sine wave such that the leading edges of bits are coincident with zero crossings of the sine wave.

Figure B-1 shows an example of transmission of a binary one, a binary zero, and two position identifiers (with the second's boundary at the leading edge of the second position identifier). The figure shows the information transmitted using an amplitude modulated signal, and a pulse width modulated signal.

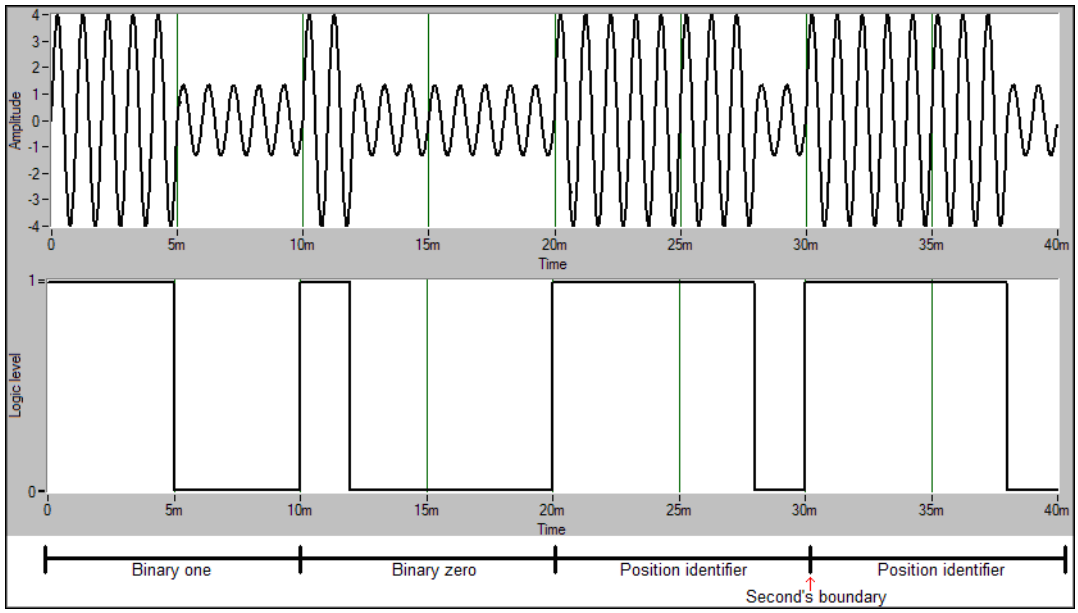


Figure B-1. IRIG-B AM and DC Transmission Example

IRIG-B is one of the most common IRIG standards used. The following table describes how the information is transmitted when using IRIG-B each second.

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Table B-3. IRIG-B Bit Assignments

Bit position	Information transmitted
0	Position identifier P_R (seconds' boundary marker)
1–4	Units of seconds
6–8	Tens of seconds
9	Position identifier P_1
10–13	Units of minutes
15–17	Tens of minutes
19	Position identifier P_2
20–23	Units of hours
25–26	Tens of hours
29	Position identifier P_3
30–33	Units of days
35–38	Tens of days
39	Position identifier P_4
40–41	Hundreds of days
49	Position identifier P_5
50–53	Units of year or control function bits
55–58	Tens of year or control function bits
59	Position identifier P_6
60–68	Control function bits
69	Position identifier P_7
70–78	Control function bits
79	Position identifier P_8
80–88	Nine lowest significant bits of time of day in straight binary seconds (bit 80 -> 2^0 … bit 88 -> 2^8)
89	Position Identifier P_9

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Table B-3. IRIG-B Bit Assignments (Continued)

Bit position	Information transmitted
90–97	Eight most significant bits of time of day in straight binary seconds (bit 90 -> 2^9 … bit 97 -> 2^{16})
99	Position identifier P_0
Bits not listed are index markers, and are sent as binary zeroes.	

The NI PXI-6682 uses the time of day information transmitted as BCD to synchronize its internal timebase. If the IRIG-B signal includes the year, then it also uses that information to synchronize its clock. Otherwise, it gets the year from the host computer. The NI PXI-6682 disregards the rest of the information contained in the IRIG-B signal. Therefore, when configured to synchronize to IRIG-B AM, the NI PXI-6682 supports IRIG-B 12X, and when configured to synchronize to IRIG-B DC, it supports IRIG-B 00X.

The following assumptions are made regarding the received IRIG-B signal. All conditions must be met for the NI PXI-6682 to be able to synchronize accurately:

- Seconds begin every minute at 0, increment to 59, and then roll-over to 0.
- Minutes begin every hour at 0, increment to 59, and then roll-over to 0.
- Hours begin every day at 0, increment to 23, and then roll-over to 0.
- Days begin every year at 1. Days increment to 365 in non-leap years, or to 366 in leap years, and then roll-over to 1. Leap years must be supported. Valid values for year are 01–99, inclusive. Years are assumed to be in the XXI Century. For instance, year *07* represents 2007. If the year is not supplied (sent as *00*), the OS system time is read and the year is derived from it.

To achieve proper synchronization of the NI PXI-6682 ensure that the IRIG-B source used conforms to the requirements listed above. Note that most IRIG-B sources conform to these requirements.

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C

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If you searched `ni.com` and could not find the answers you need, contact your local office or NI corporate headquarters. Phone numbers for our worldwide offices are listed at the front of this manual. You also can visit the Worldwide Offices section of `ni.com/niglobal` to access the branch office Web sites, which provide up-to-date contact information, support phone numbers, email addresses, and current events.

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Glossary

Symbol	Prefix	Value
p	pico	10^{-12}
n	nano	10^{-9}
µ	micro	10^{-6}
m	milli	10^{-3}
k	kilo	10^{3}
M	mega	10^{6}

Symbols

%	percent
±	plus or minus
+	positive of, or plus
–	negative of, or minus
/	per
°	degree
Ω	ohm

A

AC	alternating current
ADE	application development environment
asynchronous	a property of an event that occurs at an arbitrary time, without synchronization to a reference clock

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B

backplane	an assembly, typically a printed circuit board (PCB), with 96-pin connectors and signal paths that bus the connector pins. PXI systems have two connectors, called the J1 and J2 connectors.
bus	the group of conductors that interconnect individual circuitry in a computer. Typically, a bus is the expansion vehicle to which I/O or other devices are connected. An example of a PC bus is the PCI bus.

C

C	Celsius
CLKIN	CLKIN is a signal connected to the SMB input pin of the same name. CLKIN also can serve as PXI_CLK10_IN.
CLKOUT	CLKOUT is the signal on the SMB output pin of the same name. PXI_CLK10 can be routed to CLKOUT.
clock	hardware component that controls timing for reading from or writing to groups
CompactPCI	a Eurocard configuration of the PCI bus for industrial applications

D

DAQ	data acquisition—(1) collecting and measuring electrical signals from sensors, transducers, and test probes or fixtures and inputting them to a computer for processing; (2) collecting and measuring the same kinds of electrical signals with A/D and/or DIO devices plugged into a computer, and possibly generating control signals with D/A and/or DIO devices in the same computer
DC	direct current

E

ESD	electrostatic discharge

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F

frequency	the basic unit of rate, measured in events or oscillations per second using a frequency counter or spectrum analyzer. Frequency is the reciprocal of the period of a signal.
front panel	the physical front panel of an instrument or other hardware

G

GPS	Global Positioning System; worldwide system that allows you to receive precise location and timing information.

H

Hz	hertz—the number of scans read or updates written per second

I

IEEE	Institute of Electrical and Electronics Engineers
IEEE 1588	an IEEE standard used to synchronize separate devices
in.	inch or inches
IRIG	Inter Range Instrumentation Group
IRIG-B	a standard used to transmit precise timing information

J

jitter	the rapid variation of a clock or sampling frequency from an ideal constant frequency

L

LabVIEW	a graphical programming language
LED	light-emitting diode—a semiconductor light source

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M

master	the requesting or controlling device in a master/slave configuration
Measurement & Automation Explorer (MAX)	a controlled centralized configuration environment that allows you to configure all of your National Instruments DAQ, GPIB, IMAQ, IVI, Motion, VISA, and VXI devices

O

oscillator	a device that generates a fixed frequency signal. An oscillator most often generates signals by using oscillating crystals, but also may use tuned networks, lasers, or atomic clock sources. The most important specifications on oscillators are frequency accuracy, frequency stability, and phase noise.
output impedance	the measured resistance and capacitance between the output terminals of a circuit

P

PCI	Peripheral Component Interconnect—a high-performance expansion bus architecture originally developed by Intel to replace ISA and EISA. It is achieving widespread acceptance as a standard for PCs and work-stations; it offers a theoretical maximum transfer rate of 132 Mbytes/s.
PFI	Programmable Function Interface
PPS	Pulse Per Second
precision	the measure of the stability of an instrument and its capability to give the same measurement over and over again for the same input signal
propagation delay	the amount of time required for a signal to pass through a circuit
PXI	a rugged, open system for modular instrumentation based on CompactPCI, with special mechanical, electrical, and software features. The PXIbus standard was originally developed by National Instruments in 1997, and is now managed by the PXIbus Systems Alliance.

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PXI star	a special set of trigger lines in the PXI backplane for high-accuracy device synchronization with minimal latencies on each PXI slot
PXI_Trig/PXI_Star synchronization clock	the clock signal that is used to synchronize the PXI Triggers or PXI_STAR triggers on an NI PXI-6682
PXI Trigger	the PXI timing bus that connects PXI devices directly, by means of connectors on top of the devices, for precise synchronization of functions

S

s	seconds
skew	the actual time difference between two events that would ideally occur simultaneously. Inter-channel skew is an example of the time differences introduced by different characteristics of multiple channels. Skew can occur between channels on one module, or between channels on separate modules (intermodule skew).
slave	a computer or peripheral device controlled by another computer
slot	the place in the computer or chassis in which a card or module can be installed
Slot 2	the second slot in a PXI system which can house a master timing unit
SMB	sub miniature type B—a small coaxial signal connector that features a snap coupling for fast connection
synchronous	a property of an event that is synchronized to a reference clock

T

t_{CtoQ}	clock to output time
t_{hold}	hold time
t_{pd}	propagation delay time
TRIG	trigger signal
trigger	a digital signal that starts or times a hardware event (for example, starting a data acquisition operation)

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t_{setup}	setup time

V

V	volts
VI	virtual instrument

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