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300B Series Temperature Controllers

User's Manual

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EU Declaration of Conformity

We declare that the accompanying product, identified with the CE mark, complies with requirements of the Electromagnetic Compatibility Directive, 89/336/EEC and the Low Voltage Directive 73/23/EEC.

Model Number: Model 325B and 350B Series Temperature Controllers

Year CE mark affixed: 2004

Type of Equipment: Electrical equipment for measurement, control and laboratory use

Standards Applied:

Compliance was demonstrated to the following standards to the extent applicable:

BS EN61326-1: 1997+A1+A2 “Electrical equipment for measurement, control and laboratory use – EMC requirements”

This equipment meets the CISPR 11 Class A Group 1 radiated and conducted emission limits.

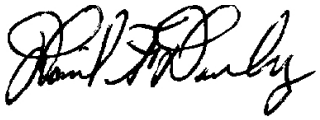
BS EN 61000-3-2:2001, Harmonic current emissions, Class A

BS EN 61000-3-3:2002, Voltage fluctuations and flicker

IEC 61010-1:2001 second edition “Safety requirements for electrical equipment for measurement, control and laboratory use”



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Warranty

Newport Corporation warrants that this product will be free from defects in material and workmanship and will comply with Newport's published specifications at the time of sale for a period of one year from date of shipment. If found to be defective during the warranty period, the product will either be repaired or replaced at Newport's option.

To exercise this warranty, write or call your local Newport office or representative, or contact Newport headquarters in Irvine, California. You will be given prompt assistance and return instructions. Send the product, freight prepaid, to the indicated service facility. Repairs will be made and the instrument returned freight prepaid. Repaired products are warranted for the remainder of the original warranty period or 90 days, whichever first occurs.

Limitation of Warranty

The above warranties do not apply to products which have been repaired or modified without Newport's written approval, or products subjected to unusual physical, thermal or electrical stress, improper installation, misuse, abuse, accident or negligence in use, storage, transportation or handling. This warranty also does not apply to fuses, batteries, or damage from battery leakage.

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First printing 2004

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This manual has been provided for information only and product specifications are subject to change without notice. Any change will be reflected in future printings.

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Part No. 41247-01, Rev. B

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Service Information

This section contains information regarding factory service for the source. The user should not attempt any maintenance or service of the system or optional equipment beyond the procedures outlined in this manual. Any problem that cannot be resolved should be referred to Newport Corporation.

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Technical Support Contacts

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Newport Corporation Calling Procedure

If there are any defects in material or workmanship or a failure to meet specifications, promptly notify Newport's Returns Department by calling 1-800-222-6440 or by visiting our website at www.newport.com/returns within the warranty period to obtain a **Return Material Authorization Number (RMA#)**. Return the product to Newport Corporation, freight prepaid, clearly marked with the RMA# and we will either repair or replace it at our discretion. Newport is not responsible for damage occurring in transit and is not obligated to accept products returned without an RMA#.

E-mail: rma.service@newport.com

When calling Newport Corporation, please provide the customer care representative with the following information:

- Your Contact Information
- Serial number or original order number
- Description of problem (i.e., hardware or software)

To help our Technical Support Representatives diagnose your problem, please note the following conditions:

- Is the system used for manufacturing or research and development?
- What was the state of the system right before the problem?
- Have you seen this problem before? If so, how often?
- Can the system continue to operate with this problem? Or is the system non-operational?
- Can you identify anything that was different before this problem occurred?

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1 Safety Precautions

1.1 Definitions and Symbols

The following terms and symbols are used in this documentation and also appear on the Model 300B Series Temperature Controllers where safety-related issues occur.

1.1.1 CSA Mark with “C” and “US” Indicators



Figure 1 CSA mark with “C” and “US” Indicators

The presence of the CSA mark with “C” and “US” indicates that it has been designed, tested and certified as complying with all applicable U.S. and Canadian safety standards.

1.1.2 European Union CE Mark



Figure 2 CE Mark

The presence of the CE Mark on Newport Corporation equipment means that it has been designed, tested and certified as complying with all applicable European Union (CE) regulations and recommendations.

1.1.3 Alternating voltage symbol



Figure 3 Alternating Voltage Symbol

This international symbol implies an alternating voltage or current.

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1.1.4 On

Figure 4 On Symbol

The On Symbol in the figure above represents a power switch position on the Model 300B Series Temperature Controllers. This symbol represents a Power On condition.

1.1.5 Off

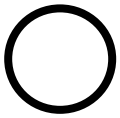


Figure 5 Off Symbol

The Off Symbol in the figure above represents a power switch position on the Model 300B Series Temperature Controllers. This symbol represents a Power Off condition.

1.1.6 Fuses



Figure 6 Fuse Symbol

The fuse symbol in the figure above identifies the fuse location on the Model 300B Series Temperature Controllers.

1.1.7 Frame or Chassis

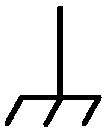


Figure 7 Frame or Chassis Terminal Symbol

This symbol identifies the frame or chassis terminal.

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1.1.8 Protective Conductor Terminal



Figure 8 Protective Conductor Terminal

The protective conductor terminal symbol in the above figure identifies the location of the bonding terminal, which is bonded to conductive accessible parts of the enclosure for safety purposes. The intent is to connect it to an external protective earthing system through the power cord.

1.2 Warnings and Cautions

The following are definitions of the Warnings, Cautions and Notes that are used throughout this manual to call your attention to important information regarding your safety, the safety and preservation of your equipment or an important tip.

WARNING

Situation has the potential to cause bodily harm or death.

CAUTION

Situation has the potential to cause damage to property or equipment.

NOTE

Additional information the user or operator should consider.

1.2.1 General Warnings

Observe these general warnings when operating or servicing this equipment:

- Heed all warnings on the unit and in the operating instructions.
- Do not use this equipment in or near water.
- This equipment is grounded through the grounding conductor of the power cord.
- Route power cords and other cables so they are not likely to be damaged.
- Disconnect power before cleaning the equipment. Do not use liquid or aerosol cleaners; use only a damp lint-free cloth.
- Lockout all electrical power sources before servicing the equipment.
- To avoid fire hazard, use only the specified fuse(s) with the correct type number, voltage and current ratings as referenced in the appropriate

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locations in the service instructions or on the equipment. Only qualified service personnel should replace fuses.

- To avoid explosion, do not operate this equipment in an explosive atmosphere.
- Qualified service personnel should perform safety checks after any service.

1.2.2 General Cautions

Observe these cautions when operating or servicing this equipment:

- Before applying power, carefully read the warning label placed over the AC power input receptacle in back of the instrument.

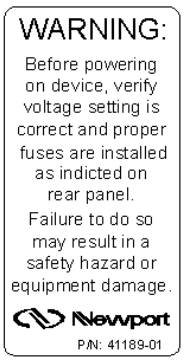


Figure 9 AC Receptacle Warning Label

- If this equipment is used in a manner not specified in this manual, the protection provided by this equipment may be impaired.
- To prevent damage to equipment when replacing fuses, locate and correct the problem that caused the fuse to blow before re-applying power.
- Do not block ventilation openings.
- Use only the specified replacement parts.
- Follow precautions for static sensitive devices when handling this equipment.
- This product should only be powered as described in the manual.
- There are no user-serviceable parts inside the Model 300B Series Temperature Controllers.
- To prevent damage to the equipment, read the instructions in the equipment manual for proper input voltage.
- Damage may occur if Voltage Select tumbler is turned without removing from the Input Power device.

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1.2.3 Summary of Warnings and Cautions

The following general warning and cautions are applicable to this instrument:

WARNING

Before operating the Model 300B Series Temperature Controllers, please read and understand all of Section 1.

WARNING

Do not attempt to operate this equipment if there is evidence of shipping damage or you suspect the unit is damaged. Damaged equipment may present additional hazards to you. Contact Newport technical support for advice before attempting to plug in and operate damaged equipment.

WARNING

To avoid electric shock, connect the instrument to properly earth-grounded, 3-prong receptacles only. Failure to observe this precaution can result in severe injury.

WARNING

To reduce the risk of electric shock or damage to the instrument, turn the power switch off and disconnect the power cord before replacing a fuse.

WARNING

Before cleaning the enclosure of the Model 300B Series Temperature Controllers, the AC power cord must be disconnected from the wall socket.

CAUTION

Make sure that the selector is set at the position that corresponds to your mains voltage. Follow directions in section 4.2.4 to properly set tumbler.

CAUTION

There are no user serviceable parts inside the Model 300B Series Temperature Controllers. Work performed by persons not authorized by Newport Corporation will void the warranty. For instructions on obtaining warranty repair or service, please refer to Section 8.

CAUTION

All units are factory preset to operate at 108-132VAC, 60Hz

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1.3 Location of Warnings

1.3.1 Rear Panel

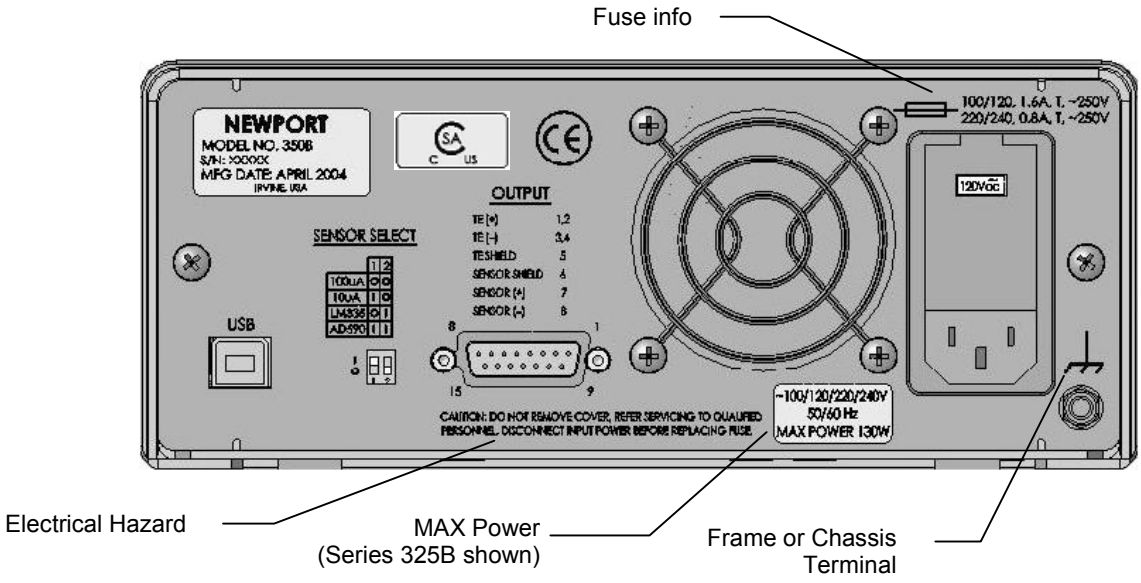


Figure 10 Locations of warnings on the rear panel

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2 General Information

2.1 Introduction

The intended use of the 300B Series Temperature Controllers is to precisely control the temperature of a thermo-electric (TE) cooler in a closed loop system using a variety of possible temperature sensors as the feedback. They offer a combination of features, performance, and value that is unmatched by other laser diode temperature controllers.

Three operating modes are user selectable: constant R (thermistor), constant T (IC sensors), or constant I_{TE} (TE cooler), while delivering high output power from 60 Watts to 130 Watts.

Quiet, safe and stable output current results from a P-I-D control circuitry with complete flexibility for adjustment through the Newport LDD/TEC Application software (included) or user developed programs. The PID control algorithm is implemented to achieve optimal stability and settling performance along with an I_{TE} current limit setting to protect TE coolers from damage, regardless of operating mode.

The P-I-D control loop renders performance for fast settling onto a low noise, bipolar current output in three operating modes: 1) constant thermistor resistance, 2) constant Temperature as monitored by an IC sensor, or 3) constant peltier-cooler (thermo-electric) temperature. A user adjustable TE-cooler current limit setting unconditionally protects the TE modules from damage by excessive drive current independent of the operating mode. The Model 300B Series of temperature controllers are compatible with thermistors, AD590 and LM135/335 Series IC temperature sensors. Temperature readings are displayed in °C when using IC sensors and provided as an option when using thermistors. A USB interface is standard feature in all models, permitting interfacing to a PC to control from Newport's LDD/TEC Application software or user's developed application using the included LabVIEW drivers.

Additional Benefits

1. Preset display lets you adjust operating setpoint before switching the output on
2. Low noise, bipolar current output
3. Wide TEC temperature range from -50 to +150°C

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4. Analog interface provides remote control capability

Specifications

		Model 325B	Model 350B
Output			
Type		Bipolar, constant current source	
TEC Control Loop Type		Hybrid P-I-D	
Maximum Current (A)		±2.5	±5
Compliance Voltage (V)		7	11
Available Output Power (W)		17.5	55
Accuracy (mA)		±5	±9
Resolution (mA)		0.042	0.084
Ripple/Noise (mA rms)		<0.03	<0.03
Current Limit			
Range (A)		0–2.52	0–5.05
Accuracy (mA)		±5	±9
Resolution (mA)		0.042	0.084
Stability			
	Short-Term Stability (1 h)	0.001°C	
	Long-Term Stability (24 h)	0.005°C	
Display			
Range			
	Temperature (°C)	-50.0 to +150.0°C	
	Resistance (10 µA) (kΩ)	0.1–200.0	
	Resistance (100 µA) (kΩ)	0.01–20.00	
	TE Current (A)	-2.50 to +2.50	-5.00 to +5.00
Resolution			
	Temperature	0.1°C	
	Resistance (10 µA) (Ω)	100	
	Resistance (100 µA) (Ω)	10	
	TE Current (mA)	10	
Accuracy			
	Temperature	±0.1°C	
	Resistance (10 µA)	±100Ω	
	Resistance (100 µA)	±10Ω	
	TE Current	±10	±10

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Temperature Sensors				
Sensor Type	Thermistor NTC 2-wire	AD592CN	LM135AH	LM335AZ
Temperature Control Resolution	0.01°C	0.1°C	0.1°C	0.1°C
Temp. Sensor Control Accuracy (at 25°C)	±0.2°C	±0.5°C	±1.0°C	±3.0°C
Sensor Bias	10/100 µA	+12 V	1 mA	1 mA

Overall Specifications

Voltage Requirements	~100/120/220/240 VAC +/-10%, 50–60Hz
Power Requirements	325B MAX POWER = 60W 350B MAX POWER = 130W
Chassis Ground	4 mm banana jack
Size (H x W x D) [in. (mm)]	3.5 (88) x 8.5 (215) x 12.6 (320)
Weight [lb (kg)]	8.9 (4.05)
Operating Temperature	0°C to 40°C (<90% humidity non-condensing)
Operating Altitude	3000 m (10,000 feet)
Storage Temperature	-29°C to + 60°C
Storage Relative Humidity	<85% humidity non-condensing
Safe Use Environment	Indoor
Electrical Class	1
Pollution Degree	2
Transient Overvoltage Category	2
Connectors	
Output Connectors TE Module and Sensor	15-pin female D-sub
Analog Output	BNC
USB Connector	Type B

Table 1 Specifications Tables

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2.2 Accessories

The Model 300B Series Temperature Controllers come with a line cord for connection to AC power. To order accessories use the following part numbers:

Model	Description
300-02	Temperature Controller Cable
300-04	TEC/Mount Cable
300-16	10.0 kW Thermistor (±0.2°C)
300-22	AD592CN IC Sensor (-45°C to +125°C Range)
35-RACK	Rack Mount Kit

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3 Getting Started

3.1 Unpacking and Handling

It is recommended that the Model 300B Series Temperature Controllers be unpacked in a lab environment or work site. Unpack the system carefully; small parts and cables are included with the instrument. Inspect the box carefully for loose parts before disposing of the packaging. You are urged to save the packaging material in case you need to ship your equipment in the future.

3.2 Inspection for Damage

The Model 300B Series Temperature Controllers are carefully packaged at the factory to minimize the possibility of damage during shipping. Inspect the box for external signs of damage or mishandling. Inspect the contents for damage. If there is visible damage to the instrument upon receipt, inform the shipping company and Newport Corporation immediately.

WARNING

Do not attempt to operate this equipment if there is evidence of shipping damage or you suspect the unit is damaged. Damaged equipment may present additional hazards to you. Contact Newport technical support for advice before attempting to plug in and operate damaged equipment.

3.3 Available Options and Accessories

Model 300B Series Temperature Controllers:

325B	2.5Amp Temperature Controller
350B	5.0Amp Temperature Controller

Accessories:

300-02	Temperature Controller Cable
300-04	TEC/Mount Cable
300-16	10.0 kW Thermistor (±0.2°C)
300-22	AD592CN IC Sensor (-45°C to +125°C Range)
35-RACK	Rack Mount Kit

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Newport Corporation also supplies temperature controlled mounts, lenses, and other accessories. Please consult with your representative for additional information.

3.4 Parts List

The following is a list of parts included with the Model 300B Series Temperature Controllers:

1. User's manual (CD) and a Printed Copy
2. Power cord
3. Temperature Controller
4. Fuses (2 pieces)
5. Temperature Controller Cable (Optional)
6. Temperature Controller /Mount Cable (Optional)
7. Rack Mount Kit (Optional)
8. Certificate of Calibration

If you are missing any hardware or have questions about the hardware you have received, please contact Newport Corporation.

3.5 Choosing and Preparing a Suitable Work Area

The Model 300B Series Temperature Controllers may be placed on any reasonably firm table or bench during operation (or Rack mounted with accessory 35-RACK). The front legs of the unit can be pulled out to tilt the unit at an angle, if desired.

Provide adequate distance between the Model 300B Series Temperature Controllers and adjacent walls for ventilation purposes. Approximately 2-inch spacing for all surfaces is adequate.

CAUTION

The primary means for disconnection from the AC mains is disconnecting the power cord from the instrument. Do not position this instrument that makes it difficult to disconnect the power cord.

3.6 Electrical Requirements

Before attempting to power up the unit for the first time, the following precautions must be followed:

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WARNING

To avoid electric shock, connect the instrument to properly earth-grounded, 3-prong receptacles only. Failure to observe this precaution can result in severe injury.

- Have a qualified electrician verify the wall socket that will be used is properly polarized and properly grounded.
- Set the mains selector tumbler to the voltage that matches the power outlet AC voltage. Follow directions in section 4.2.4 to properly set tumbler.

3.7 Power Supplies

AC power is supplied through the rear panel input power connector that provides in-line transient protection and RF filtering. The input power connector contains the fuses and the switch to select series or parallel connection of the transformer primaries for operation at 100VAC, 120VAC, 220VAC or 240VAC. Refer to paragraph 4.2.4 before applying power.

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4 System Operation

WARNING

Before operating the Model 300B Series Temperature Controllers, please read and understand all of Section 1.

4.1 Front Panel

The front panel of the Model 300B Series Temperature Controllers is arranged for easy operation. Six distinct areas, each with a specific set of related functions, and a control knob are located on the front panel, as shown in Figure 11 below.

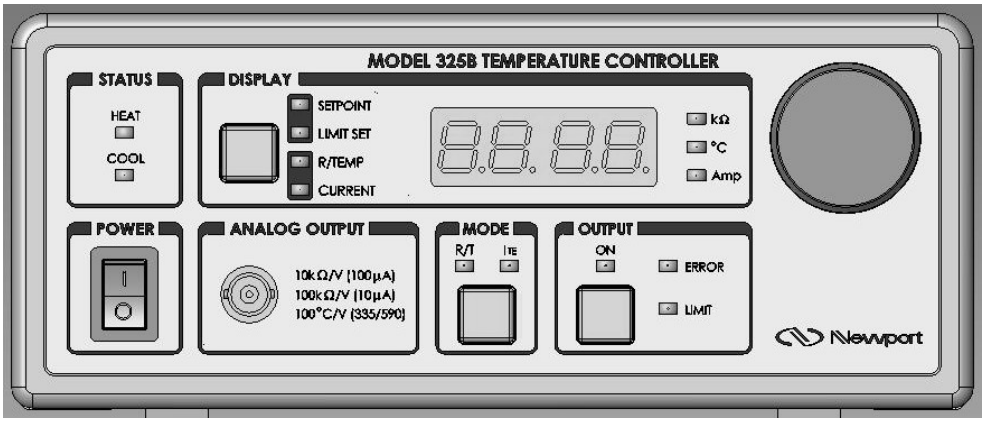


Figure 11 Front Panel Layout (325B shown)

4.1.1 AC Power Switch

When the AC power is turned on the unit starts up with the OUTPUT off, display in SETPOINT mode, and mode of operation in either R/T or ITE mode depending upon the mode selected when the unit was last turned OFF.

4.1.2 Analog Output

A BNC connector can be used to monitor the temperature sensor value. The transfer function of the output is dependent on the sensor type selected.

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The thermistor current selection values are either 10µA or 100µA and result in either 100 kΩ/V or 10 kΩ/V respectively. Both IC sensors have a transfer function of 100°C/V.

Analog Output Level, VDC (BNC Connector)

R/T or ITE MODE

Range	Output Voltage Level	Corresponding R/T Value
100µA	0 to 2V	0 to 20 kΩ
10µA	0 to 2V	0 to 200 kΩ
AD590	-0.50V to +1.50V	-50.0°C to +150°C
LM135	-0.50V to +1.50V	-50.0°C to +150°C
LM335	-0.40V to +1.00V	-40.0°C to +100°C

4.1.3 Mode Switch

The Model 300B Series can be operated in either 1) constant R (thermistor resistance), 2) constant T (thermistor and IC sensors), or 3) constant ITE mode. The R/T mode is used with temperature sensors and the ITE mode to maintain a constant output current. If constant T mode is selected and the sensor type is a thermistor, all temperature to resistance conversions are done using the Steinhart-Hart equation. Please refer to "TEC:CONST" command to modify the sensor constants.

4.1.4 Output Section

Output ON Switch

Pushing this switch allows current flow to the TE module. The output stays on, as indicated by the green LED above, until the switch is pushed again or an error condition occurs.

Error Indicator LED

An ERROR condition occurs when there is an open circuit to the TE module or temperature sensing device. The output current is automatically turned off. Once the device is replaced or reconnected, pushing the output switch twice will clear the error indication and restore the output on condition.

Limiting Indicator LED

This LED lights up whenever the output current reaches a user adjustable threshold, limiting the current flow to the TE module. It usually occurs during initial startup as the drive circuitry attempts to reach equilibrium.

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4.1.5 Status

The STATUS indicator LEDs show whether the device under temperature control is being heated or cooled.

4.1.6 Display

A 3 1/2 digit green LED display is located in the top center of the front panel. It reads in kΩ when displaying a thermistor resistance value, °C when displaying an IC sensor temperature or temperature equivalent to a thermistor resistance value, or Amps when in the constant current I_{TE} mode. Pushing the switch cycles through the display values as described below. Display modes can be toggled with the output on or off.

SETPOINT Display

The SETPOINT display mode is used to set the appropriate output value using the rotary control knob before turning the OUTPUT on. Once the control level is set, the OUTPUT may be turned on and the actual SENSOR or CURRENT value can be monitored.

LIMIT SET Display

This mode allows setting output current limit level with the control knob.

R/TEMP Display

The actual temperature sensor value is monitored in this mode. The value displayed depends on the sensor being used and the mode of operation. See table below for details.

	R MODE	T MODE	I_{TE} MODE
Thermistor	kΩ	°C	°C
IC Sensors	Not Applicable	°C	°C

CURRENT Display

This readout monitors the actual current level in Amps being supplied to the TE module. When the OUTPUT is first selected this current value may be as high as the LIMIT value. As the temperature stabilizes the output current will decrease.

Indicator LEDs

To the right of the numeric display are three LEDs which indicate measurement units: 1) resistance in kΩ, 2) temperature in °C, or 3) output current in Amps.

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4.1.7 Control Knob

The knob control on the right side of the front panel sets the appropriate reference value corresponding to either resistance (thermistor), temperature (thermistor and IC sensors), or TE current (I_{TE}) to be maintained by the Model 300B Series Temperature Controller.

4.2 Rear Panel

Figure 12 shows the layout of the rear panel that contains OUTPUT and USB connectors, the sensor select switch, and the AC power inlet.

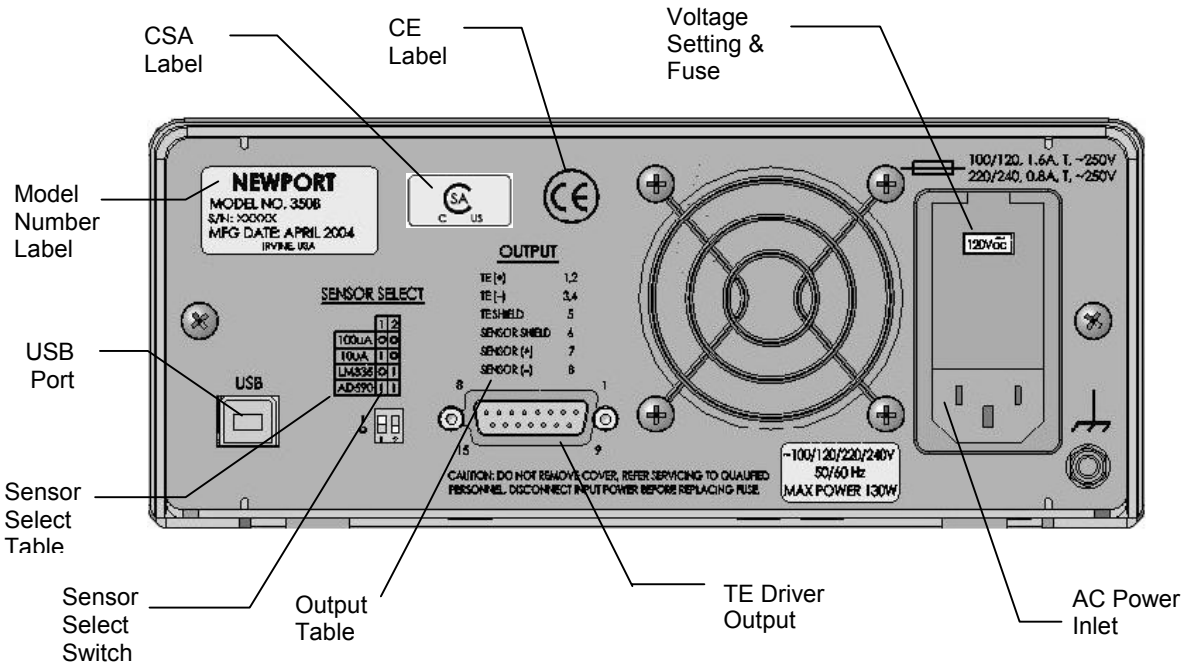


Figure 12 Rear Panel

4.2.1 USB Interface

The instrument is designed to communicate with standard USB interfaces. The cable required is a USB A/ B connection cable.

4.2.2 Sensor Select Switch

This dual-position DIP switch is used to select the appropriate bias for each one of the sensor types. The switch position for each sensor is printed on the rear panel next to the switch.

4.2.3 TE Driver Output Connector

Connections to the TE module and temperature sensor are made using a 15-pin, D-sub connector respectively. There are two pins each for the TE+ and

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TE- Connections to provide redundancy and reduce the voltage drop in the cable.

Pin #	Connection	Wire Color (300-02 cable)
1 & 2	TE +	RED
3 & 4	TE -	BLACK
5	TE SHIELD	
6	SENSOR SHIELD	
7	SENSOR +	GREEN
8	SENSOR -	WHITE

4.2.4 AC Power Inlet

The input voltage setting is indicated in a small window on the face of the power module. A small screwdriver is needed to flip down the panel once the AC line cord is removed. Carefully remove plastic tumbler and reinsert it to show the appropriate power grid voltage. The fuse is also located behind this panel and can be pulled out, for replacement with the appropriate size, as indicated on the back panel.

All units are preset at the factory for operation at 108-132VAC, 60HZ.

The fuse must be changed for 198-242VAC and 216-264VAC operation.

Select

- 100VAC for operation at 90-110VAC, 60Hz
- 120VAC for operation at 108-132VAC, 60Hz
- 220VAC for operation at 198-242VAC, 50Hz
- 240VAC for operation at 216-264VAC, 50Hz

The line cord supplied with each unit should be plugged only into a properly grounded three-prong outlet to prevent electrical shock in the event of an internal short circuit to the metal cabinet.

4.2.5 Frame or Chassis Terminal

This terminal provides the means to connect to the enclosure.

4.2.6 Power Inlet Socket

Plug the included power cord into the Power Inlet Socket on the rear of the instrument, then plug the power cord into a wall socket with proper earth grounding.

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5 Computer Interfacing

5.1 Memory

The calibration constants and other temperature controller parameters that must be retained even when the power is removed from the unit are stored in an electrically erasable programmable memory (EEPROM).

5.2 Commands and Queries

There are two types of device commands: commands that cause the instrument to take a desired action, and queries that return a stored value or state of the instrument. Queries must end with a question mark (?), while commands may require parameter(s) to follow:

TEC:LIMit:I 2.00

For example, the value "2.00" in the command **TEC:LIMit:I 2.00**, sets the output current limit at 2.00. Table 2 below summarizes all the commands and queries supported by the instrument. The command/query MUST contain all of the letters which are shown in upper case in this table. The lower case letters shown with the commands are optional, and may be used for clarity.

The commands may be sent to the instrument in either upper or lower case or in any combination. For example, the following commands are equal:

TEC:LIMit:I 2.00

TEC:LIM:I 2.00

tec:LIM:I 2.00

TeC:Lim:I 2.00

COMMAND EXECUTION:

The controller interprets the commands in the order they are received and execute them sequentially. If a set of commands have to be executed closer to each other, these commands can be sent to the controller simultaneously by creating a command string with semicolon (;) used as a command separator. The command string length should not exceed 50 characters. In the example shown below, a command string was created with semicolon

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separating 5 queries. The controller responds to this command string with a response that has 5 values using a comma (,) as a separator.

COMMAND STRING:

TEC:OUT?;TEC:SET:I?;TEC:I?;TEC:SET:R?;ERR?

INSTRUMENT RESPONSE:

0,1.25,0.00,10.00,0

COMMAND TERMINATION:

All commands sent to the instrument must be terminated by <Carriage Return><Line Feed>.characters. All responses sent out by the instrument are terminated by the same characters.

NOTE

For compatibility, some commands have optional entries; such as **TEC:ITE**, which can also be **TEC:I**. Options are shown in Table 2 as parenthesis; such as **TEC:ITE (I)**. After Table 2, each command and query is detailed.

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Commands common to both Temperature Controllers and Laser Diode Drivers:

Command Syntax	Command Description	Remarks
***CLS**	Clear status and response buffer command	
***IDN?**	Identification Query	
***RCL**	Recall Settings	Restore instrument to setup state stored in its non-volatile local memory
***RST**	Reset Instrument	
***SAV**	Save Settings	Save instrument's current settings in its non-volatile local memory
***STB?**	Status Byte Query	Returns "message available" and "error message available" status and "output out of tolerance" status
ADDRess	Address Command	Sets the controller USB address
ADDRess?	Address Query	Returns the controller's USB address
ERRors?	Error query	Returns error code
ERRSTR?	Error string query	Returns error string
HWTemp?	Temperature query	Returns instrument temperature in deg. C
LOCAL	Return to local mode	Makes front panel buttons active

Commands specific to Temperature Controllers:

Command Syntax	Command Description	Remarks
TEC:CONST	TEC sensor constants command	
TEC:CONST?	TEC sensor constants query	
TEC:GAIN:PID	TEC PID settings	
TEC:GAIN:PID?	TEC PID settings query	
TEC:ITE(I)	TEC I_{TE} set point	
TEC:ITE? (I?)	TEC measured I_{TE} query	
TEC:LIMit:ITE(I)	TEC I_{TE} current limit set	
TEC:LIMit:ITE? (I?)	TEC I_{TE} current limit set query	
TEC:MODE:ITE(I)	I_{TE} mode	
TEC:MODE:R	Resistance mode	Valid if sensor is thermistor
TEC:MODE:T	Temperature mode	Valid for thermistor and IC sensors
TEC:MODE?	TEC mode query	
TEC:OUTput	TEC output enable/disable	
TEC:OUTput?	TEC output enable status query	
TEC:R	TEC thermistor set point	Valid if sensor is thermistor
TEC:R?	TEC measured R query	Valid if sensor is thermistor
TEC:SENsor?	TEC sensor type setting query	
TEC:SET:ITE? (I?)	TEC I_{TE} set point query	
TEC:SET:R?	TEC thermistor set point query	Valid if sensor is thermistor
TEC:SET:T?	TEC temperature set point query	Valid for thermistor and IC sensors
TEC:T	TEC temperature set point	Valid for thermistor and IC sensors
TEC:T?	TEC measured temperature query	Valid for thermistor and IC sensors

Table 2 Command Summary

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*CLS

Description Clear status and response buffer command

Syntax ***CLS**

Remarks The ***CLS** command is used to clear the status byte register and the response buffer. This command may be issued if query commands and their responses fall out of sync with each other.

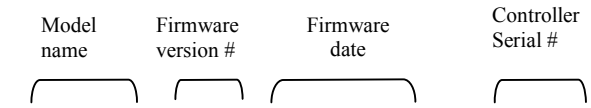
See Also ***STB?**

*IDN?

Description Identification query.

Syntax ***IDN?**

Remarks This query will cause the instrument to return an identification string.



NEWPORT XXXX vYYY mm/dd/yy, SN ZZZZ

Examples:
NEWPORT 325B v2.00 05/17/04,SN 1
NEWPORT 350B v2.00 05/17/04,SN 1

*RCL

Description Recall command.

Syntax ***RCL value**

Argument	Value	Description
Value	0	Restores Factory Default settings
	1	Restores last saved working setting
	2	Restores last saved user settings

Remarks The recall command restores the instrument to the setup state which was last saved using *SAV Command.

See Also ***RST**, ***SAV**

*RST

Description Reset command.

Syntax ***RST**

Remarks The reset command performs a device reset.

See Also ***RCL**

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*SAV

Description Save command.

Syntax ***SAV value**

Argument	Value	Description
Value	**0**	**Invalid**
	1	**Saves current settings to working settings**
	2	**Saves current settings to user settings**

Remarks The save command stores the current state of the instrument in non-volatile local memory. This state is then recalled by using the ***RCL** recall command.

See Also ***RCL**

*STB?

Description Status Byte Register query.

Syntax ***STB?**

Remarks The Read Status Back query allows the programmer to read the Status Byte Register.

Response	Description	
Status Byte Register	bit 0	Reserved
	bit 1	Reserved
	bit 2	Reserved
	bit 3	Reserved
	bit 4	Message Available
	bit 5	Reserved
	bit 6	Reserved
	bit 7	Error Message Available

ADDRess

Description USB address command.

Syntax **ADDRess** value

Remarks **The ADDRess** command sets the instrument USB address. After changing USB address, the communication with the instrument has to be re-initialized. This can be accomplished by calling "InitSystem" function in the DLL available in the CD provided with the instrument.

Argument	Value	Description	
	Value	*0*	*Reserved*
		1 to 99	*Valid USB address range*

See Also **ADDRess?**

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ADDRess?

Description USB address query.

Syntax **ADDRess?**

Remarks **The ADDRess** query returns the controller's USB address.

Response	Value	Description
address	*0*	*Reserved*
	1 to 99	*Valid USB address range*

See Also **ADDRess**

ERRors?

Description Error query.

Syntax **ERRors**?

Remarks The **ERRors?** query returns a list of commands and device errors which have occurred since the last query. These errors are indicated by a number that corresponds to the type of error which occurred.

Response	Description
Error code	Error code number, 0 if no errors

See Also **ERRSTR?**

Error Messages

0 NO ERROR
No errors exist in the output buffer.

115 IDENTIFIER NOT VALID
The issued command does not exist. Check the command syntax.

200 REMOTE MODE
Instrument is presently in remote mode. As a result, the rotary knob, "MODE" and "OUTPUT" switches have been made inactive. Issue "LOCAL" command to make the knob and switches active.

201 VALUE OUT OF RANGE
The specified parameter is out of range. Refer to the description of issued command for valid parameter range.

402 SENSOR OPEN
The output has been turned OFF because the input voltage from AD590 sensor is less than –0.50V or voltage from LM135/335 sensor is greater than 1.50V. Once the fault is corrected, "TEC:OUTput 1" command must be issued once to clear the error indication, and a second time to restore current to the TE module.

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405 COMP VOLTAGE LIMIT ERROR

The output has been turned OFF because the forward voltage drop of a TE module exceeds the compliance voltage specified in the Specification table. Once the fault is corrected, "TEC:OUTput 1" command must be issued once to clear the error indication, and a second time to restore current to the TE module.

409 SENSOR CHANGE

The output has been turned OFF because a sensor change was done by modifying the sensor select switch setting. Sensor select switch is located in the rear panel of the instrument.

415 SENSOR CHANGE

The output has been turned OFF because the input voltage from AD590 sensor is greater than 1.50V or voltage from LM135/335 sensor is less than –0.50V. Once the fault is corrected, "TEC:OUTput 1" command must be issued once to clear the error indication, and a second time to restore current to the TE module.

419 MODE CHANGE

The output has been turned OFF because a mode change was commanded using either "TEC:MODE:I" or "TEC:MODE:R" or "TEC:MODE:T" commands.

420 SENSOR MISMATCH

The command issued is not supported for the selected sensor type. This message is obtained when an IC sensor is selected, and resistance related commands are issued.

901 SYSTEM OVER TEMPERATURE ERROR

The output has been turned OFF because temperature inside the instrument has exceeded 75 degC. Once the fault is corrected, "TEC:OUTput 1" command must be issued once to clear the error indication, and a second time to restore current to the TE module.

ERRSTR?

Description Error string query.

Syntax **ERRSTR**?

Remarks The **ERRSTR?** query returns a list of commands and device error numbers along with the corresponding error text strings which have occurred since the last query.

Response	Description
Error code, "text"	Error code and text for error code as per chapter, 0 if no errors

See Also **ERRors?**

HWTemp?

Description Hardware (chassis) temperature query.

Syntax **HWTemp?**

Remarks The **HWTemp?** query returns the value of the hardware temperature measurement.

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Response	Description
measured temp	Measured temperature in °C

This measurement is updated approximately once every 225 milliseconds.

LOCAL

Description Return to local mode (from USB remote)

Syntax **LOCAL**

Remarks Returns the controller to local mode after being placed in remote mode by the USB interface. The instrument will be set to Local Mode if no commands are sent to it via its USB interface for 10-seconds.

TEC:CONST

Description TEC sensor constants command.

Syntax **TEC:CONST** *C1, C2, C3*

Remarks The **TEC:CONST** command sets the TEC constants for the Steinhart-Hart equation for thermistors.

Argument	Description	
For thermistors		
C1	$\pm 9.999 \times 10^{-3}$	Steinhart-Hart constants
C2	$\pm 9.999 \times 10^{-4}$	
C3	$\pm 9.999 \times 10^{-7}$	

See Also **TEC:CONST?**

TEC:CONST?

Description TEC sensor constants query.

Syntax **TEC:CONST?**

Remarks The **TEC:CONST?** query returns the TEC constants for the Steinhart-Hart equation for thermistors.

Response	Description
C1	See **TEC:CONST** for a description of these constants.
C2	
C3	

See Also **TEC:CONST**

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TEC:GAIN:PID

Description TEC PID controller gain constants command.

Syntax **TEC:GAIN:PID Kp,Ki,Kd**

Remarks The **TEC:GAIN:PID** command sets the proportional, integral and derivative control gain constants.

Argument	Value	Description
Kp	1 to 1000	Proportional gain constant
Ki	1 to 1000	Integral gain constant
Kd	1 to 1000	Derivative gain constant

Examples TEC:GAIN:PID 50,2,20

Action: sets Kp to 50; Ki to 2; Kd to 20

See Also **TEC:GAIN:PID?**

TEC:GAIN:PID?

Description TEC PID controller gain constants query.

Syntax **TEC:GAIN:PID?**

Remarks The **TEC:GAIN:PID?** command returns the proportional, integral and derivative control gain constants.

Response	Description
Kp	Proportional gain constant
Ki	Integral gain constant
Kd	Derivative gain constant

See Also **TEC:GAIN:PID**

TEC:ITE(I)

Description TEC I_{TE} set point command.

Syntax **TEC:ITE** *set point*

Remarks The **TEC:ITE** command sets the TEC control current set point.

Argument	Description
set point	set point in Amps

See Also **TEC:ITE?, TEC:LIMit:ITE, TEC:SET:ITE?**

TEC:ITE?(I?)

Description TEC measured I_{TE} query.

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Syntax **TEC:ITE?**

Remarks The **TEC:ITE?** query returns the value of the measured TEC output current.

Response	Description
measured output	Current in Amps

The TEC current is constantly measured and updated, regardless of the TEC mode of operation.

This measurement is updated approximately once every 225 milliseconds.

See Also **TEC:ITE**

TEC:LIMit:ITE

Description TEC ITE current limit command

Syntax **TEC:LIMit:ITE** *limit*

Remarks The **TEC:LIMit:ITE** command sets the TEC ITE current limit value.

Argument	Description
limit	Limit in Amps

The factory default current limit is 50% of the maximum current.

See Also **TEC:ITE**

TEC:LIMit:ITE?

Description TEC ITE current limit query

Syntax **TEC:LIMit:ITE?**

Remarks The **TEC:LIMit:ITE?** query returns the value of the TEC current limit.

Response	Description
limit	Limit in Amps

See Also **TEC:LIMit:ITE**

TEC:MODE:ITE(I)

Description TEC ITE mode command.

Syntax **TEC:MODE:ITE**

Remarks The **TEC:MODE:ITE** command selects TEC constant current mode.

Changing modes causes the output to be forced off, and the new mode's set point value will be displayed.

See Also **TEC:I, TEC:MODE?**

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TEC:MODE:R

Description TEC R mode command.

Syntax **TEC:MODE:R**

Remarks The **TEC:MODE:R** command selects TEC constant thermistor resistance mode.

Since sensor resistance (or linear sensor reference) is a function of temperature, this mode also controls the TEC output temperature, but it bypasses the use of the conversion constants for set point calculation. This allows finer control of temperature in cases where the sensor's temperature model (and therefore the constants) is not known.

Changing modes causes the output to be forced off, and the new mode's set point value will be displayed.

See Also **TEC:MODE?, TEC:R**

TEC:MODE:T

Description TEC temperature mode command.

Syntax **TEC:MODE:T**

Remarks The **TEC:MODE:T** command selects TEC constant temperature mode.

Since TEC temperature is derived from thermistor or RTD resistance, or, linear sensor current or voltage, constant R and T modes are related. In T mode the set point is converted to resistance voltage or current by using the appropriate constants and conversion model.

Changing modes causes the output to be forced off, and the new mode's set point value will be displayed.

See Also **TEC:MODE?, TEC:T**

TEC:MODE?

Description TEC control mode query.

Syntax **TEC:MODE?**

Remarks The **TEC:MODE?** query returns the selected TEC control mode.

Response	Value	Description
mode	ITE	constant current
	R	constant R
	T	constant T

See Also **TEC:MODE:ITE, TEC:MODE:R, TEC:MODE:T**

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TEC:OUTput

Description TEC output enable command.

Syntax **TEC:OUTput** *enable*

Remarks The **TEC:OUTput** command enables or disables the TEC output.

Argument	Value	Description
enable	0	off
	1	on

After the output is turned on, it may be useful to wait until the output is stable (within tolerance) before performing further operations.

See Also **TEC:OUTput?**

TEC:OUTput?

Description TEC output enable query.

Syntax **TEC:OUTput?**

Remarks The **TEC:OUTput?** query returns the status of the TEC output.

Response	Value	Description
enable	0	off
	1	on

Although the status of the switch is on, the output may not have reached the set point value.

See Also **TEC:OUTput**

TEC:R

Description TEC R set point command.

Syntax **TEC:R** *set point*

Remarks The **TEC:R** command sets the TEC constant thermistor set point.

Argument	Description
set point	Thermistor set point in k Ohms

See Also **TEC:R?**

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TEC:R?

Description TEC measured R query.

Syntax **TEC:R?**

Remarks The **TEC:R?** query returns the value of the TEC thermistor measurement.

Response	Description
R value	Measured Thermistor resistance in k Ohms

This measurement is updated approximately once every 225 milliseconds.

See Also **TEC:R**

TEC:SENsor?

Description TEC sensor select query.

Syntax **TEC:SENsor?**

Remarks The **TEC:SENsor?** query returns the sensor type. This value is a coded representation of the sensor type/thermistor current. Refer to the The Steinhart-Hart Equation, Section 7.2.1, for further details.

Response	Description	
sensor	1	Thermistor at 100 µA drive
	2	Thermistor at 10 µA drive
	3	LM335
	4	AD590

See Also **TEC:SENsor**

TEC:SET:ITE?(I?)

Description TEC ITE set point query.

Syntax **TEC:SET:ITE?**

Remarks The **TEC:SET:ITE?** query returns the TEC constant current set point value.

Response	Description
set point	ITE set point in Amps

See Also **TEC:I**

TEC:SET:R?

Description TEC R set point query.

Syntax **TEC:SET:R?**

Remarks The **TEC:SET:R?** query returns the TEC constant thermistor set point value.

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Response	Description
set point	Thermistor set point in k Ohms

See Also **TEC:R**

TEC:SET:T?

Description TEC temperature set point query.

Syntax **TEC:SET:T?**

Remarks The **TEC:SET:T?** query returns the TEC constant temperature set point value in °C.

Response	Description
set point	Set point in °C

See Also **TEC:T**

TEC:T

Description TEC temperature set point command.

Syntax **TEC:T**

Remarks The **TEC:T** command sets the TEC constant temperature set point.

Argument	Description
set point	Set point in °C

See Also **TEC:SET:T?, TEC:T?**

TEC:T?

Description TEC measured temperature query.

Syntax **TEC:T?**

Remarks The **TEC:T?** query returns the value of the TEC temperature measurement.

Response	Description
measured temp	Measured temperature in °C

This measurement is updated approximately once every 225 milliseconds.

See Also **TEC:T**

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6 Software Application

6.1 Overview

The 300B/500B Controllers have a USB 2.0 connector on the back of the unit that is used to connect to a computer. This connector will work with USB 1.0 and 1.1 also, as it is fully backwards compatible.

Provided on the CD that comes with the unit is an installation for a software application that communicates with the 300B/500B using the USB port. The installation installs the USB drivers that are required to use USB communication.

The design of the software is to allow the user to remotely control the functions of the instrument.

6.2 Connection

Set the USB (Virtual) Address and click the CONNECT button to start communicating with the instrument.

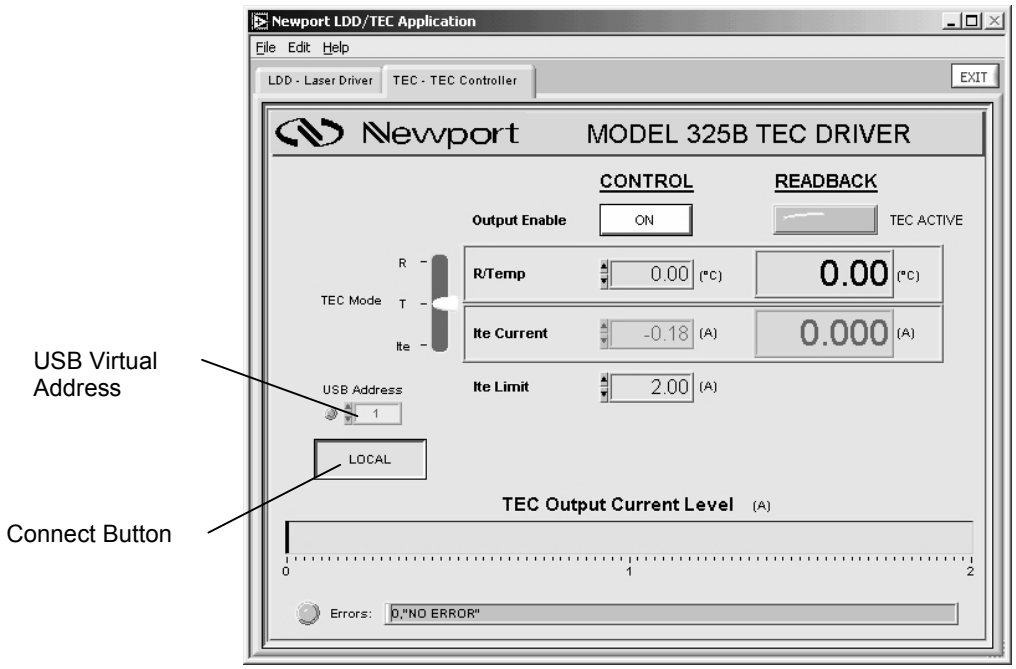


Figure 13 Application front panel (TEC Tab)

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6.3 General Usage

This software application allows the user to setup and monitor the instrument remotely.

The controls on the instrument are available in the software in a very easy to read and change format.

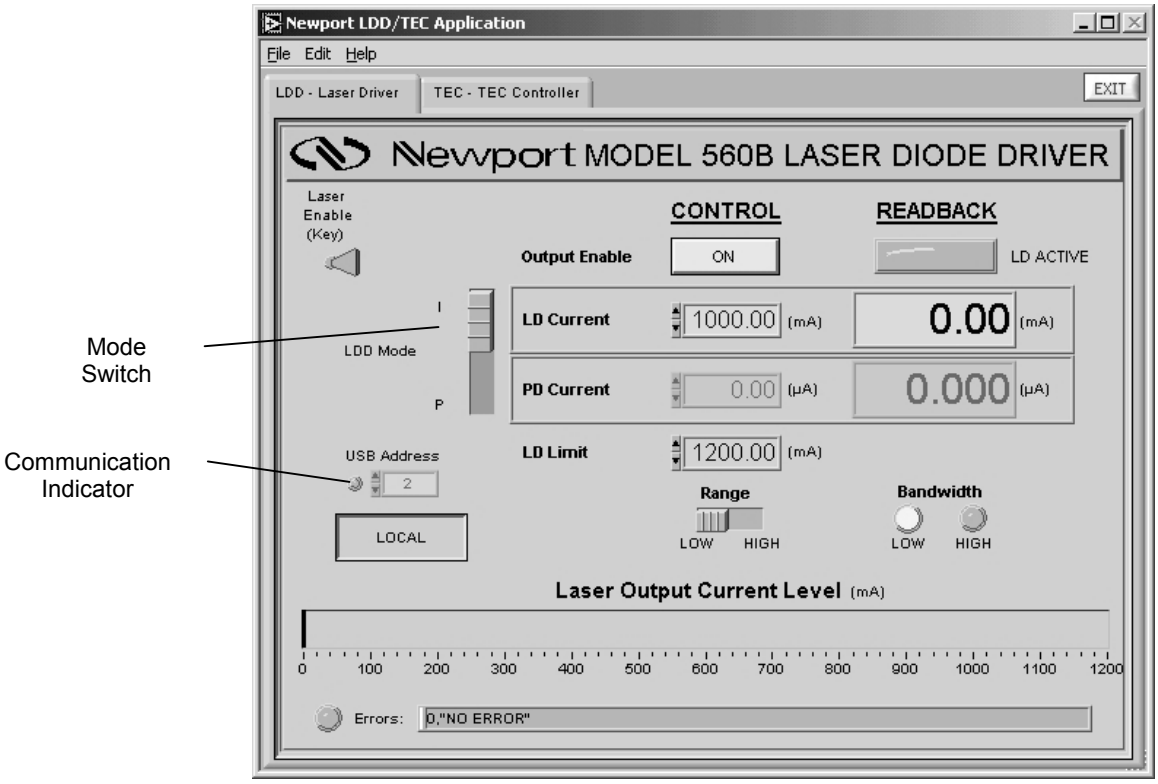


Figure 14 Application front panel when communicating (LDD Tab)

The software has two tabs, one for the (300B) TEC specific functions, and one for the (500B) LDD functions. The individual TEC and LDD specific tabs have two columns labeled on the top as CONTROLS and READBACK.

6.3.1 LDD Tab

CONTROLS:

LDD Mode	- Sets I/P mode of control
Output Enable	- Turns on/off the output
LD Current	- Sets the forward laser current
PD Current	- Sets the monitor diode (PD) current
LD Limit	- Set the maximum limit for forward current

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Range	- Set the operating range - Low/High

READBACK:

Output Enable	- Displays output on/off state
LD Current	- Displays the forward laser current
PD Current	- Displays the monitor diode (PD) current
Bandwidth	- Displays the current bandwidth setting

6.3.2 TEC Tab

CONTROLS:

TEC Mode	- Sets R/T/I mode of control
Output Enable	- Turns on/off the output
Temp/R	- Sets the Temperature or Resistive setpoint
I_{TE}	- Sets TEC Current
I_{TE} Limit	- Set the maximum limit for TEC current

READBACK:

Output Enable	- Displays output on/off state
Temp/R	- Displays the Temperature or Resistance
I_{TE}	- Displays the TEC Current

The Laser Output Current Level display on the bottom is a visual indicator of the current readback for forward current (LD Current), with the upper limit of LD Limit.

On the very bottom are an Error indicator light and a display of the last Errors, if any.

6.4 Menu Structure

To Exit the application go to the File menu and select Exit.

The Edit/TEC Settings menu option had additional TEC settings, such as PID gain settings.

The Edit/Advanced Properties menu option had additional property settings, including search for instruments and data logging options.

The File/Print will print the window.

The Help/About will show information about the application.

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7 Principles of Operation

7.1 Introduction

Three factors must be taken into account when optimizing the operation of a Model 300B Series Temperature Controller: selection of both the appropriate temperature sensor and TE module heat sink, and the manner in which they are mounted. Selecting the proper thermistor to cover a specific temperature range of operation is a simple but important procedure. The proper TE module must be selected to remove the heat dissipated by the laser diode or other device. Finally, the arrangement of the TE module and the heat sink, as well as the heat sink size, are crucial in maximizing the heat transfer efficiency.

7.2 Thermistor

Model 300B Series Temperature Controllers are designed to operate using a thermistor as one of the temperature sensing devices. Temperature is displayed as a resistance (kΩ) corresponding to the temperature of the thermistor. The actual temperature of the thermistor can be determined from the manufacturers curves or tables listing temperature vs. resistance. Two precision current sources, 10µA and 100µA, are used to generate a voltage across the thermistor and it is this voltage that is read on the front display. For the 10µA current source the maximum resistance that can be displayed is 200.0 kΩ, while for the 100µA source the maximum reading is 20.0 kΩ. The minimum resistance value that can accurately be read is 200 ohms (100µA current source). These two current values allow a wide range of temperatures to be controlled by the Model 300B Series Temperature Controllers. Different ranges of temperatures can be adjusted for by selecting the proper thermistor value. The following table illustrates this point:

Temperature vs. Thermistor Resistance

Thermistor value @ 25°C	1k	10k	100k
200 kΩ	-75°C	-37°C	-11°C
100 kΩ	-66°C	-24°C	25°C
20 kΩ	-40°C	8°C	65°C
10 kΩ	-27°C	25°C	85°C
1 kΩ	25°C	93°C	>150°C
100 kΩ	100°C	>150°C	>150°C
100 Ω	100°C	>150°C	>150°C

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Careful thermistor value selection therefore enables control over a wide temperature range.
The temperature resolution and thermistor sensitivity must also be taken into account. Thermistors achieve their highest sensitivity at the lower end of their temperature range. Therefore, the lower the absolute temperature to be maintained, the lower the resistance value the thermistor should be. For example, to operate at 0°C a 5k ohm thermistor would be the best selection while at 100°C a 100k ohm thermistor would be a better selection.
The rule of thumb is to operate the thermistor near the lower end of its temperature range and use the 100µA current bias. Please contact Newport's applications engineers if you have any questions regarding the selection of the proper thermistor for your application.
Thermistors have large resistance variations over temperature. Therefore, users should check if the thermistor resistance value over the desired temperature range, times the thermistor current (10µA or 100µA) is inside the voltage span of 0 to 2V for proper operation of the thermal feedback loop. This can be checked by monitoring the voltage at the front panel BNC connector (Analog Output).

7.2.1 The Steinhart-Hart Equation

The Steinhart-Hart equation is used to derive temperature from the non-linear resistance of an NTC (Negative Temperature Coefficient) thermistor.

Two terminal thermistors have a non-linear relationship between temperature and resistance. The resistance versus temperature characteristics for a family of similar thermistors is shown in Figure15. The resistance-versus-temperature relationship for most common negative temperature coefficient (NTC) thermistors can be accurately modeled by a polynomial expansion relating the logarithm of resistance to inverse temperature. The Steinhart-Hart equation is one such expression and is given as follows:

$1/T = C1 + C2\ (Ln\ R) + C3\ (Ln\ R)^3$

Where T is in Kelvin. To convert T to °C, subtract 273.15.

Once the three constants C1, C2, and C3 are accurately determined, only small errors in the calculation of temperature over wide temperature ranges exist. Table3 shows the results of using the equation to fit the resistance verses temperature characteristic of a common 10 k Ohm (at room temperature) thermistor. The equation will produce temperature calculation errors of less than 0.01°C over the range -20 °C to 50 °C.

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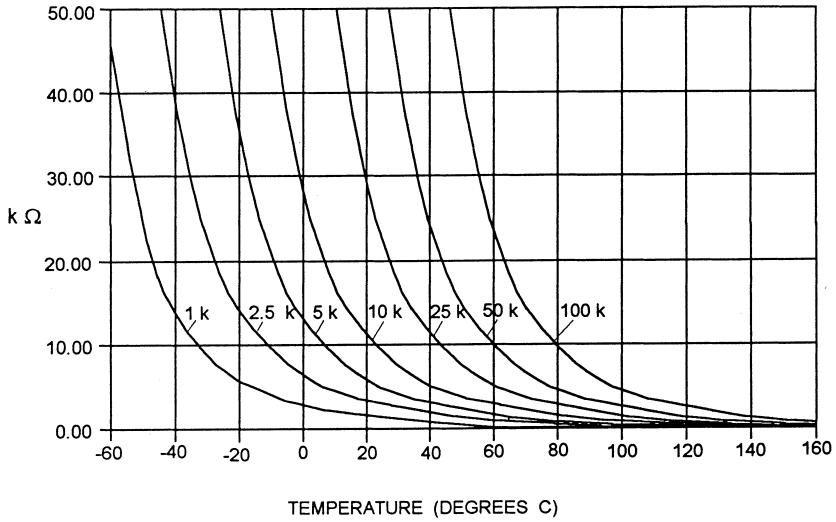


Figure 15 Thermistor Resistance versus Temperature

	Error T (°C)	
R[1]	T Actual	Third Order Fit. Eq. 1[2]
97072	-20.00	-0.32
55326	-10.00	-0.06
32650	0.00	0.09
19899	10.00	0.15
12492	20.00	0.13
10000	25.00	0.08
8057	30.00	0.01
5326	40.00	-0.20
3602	50.00	-0.50

Table 3 Comparison of Curve Fitting Equations

The constants C1, C2, and C3 may all be expressed in the form n.nnn simplifying entry into the 300B.

7.2.2 Table of Constants

We have listed some common thermistors and included the appropriate calibration constants for the temperature range -20 °C to 50 °C in Table 4. Model 300B, by default, uses the BetaTHERM 10K3A2 thermistor values.

[1] Resistance of a 10K, Fenwal UUA41J1 thermistor.
[2] Constants C1 = $1.125 * 10^{-3}$
C2 = $2.347 * 10^{-4}$
C3 = $0.855 * 10^{-7}$

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Manufacturer	*C1*10^{-3}*	*C2*10^{-4}*	*C3*10^{-7}*
BetaTHERM 10K3	1.129241	2.341077	0.877547
BetaTHERM 0.1K1	1.942952	2.989769	3.504383
BetaTHERM 0.3K1	1.627660	2.933316	2.870016
BetaTHERM 1K2	1.373419	2.771785	1.999768
BetaTHERM 1K7	1.446659	2.682454	1.649916
BetaTHERM 2K3	1.498872	2.379047	1.066953
BetaTHERM 2.2K3	1.471388	2.376138	1.051058
BetaTHERM 3K3	1.405027	2.369386	1.012660
BetaTHERM 5K3	1.287450	2.357394	0.950520
BetaTHERM 10K3	1.129241	2.341077	0.877547
BetaTHERM 10K4	1.028444	2.392435	1.562216
BetaTHERM 30K5	0.933175	2.213978	1.263817
BetaTHERM 30K6	1.068981	2.120700	0.901954
BetaTHERM 50K6	0.965715	2.106840	0.858548
BetaTHERM 100K6	0.827111	2.088020	0.805620
BetaTHERM 1M9	0.740239	1.760865	0.686600

Table 4 Thermistor Constants

7.3 Working With IC Sensors

Two IC temperature sensors may be used with the Model 300B Series Temperature Controllers, the AD590 Series and the LM135/335 Series. Both come in several different package types having various accuracy and stability characteristics. These temperature sensors are easy to use and give a temperature reading directly in °C on the Model 300B Series display. Sensor selection is accomplished in the Sensor Select block of the TEC board, LM135/335 and AD590 IC temperature sensors may also be selected. The AD590 has a +12 VDC bias voltage, and the LM135/335 has a 1mA bias current.

The output of the Sensor Select block of the TEC board is a voltage which is proportional to the actual temperature. This voltage is fed to the A/D converter which provides a digital measurement to the microprocessor, and is also fed to the PID control loop to close the feedback loop when the temperature is being controlled.

7.3.1 AD590 Series IC Sensors

The AD590 Series devices are two-terminal IC temperature sensing devices, which produce an output current directly proportional to the absolute temperature at 1µA/°K. The AD590 Series sensor is particularly useful in remote sensing applications where long cable lengths are used, due to its high impedance current output. A linear output is displayed in °C on the Model 300B Series Temperature Controller, which makes it ideally suited for most temperature sensing applications. The recommended upper operating limit for AD590 Series devices is 150°C.

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7.3.2 LM135/335 Series IC Sensors

The LM135/335 Series devices are similar to the AD590 in that they are two terminal devices and their output is directly proportional to absolute temperature. Operating like a two terminal zener diode, the LM135/335 Series temperature sensors have a breakdown voltage directly proportional to absolute temperature at +10mV/°K. When using the LM135/335 Series sensors, voltage drops resulting from using long cables will introduce inaccuracies in the temperature display measurement.

7.4 Using Thermo-Electric Modules

Thermo-electric (TE) modules are semiconductor devices that act as heat pumps when a voltage is applied to them. This effect is called Peltier cooling or heating. The direction of the current flow determines whether the TE module is cooling or heating a device such as a laser diode or IR detector. A TE module consists of a matrix of thermoelectric couples made of p-type and n-type semiconductor material. A TE module can be fabricated with as few as one couple or with as many as several hundred couples sandwiched between two ceramic plates. The ceramic plates form the top and bottom of the TE module and provide structural integrity as well as electrical insulation from, and thermal conduction to, the heat sink and the device being cooled or heated.

Model 300B Series Temperature Controllers are designed to control the rate and amount of cooling or heating through the use of a feedback loop. The arrangement of the TE module in the cooling mode is shown in Figure 16. When a positive DC voltage is applied to the n-type element, electrons pass from the p-type to the n-type elements and the temperature decreases as heat is absorbed by the cold side of the TE module. The heat absorbed is proportional to the amount of current flowing through the TE module and the number of p-type and n-type elements in the TE module.

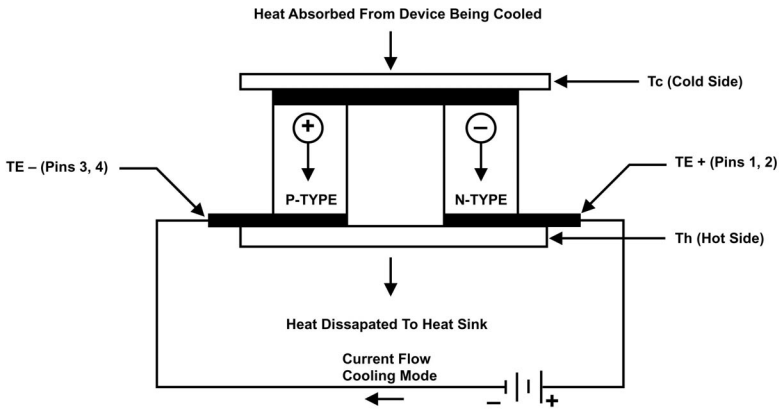


Figure 16 TE Module Configuration

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It is necessary to remove the heat from the hot side of the TE module. The amount of heat to be dissipated is equal to the heat pumped from the cold side plus the input power to the TE module. Although the amount of cooling is proportional to the current flowing through the TE module, the power dissipated by Joule heating (input power heating) in the TE module is proportional to the square of the current. Half of this heat must be pumped from the cold side of the TE module. When exceeding a maximum current value (Imax), which is device dependent, the net cooling of the TE module decreases because Joule heating is increasing at a greater rate than Peltier cooling. The manufacturer of the TE module will state the maximum current for each TE module and this current value should not be exceeded.
The LIMIT SET feature on the Model 300B Series Temperature Controllers allows you to limit the maximum current flowing through the TE module.

7.5 Mounting Considerations

The physical arrangement of the TE module, thermistor, heatsink, and the device to be cooled or heated are crucial to the operation of a Model 300B Series Temperature Controller. This arrangement determines the thermal load and the rate of heat dissipation to which the control circuitry must respond. To achieve optimum temperature control the thermal path between the device to be cooled or heated and the face of the TE module must be as short as possible and must have high thermal conductivity.
This arrangement also determines the delay that the control circuitry must respond to, and affects the gain setting of the control loop. Another factor that must be taken into account is the mass of the heat sink required to dissipate heat from the TE module. The better the heat sink dissipates heat, thus reducing the thermal gradient across the TE module, the more efficient the TE module is at removing heat from the device being cooled.
Figure 17 shows an arrangement that optimizes the cooling and temperature stability achievable with the Model 300B Series Temperature Controller. Two TE modules connected in parallel are shown in the diagram. The actual connection of the TE module depends on the manufacturer's specifications for the voltage drop across the TE module and its current requirement.

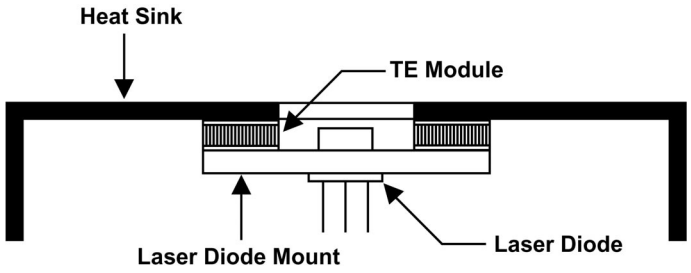


Figure 17 Mounting arrangement of a TE module, heat sink and laser diode

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7.6 PID Tuning

The basic block diagram of a temperature control system is shown in Figure 18. The main objective of this control system is to insure that the deviation between actual temperature and desired temperature setpoint is within acceptable limits. The temperature controller attains this by monitoring the actual temperature (output of temperature sensor), comparing this value to a desired setpoint, and driving the TE module (heating/cooling the mount). There are various ways in which the performance of such a control loop can be quantified: settling time, overshoot, etc. In Model 300B series instruments, a PID control algorithm is implemented to achieve optimal stability and settling performance.

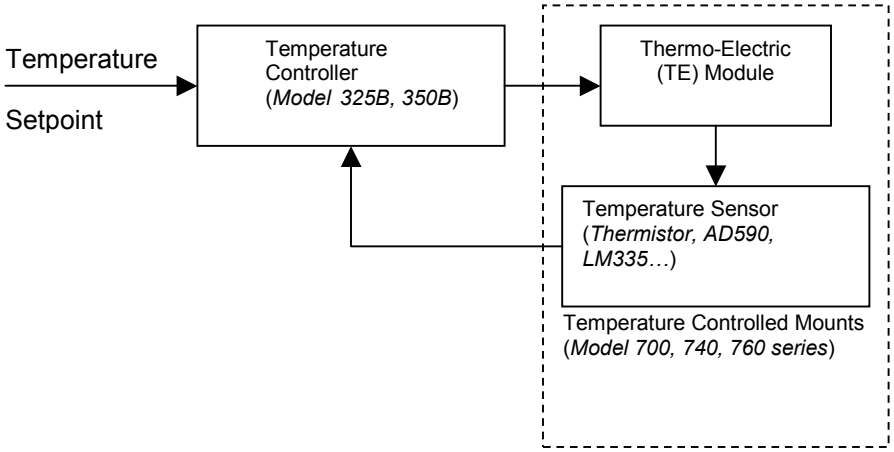


Figure 18 Basic block diagram of a temperature control system

7.6.1 PID Control Loop

The PID term comes from the proportional, integral and derivative gain factors that are at the basis of the control loop calculation. The common equation given for it is:

$$u = K_p \cdot e + K_i \int e \cdot dt + K_d \cdot \frac{de}{dt}$$

where Kp = proportional gain factor

Ki = integral gain factor

Kd = derivative gain factor

e = instantaneous error (desired temperature setpoint minus actual temperature)

u = temperature controller (current that drives the TE module)

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The problem for most users is to get a feeling for this formula, especially when trying to *tune* the PID loop. *Tuning* the PID means changing its three gain factors to obtain a certain system response, a challenging task to achieve without some basic understanding of its behavior.

The following paragraphs explain the PID components and their operation.

7.6.2 P Loop

Let us start with the simplest type of closed loop control, the **P** (proportional) loop. The diagram in Figure 19 shows its configuration.

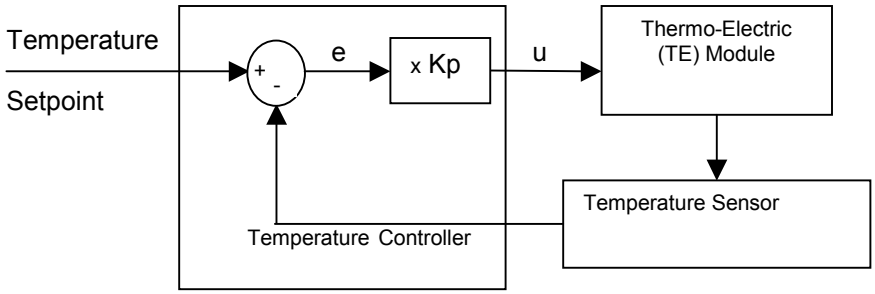


Figure 19 Proportional Temperature Controller Block Diagram

The controller continuously compares the actual temperature, as reported by the temperature sensor, to the desired temperature (setpoint). The difference **e** is the temperature following error. It amplifies this error (by multiplying it with **Kp**) and generates a control signal (current) that drives the TE module.

There are a few conclusions that could be drawn from studying this block diagram:

- The control signal is *proportional* to the temperature following error.
- There must be a following error in order to drive the TE module.
- Small errors cannot be corrected if they do not generate enough current for the TE module to overcome any thermodynamic effects from the mounts.
- Increasing the **Kp** gain reduces the necessary following error but too much of it will generate instabilities and oscillations.

7.6.3 PI Loop

To eliminate the small errors that cannot be compensated by P loop alone, an *integral* term can be added to the control loop. This term integrates (adds) the error continuously and the value, multiplied by the **Ki** gain factor, is added to the control signal (Figure 20).

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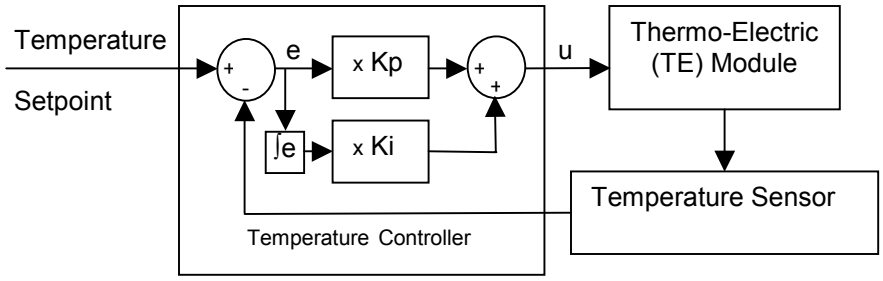


Figure 20 PI Temperature Controller Block Diagram

The result is that the contribution of integral term to the control signal will increase until it reduces the temperature following error to zero. While this is desirable for many situations, the integral term can have a severe destabilizing effect on the control loop if increased too much.

7.6.4 PID Loop

The third term of the PID loop is the *derivative* term. This term amplifies the rate of change of temperature following error by **Kd** gain factor. If the following error does not change, the contribution of derivative term to the control signal is zero. Figure 21 shows the PID control loop diagram.

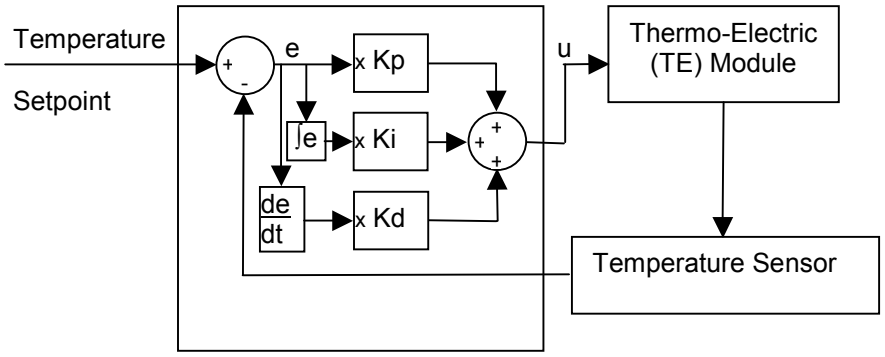


Figure 21 PID Temperature Controller Block Diagram

The derivative term adds a damping effect which helps prevent oscillations and temperature overshoot. It also supports achieving optimal stability and settling time.

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7.7 Model 300B Series Setup

Setting up the Model 300B Series Temperature Controller is a simple procedure.
An AC power cord, supplied with each unit, must be plugged into a properly grounded outlet. The tilt up feet, at the bottom of the unit, may be extended to enhance the viewing angle of the front panel. Connection to TE modules and temperature sensors are made with one of the accessory cables (part #300-02 or #300-04).

7.7.1 Rack Mounting Model 300B Series Units

Two units, either Model 300B's or Model 500B's or one of each, may be mounted side by side in the standard rack mount kit (part #35-RACK). Remove the four feet on the bottom of the instrument. Use the screws supplied with the rack mount kit and secure the bottom of the unit(s) to the bracket using the two original front feet mounting positions. After tightening the screws the unit(s) may be slid into a 19" rack and secured to the side rails.

7.7.2 Model 300B Series Operating Checklist

The following steps should be followed when operating a Model 300B Series Temperature Controller.

a. Check the AC voltage selection of the unit to be sure that it is compatible with the outlet to be used. All units are factory preset for operation from 108–132VAC.

b. Connect the temperature sensor and TE module to the 15-pin output connector.

c. Check that the proper temperature sensor bias is selected.

d. Turn on the AC power switch and the unit will start-up with the output to the TE module off. The display will be in the PRESET mode.

e. Before setting any values on the DISPLAY select the operating mode, R/T or I_{TE}.

f. Change the display to the LIMIT display mode and set the maximum current allowed to the TE module. For this, push the display button until the LIMIT SET LED is lit. Turn the control knob until the display shows the desired limit current.

NOTE

The maximum current is specified by the manufacturer and must not be exceeded or damage to the TE module may occur.

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g. If the operating set-point has not been set or needs to be changed, select the PRESET display mode and use the control knob to set the correct value. The operating temperature, resistance or TE current is set before turning the OUTPUT on.

h. The OUTPUT can now be turned on and the Model 300B Series Temperature Controller will automatically control the temperature or I_{TE}. Push the OUTPUT switch once to turn the current on to the TE module and a second time to turn the current off. If there is an error condition the current will not turn on and the ERROR indicator LED will come on. If this occurs verify that the temperature sensor and TE connections are correct. After an ERROR condition has occurred the OUTPUT switch must be pushed once to reset the control circuitry. After the fault is corrected and the circuitry is reset the OUTPUT switch can be pushed a second time and the output current will turn on.

i. During the operation of the Model 300B Series Temperature Controller any of the parameters may be displayed and the status of the Model 300B Series Temperature Controller may be monitored.

NOTE

Newport Corporation is not in any way responsible for any damage to any device used in conjunction with the Model 300B Series products.

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8 Maintenance and Service

CAUTION

There are no user serviceable parts inside the Model 300B Series Temperature Controllers. Work performed by persons not authorized by Newport Corporation will void the warranty.

8.1 Enclosure Cleaning

WARNING

Before cleaning the enclosure of the Model 300B Series Temperature Controller, the AC power cord must be disconnected from the wall socket.

The enclosure may be cleaned with a soft cloth dampened with either a mild soapy water solution or Isopropyl Alcohol. Do not use any other chemicals or solutions.

8.2 Fuse Replacement

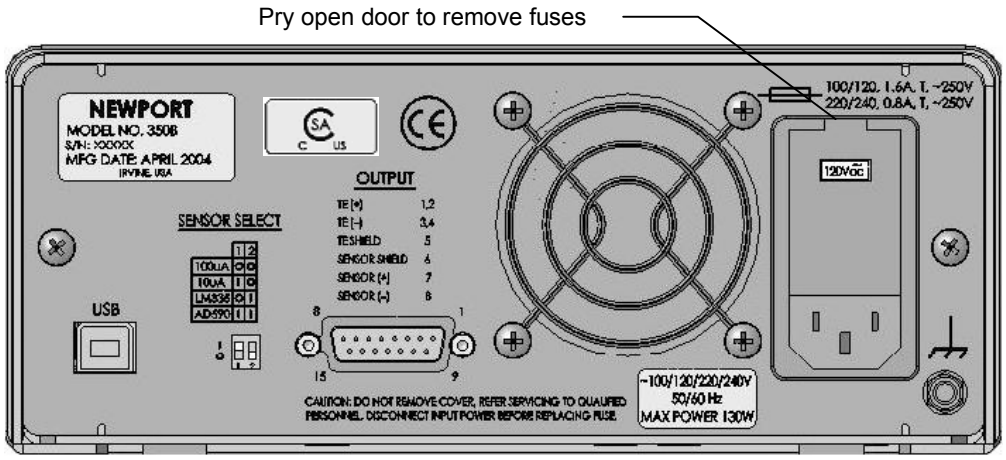


Figure 22 Fuse Replacement

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WARNING

To reduce the risk of electric shock or damage to the instrument, turn the power switch off and disconnect the power cord before replacing a fuse.

If a fuse blows:

1. Disconnect the power cord from the controller
2. Pry open tab at top of power receptacle and open panel to access fuses. (See Figure22)
3. Replace the fuse(s).

   Use only 5mm x 20mm fuses as indicated below

Fuse Replacement	Line Voltage
1.6 Amp, (T), 250V	100/120VAC
0.8 Amp, (T), 250V	220/240VAC

4. Reconnect the power cord and turn on the instrument.
5. If the problem persists, contact Newport Corporation for service.

8.3 Obtaining Service

The Model 300B Series Temperature Controller contains no user serviceable parts. To obtain information regarding factory service, contact Newport Corporation or your Newport representative. Please have the following information available:

1. Instrument model number (on the rear panel)
2. Instrument serial number (on rear panel)
3. Description of the problem.

If the instrument is to be returned to Newport Corporation, you will be given a Return Number, which you should reference in your shipping documents. Please fill out a copy of the service form, located on the following page, and have the information ready when contacting Newport Corporation. Return the completed service form with the instrument.

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8.4 Service Form



Newport Corporation
U.S.A. Office: 800-222-6440
FAX: 949/253-1479

Name _____ **Return Authorization #_____**
(Please obtain RA# prior to return of item)

Company _____
(Please obtain RA # prior to return of item)

Address _____ _____Date _____

Country _____ Phone Number _____

P.O. Number _____ FAX Number _____

Item(s) Being Returned:

Model # _____ Serial # _____

Description _____

Reason for return of goods (please list any specific problems):

_____

_____

_____

_____

_____

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Notes:

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