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Section 1
850G Series Linear Actuator User Manual

1.0 Introduction

This manual describes the operation of Newport 850G Series Linear Actuator. When purchased with a Newport controller, the 850G is fully compatible with the ESP MotionMaster, and PMC200 series controllers. If you have purchased the 850G for use with your existing Newport controller, please read carefully the section below listing your controller for compatibility and upgrade information.

Section 2

2.0 Description

The 850G actuator incorporates a versatile design which can be configured with travel limits from as little as approximately 1/32 inch to 2 inches (0.8mm – 50mm), enabling it to be used on a wide variety of Newport translation stages and mirror mounts. Mechanical limit switches cut motor power preventing accidental over-travel. The actuator incorporates a manual actuation knob for coarse adjustment (with the motor power off).

To provide accurate motion, the actuator's 3/16 inch diameter plunger is non-rotating. The standard gearbox ratio actuator can produce a maximum thrust in excess of 25 pounds (11 kg); but, when operating continuously over many cycles, the maximum load is rated at 18 pounds (8 kg).

The actuator's internal structure is a precision-rolled leadscrew with a 0.8mm pitch. The pitch of the leadscrew has been chosen to provide the same encoder resolution when combined with the standard gearbox ratio (See table section 3.4). Production variations about this average figure can be compensated by Newport controllers via software commands allowing the user to limit cumulative, monotonic inaccuracies to within 0.005%. A non-rotating low friction Turcite nut engages the leadscrew and pushes the plunger. A Turcite half-nut is used to trigger a travel limit in the extended position while the lead screw nut trips the limit at full retraction. The limit switches are repeatable to approximately 40µm.

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CAUTION

If the actuator encounters a hard stop within its range of travel (a translation stage's or mirror mount's end of travel for example), slip clutch releases to prevent damage to the gearhead. The clutch is designed to slip just below the motor's maximum torque. The motor should be stopped as soon as possible to prevent overheating in this high torque condition.

These actuators are powered by a low inertia DC motor to provide smooth movement with low acoustic and mechanical noise. Submicron resolution is obtained with a precision-rolled and electropolished stainless steel leadscrew driven through a low backlash reduction gear. The overall drive train backlash of approximately 15µm can be compensated by Newport controllers. Bi-directional repeatability to 1.0µm can be achieved through this feature.

The motor has an ironless-rotor to permit fast response due to its low inertia. The brushes are precious-metal plated for long life. The factory lubrication has a vapor pressure of 10-6 Torr at 25°C.

2.1 Controller Interfaces

The 850G Series actuators incorporate many new features, such as travel limit switches and manual actuation, not found in previous Newport actuators like the 850, 850A, and 850B Series. Additionally, since the 850G use a higher torque motor, the servo parameters required for smooth operation are different than for previous actuators. For these reasons, controllers sold before the introduction of the 850G may not be compatible and will require a special interface adapter. Some controllers have been phased out and are not supported for the 850G.

2.1.1 MM1000DC/DCS750

The MM1000DC Controller/Driver (formerly DCS750) has been phased out and is not supported to drive 850G Series actuators.

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2.1.2 MM2000 PC Card Motion Controller

The MM2000 controller drives up to four 850G actuators via Newport's Universal Interface box (UIB) P/N 21463-01 and using firmware version 1.5 or later. The controller firmware version may be displayed by using the VE command. (Note that since the actuators are using the computer's internal power supply, there is a limitation of 2 axes that may move simultaneously. Future versions of the UIB will incorporate an external power supply for applications requiring 3 or more axes of simultaneous movement.)

The UIB provides relays to cut motor power for manual knob use and firmware version 1.5 or later provides commands to properly enable manual positioning and keep track of encoder counts during a manual move. The UIB may be purchased as an option when ordering an MM2000 controller and the proper version of the firmware is assured. To upgrade an existing MM2000 controller with firmware version 1.4 or earlier, the UIB must be purchased separately. The existing firmware may be used with the following work around for manual actuation. When sending the MOTOR OFF (MO) command, the I/O bits on the UIB which control the power relays must be logged manually using the DEFINE BITS (BO), CLEAR BITS (CB), and SET BITS (SB) commands. Refer to the MM2000 user manual and the data sheet included with the UIB for more details.

CAUTION

Failure to manually toggle the I/O bits on the UIB for controllers with firmware version 1.4 or earlier will leave power applied to the motor after the MOTOR OFF command has been issued. Do not try to manually adjust actuator position with power applied to the motor or damage will result to the gearhead. Manual positioning should not require more torque to turn the knob with the actuator cable attached than with it unplugged. If you're unsure about the effort required, unplug the actuator to compare the feel of the knob before proceeding.

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2.1.3 MM2000RX Rack Mounted PC Card Controller

Existing MM2000RX controllers are incompatible with the 850G. Factory upgrades may be done on a special request basis. New MM2000RX controllers may be purchased to be compatible with the 850G on a special request basis. Please call Newport for the latest information.

2.1.4 MM3000 Motion Controller/Driver

The MM3000 is completely compatible with the 850G Series actuators. All that is required is to configure the controller with the proper driver card and adjust the servo parameters per the specifications included in the controller documentation.

2.1.5 MM4000/4005 Motion Controller

The MM4000/4005 are completely compatible with the 850G Series actuators. All that is required is to configure the controller with the proper driver card and adjust the servo parameters per the specifications included in the controller documentation.

2.1.6 PMC100 Single Axis Controller

Existing PMC100 controllers are incompatible with 850G Series actuators. Please call Newport for the latest information regarding upgrades for the PMC100.

2.1.7 PMC200/PMC200-P Dual Axis Controller

PMC200 Series Controllers using version 3.1 or earlier firmware are incompatible with 850G Series actuators and require an upgrade. The firmware version is displayed on power up. Please call Newport for the latest information regarding upgrades. PMC200 Series Controllers using version 4.0 or later are compatible with the 850G Series actuators and include the proper interface to handle the limit switches and manual knob. Servo parameters may be set selecting type 850G in the controller setup menu. There is also a menu to toggle motor power off for manual positioning. An adapter cable (P/N 21731-01) must be ordered for each 850G actuator.

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CAUTION

Failure to toggle motor power off before attempting to manually position the 850G will result in damage to the motor gearhead. Manually positioning should not require more torque to turn the knob with the actuator attached than with it unplugged. If you are unsure about the effort required, unplug the actuator to compare the feel of the knob before proceeding.

2.1.8 PMC400 Multi-Axis Controller/Driver

The PMC400 Controller/Driver has been phased out and is not supported to drive 850G Series actuators.

2.1.9 ESP Series Controller/Driver

All ESP Series Motion Controller/Drivers are compatible with the 850G Series actuator. The 850G actuator has an ESP smart chip inside, which configures the ESP controller/driver, setting default parameters. Thus, the 850G actuator is 'plug-and-play' compatible with the ESP controller/driver.

2.1.10 Non-Newport Controllers

If you are using a non-Newport controller/driver please refer to the connector pinout provided. Note that in order to utilize the manual knob feature, power must be removed from the motor (open circuit). Failure to do so properly may result in dynamic braking on the motor and cause damage to the gearhead, invalidating your warranty.

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Notes

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Section 3

3.0 Installation, Set-up, and Operation

The actuators are shipped in sturdy, foam-cushioned boxes. Please inspect the actuators and/or controllers immediately and notify the carrier if damage is obvious. The actuator includes a wrench to access the travel limit adjustment and a retaining nut for actuator mounting.

3.1 Setting the Travel Limits

Before mounting the 850G actuator, follow the directions below to adjust the travel limits such that the actuator will trigger one of its limit switches before encountering any external hard stop such as the end of travel of a translation stage. Failure to do this may result in damage to the actuator and/or the stage. Actuators are shipped with the travel limit set to less than 1/2 inch (12mm) to prevent accidental over-travel in most instances.

3.1.1 Remove the Coarse Travel Indicator Window

Find a clean flat surface to disassemble the actuator. (Tapped hole optical tables are not recommended since many of the parts are small and may drop into the table). Using the manual knob, adjust the actuator to the zero position as read on the coarse position scale as shown in Figure 1. Remove the four M2 flat head screws holding the cover, and place them to the side. Gently pry off the cover as shown in Figure 2.

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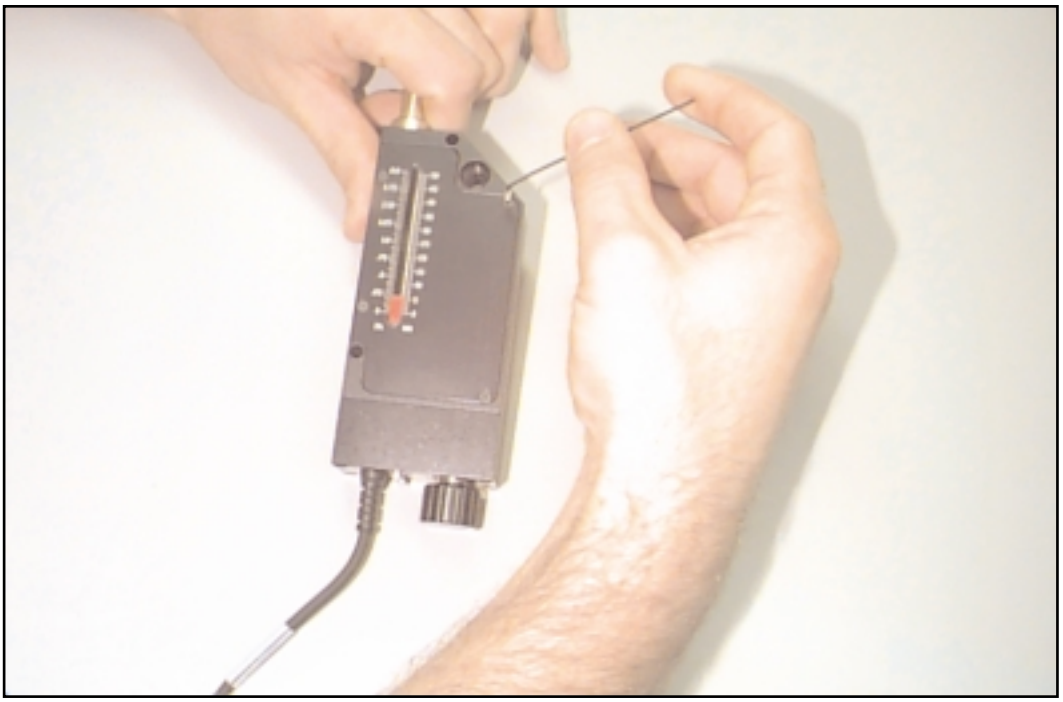


Figure 1: Remove the cover with the Actuator in the zero position

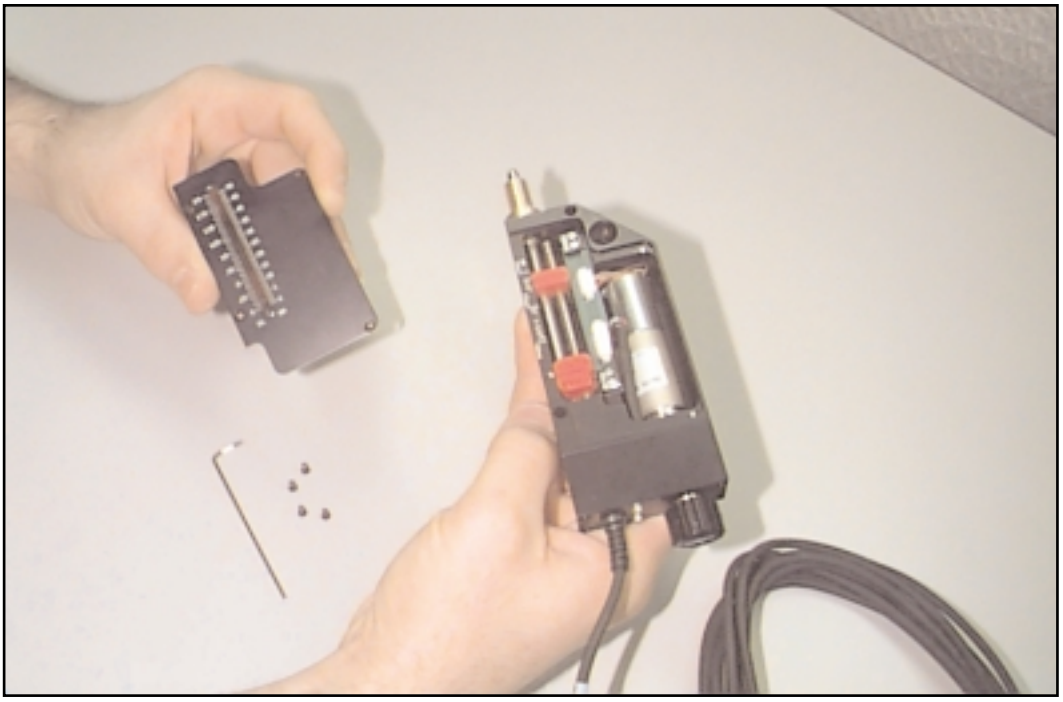


Figure 2: Approximate travel range markings assist in quick travel adjustment

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3.1.2 Reposition the Half-Nut to the Desired Travel

After removing the cover, laser marked lines indicating approximate travel ranges can be seen. Remove the half-nut by lifting it from the lead-screw. Note its orientation with respect to the lead-screw since it only fits one way. (Figure 3). Approximate travel is set by replacing the half-nut onto the lead-screw with its center scribe mark aligned to one of the markings on the actuator body (Figure 4). These marks are only an aid to determining travel.

The half-nut may be placed anywhere along the lead-screw. For full 2 inch (50mm) travel, remove the half-nut completely and store it in a safe place for future use in case shorter travel is desired.



Figure 3: The half-nut's ramped corner triggers the positive limit switch

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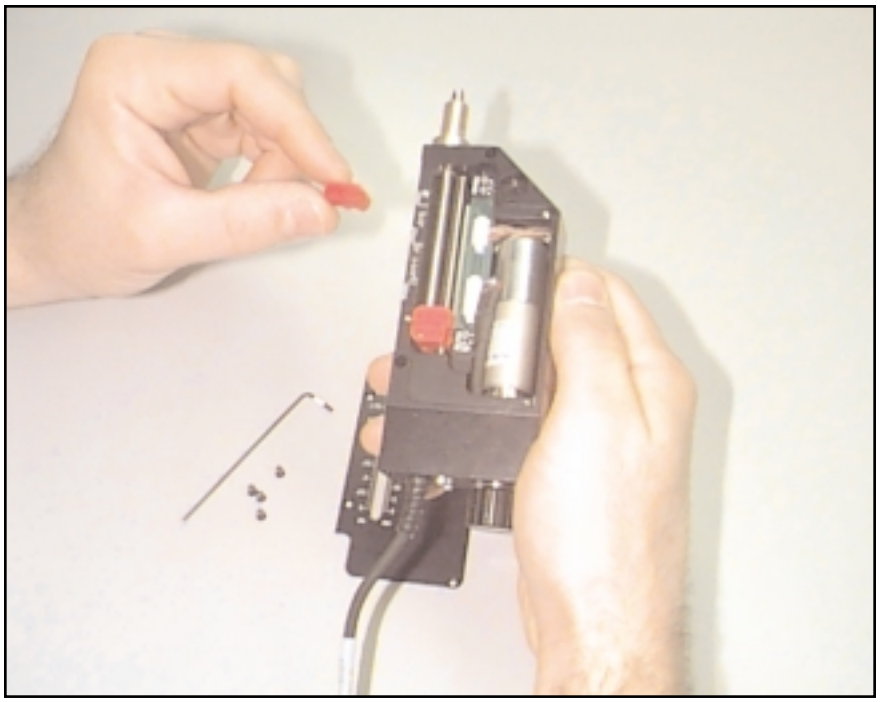


Figure 4: Place the half-nut on the lead-screw to set the approximate travel

3.1.3 Replace the Coarse Travel Indicator Window

After inspecting the half-nut placement to ensure that it is fully seated on the lead screw, replace the cover and tighten the four M2 screws. Be sure to tighten the screws completely for proper operation (Figures 5 & 6). If the cover is loose, the half nut may ride up off of the lead-screw at the end of travel and defeat the purpose of the limit switch resulting possibly in damage to the actuator or the equipment it is moving.

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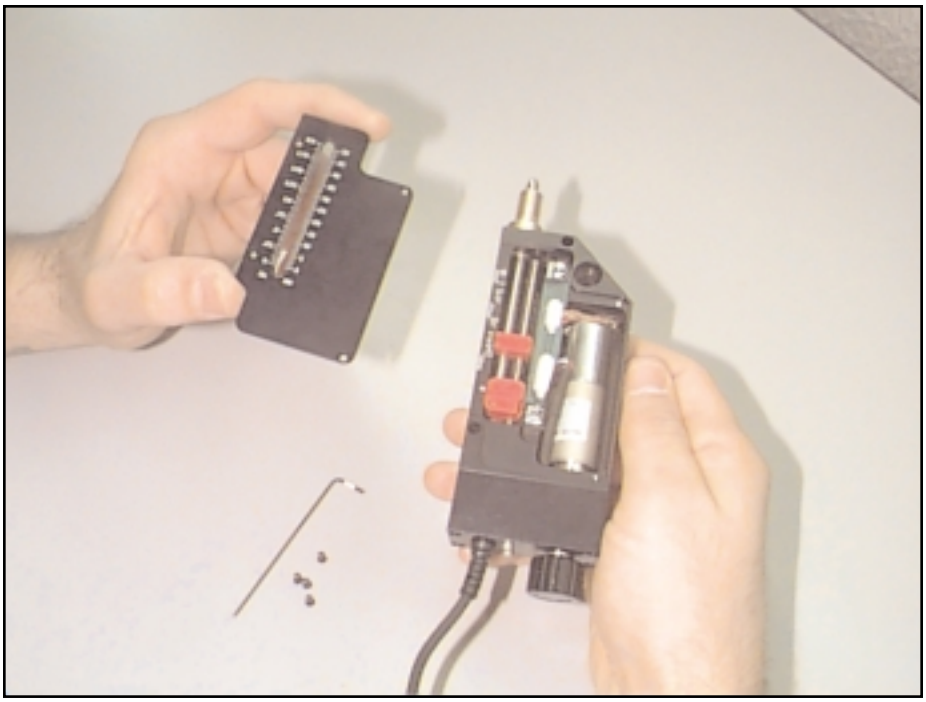


Figure 5: Replace the actuator cover, after seating the half-nut on the lead-screw

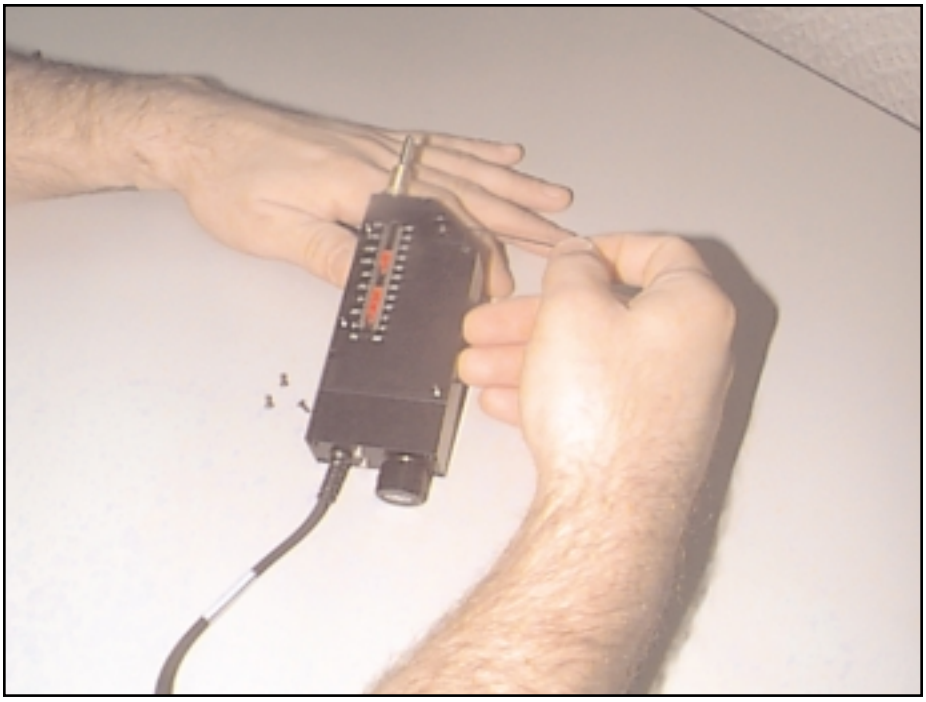


Figure 6: Tighten all four screws securely for proper operation

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3.2 Actuator Mounting

The actuator may be mounted using either the 3/8 inch brass mounting sleeve or by attachment using the clearance holes in the actuator body. When using the brass mounting sleeve, the actuator may be mounted to a wide variety of Newport components in one of four ways:

1. Unscrew the retaining nut and insert the 850G into the mount. Use a spanner wrench included to tighten the nut.
2. If the mount has a clamping screw, the retaining nut is not used. Simply insert the actuator and tighten the screw.
3. In the rare case, that neither of the above clamping methods can be used, it might be necessary to partially disassemble the device the actuator is being used in. When access to the retaining nut side is reached, simply follow method No.1 above.
4. For mounting in panels up to $^{1}/_{2}$" thick, drill a $^{3}/_{8}$" hole, insert actuator and tighten retaining nut.

3.3 Manual Operation

The 850G is equipped with a knob for manual coarse positioning (except low speed versions, 850G-LS). Approximate position in both inches and millimeters, can be read using the scales on the window and the scribe mark on the lead-screw nut. A small amount of resistance should be felt when turning the knob. This is a result of back driving the gearhead motor assembly and is normal. Attempt to turn the knob smoothly, avoiding abrupt starts and stops, to minimize the chance of damaging the motor gearhead. Power to the motor must be off while executing a manual move or damage may result to the gearhead. If excessive resistance is felt while trying to turn the manual knob, check to verify motor power is off. If you are still unsure, disconnect the actuator cable completely and compare the turning resistance. It should be approximately the same as when the cable is attached with the motor power off.

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CAUTION

As long as the cable remains attached, the encoder count is preserved and when power is reapplied to the motor, the new encoder count is updated to be the current position in the controller. Incompatible and non-Newport controllers, who do not properly implement this feature, may cause the actuator to jump to a previous position upon power on and this may result in damage to the attached equipment if a crash occurs.

3.4 High and Low-Speed Versions

The 850G actuator is also available with two alternate speed ranges. This is accomplished through use of different gearbox ratios and motors with different torque characteristics as listed below:

Model	Gearbox	Motor	Relative Speed Resolution	Encoder
Standard Speed 850G, 850GV6	261.409912:1	1624	1x	0.051005µm
High Speed 850G-HS	22.0335039:1	1624	~ 12x	0.60514µm
Low Speed 850G-LS	1669.99476:1	1516	~ 1/6x	0.007985µm

PMC200 Series Controllers accommodate the differing gear ratios via the "special" actuator coupling ratio parameter. The procedure for setting this parameter is documented in your controller's manual. The coupling ratio can be calculated by the following simple formula:

Coupling Ratio = 20,000 * gear ratio / 262

That is, a standard speed actuator has a coupling ratio of 20,000. High-speed actuators have a coupling ratio of 1,685.8 Low-speed actuators have a coupling ratio of 127,768.4. The units of the coupling ratio parameter are encoder-quadratures-per-millimeter.

For MotionMaster controllers, use the CO command to compensate for the differing gearhead ratios.

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CAUTION

Actuators with gearhead ratios greater than 485:1 are more susceptible to damage when crashed into a hard stop. For high gearhead ratios, the motor's momentum appears to be extremely high when moving at full speed. The mechanical limit switches will prevent a crash due to over-travel, but will not prevent the actuator from hitting a hard stop within the travel range (the end of run on a translation stage or mirror mount for example). Be sure to adjust the travel limits (Section 3.1) such that the limit switches are activated before the actuator reaches the end of stage travel. A slip clutch has been implemented in the drive train to minimize the probability of damage if a hard stop is encountered, but special care should be taken to avoid crashing the actuator.

3.5 Vacuum Compatible Versions

Standard speed 850G actuators can be ordered to operate cleanly within a vacuum environment. The following describes the alterations that make the standard actuators vacuum compatible.

The high vacuum model of the 850G Series Linear Actuator, model 850GV6, incorporates the following features:

1. Six foot Teflon-coated cable from actuator attached to six foot standard cable.
2. Unanodized aluminum body without label.
3. No fastener sealing compound.
4. The window material is removed.
5. Special lubricant with vapor pressure of 10^{-6} Torr at 39°C.
6. Vented motor/gearhead/encoder cavities.
7. No scale on the cover and body.

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Section 4

4.0 Maintenance and Service

This section describes maintenance and adjustment procedures that may be performed by the user.

CAUTION

Do not attempt to adjust the actuator mechanical assembly in any way other than outlined above (See Setting the Travel Limits). Any attempt to disassemble the actuator will cause a misalignment. Call the factory before you try to adjust, repair, or alter any of the 850G Series actuators without factory-provided instructions. Any unauthorized attempts to adjust, repair, or alter the actuators or controllers will invalidate your warranty.

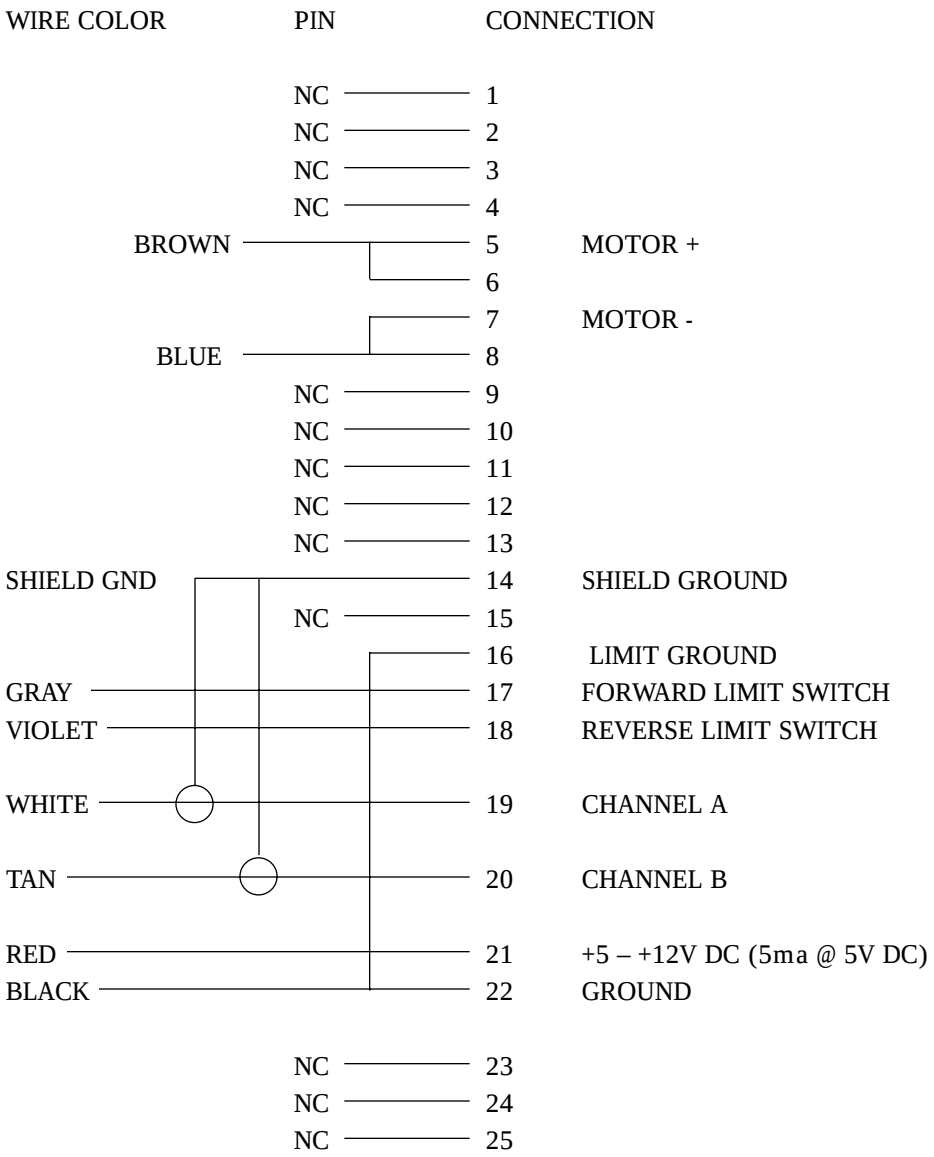
No scheduled maintenance is required for this product. The actuator should be cared for and handled as any fine instrument. Keep the unit clean and free of moisture, solvents, or other foreign matter.

Sometimes general wear and tear can cause the actuator's performance to degrade, indicating a need for service. Very often such problems as the actuator moving on its own and the actuator lacking thrust can be corrected by adjusting your controller servo parameters.

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Section 5

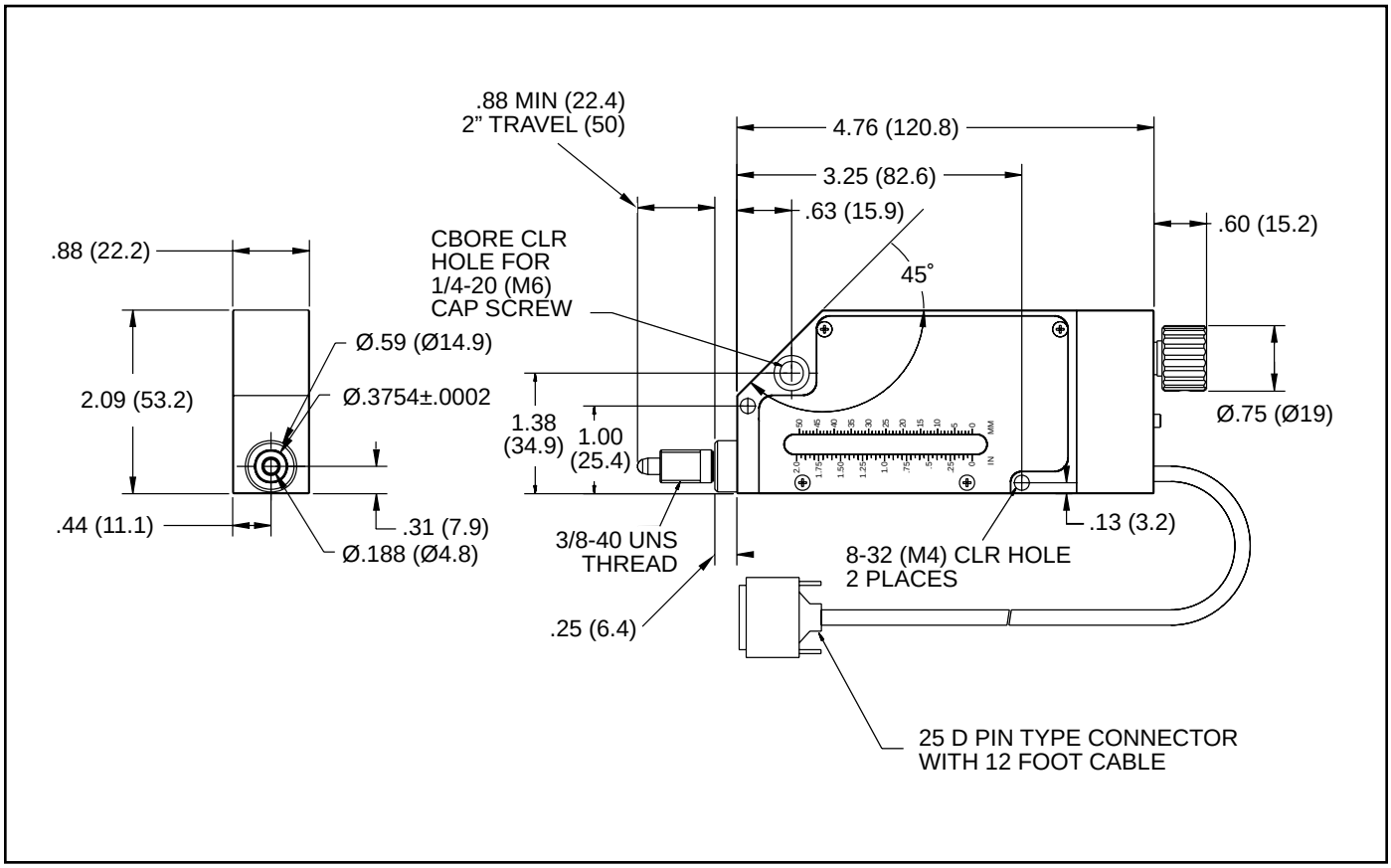
5.0 Connector Pin Assignments



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Section 6

6.0 Drawing



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Service Form

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The user should photocopy and return the completed form to Newport Corporation.

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Name _____ RETURN AUTHORIZATION # _____
(Please obtain prior to return of item)

Company _____

Address _____

Country _____ Date _____

P.O. Number _____ Phone Number _____

Item(s) Being Returned:

Model # _____ Serial # _____

Description: _____

Reason for return of goods (please list any specific problems) _____

_____

Please complete the below, as appropriate:

List all control settings and describe problem: _____

_____

_____

_____ (Attach additional sheets as necessary)

Show a block diagram of your measurement system including all instruments connected (whether power is turned on or not). Describe signal source. If source is a laser, describe output mode, peak power, pulse width, repetition rate and energy density.

Where is the measurement being performed?

(factory, controlled laboratory, out-of-doors, etc) _____

What power line voltage is used? _____ Variation? _____

Frequency? _____ Ambient Temperature? _____

Variation? _____ °F. Rel. Humidity? _____ Other? _____

Any additional information. (If special modifications have been made by the user, please describe below).

_____

_____

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WORLDWIDE HEADQUARTERS
NEWPORT CORPORATION
1791 Deere Avenue
Irvine, CA 92606

(In U.S.): 800-222-6440
Tel: 949-863-3144
Fax: 949-253-1680

INTERNET
sales@newport.com

BELGIUM
Tel: 016 402927
Fax: 016 40 2227

CANADA
In Canada: 800-267-8999
Tel: 905-567-0390
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FRANCE
Tel: 01 60916868
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Tel: +49 (0)6151 3621-0
Fax: +49 (0)6151 3621-52

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850G Series
Linear Actuator



USER MANUAL

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Product Warranty

Because we are confident that they will meet your high standards, our products carry the following warranty, effective for a period of one year from the original invoice date unless otherwise stated in the product literature.

- Products will be free of defects in material and workmanship.
- Products will meet the specifications stated in this document.

If you find any defects in material or workmanship or a failure to meet specifications within the warranty period, return the product to us clearly marked with a Return Authorization Number (RA#) and we will either repair or replace it at our discretion.

Our warranty excludes products that have been improperly installed or maintained, modified or misused. Notification of claim must occur within the warranty period. Newport's liabilities are limited as set forth in our standard terms and conditions, copies of, which is available upon request.

Non-Warranty Repairs

If a product needs repairing after the one-year warranty period expires; we will first provide an estimate of repair charges and then repair the product upon receiving authorization from you. Repairs are warranted for 90 days.

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IN-12981 (12-98)

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Specifications

Encoder Resolution		Part Number
Standard Actuators:	0.05101µm	850G, 850GV6
High Speed Actuators:	0.60514µm	850G-HS
Low Speed Actuators:	0.007985µm	850G-LS

Nominal Gearbox Ratio and Maximum Speed	
Standard Actuators:	262:1 ratio (1624 motor); 500µm/sec.
High Speed Actuators:	22:1 ratio (1624 motor); 6000µm/sec.
Low Speed Actuators:	1670:1 ratio (1516 motor); 78µm/sec.
Backlash	< 20 micron typical with external load of 2 lbs.(1 kg) minimum
Accuracy	< 0.1% of travel, cumulative
Bi-directional	Repeatability: Better than 1 micron when backlash is compensated by controller (standard actuators) *1
Encoder	Magnetic, 2KHz; open collector, quadrature output, +5V to +12V supply
Absolute cyclic pitch	Error < 1 micron
Time to reach full speed	< 50 msec at max. speed and acceleration settings
Max. Side Load	5 lb. (2.3 kg) at full shaft extension
Max. Axial Load	18 lb. (8 kg) standard and low speed actuators
Cable	12 foot (3.6 m) cable integral to actuator terminated with 25-pin male Dsub connector

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Specifications (Continued)

Temperature Range	
Storage Temperature	0°F to +120°F
Operating Temperature	40°F to + 100°F
Actuator Case	Black anodized aluminum
Vacuum Compatibility	Special-order vacuum compatible versions for operation to 10-6 Torr, temperature range restricted as stated above

*** NOTE:** Backlash can be compensated by MotionMaster and PMC200 Series Controllers. Cumulative, monotonic error due to leadscrew pitch error or mounting errors can be compensated via the CO command in MotionMaster Controllers, and via the coupling ratio parameter in PMC200 Series Controllers.

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Notes

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