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O C T A G O N S Y S T E M S

Embedded PCs For Extreme Environments

PC-510 User's Manual

5171 (0505)

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IMPORTANT!

Please read the following section before installing your product:

Octagon's products are designed to be high in performance while consuming very little power. In order to maintain this advantage, CMOS circuitry is used.

CMOS chips have specific needs and some special requirements that the user must be aware of. Read the following to help avoid damage to your card from the use of CMOS chips.

≡ Using CMOS circuitry in industrial control

Industrial computers originally used LSTTL circuits. Because many PC components are used in laptop computers, IC manufacturers are exclusively using CMOS technology. Both TTL and CMOS have failure mechanisms, but they are different. Described below are some of the failures which are common to all manufacturers of CMOS equipment. However, much of the information has been put in the context of the Micro PC.

Octagon has developed a reliable database of customer-induced, field failures. The average MTBF of Micro PC cards exceeds 11 years, yet there are failures. Most failures have been identified as customer-induced, but there is a small percentage that cannot be identified. As expected, virtually all the failures occur when bringing up the first system. On subsequent systems, the failure rate drops dramatically.

- Approximately 20% of the returned cards are problem-free. These cards, typically, have the wrong jumper settings or the customer has problems with the software. This causes frustration for the customer and incurs a testing charge from Octagon.
- Of the remaining 80% of the cards, 90% of these cards fail due to customer misuse and accident. Customers often cannot pinpoint the cause of the misuse.
- Therefore, 72% of the returned cards are damaged through some type of misuse. Of the remaining 8%, Octagon is unable to determine the cause of the failure and repairs these cards at no charge if they are under warranty.

The most common failures on CPU cards are over voltage of the power supply, static discharge, and damage to the serial and parallel ports. On expansion cards, the most common failures are static discharge, over voltage of inputs, over current of outputs, and misuse of the CMOS circuitry with regards to power supply sequencing. In the case of the video cards, the most common failure is to miswire the card to the flat panel display. Miswiring can damage both the card and an expensive display.

- **Multiple component failures** - The chance of a random component failure is very rare since the average MTBF of an Octagon card is greater than 11 years. In a 7 year study, Octagon has never found a single case where multiple IC failures were not caused by misuse or accident. It is very probable that multiple component failures indicate that they were user-induced.

- **Testing "dead" cards** - For a card that is "completely nonfunctional", there is a simple test to determine accidental over voltage, reverse voltage or other "forced" current situations. Unplug the card from the bus and remove all cables. Using an ordinary digital ohmmeter on the 2,000 ohm scale, measure the resistance between power and ground. Record this number. Reverse the ohmmeter leads and measure the resistance again. If the ratio of the resistances is 2:1 or greater, fault conditions most likely have occurred. A common cause is miswiring the power supply.

- **Improper power causes catastrophic failure** - If a card has had reverse polarity or high voltage applied, replacing a failed component is not an adequate fix. Other components probably have been partially damaged or a failure mechanism has been induced. Therefore, a failure will probably occur in the future. For such cards, Octagon highly recommends that these cards be replaced.

- **Other over-voltage symptoms** - In over-voltage situations, the programmable logic devices, EPROMs and CPU chips, usually fail in this order. The failed device may be hot to the touch. It is usually the case that only one IC will be overheated at a time.

- **Power sequencing** - The major failure of I/O chips is caused by the external application of input voltage while the Micro PC power is off. If you apply 5V to the input of a TTL chip with the power off, nothing will happen. Applying a 5V input to a CMOS card will cause the current to flow through the input and out the 5V power pin. This current attempts to power up the card. Most inputs are rated at 25 mA maximum. When this is exceeded, the chip may be damaged.

- **Failure on powerup** - Even when there is not enough current to destroy an input described above, the chip may be destroyed when the power to the card is applied. This is due to the fact that the input current biases the IC so that it acts as a forward biased diode on powerup. This type of failure is typical on serial interface chips.

- **Hot insertion** - Plugging cards into the card cage with the power on will usually not cause a problem. (**Octagon urges that you do not do this!**) However, the card may be damaged if the right sequence of pins contacts as the card is pushed into the socket. This usually damages bus driver chips and they may become hot when the power is applied. This is one of the most common failures of expansion cards.
- **Terminated backplanes** - Some customers try to use Micro PC cards in backplanes that have resistor/capacitor termination networks. CMOS cards cannot be used with termination networks. Generally, the cards will function erratically or the bus drivers may fail due to excessive output currents.
- **Excessive signal lead lengths** - Another source of failure that was identified years ago at Octagon was excessive lead lengths on digital inputs. Long leads act as an antenna to pick up noise. They can also act as unterminated transmission lines. When 5V is switch onto a line, it creates a transient waveform. Octagon has seen submicrosecond pulses of 8V or more. The solution is to place a capacitor, for example 0.1 µF, across the switch contact. This will also eliminate radio frequency and other high frequency pickup.

≡ Avoiding physical damage to the heatsink/CPU

WARNING!

When handling any Octagon CPU card, extreme care must be taken not to strike the heatsink against another object, such as a table edge. Also, be careful not to drop the CPU card, since this may cause damage to the heatsink/CPU as well.

Epoxy adhesive bonds the heatsink to the CPU chip. When the heatsink is struck, the epoxy adhesive does not allow the heatsink to separate from the chip. The force of the blow to the heatsink then causes the legs of the CPU chip to separate from the PCB. This force damages both the CPU chip and the PCB.

Note Any physical damage to the CPU control card is **not** covered under warranty.

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Abbreviations and terms used in this manual

Throughout this manual, the following symbols and terms are used:

Autoexecution	Automatic execution of a program on powerup or reset.
BIOS	Basic Input Output System. Detailed instructions that activate peripheral devices. See ROM-DOS.
BIOS drive	The solid-state disk which contains the system BIOS and ROM-DOS.
bpp	bits per pixel
Console port	Video card or COM1 where BIOS and DOS messages appear and keyboard input is available.
DRAM	Dynamic Random Access Memory devices. DRAMs provide volatile memory with unlimited read and write cycles.
Expansion card	The expansion cards add I/O functions to the Micro PC system, such as analog input/output, digital input/output, motion control, and display.
EZ I/O	This digital I/O chip supplies 24 I/O lines which can be individually programmed as 5V input or 5V output.
h	The suffix "h" denotes a hexadecimal number. A decimal number has no prefix or suffix. For example, 1000h and 4096 are equivalent.
KB	Kilobyte (1,024 8-bit bytes).
MB	Megabyte (1,048,576 8-bit bytes).
Memory device	The type of static RAM, DRAM, EPROM, or flash device specified for either volatile or nonvolatile memory.
PC/104 expansion	An expansion bus used for holding 8- and 16-bit expansion cards.
PC SmartLINK	A serial communications software package designed by Octagon for use with the PC-510 single board computer. Refers to all versions of PC SmartLINK.
PC Video	A feature on the PC-510 which imports an external video source into the virtual graphics array (VGA) system. This feature allows for advanced video connections including video overlays.

PICO FA	Phoenix's flash file system used to access SSDs from DOS as a read/write DOS drive.
ROM	Read Only Memory devices. ROMs provide nonvolatile memory, have a limited number of write cycles, and include EPROMs, EEPROMs, and flash memory.
ROM-DOS	Operating system included in Micro PC ROM.
Single board computer	A printed circuit board that contains a complete computer: CPU, memory, I/O, and clock. The single board computer controls the operation of all the expansion cards.
Solid-state disk (SSD)	A simulated disk which uses a high speed solid-state memory device. For example, flash memory, EEPROM, or static RAM.
Static RAM	Static Random Access Memory device. Static RAMs provide volatile memory with unlimited read and write cycles. They may be used with a backup battery.
TTL compatible	Transistor transistor logic compatible; 0-5V logic levels.
Virtual drive	A disk created in DOS or extended memory which emulates an actual disk. The virtual drive provides temporary storage for files. When power to the computer is turned off the virtual drive disappears.
W[-]	Denotes a jumper block and the pins to connect.
XMODEM	A communications protocol which allows transfer of files between two computers.
XON/XOFF	A communications protocol for asynchronous connections. The receiver can pace the sender by sending the XOFF and XON characters to stop and continue the data flow.
+5V Safe	+5V at the I/O connectors that is protected by a 0.75A fuse.

Conventions used in this manual

This section explains the format used for notes, warnings, and command entry.

≡ Notes and warnings

Special notes and warnings appear in this manual. Each one has a different meaning and format. They are as follows:

Note A note is supplementary or background information. At other times, it is a hint or reminder that makes a task easier or quicker.

WARNING!

A warning gives vital information. Failure to heed a warning may cause system failure, equipment damage, or bodily harm to the system operator.

≡ Command format and procedures

For some commands, you will only enter a single keyword (for example, **reset**). For most commands, however, you will enter several keywords followed by one or more parameters for which you must supply values.

Commands must be entered in a specific format. To indicate the format, this manual uses a series of conventions that are explained below. The conventions cover the rules for issuing all commands, including the most complex ones. Most commands, however, are much simpler.

The command format looks like this:

command [**type_this** | **or_ this**] *input* {*optional_input*}

Follow these rules and conventions:

- Information which appears on your screen is shown in a different type face, for example:

```
PhoenixBIOS(TM) A486 Version 1.03
Copyright (C) 1985-1994 Phoenix Technologies,Ltd.
All Rights Reserved
Octagon Systems Corp. PC510 CPU
```

- Commands that you must key in are shown in **Courier Bold**, for example:

```
C:> RESET
```

- Italicized refers to information that is specific to your particular system or program, e.g.,

  Enter *filename* means enter the name of your file.

- Paired angle brackets are used to indicate a specific key on your keyboard, e.g., <ESC> means the escape key; <CTRL> means the control key; <F1> means the F1 function key.

- All addresses are given in hexadecimal, for example, 328h.

About this manual

The *PC-510 user's manual* provides information about installing and configuring the PC-510. This manual is divided into four sections:

- Section 1 – Installation

  Chapter 1: Overview
  Chapter 2: Quick start
  Chapter 3: SETUP programs
  Chapter 4: Save and run programs

- Section 2 – Hardware

  Chapter 5: Serial ports
  Chapter 6: LPT1 parallel port
  Chapter 7: Console devices
  Chapter 8: SSDs, DRAM, and battery backup
  Chapter 9: External drives
  Chapter 10: IRQ routing and opto IRQs
  Chapter 11: EZ I/O
  Chapter 12: LED signaling and "beep" codes
  Chapter 13: CRTs and flat panels
  Chapter 14: GPS interface
  Chapter 15: PC/104 expansion

- Section 3 – System management

  Chapter 16: Watchdog timer and hardware reset
  Chapter 17: Serial EEPROM and CMOS RAM
  Chapter 18: Transferring files/remote disks
  Chapter 19: Managing SSDs
  Chapter 20: User-defined jumper
  Chapter 21: CPU power management
  Chapter 22: Troubleshooting

- Section 4 – Appendices

  Appendix A: Technical data
  Appendix B: Software utilities
  Appendix C: Third party support
  Appendix D: Accessories

Overview: Section 1 – Installation

Section 1 provides installation and programming instructions, startup options, and system configuration program examples. The following chapters are included:

Chapter 1: Overview
Chapter 2: Quick start
Chapter 3: SETUP programs
Chapter 4: Save and run programs

Chapter 1: Overview

≡ Description

The PC-510 Mobile Industrial Computer™ (MIC) is a high performance, single board PC in Octagon's semi-custom product line. The PC-510 integrates serial communication, industrial digital I/O, a floppy and a hard disk port, a multifunctional parallel port, and a local bus video which supports monitors and flat panels. It has an interrupt routing matrix, two solid-state disks, and a PC/104 interface. The PC-510 can have up to 16 MB of on-board DRAM. This board is supplied with DOS 6.22 in ROM but will also execute other operating systems such as Windows™, Windows NT™, and QNX®. Since the PC-510 uses the same functional blocks as the Micro PC™, the circuitry has been fully proven as reliable and the software is compatible with the software in the Micro PC series.

Specified to your engineering needs, the PC-510 can be ordered as a semi-custom board in OEM quantities. The stocked version of the PC-510 is listed below with the standard and optional features. The standard version can be used for system development and an optional version of the PC-510 is usually application specific.

≡ PC-510 major hardware features

CPU

The high performance 586 CPU comes in two versions. One version is a 120MHz586 and the other is a 133MHz586. Both versions operate at 3.3V for low power consumption. The PC-510 has a local bus speed of 33 MHz and an ISA bus speed of 8.33 MHz.

Up to 48 MB DRAM

The standard unit is supplied with 1 MB of fast, EDO surface mount DRAM. The use of EDO DRAM increases performance by 20% which, in most cases, eliminates the need for an expensive L2 cache. The PC-510 can contain up to 16 MB of on-board DRAM. Up to 32 MB of additional DRAM can be added through an optional DIMM module, which makes a total of 48 MB DRAM. Two holes are on-board the PC-510 to secure the DIMM module in high vibration environments. All surface mount DRAM and DIMM modules from Octagon meet the full PC-510 temperature range. Customers who need a 0° to 70°C range can install commercially available DIMM modules onto the PC-510.

- 1 MB EDO surface mount standard
- 4 MB EDO surface mount optional
- 16 MB EDO surface mount optional
- SO-DIMM socket installed standard
- SO-DIMM socket not installed optional

Solid-state disks

SSD0

A 32-pin DIP socket accepts either a 5V flash, SRAM, or 512 KB/1 MB EPROM. To use an optional 512 KB SRAM, the PC-510 requires a factory change. The socket exhibits high retention force and affords a gas tight contact. SSD0 optionally contains the BIOS drive and ROM-DOS 6.22 in ROM. By default, the optional SSD0 reserves 192 KB for BIOS and 320 KB for a drive area. Flash file system software is included which allows the SSDs to emulate hard disk operation. SSD0 options include:

- SSD0 socket installed standard
- SSD0 socket not installed optional
- SSD0 socket/EPROM installed optional
- SSD0 support from SRAM optional

For information on changing the device type, refer to the W5 SSD0 table in the *Quick start* chapter. You can also install compatible PROMs into SSD0 through the supplied utility programs found on the PC-510 utility disk. You can format the flash or SRAM while in the socket. EPROM usage, however, requires off-card programming from either a master flash or a master SRAM.

SSD1

SSD1 is used for storage of the applications program. A standard 2 MB 5V flash is soldered on-card. The flash programmer is built-in which allows on-card programming of the device. The PC-510 includes flash file system software, which permits the SSDs to emulate hard disk operation. Automatic "wear leveling" ensures that no single section of a chip will reach its life span (100,000 times), while other sections will scarcely be used. A 1 MB device reserves 192 KB for BIOS and 832 KB for a drive area, a 2 MB device reserves 192 KB for BIOS and 1856 KB for a drive area.

- 2 MB EPROM standard
- 1 MB EPROM optional
- SSD1 not installed optional

Serial ports protected against ESD

The PC-510 can have either two or six serial ports. All six serial ports are standard, while COM5 and COM6 can be optionally omitted from the PC-510. COM1 through COM4 are RS-232 and have the full 8-wire PC signal or they can optionally have 4-wire industrial RS-232 serial port lines. The 4-wire industrial RS-232 lines support RxD, TxD, RTS, CTS and the DTR pin with a 1K pull-up to 5V. The interface to COM5 is 4-wire industrial RS-232, configurable to TTL for interface to a GPS receiver. COM6 is 4-wire industrial RS-232, configurable to a 2-wire RS-485. COM5 and COM6 are always supplied side by side. COM1 through COM6 have the following specifications:

- IEC1000, level 3, ESD protection specification
  - — Contact discharge ±6 kV
  - — Air-gap discharge ±8 kV
- Backdrive protection
- 16C550 compatible
- Up to 115.2K baud
- 16 byte FIFO buffers
- RS-232 voltages generated on-card
- COM1 through COM6 standard
- Omission of COM3 through COM6 optional

Local bus SVGA, flat panel interface, and GUI accelerator

The video system on the PC-510 uses the advanced 65550 video chip from Chips & Technologies. It supports CRT, LCD and EL displays with resolutions to 1280 x 1024 bpp. Displays from CGA through SVGA are supported. The 65550 is also a graphics accelerator with real time PC-video being supported. Since the video circuitry operates on the local bus at the full processor speed, programs like Windows execute very rapidly. The video section has 2 MB of video RAM for high resolution displays and simultaneous CRT and flat panel operation. The PC-510 also supports 5V and newer generation displays, which use 3.3V.

- Local bus flat panel video present standard
- No local bus flat panel video present optional

Adjustable display bias supply

An on-board voltage converter eliminates the need for a separate bias supply for the LCD contrast control. The on-board power converter is factory configurable and can be made to be compatible with most LCD displays. The standard default range for the power converter is from +23V to +29V.

- + Bias voltage 23V to 29V standard
- – Bias voltage/other range optional
- No bias supply optional

Industrial I/O using EZ I/O

The PC-510 can be supplied with 24 or 48 lines of industrial I/O, using the Octagon "EZ I/O" digital I/O chip. Each EZ I/O line is programmable as an input or output. The lines are 5V compatible and can sink and source 15mA. The EZ I/O port can drive the Octagon MPB series opto-isolation module (Opto 22, G4 style) racks directly, controlling AC and DC loads to 240V at 3A.

- 48 lines standard
- 24 lines optional
- 0 lines optional

Speaker, keyboard, and mouse ports

The speaker connector is PC compatible and is a standard feature. The keyboard controller accepts an AT style keyboard and has a PS/2 type connector. The keyboard port is standard. The mouse port is optional and follows the PS/2 standard. Neither the keyboard nor the mouse are required for operation.

- Mouse port included standard
- Mouse port not included optional

PC/104 16-bit interface

This interface is a standard feature on the PC-510 and accepts an 8- or a 16-bit PC/104 expansion board. PC/104 expansion boards are available from several manufacturers. As many as three PC/104 expansion boards may be stacked on the PC-510.

≡ PC-510 major software features

Advanced power management and system management input

Power management can be used to reduce power consumption or to freeze the state of the program on the occurrence of a power management interrupt. Power consumption can be reduced by more than 60%. This reduces the heat load and extends the battery life in mobile applications. There are opto-isolated system management and suspend/resume inputs with 4-6V ranges. A system management input (SMI) will cause the PC-510 to save its current status. When the system is

signaled to restart, execution resumes at the point the system last stopped. The following are functions in the advanced power management and SMI:

- Suspend/resume by SMI input and software — halts CPU
- Wake up through various interrupts including keyboard, SMI and serial port
- Slow CPU by dividing clock
- Contextual save to disk.

Diagnostic software verifies system integrity automatically

The PC-510 has built-in diagnostic software that can be used to verify on-card I/O and memory functions. On powerup, a series of tests is performed. If a problem occurs, the failed test can be identified by the color sequence on an on-board, bicolored LED. The test is performed automatically every time the system is reset or powered up. Software, test equipment, monitor, keyboard, disks, or test fixtures are not required for memory verification. See the *LED signaling and "beep" codes* chapter for a complete listing of tests and failures and their descriptions.

SETUP information stored in EEPROM for high reliability

Loss of SETUP data is serious in industrial applications. Most PCs store SETUP information in battery-backed CMOS RAM. If the battery fails or is replaced during routine maintenance, this information is lost. Without a keyboard and monitor in embedded applications, time consuming re-initialization is required. The PC-510 stores the SETUP information in EEPROM with 1,536 bytes available to the user. Software routines to use this available memory come with the PC-510.

Phoenix BIOS

The PC-510 has a Phoenix AT BIOS with power management and Octagon BIOS extensions. The AT BIOS supports up to four EIDE drives.

"Instant DOS" operating system

Datalight ROM-DOS v6.22 operating system is in flash. This means that this version is always present on powerup. The system boots and operates the same way as a desktop PC. Since all software and hardware are included, the system is fully operational "out of the box."

Programmable video BIOS

The flash device contains a video BIOS, which controls the on-board SVGA controller. To support other flat panels, you can reprogram a new video BIOS. By default, the video BIOS supports a CRT and Sharp monochrome dual drive flat panel in simultaneous mode.

On-board flash file system

The Phoenix PICO FA flash file system controls the on-board SSDs, which allows read/write DOS access to the flash/SRAM devices. SSD0 can also use EPROM/OTPROM. For certain types of flash devices, the flash file system uses "wear leveling" to spread the usage and maximize the lifetime of these devices.

Octagon BIOS extensions

On-board BIOS extensions allow easy access to digital I/O, serial EEPROM, LCD bias control, watchdog timer functions, etc.

Interrupt routing: In system and programmable

Software is on-board the PC-510 to change the interrupt routing and some other features. The software allows more flexible use of interrupts on the PC-510 and outboard systems such as the PC/104 expansion card.

Floppy and hard disk ports

The floppy disk port supports two drives with either 720 KB or 1.44 MB capacities. The floppy port is terminated with a 34-pin IDC connector. The EIDE hard drive port is terminated with a 44-pin, 2 mm connector. +5V is supplied to a 2mm hard drive through the EIDE connector and +5V is also optionally supplied to the floppy drive through the IDC connector.

Boot sequence

A PC-510 can be configured to boot from the on-card, solid-state disk, an external floppy or hard disk.

Multifunctional printer port

The PC-510 incorporates the latest enhanced parallel port.

- Unidirectional
- Bidirectional
- IEEE 1284, ECP and EPP modes
- 24 mA of drive current
- Backdrive protection

The following represent applications in the multifunctional parallel port:

- LPT1 for PC compatible printers
- 17 general purpose digital I/O lines
- Up to a 4 x 4 matrix keypad
- 4-line alphanumeric display
- MPB-16PC, 16-position opto-module rack.

Watchdog timer added for safety

The watchdog timer resets the system if the program stops unexpectedly. The watchdog is enabled, disabled and strobed under software control. The time-out is 1.6 seconds (typical).

Real time calendar/clock with battery-backup

The real time clock is fully AT compatible and uses the standard DOS calls. An optional off-card battery powers the real time clock when the 5 volt supply is removed. A connector is provided for the external battery. The real time clock also provides the user with 128 bytes of user-defined CMOS-RAM.

I/O connectors

With the exception of the mouse, keyboard, and IDE, all I/O connectors can be latched to prevent connector movement during shock or high vibration.

Keypad and LCD display support for low-cost operator interface

For embedded applications, the parallel printer port or the EZ I/O port can interface with a 16-key matrix keypad and a 2- or 4-line LCD display. The PC-510 is supplied with software that provides keypad scanning and display operation. Supplied display and keypad drivers in C support these devices.

Hardware reset

A hardware reset can be done by any of the following methods:

- Issuing the RESET software command (using the watchdog function)
- Depressing the reset switch
- Cycling power
- Configuring the opto channel for RESET.

A hardware reset ensures complete reset of the system and all attached peripherals. An expired watchdog timer cycle also causes a hardware reset to occur.

5 Volt operation lowers system cost

The PC-510 operates from a single 5V ±5% supply. Located across the power supply, the 6.2V, 5W zener diode protects against reverse voltage and limits over voltage. The power supply generates the RS-232 voltages on-board the PC-510. The locking power connector is a standard PC power header connector.

- 5V ±5%, 1.0A to 2.0A (dependent upon processor, speed and I/O devices), less than 500 mA in standby
- +12V, -12V and -5V supplied to PC/104 expansion connector and display connector, not required for PC-510 operation
- A standard PC power supply may be used. See the *Power supply requirements* section in the *Quick start* chapter for more information on power supply selection and criteria.

Rugged environmental operation

Operating temperature	-40° to 70°C, operating with adequate airflow
Nonoperating temperature	-55° to 90°C, nonoperating
Relative humidity	5% to 95% noncondensing
Altitude	-100 to 10,000 m
Shock	10g, 3 axis
Vibration	3g, 3 axis

Note Forced air cooling is required above 45°C if power management is not used.

Size

5.75" x 8.0" x 0.9375"

Chapter 2: Quick start

This chapter covers the basics of setting up a PC-510 system and tells you:

- How to install and power on the PC-510 and run a demo program
- How to use a serial console instead of the on-board SVGA video.

Follow the mounting procedures for the PC-510. To establish a serial console link, go to the *Serial console* section in the *Console devices* chapter.

≡ Installing the PC-510

To install the PC-510 you will need the following equipment (or equivalent):

- PC-510 Mobile Industrial Computer
- +5V power module
- AT compatible keyboard with PS/2 connector
- VGA monitor
- VGA-12 cable

1. Refer to the PC-510 component diagram (Figure 2-1) for the location of various connectors, before installing your PC-510 system.

WARNING!

The PC-510 Mobile Industrial Computer contains static sensitive CMOS components. Do the following to avoid damaging your card and its components:

- **Ground yourself before handling the PC-510 card**
- **Disconnect power before removing or inserting a PC/104 expansion card**
- **When programming a memory device, place the device in the socket before applying power.**

Hardware components required to mount the PC-510:

- 8 threaded hex stainless steel standoffs (4-40 x 3/8")
- 8 screws (4-40 x 1/4")
- 8 internal star lock washers (4-40)

2. Use the #4 standoffs, washers, and screws and place them in the eight holes on the PC-510 board. Refer to Figure 2-2 for the center-to-center mounting hole dimensions and for the location of the designated holes used for mounting the hardware.

Figure 2-1 PC-510 component diagram

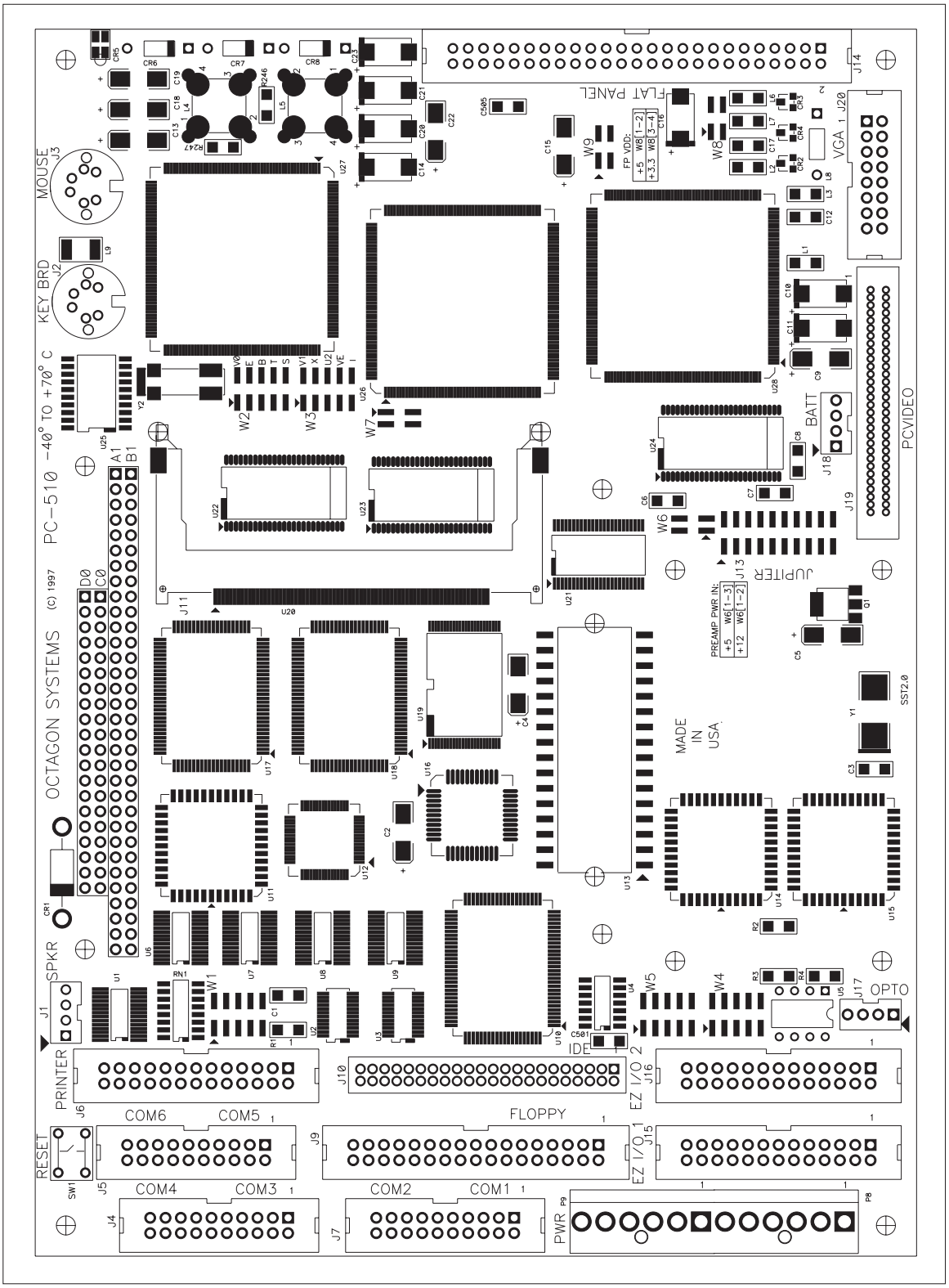
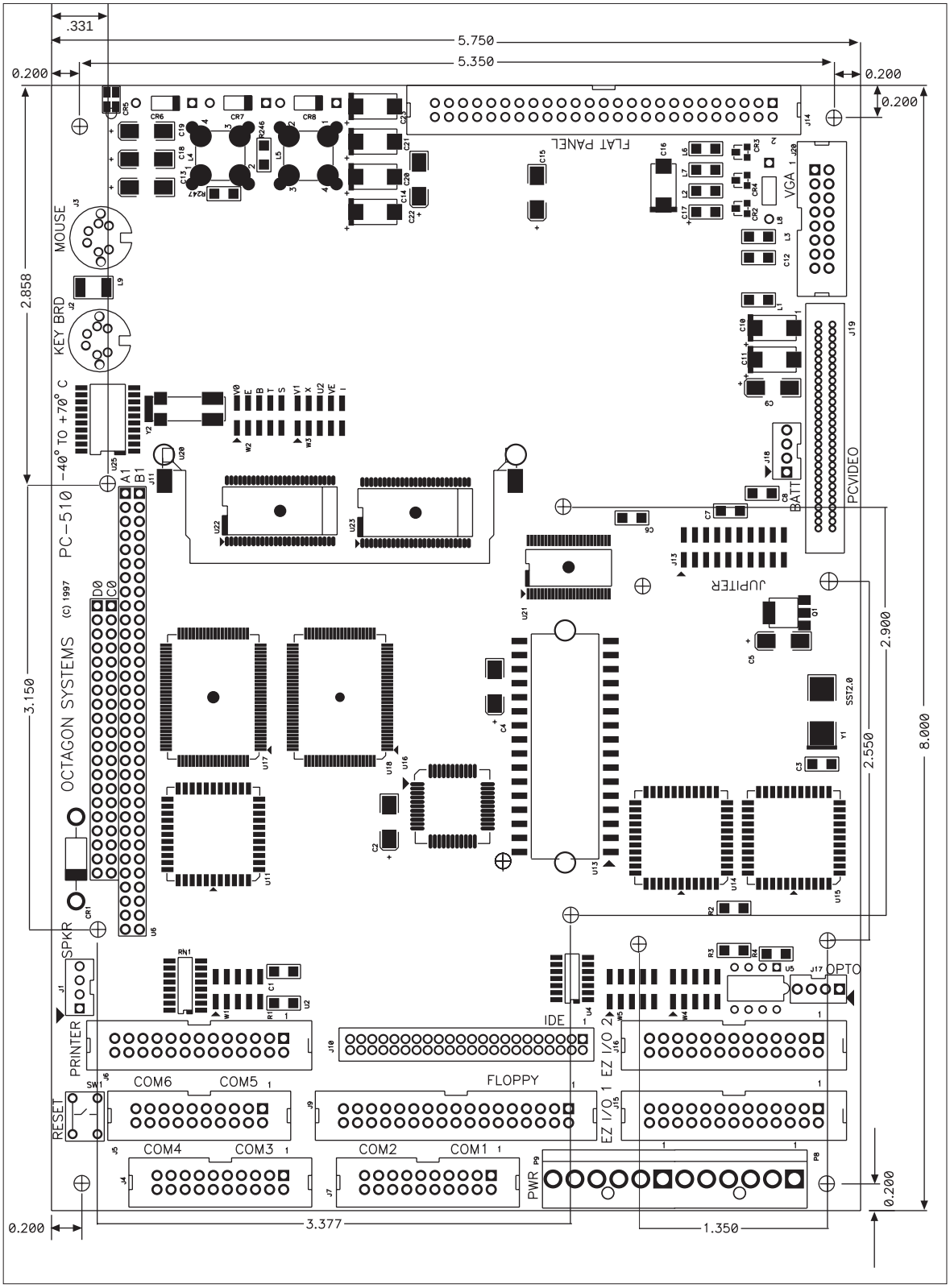


Figure 2-2 PC-510 center-to-center hole dimensions



WARNING!

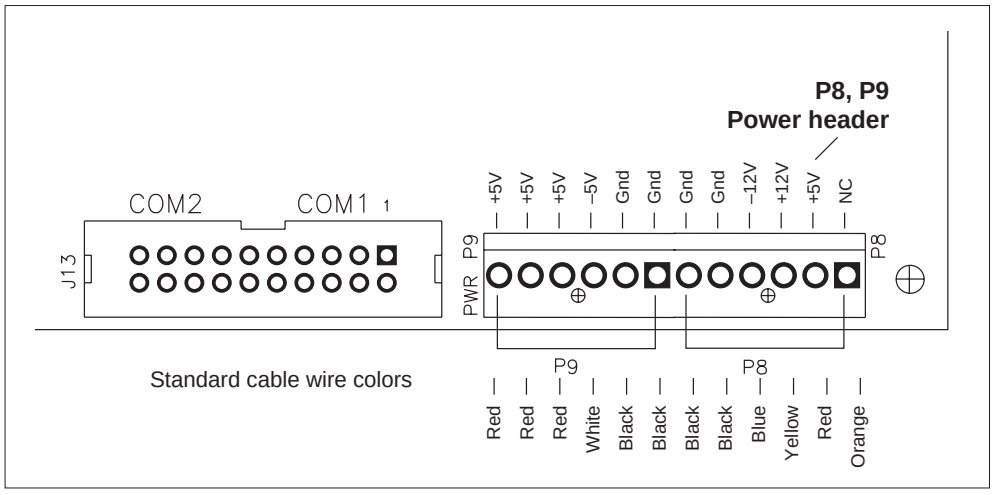
Before the PC-510 is powered on, all eight standoffs, screws and washers should be secured to the board. The standoff pieces will ensure full support of the PC-510 not only on all four sides, but also in the middle of the board. These hardware pieces will reduce the circuit board flex when the PC/104 expansion board and/or the SSD0 are inserted. Flexing of the PC-510 board should be avoided, since it can cause problems with the copper circuit traces and the surface mounted components.

3. The power supply connector is located at P8, P9. Make certain to connect the ground wires (typically black) to all ground connectors at P8, P9 on the PC-510. Refer to Figure 2-3.

WARNING!

Accidently crossing the wires, i.e., plugging +5V wires into the ground connector or the ground wires into the +5V connector can damage the PC-510.

Figure 2-3 Power connector: P8, P9



Note By removing the keys on the PC-510, it is possible to key your power connector header to your power supply connector. To insert the power connector without removing the keys, angle the connector at 90° and then place it on P8, P9.

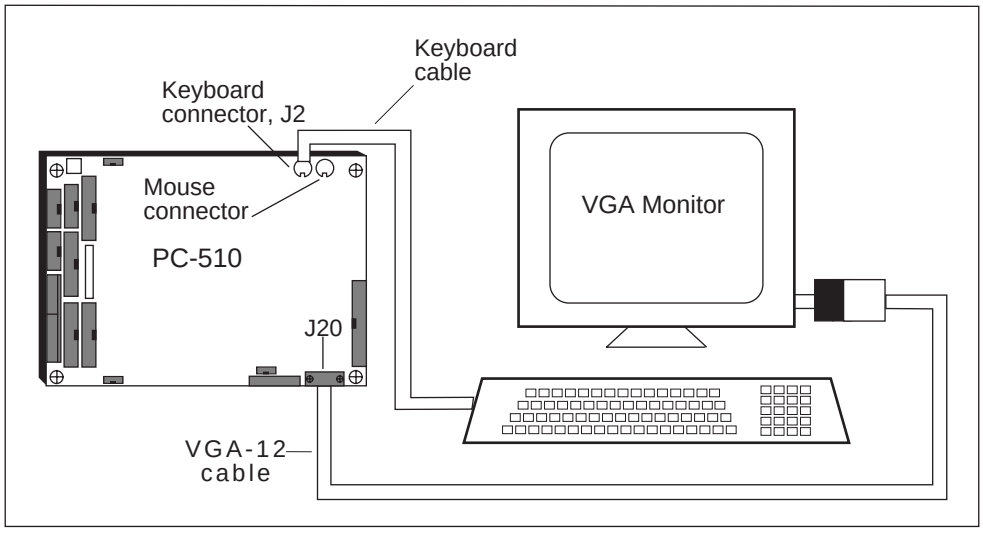
Table 2-1 Power connector: P8, P9

Pin	Description (P8)	Pin	Description (P9)
1	N.C.	1	Gnd
2	+5V	2	Gnd
3	+12V	3	–5V
4	–12V	4	+5V
5	Gnd	5	+5V
6	Gnd	6	+5V

Note See the *Accessories* appendix for connector information on the power connector.

4. Connect the PS-2 style keyboard directly to the keyboard port at J2 and a VGA monitor to J20 using a VGA-12 cable. Refer to Figure 2-4.

Figure 2-4 PC-510, keyboard, and monitor



≡ Reference designators

The following tables illustrate jumper connections and pins jumpered on the PC-510:

Table 2-2 PC-510 connectors

Reference designator	Description	Reference designator	Description
J1	Speaker	J13	GPS module
J2	Keyboard	J14	Flat panel
J3	Mouse	J15	EZ I/O 1
J4	COM3/COM4	J16	EZ I/O 2
J5	COM5/COM6	J17	OPTOA/OPTOB
J6	LPT1 Printer	J18	Battery
J7	COM1/COM2	J19	PC Video
J9	Floppy disk drive	J20	SVGA CRT analog
J10	IDE hard drive	P8, P9	Power
J11	PC/104		
J12	N/A		

Note See the *Accessories* appendix for connector information on the above connectors.

Table 2-3 RS-485 termination select jumper: W1

Pins	Description
[1–2]	No function, used for shunt storage
[3–4]	No function, used for shunt storage
[5–6]*	No function, used for shunt storage
[7–8]	RS–485 terminated(–), idle line at space
[9–10]	RS–485 terminated(+), idle line at space
[7–9]*	RS–485 terminated(–), idle line at mark
[8–10]*	RS–485 terminated(+), idle line at mark

* = default, pins jumpered.

Table 2-4 BIOS and boot option jumper: W2

Pins	Label	Description
[1–2]*	V0	C0000–C7FFF BIOS region toggle** (video BIOS region 1)
[3–4]	E	Enhanced mode, CPU clock speed: on = 133MHz; off = 120MHz
[5–6]*	B	BIOS device: on = SSD1; off = SSD0
[7–8]*	T	SSD0 type: on = flash/SRAM; off = EPROM
[9–10]*	S	Use SETUP information: on = EEPROM; off = BIOS default

* = default, pins jumpered
** = Toggles in BIOS extension areas work in combination with toggles in the SETUP BIOS extension areas. See the *Console devices* chapter for more information on the BIOS regions.

Table 2-5 Auxiliary option jumper: W3

Pins	Label	Description
[1–2]*	V1	C8000–CFFFF BIOS region toggle** (video BIOS region 2)
[3–4]*	X	D8000–DFFFF BIOS region toggle*** (PICO FA)
[5–6]*	U2	User option jumper 2
[7–8]*	VE	VGA controller: on = enabled; off = disabled
[9–10]	I	IRQ matrix: on = disabled; off = enabled

* = factory default, pins jumpered
** = Toggles in BIOS extension areas work in combination with toggles in the SETUP BIOS extension areas. See the *Console devices* chapter for more information on BIOS regions.
*** = Enables or disables PICO Flash Array extended BIOS.

Table 2-6 EZ I/O pull-up/pull-down, user option jumper: W4

Pins	Label	Description
[1–2]*		EZ I/O 1 pull up to +5V
[2–4]		EZ I/O 1 pull down to Gnd
[5–6]*		EZ I/O 2 pull up to +5V
[6–8]		EZ I/O 2 pull down to Gnd
[9–10]*	U	User option jumper 1

* = default, pins jumpered

Table 2-7 SSD0 device selection jumpers: W5, W2[7-8]

Pins	Description
W5[1-3, 2-4, 5-7, 8-10] W2[7-8]	SRAM with battery backup*
W5[1-2, 3-4, 5-6, 9-10] W2[7-8]	Flash
W5[1-2, 3-4, 5-6, 9-10]	EPROM**

* = default, pins jumpered
** = W2[7-8] is not jumpered

Table 2-8 Jupiter module antenna voltage select: W6

Pins	Description
[1–2]	12V*
[1–3]	5V

* = default, pins jumpered

Table 2-9 Flat panel interface voltage select: W8

Pins	Description
[1–2]	5V*
[3–4]	3.3V

* = default, pins jumpered

Table 2-10 Inverted shift clock signal voltage level select: W9

Pins	Description
[1–2]	3.3V
[3–4]	5V*

* = default, pins jumpered

≡ PC-510 power supply requirements

The PC-510 is designed to operate from a single +5VDC supply. An AT compatible power supply connector header (P8, P9) is on board and ensures the required number of power and ground paths from the power supply. Make sure that you utilize all three +5 VDC conductors and all four ground conductors.

The power connector at P8, P9 also provides +/-12VDC and -5VDC required for any PC/104 expansion board. P8, P9 also supplies the correct voltage, +12 VDC, for flat panels that require back light operation. Refer to the P8, P9 power connector Table 2-1 for a complete listing of pinouts and their description.

The maximum current requirements for the PC-510 is 2.0 A provided through P8, P9. It is important that a quality power supply be used with the PC-510. For example, when a particular application calls for a custom power supply, there are several internal issues to consider such as current capacity, line and load regulation, maximum ripple, hold up time, efficiency, and current limiting. The user should also consider the power devices and equipment such as the power cable conductor gauge, number and length of conductors, mating connectors, and the power supply to external devices such as hard drives, floppy drives, displays, mouse, and keyboard.

The proper selection of a quality power supply ensures reliability and proper functioning of the PC-510.

WARNING!

Make sure the power supply is OFF when connecting the power cable to the PC-510 board. Damage to the PC-510 may occur if the power is ON when connecting the power cable.

≡ Running a demo program

Logon message

1. Power on the PC-510.
2. A logon message similar to the one below appears on your PC monitor:

```
PhoenixBIOS(TM) A486 Version x.xx
Copyright (C) 1985-1994
Phoenix Technologies, Ltd.

All Rights Reserved

Octagon Systems Corp. PC-510 CPU
PC510 BIOS vx.xx - mm/dd/yy

Am586-WB processor detected operating at 133 MHz

640K Base Memory, 5x86 133 MHz
On board memory configured as EDO DRAM

INT 17h BIOS extension vx.xx
Copyright (c) 1995-96  Octagon Systems Corporation

PICO Flash Array
Copyright (c) 1996, Phoenix Technologies Ltd.
Resident Flash (RFA) OEM Layer

Phoenix Pico Flash Array
```

```
    Octagon Systems vx.xx
    First drive is in SSD1 (1856K, AMD 2 MB flash)

Starting ROM-DOS...

HIMEM v6.22 (Revision x.xx)
Copyright (c) 1989-1995 Phoenix, Inc.

VDISK v6.22 (Revision x.xx)
Copyright (c) 1989-1995 Datalight, Inc.
Extended Memory Present

VDISK v6.22 (Revision x.xx)
Copyright (c) 1989-1995 Datalight, Inc.
Formatting 2304K XMS memory as drive E:

PC510 C:\> demo

To begin the demo.exe program, press any key.
```

Then a demonstration program will begin. If you do not get the proper logon message, please do the following:

- Make sure all jumpers are set to factory defaults. Refer to the *Technical data* appendix for all default jumper settings.
- If the system still does not respond, remove W2[9-10] to run BIOS default SETUP and try again. Also, refer to the *Troubleshooting* chapter.

3. Use the directory command to make sure your equipment and software are working properly. Enter:

```
PC510 C:\> DIR
```

A directory listing of files stored in the SSD1 socket should appear:

```
Volume in drive C is SSD1
Volume Serial Number is 3214-1BE4
Directory of C:\

COMMAND    COM   26,321   04-12-96   6:22p
AUTOEXEC   BAT       38   04-12-96   8:26p
CONFIG     SYS       67   04-12-96   8:26p
DOS        <DIR>          04-12-96   8:26p
UTILS      <DIR>          04-12-96   8:26p
DEMO.EXE   EXE   27,922   04-12-96   8:26p
DEMO       BAS    5,045   04-12-96   8:26p
             7 file(s)   26,426 bytes
                         105,472 bytes free
```

≡ What's next

1. To run SETUP and configure the system, see the *SETUP programs* chapter.
2. To connect a floppy and/or hard drive, see the *External drives* chapter.
3. Refer to the *Transferring files/remote disks* chapter to transfer files from a host PC and to use a remote disk via a serial connection.
4. To use a serial console, refer to the *Console devices* chapter.

Chapter 3: *SETUP programs*

≡ Introduction

Three system configuration programs exist for the PC-510. They are:

- SETUP – Configures devices set up by the BIOS such as serial ports and floppy drives
- SETSSD – Configures PICO FA SSD device order
- PMISETUP – Configures power management options at a more detailed level than SETUP
- SETIRQ – Configures the interrupt routing matrix.

≡ SETUP

SETUP can be entered in one of two ways:

- Run SETUP.COM
- Press the "backspace" key followed by the "S" key during BIOS POST sequence (this occurs between the memory test and boot).

  Also, by removing the USESETUP jumper from W2[9-10], you may force the setup to temporarily revert to the BIOS defaults (Table 3-1) and also allow the user to reconfigure the setup options.

  The SETUP program defines the PC-510 system parameters. This program is shipped with default configuration parameters stored in the serial EEPROM. Changes are made by running the SETUP program. The SETUP program is stored on the SSD1 drive and on the PC-510 utility disk.

Table 3-1 PC-510 SETUP parameters

SETUP parameters	Description	Default
Serial console on COM1	Allows COM1 to be used as a console when on-board video is disabled	Enabled
COM1 console baud rate	Specifies communications rate between PC and PC-510 when serial console is in use	9600
Power-on memory test	Extensive memory testing performed on bootup	Enabled
Boot sequence	Specifies whether the floppy drive will be ignored as a boot device	C: Only
Serial port COM1	Specifies COM1 enable/disable	Enabled
Serial port COM1 address	COM1 address	3F8h
Serial port COM2	Specifies COM2 enable/disable	Enabled
Serial port COM2 address	COM2 address	2F8h
Parallel (LPT) port	Specifies LPT port enable/disable	Enabled
Parallel port mode	Specifies mode to use with parallel port	Bidirectional printer port
Parallel port address	Specifies address to use w/parallel port	378h
Number of floppy drives	Specifies number of floppy drives attached	0
On-board floppy controller	Specifies location of floppy: on-board or on PC/104 bus	Disabled
On-board IDE interface	Specifies usage of on-board IDE connector or PC/104 bus	Disabled

Table 3-1 PC-510 SETUP parameters (cont'd)

SETUP parameters	Description	Default
Primary master fixed disk	Specifies which IDE interface is used	None
Primary slave fixed disk	Specifies which IDE interface is used	None
Secondary master fixed disk	Specifies which IDE interface is used	None
Secondary slave fixed disk	Specifies which IDE interface is used	None
Internal CPU cache	Specifies CPU cache enable/disable	Enabled
CPU cache mode	Specifies write-through/ write-back on some CPUs (processor specific)	Write-back
Limit CPU to half speed	Limits the top CPU speed	No
SETUP entry via hotkey	Specifies <backspace><S> hotkey enable/disable	Enabled
Power management	Specifies power management enable/disable	Enabled
Doze clock	Specifies doze mode in power management is to slow or stop the clock	Slow
Time update after suspend	Specifies to allow update of time after suspend mode	Enabled
DIMM module type	Specifies the type of DIMM module	EDO
ROM Enable	Toggles video BIOS region (first 32 KB)	Enabled
ROM Enable C8000-CFFFFh	Toggles video BIOS, second region (first 8 KB is video BIOS)	Enabled
ROM Enable D8000h-DFFFFh	Toggles extended BIOS area for PICO FA and INT 17h BIOS	Enabled
Shadow C0000h-C7FFFh	Specifies video BIOS shadow enable/disable (first 32 KB)	Enabled
Shadow	Shadow enable/disable (first 8 KB is video BIOS)	Enabled
Shadow	Shadow enable/disable	Disabled
Shadow	Shadow enable/disable	Disabled

Running SETUP over the console port

1. To run SETUP make sure you have established a communications link between a keyboard and monitor with the PC-510 *or* a serial communications link between the PC-510 and your PC. See the *Console devices* chapter for more information on these two links.

2. Enter:

   ```
   PC510 C:\> SETUP
   ```

Note If you are not booting from the SSD0 drive, the drive designator may differ.

Note You may also enter **SETUP** after the memory test and before the system has booted by pressing the "backspace" key followed by the "S" key.

3. The system will display the PC-510 setup parameters and available options. Select the option by pressing the space bar until the correct information appears, then press <ENTER>. Press <ESC> twice if you want to exit SETUP without saving your responses.

Note Options having an * are default settings.

- `Serial Console on COM1:`

  ```
  ENABLED*
  DISABLED
  ```

> **WARNING!**
>
> **Disabling the serial console when there is no video monitor present will stop further serial console communication with the system after the system resets. Once disabled, you may re-enable the serial console by running SETUP. To run SETUP, do one of the following steps:**
>
> - **Remove the USESETUP jumper, reboot and run SETUP**
> - **Install a video monitor, reboot and run SETUP. You have elected to DISABLE the serial console.**

- `Serial Port COM1 Console Baud Rate:`

  ```
  1200
  2400
  4800
  9600*
  14400
  19200
  28800
  38400
  57600
  115200
  ```

- Power on memory test:

  Enabled*
  Disabled

You may want to disable the memory test to speed up the boot process. You may also press the space bar to cancel the memory test while in progress.

- Boot Sequence:

Note Standard mode is provided for compatibility only. We recommend the use of bidirectional mode. EPP and ECP modes are provided for equipment that has the capability to operate in these modes for enhanced performance.

- Number of floppy drives:

  0*, 1, 2

  C: Only*
  A: Then C:

- Serial Port COM1:

  Enabled*
  Disabled

- Serial Port COM1 address:

  3F8h*
  2F8h
  338h
  3E8h
  2E8h
  220h
  238h
  2E0h
  228h

- Serial Port COM2:

  Enabled*
  Disabled

- Serial Port COM2 address:

  2F8h*
  338h
  3E8h
  2E8h
  220h
  238h
  2E8h
  2E0h
  228h

Note Octagon strongly recommends the use of 3F8h for COM1 and 2F8h for COM2.

Note The choices for COM1 and COM2 addresses are mutually exclusive; therefore, you may not see all the choices listed above. COM1 and COM2 addresses may also conflict with those belonging to COM3 through COM6. Refer to the *Serial ports* chapter for a complete description on conflicting addresses.

- Parallel (LPT) Port:

  Enabled*
  Disabled

- Parallel Port Mode:

  Bidirectional mode*
  EPP mode
  ECP mode
  Standard (Unidirectional) mode

- Parallel Port Address:

  378h*
  278h
  3BCh

- IRQ for LPT port

  IRQ7*
  IRQ5

- Onboard floppy controller:

  Enabled (enables onboard floppy connector, J9)
  Disabled*

- Drives A and B:

  No* - requires a swap in the cable
  Yes - does not require a swap in the cable

- Floppy drive 1 size:

  Not Installed
  5.25", 360 KB
  5.25", 1.2 MB
  3.5", 720 KB
  3.5", 1.44 MB*

- Floppy drive 2 size:

  Not Installed
  5.25", 360 KB
  5.25", 1.2 MB
  3.5", 720 KB
  3.5", 1.44 MB*

- Onboard IDE interface:

  Disabled*
  Enabled (enables J10)

- Primary master fixed disk:

  None*
  Auto - detects hard disk parameters
  User - detects hard disk parameters

- Drive 1 parameters:

  Cylinders (xxx)
  Heads (xx)
  Sectors (xx)

- Internal CPU cache:

  Enabled*
  Disabled

- Limit CPU to half speed:

  NO*
  YES

- Setup entry via hotkey:

  Enabled*
  Disabled

- Power management:

  Enabled*
  Disabled

- Doze clock:

  Slow*
  Stop

- Time update after suspend:

  Enabled*
  Disabled

- DIMM module type:

  EDO*
  Standard

- Shadow C0000h - C7FFFh:

  Disabled
  Enabled*

- Shadow C8000h - CFFFFh:

  Disabled
  Enabled*

- Shadow D0000h - D7FFFh:

  Disabled*
  Enabled

- Shadow D8000h - DFFFFh:
  Disabled*
  Enabled

```
Press ENTER to SAVE the changes or
Press ESC to EXIT without saving the changes.
Saving options.
Options saved.
```

Depending on the options you have selected, the system may display the following message:

```
You must reset for these options to take effect.
```

If you entered SETUP with the hotkeys (i.e., "backspace" and "S" keys), the system will reboot automatically.

SETUP example

The following example configures a system with no memory test, 9600 baud, printer at 378h, and booting from C:

```
                OCTAGON SYSTEMS CORPORATION
                  PC510 SETUP UTILITY Vx.x
            (c) Phoenix Technologies, Ltd. 1985, 1995
 ____________________________________________________________
 (Press SPACE to CHANGE, ENTER to ACCEPT, ESC to EXIT)

Serial Console on COM1:          ENABLED
 COM1 Console Baud Rate:         9600
Power on memory test:            DISABLED
Boot Sequence:                   C: ONLY
Serial Port COM1:                ENABLED
  Serial Port COM1 Address:      3F8h (default)
Serial Port COM2:                ENABLED
  Serial Port COM2 Address:      2F8h (default)
Parallel (LPT) Port:             ENABLED
 Parallel Port Mode:             Bidirectional Printer
Port
 Parallel Port Address:          378h
Number of floppy drives:         1
 Onboard Floppy Controller:      ENABLED
 Swap drives A and B:            NO
Floppy drive 1 size:             3.5", 1.44 MB
Onboard IDE Interface:           ENABLED
Primary Master Fixed Disk:       AUTO
Primary Slave Fixed Disk:        USER
Secondary Master Fixed Disk:     NONE
Secondary Slave Fixed Disk:      NONE
Internal CPU cache:              ENABLED
Limit CPU to half speed:         NO
SETUP Entry via Hotkey:          ENABLED
Power Management:                ENABLED
 Doze Clock (slow, stop):        SLOW
 Time Update after Suspend:      ENABLED
DIMM Module Type:                EDO
Enable ROM at C0000h-C7FFFh:     ENABLED
Enable ROM at C8000h-CFFFFh:     ENABLED
Enable ROM at C8000h-DFFFFh:     ENABLED
```

```
Shadow  D0000h-C7FFFh:          ENABLED
Shadow  C8000h-CFFFFh:          ENABLED
Shadow  D0000h-D7FFFh:          DISABLED
Shadow  D8000h-DFFFFh:          DISABLED

Press ENTER to SAVE the changes
Press R to RESTART with original values or
Press ESC to EXIT without saving the changes:

Options Saved.

You must reset for these options to take effect.
PC510 C:\>
```

Note Executing SETUP /D will change all setup parameters to default values.

≡ SETSSD

For more information on SETSSD, refer to the *Defining SSDs using SETSSD* section in the *Managing SSDs* chapter.

≡ PMISETUP

PMISETUP allows the user to customize the power management features of the PC-510. Refer to the *CPU power management* chapter. See also the *Software utilities* appendix for details.

≡ SETIRQ.EXE

To change interrupts via software using SETIRQ.EXE, refer to the *Programming* section in the *IRQ routing opto IRQs* chapter.

Chapter 4: Save and run programs

≡ Save and run your programs on the PC-510

Once you have written, tested and debugged your application, you can then save it to flash memory in SSD1 or SSD0 (if flash or SRAM). When you reboot the PC-510, your program can automatically load into DOS memory and execute. As shipped from the factory, SSD1 already contains a bootable ROM-DOS.

This chapter describes the following:

- Saving an application program to SSD1
- Autoexecuting the program from the PC-510
- Overriding autoexecution of your program.

The information in this chapter assumes you are using ROM-DOS in your application. Some Microsoft programs make undocumented DOS calls. With ROM-DOS, an error returns when an undocumented DOS call is made, causing your program to operate erratically. We recommend booting from SSD1, using your own DOS, when using programs with undocumented DOS calls. Refer to the section *Adding operating system startup files* in the *Managing SSDs* chapter for more information on saving and autoexecuting programs.

≡ Saving programs and support files

By default, the drive in SSD1 comes preformatted from the factory, loaded with ROM-DOS startup files and an example demo program. To replace the demo program on SSD1 with your own, see the section *Adding your application*, in this chapter. To reformat an SSD or to add your own operating system, please refer to the *Managing SSDs* chapter.

WARNING!

Reformatting SSD1 requires the use of a floppy or a hard disk to restore system files.

Adding your application

To add your application to your SSD, do the following:

1. Three methods of copying your application to the SSD are available. Do one of the following:
   - From a local drive to the PC-510, issue the COPY command.
   - From a host drive, download your application by issuing the TRANSFER command when using PC SmartLINK. Refer to the section, *Transferring files between the PC-510 and your PC* in the *Transferring files/remote disks* chapter.
   - To establish a remote drive and copy from it, issue the REMDISK and REMSERV commands. Refer to the section, *Transferring files between the PC-510 and your PC* in the *Transferring files/remote disks* chapter.
2. Add or remove any device drivers for your application. You may want to do the same for the CONFIG.SYS file on SSD1. Remember to add these drivers to your drive as well.
3. To autoexecute your application, add your application name to the AUTOEXEC.BAT file. To replace our example program (DEMO.EXE) with your application, substitute DEMO in the AUTOEXEC.BAT file with your applications' filename.

Autoexecuting your application

This section describes how to autoexecute your application.

1. To autoexecute your application in SSD1, use the SETSSD command to define your SSD as the boot device. Since you need to define the order of SSD1 as the first of the SSDs (and before any IDE drives), enter the following command:

   ```
   PC510 C:\> SETSSD SSD1 SSD0 /before
   ```

2. Reset the system. SSD1 is now drive C: and your application should begin execution.

Note If the SETUP option "Boot Sequence" is set to "A: THEN C:", remove any floppy in drive A: before resetting the system.

Note We recommend that you leave SSD0 in the SETSSD options or that you have a copy of SETSSD.EXE on SSD1. This allows you to change your boot device back to SSD0 when needed.

Note The SETSSD options are not used when W2[9-10] is not jumpered.

Overriding the autoexecution of your application

You may stop the autoexecution of your application by doing one of the following options:

Option 1

1. Press F5 or F8 on your local keyboard. For more information, see your ROM-DOS manual.

Option 2

1. Change AUTOEXEC.BAT and/or CONFIG.SYS to **not** call out your program.

Option 3

1. Install a floppy.
2. Change SETUP option "Boot Sequence" to "A: THEN C:"
3. Change SETUP to enable the floppy.
4. Boot from floppy.
5. Change AUTOEXEC.BAT on C:.

Overview: Section 2 – Hardware

Section 2 discusses usage, functions, and system configurations of the PC-510's major hardware features. The following chapters are included:

Chapter 5:	Serial ports
Chapter 6:	LPT1 parallel port
Chapter 7:	Console devices
Chapter 8:	SSDs, DRAM, and battery backup
Chapter 9:	External drives
Chapter 10:	IRQ routing and opto IRQs
Chapter 11:	EZ I/O
Chapter 12:	LED signaling and "beep" codes
Chapter 13:	CRTs and flat panels
Chapter 14:	GPS interface
Chapter 15:	PC/104 expansion

Chapter 5: Serial ports

≡ Description

The PC-510 has six standard serial ports, COM1 through COM6, that are 16C550 compatible. Under OEM contract, COM5 and COM6 can be omitted. These serial ports interface to a printer, terminal or other serial device. All ports support 5-, 6-, 7-, or 8-bit word lengths, 1, 1.5, or 2 stop bits, and baud rates up to 115.2K. All ports have the following specifications:

- 16C550 compatible
- 16 byte FIFO buffers
- IEC 1000, level 3, ESD protection
  - — Contact discharge ±6 kV
  - — Air-gap discharge ±8 kV
- Backdrive protection
- Up to 115.2k baud operation
- 5-, 6-, 7-, or 8-bit word lengths
- 1-, 1.5-, or 2-stop bits

≡ Serial port options

The standard version PC-510 has COM1 and COM2 installed as an 8-wire interface. Under OEM contract, you can order all six serial ports in various configurations, tailored to your application.

Table 5-1 COM port options

COM ports	Standard features	Optional features
COM1 standard	8-wire industrial interface	4-wire industrial interface
COM2 standard	8-wire industrial interface	4-wire industrial interface
COM3 (optional)	8-wire industrial interface	4-wire industrial interface
COM4 (optional)	8-wire industrial interface	4-wire industrial interface
COM5 (optional)	4-wire industrial interface/ GPS interface	None
COM6 (optional)	4-wire industrial interface/ RS-485/GPS auxiliary	None

≡ Description of serial ports

Conflicting COM port addresses

The following table lists the COM1 and COM2 addresses that conflict with those addresses belonging to COM3 through COM6.

Table 5-2 Conflicting COM port addresses

COM1	COM2	COM3	COM4	COM5	COM6
220h	220h				
228h	228h				
238h	238h				238h*
2E0h	2E0h				
2E8h	2E8h		2E8h*		
2F8h	2F8h*				
				320h*	
338h	338h				
3E8h	3E8h	3E8h*			
3F8h*	3F8h				

* = default

COM1

COM1 is either a full 8-wire RS-232 (standard) or an industrial 4-wire RS-232 (optional) configuration. The I/O address for COM1 is 3F8h (default) but can be changed in SETUP to any of the addresses in the table below. Refer to the *SETUP programs* chapter for more information on running SETUP. IRQ4 is dedicated to COM1 and if COM1 is not used under interrupt control, IRQ4 may be used by other resources. For example, when COM1 is the console, COM1 uses IRQ4. COM1 can be used for console I/O or RS-232 I/O. COM1 and COM2 share the J7, 20-pin header. See the chapter on *IRQ routing and opto IRQs* for more details.

Table 5-3 COM1 available addresses (IRQ4 dedicated)

COM1 available addresses	
220h	2F8h
228h	338h
238h	3E8h
2E0h	3F8h*
2E8h	

* = default

COM2

COM2 is either a full 8-wire RS-232 (standard) or an industrial 4-wire RS-232 (optional) configuration. RI on COM2 can be used as a method of "waking up" the PC-510 from a power management SUSPEND operation. Refer to the *CPU power management* chapter for more information. The I/O address for COM2 is 2F8h (default) but can be changed in SETUP to any of the addresses in the table below. For more information on running SETUP, refer to the *SETUP programs* chapter. IRQ3 is dedicated to COM2. If COM2 is not used under interrupt control, IRQ3 may be used by other resources such as the PC/104 expansion board, the GPS module, IRQ routing, etc. Refer to the *IRQ routing and opto IRQs* chapter for details. COM1 and COM2 share the J7, 20-pin header.

Table 5-4 COM2 available addresses (IRQ3 dedicated)

COM2 available addresses	
220h	2F8h*
228h	338h
238h	3E8h
2E0h	3F8h
2E8h	

* = default

Note See the *Accessories* appendix for connector information on COM1 and COM2.

COM3 through COM6 interrupt/status port

COM3 through COM6 share the same interrupt—they default to IRQ15. To determine which serial port caused the interrupt, you must first read the interrupt status port. Follow these steps to read the interrupt status port:

1. Refer to Table 5-5 to read register 0A9h, which includes I/O range select A (bit 5) and I/O range select B (bit 4) information.

Table 5-5 Register 0A9h

Bit	Description
7	Enhanced mode, CPU clock speed (W2[3-4])
6	Not used
5	I/O range select A (ISP file dependent)
4	I/O range select B (ISP file dependent)
3	Not used
2	User option jumper 1 (W4[9-10])
1	User option jumper 2 (W3[5-6])
0	USESETUP jumper (W2[9-10])

2. Determine the interrupt status port address based on bit 5 (I/O range select A) and bit 4 (I/O range select B) at register 0A9h. See the table below.

Table 5-6 Reading the interrupt status port: Register 0A9h

I/O range select A†	I/O range select B†	COM3 addresses	COM4 addresses	COM5 addresses	COM6 addresses	Interrupt status port
1	1	3E8h	2E8h	320h*	328h*	338h*
0	0	3E8h	2E8h	140h	148h	158h
0	1	3E8h	2E8h	120h	128h	138h
1	0	3E8h	2E8h	340h	348h	358h

* = default

† = I/O range select A = bit 5, I/O range select B = bit 4

For example, if bits 5 and 4 are both 1, the interrupt status port address is 338h (default). If bits 5 and 4 are both 0, the interrupt status port address is 158h; if bit 5 is 0 and bit 4 is 1, the address for the interrupt status port is 138h; and if bit 5 is 1 and bit 4 is 0, the address for the interrupt status port is at 358h.

3. Inside your interrupt handler, read the interrupt status port. Bit 0 through bit 3 show which serial port caused the interrupt.

   For example, when there is a 1 in bit 3, this means COM3 caused the interrupt; a 1 in bit 2 shows that the interrupt came from COM4; a 1 in bit 1 means that COM5 caused the interrupt; and by default, when a 1 is in bit 0, then COM6 caused the interrupt. See the table above to read the interrupt status port.

Note Exit the interrupt handler only when bits 0 through 3 are all at 0.

Table 5-7 Interrupt status port (138h, 158h, 338h, and 358h)

Bit	Location
3	COM3
2	COM4
1	COM5
0	COM6

Note All 0s as bits indicate no interrupt and a 1 indicates an interrupt.

It is possible to change the interrupt through the IRQ routing matrix. You can also change bits 4 and 5 I/O ranges, COM5 and COM6 addresses, and the status port addresses through the IRQ routing matrix. See the *IRQ routing and opto IRQs* chapter for more details on how to change and reroute base addresses.

COM3

COM3 can be ordered either as an 8-wire RS-232 (standard) or as an industrial 4-wire RS-232 (optional) interface. The I/O address for COM3 is 3E8h. The interrupt for COM3 is logically OR'd with COM4 through COM6. COM3 and COM4 share the J4, 20-pin header. For more information, see the *COM3 through COM6 interrupt/status port* section in this chapter.

Table 5-8 COM3 available address and IRQ routing

Address	IRQ
3E8h	IRQ15*

* = default, routable

COM4

COM4 can be ordered either as an 8-wire RS-232 or as a 4-wire industrial RS-232 configuration. The I/O address for COM4 is 2E8h. The interrupt for COM4 is logically OR'd with COM3, COM5, and COM6. COM3 and COM4 share the J4, 20-pin header. For more information, see the *COM3 through COM6 interrupt/status port* section in this chapter.

Table 5-9 COM4 available address and IRQ routing

Address	IRQ
2E8h	IRQ15 *

* = default, routable

Note See the *Accessories* appendix for connector information on COM3 and COM4.

COM5

COM5 functions either as an RS-232 serial port or as a global positioning system (GPS) module port. Both configurations are standard features and may be omitted from OEM boards. The GPS port located at J13 accepts the Rockwell Jupiter GPS module directly. Refer to the *GPS interface* chapter for more information. The I/O address for COM5 is 320h (default). You can change the default address to 120h, 140h, or 340h through the interrupt routing matrix. The interrupt for COM5 is logically OR'd with COM3, COM4, and COM6. COM5 and COM6 share the J5, 20-pin header. For more information, see the *COM3 through COM6 interrupt/status port* section in this chapter.

Table 5-10 Available addresses for COM5 at port 0A9h (IRQ 15 default, routable)

I/O range select A (bit 5)	I/O range select B (bit 4)	COM5 addresses
0	1	120h
0	0	140h
1	1	320h*
1	0	340h

* = default

COM6

COM6 is an industrial RS-232 or a two-wire RS-485 port. COM6 can also be used to route the RTCM SC-104 differential correction data to the GPS receiver. When using this port to route the RTCM SC-104 data to the GPS receiver, the RS-485 portion of the interface remains fully functional, however, the RS-232 function is lost. The I/O address for COM6 is 328h (default). You can change the default address to 128h, 148h, and 348h through the interrupt routing matrix. The interrupt for COM6 is logically OR'd with COM3 through COM5. COM5 and COM6 share J5, 20-pin header. For more information, see *COM3 through COM6 interrupt/status port* section in this chapter.

Table 5-11 Available addresses for COM6 at port 0A9h (IRQ 15 default, routable)

I/O range select A (bit 5)	I/O range select B (bit 4)	COM6 addresses	RS-485 transmitter control (bit 1)
0	1	128h	12Ch
0	0	148h	14Ch
1	1	328h*	32Ch*
1	0	348h	34Ch

* = default

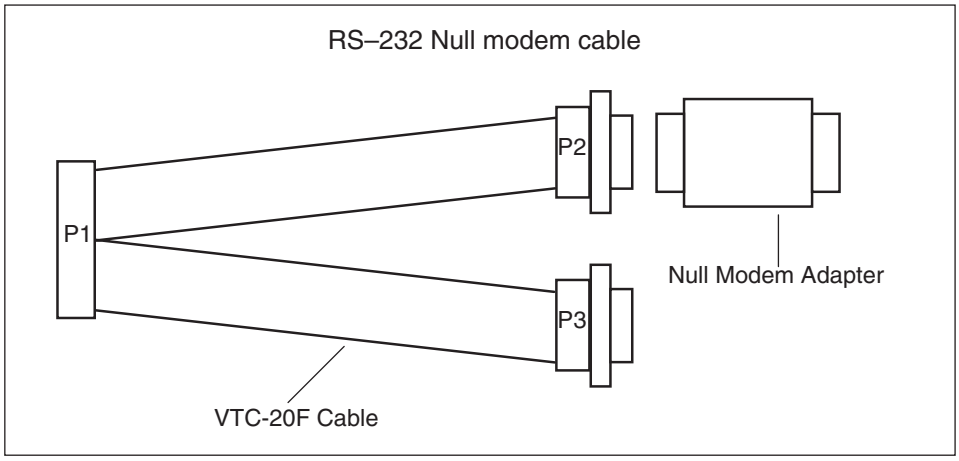
Note See the *Accessories* appendix for connector information on COM5 and COM6.

≡ Null modem cable

Use a VTC-20F cable to connect either COM1 and COM2, or COM3 and COM4, or COM5 and COM6 ports to external serial equipment. The P2 and P3 connectors are DB-9 female connectors which plug directly into a 9-pin PC serial cable. When interfacing the PC-510 to your desktop PC, you must use a null modem adapter.

The PC-510 requires an RS-232 null modem cable to interface to your desktop PC.

Figure 5-1 Null modem adapter and VTC-20F cable



Building your own cable

If you are not using a VTC-20F series cable, then you can build your own RS-232 communications cable. This is a simple null modem cable where RxD and TxD signal are crossed. Cable pins 4 and 6 in the first COM port connector of the PC-510 are tied together, and cable pins 14 and 16 in the second COM port connector of the PC-510 are tied together. Pins 7 and 8 are tied together on each DB-9 cable connector. Pins 4 and 5 are tied together on each DB-25 cable connector. Refer to the following table and diagram for a complete listing of all cable connections for the PC-510.

Table 5-12 Custom RS-232 null modem cable for the PC-510: First COM port

COM1, COM2 or COM3, COM4 or COM5, COM6	**serial port signal**	**DB-9 pin**	**DB-25 pin**	**PC port signal**
1	DCD	7 |	4 |	RTS
		8 |	5 |	CTS
2	DSR	4	20	DTR
3	RxD	3	2	TxD
4 |	RTS	1	8	DCD
6 |	CTS			
5	TxD	2	3	RxD
7	DTR	6	6	DSR
8	RI	NC	NC	RI
9	Gnd	5	7	Gnd
10	+5V Safe	NC	NC	

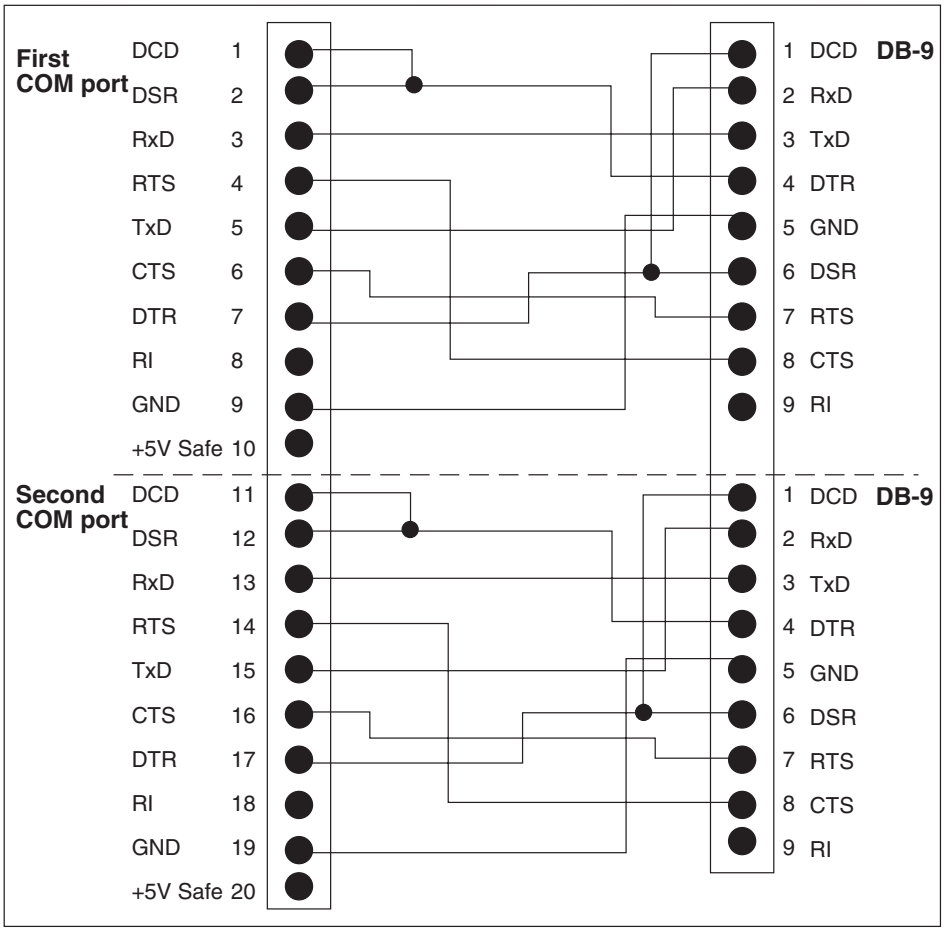
| = pins tied together

Table 5-13 Custom RS-232 null modem cable for the PC-510: Second COM port

PC-510 COM1, COM2 or COM3, COM4 or COM5, COM6	PC-510 serial port signal	DB-9 pin	DB-25 pin	PC port signal
11	DCD	7 |	4 |	RTS
		8 |	5 |	CTS
12	DSR	4	20	DTR
13	RxD	3	2	TxD
14 |	RTS	1	8	DCD
16 |	CTS			
15	TxD	2	3	RxD
17	DTR	6	6	DSR
18	RI	NC	NC	RI
19	Gnd	5	7	Gnd
20	+5V Safe	NC	NC	

\| = pins tied together

Figure 5-2 Custom null modem cable for the PC-510



≡ Function and use of serial ports

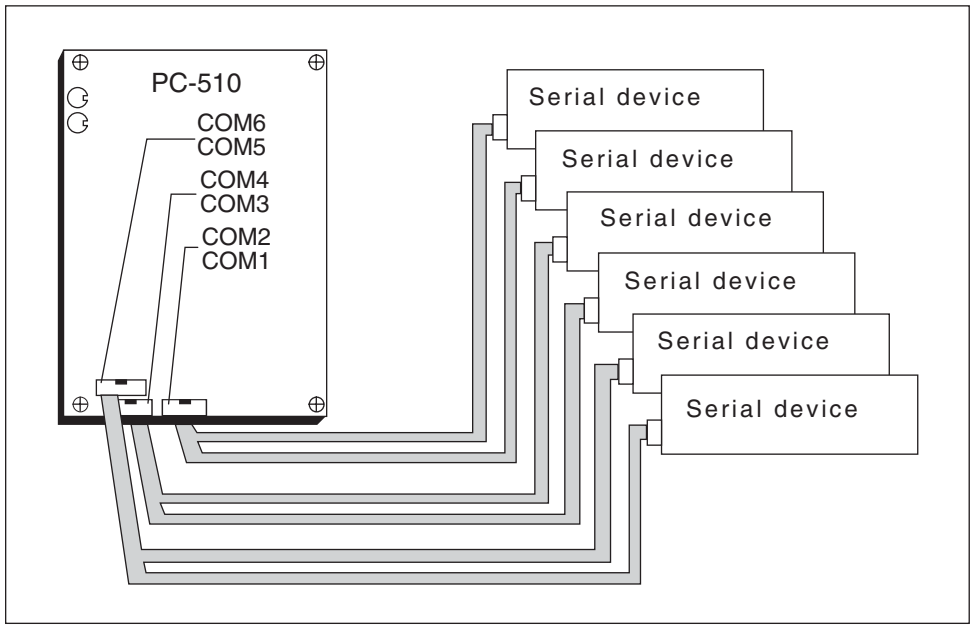
COM1 as serial console device

Instead of the on-board local bus SVGA, you can use COM1 as the console device. See the *Console devices* chapter for more information. When COM1 is not used as a console device, then it is available to your program as a standard RS-232 port. Octagon Systems strongly urges that you leave COM1 at the 3F8h default address.

COM1 through COM6 as RS-232 I/O

COM1 through COM6 can also be used as RS-232 serial ports. Depending upon the design of each port, COM1 through COM4 can support 4- or 8-wire configurations, and COM5 and COM6 are 4-wire only configurations. Use a VTC-20F cable to interface from the PC-510 and the serial device.

Figure 5-3 PC-510 serial devices



COM5 as GPS I/O

COM5 also supports the Rockwell Jupiter GPS module and is accessed at connector J13. Refer to the *GPS interface* chapter for more information.

COM6 RS-485 transmitter control

COM6 can either have an RS-232 or an RS-485 interface. The default configuration is for an RS-232 port. To change this configuration, use the SETIRQ.DOC support command found in the ISP directory on your PC-510 utility disk.

COM6 defaults to base address 328h. For a complete listing of COM6 addresses, see the *COM3 through COM6 interrupt/status port* section in this chapter. The RS-485 transmitter is controlled by the COM6 RTS signal. To turn the transmitter ON and OFF through software control, toggle bit 1 of base address + 4 (32Ch). Refer to the following table on RS-485 terminations.

Table 5-14 RS-485 transmitter control: COM6 at location 32Ch

Program statement	Description
Set bit 1 at location 32Ch high	Enables COM6 RTS which enables RS-485 transmitter output
Set bit 1 at location 32Ch low	Disables COM6 RTS which disables RS-485 transmitter output

Note The above address at COM6 for the RS-485 transmitter control may change. Refer to Table 5-11 for a complete listing of COM6 addresses.

The RS-485 port is configured for termination for either marking or spacing idle condition, or not terminated. Any node located between the end points should not be terminated. Use W1[1-2][3-4] to disable termination. Jumper W1[7-9][8-10] to provide for marking condition and make sure that both ends of the network are terminated.

Table 5-15 RS-485 termination select jumper: W1

Pins	Description
[1–2]	No function, used for shunt storage
[3–4]	No function, used for shunt storage
[5–6]*	No function, used for shunt storage
[7–8]	RS–485 terminated(–), idle line at space
[9–10]	RS–485 terminated(+), idle line at space
[7–9]*	RS–485 terminated(–), idle line at mark
[8–10]*	RS–485 terminated(+), idle line at mark

* = default, pins jumpered.

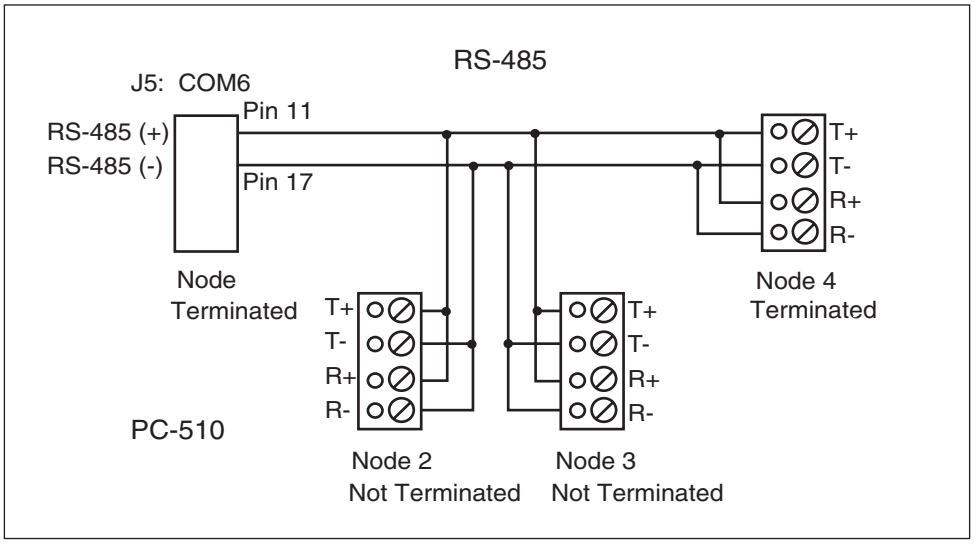
≡RS-485 network

An application may implement a node as either the "host" node or as a "remote" node in an RS-485 network. There can be as many as 32 nodes without any bus repeaters in the network. A "host" is referred to as the node that initiates communication; while a "remote" is referred to as a node that is addressed by the host.

In any given communication sequence in an RS-485 network, there can only be one host. The host is responsible for initiating communication, maintaining network registration, and providing housekeeping tasks with other nodes. Remotes, however, cannot initiate a communication. They can only respond to messages that are addressed to them from the host.

The following diagram demonstrates how a typical two-wire transmission is implemented in the RS-485 network.

Figure 5-4 RS-485 two-wire (half duplex) transmission



Chapter 6: LPT1 parallel port

≡ LPT1 parallel port

The LPT1 port has a 26-pin connector. It supports the unidirectional standard mode, bidirectional mode, enhanced parallel port (EPP) mode, and extended capabilities port (ECP) mode. The default I/O address is 378h (IRQ7). You may choose other nonstandard addresses between 278h (IRQ7) and 378h (IRQ7) in the PC-510 SETUP utility.

The LPT1 port supports a number of devices including a PC compatible printer, a multiline display, a matrix keypad or an opto rack with opto-isolated digital I/O modules.

Note Make sure that the interrupt used for COM3 through COM6 does **not** conflict with the IRQ selected for the LPT in SETUP.

≡ Printer

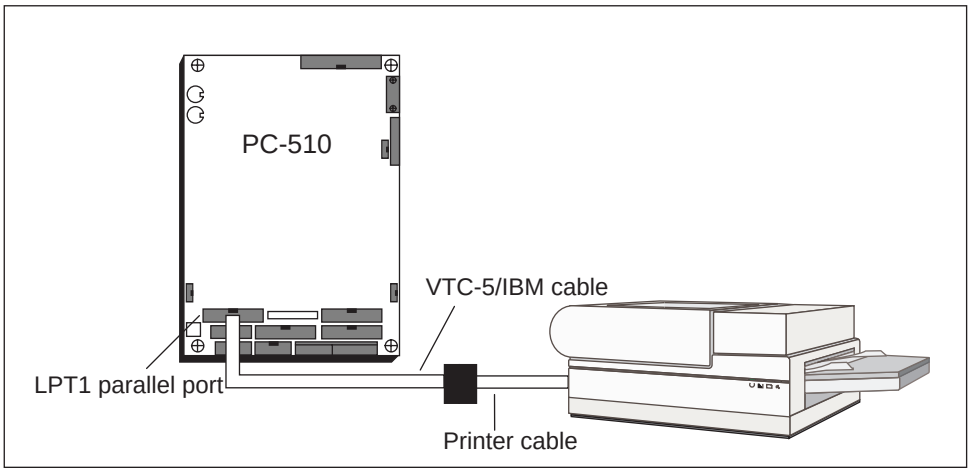
The following table illustrates the pinout for the LPT1 parallel port used as a printer port.

Note See the *Accessories* appendix for connector information on the LPT1 printer port connector.

Installing a printer

1. Make sure that the LPT1 port is in standard or bidirectional mode.
2. Connect an Octagon VTC-5/IBM cable from the LPT1 port (J6) to the 25-pin connector on your printer cable.
3. Connect the cable to your printer.

Figure 6-1 LPT1 as a printer port



≡ Display

The LPT1 port supports either a 4 x 20 or a 4 x 40 liquid crystal display (LCD). To interface the displays to the PC-510, use the Octagon 2010 interface board. A CMA-26 cable is required to connect the interface board to the PC-510. The program DISPLAY.EXE (found on the PC-510 utility disk) provides an easy method to use the display. Refer to the file DISPLAY.DOC on the PC-510 utility disk for information on initializing and using the display. Also, refer to the *2010 product sheet* for more information on the interface board.

Installing a display

1. Connect a CMA-26 cable from the LPT1 port on the PC-510 (J6) to J1 on the 2010. See Figure 6-2.
2. Connect the display cable to either the 14-pin or 16-pin header on the 2010. The size of the display will determine which header to use.
3. Refer to the file DISPLAY.DOC for more information on initializing and using the display.

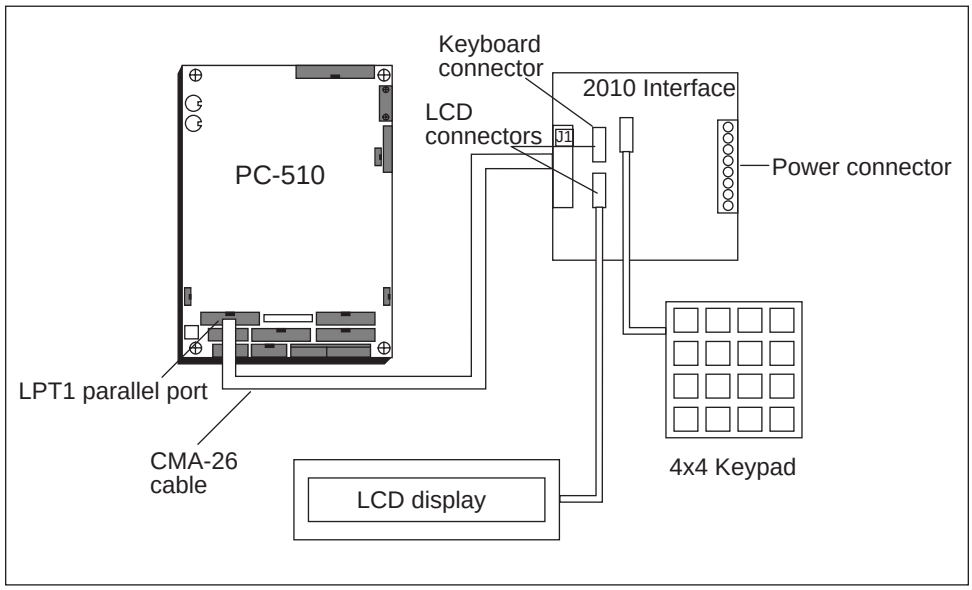
≡ Keypad

LPT1 also supports 4 x 4 matrix keypads. To interface the keypad to the PC-510, use the Octagon 2010 interface board. A CMA-26 cable is required to connect the interface board to the PC-510. The program DISPLAY.EXE (found on the PC-510 utility disk) provides an easy method to use the keypad. Refer to the file DISPLAY.DOC on the PC-510 utility disk for information on initializing and using the keypad. Also, refer to the *2010 product sheet* for information on the interface board.

Installing a keypad

1. Connect a CMA-26 cable from the LPT1 port on the PC-510 (J6) to J1 on the 2010. See Figure 6-2.
2. Connect the keypad cable to the 10-pin header on the 2010.
3. Refer to the DISPLAY.DOC file for more information on reading the keypad.

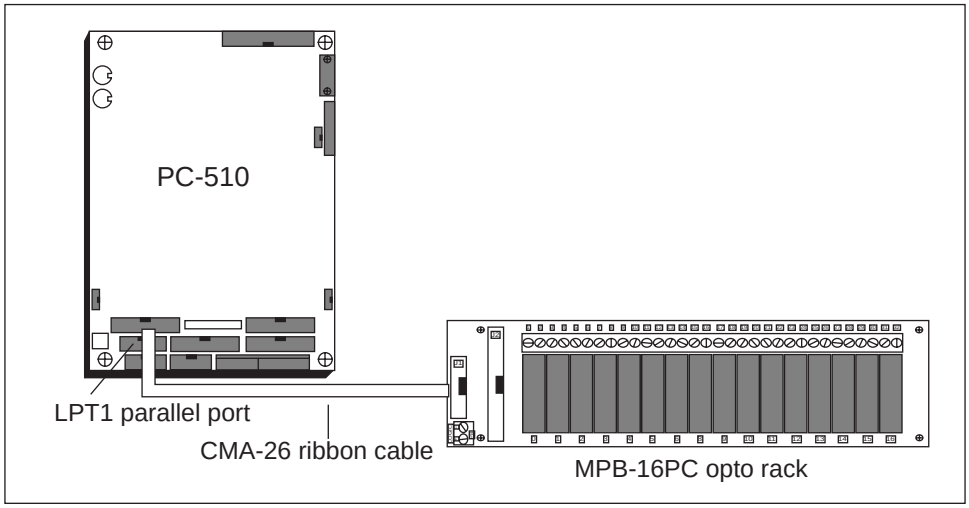
Figure 6-2 LPT1 as a display or keypad port



≡ Opto rack

The Octagon MPB-16PC opto rack interfaces directly to the parallel printer port and can control high voltage/high current G4 opto-isolated modules. Of the sixteen positions available, eight can be either input or output, four are dedicated as inputs and the other four are dedicated as outputs. Refer to the *MPB-16PC opto module rack product sheet* for more information.

Figure 6-3 LPT1 and an opto rack



Chapter 7: Console devices

≡ Description

The PC-510 has three options for console devices. You can use the on-board video with a monitor and a keyboard as your console. You can also use COM1 as the console or you can run the system without a console device.

≡ Selecting console devices

The following represent the PC-510's three options for console devices:

- Local bus SVGA and a local keyboard. The local bus SVGA can also drive flat panel displays.
- Serial console from COM1. A serial cable/null modem adapter plugged into a host PC running SmartLINK provides both input and output. The local keyboard also allows input.
- No console device means no video output, either from the SVGA monitor or the serial console. The local keyboard allows input.

Local bus SVGA

For correct usage of the CRT and flat panel, see the *CRTs and flat panels* chapter.

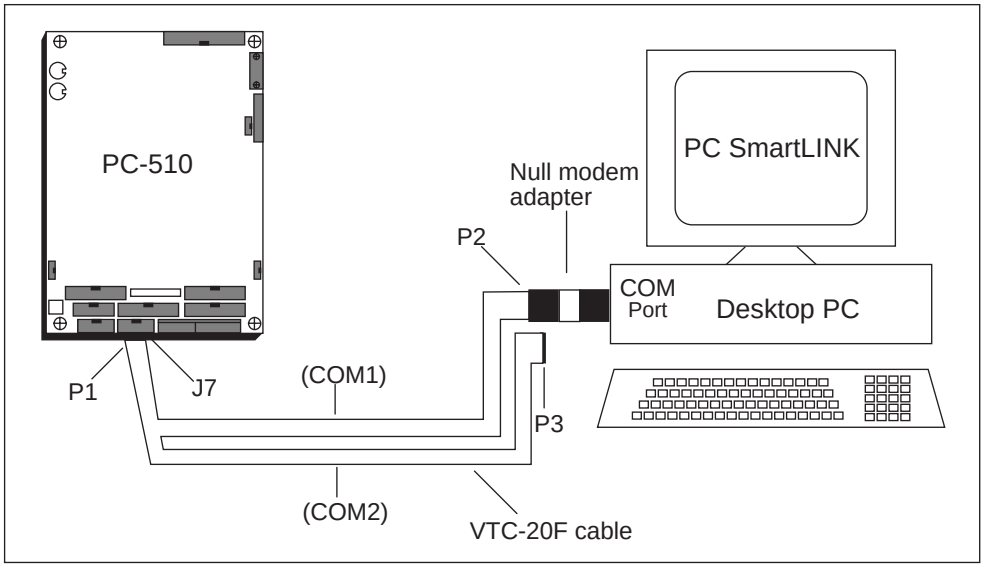
Serial console

If the serial console is enabled and the video BIOSes are disabled, then COM1 acts as the console device.

Follow these steps to use the serial console:

1. Power off the PC-510.
2. Connect a VTC-20F cable to J7 of the PC-510. Refer to Figure 7-1.
3. Connect P2 (COM1 side of the VTC-20F cable) to the 9-pin null modem adapter. Refer to Figure 7-2.

Figure 7-1 The PC-510 and a serial console

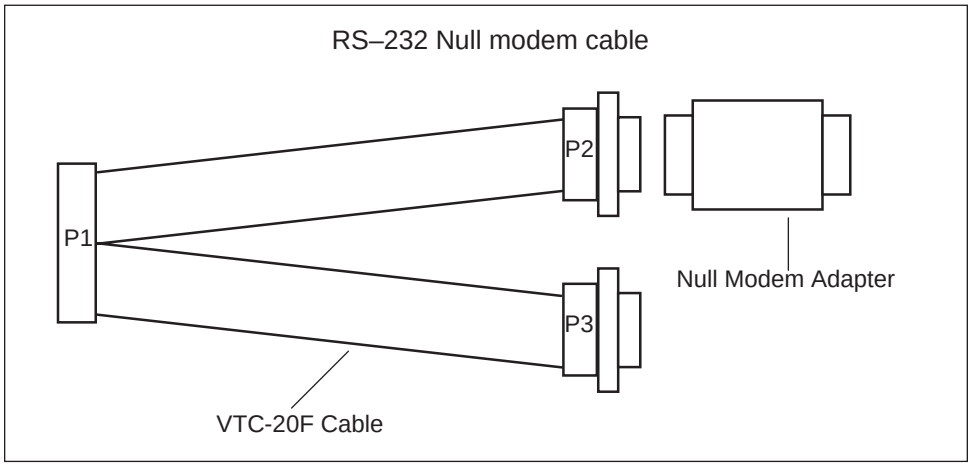


4. If your PC has a 9-pin serial connector, connect the 9-pin null modem adapter to any serial port (COM1-COM4) on your PC.
5. If your PC has a 25-pin serial connector, attach a 9- to 25-pin adapter to the 9-pin null modem adapter, and then insert the matching end of the 9- to 25-pin adapter into the serial port.
6. Start PC SmartLINK.
7. Remove W2[1-2] and W3[1-2] to disable the video BIOS.

Note For more information on enabling and disabling the video BIOS, refer to the following section in this chapter.

8. Power on the PC-510.

Figure 7-2 VTC-20F cable and null modem adapter



Keyboard

You can use any of the console options mentioned in the *Selecting console devices* section with a local keyboard.

Note See the *Accessories* appendix for connector information on the keyboard, speaker, and mouse connectors.

Speaker

You can also use a local speaker with any of the console options listed above in the *Selecting console devices* section. Interface the speaker via a 4-pin connector at J1. You may use any external speaker from 8-50 ohms.

Mouse

You can also add the use of a mouse to the list of serial console devices mentioned in the *Selecting console devices* section in this chapter. The mouse connects to J3 on the PC-510.

≡ Enabling/disabling the video BIOS

The BIOS checks for a video BIOS to determine which console device to use. If a console device exists, the BIOS will use the console device, the CRT, or the flat panel. When the console device does not exist , the BIOS will otherwise use a serial console, if it has not been disabled in SETUP.

To enable/disable the video BIOS area, either change W2[1-2]/W3[1-2] *or* run SETUP and change C0000h-C7FFFh or C8000h-CFFFFh ROM enable options. The jumpers work as a toggle for the SETUP options. That is, if the SETUP previously shows the BIOS regions as "enabled," then changing the state of W2[1-2]/W3[1-2] will disable the regions.

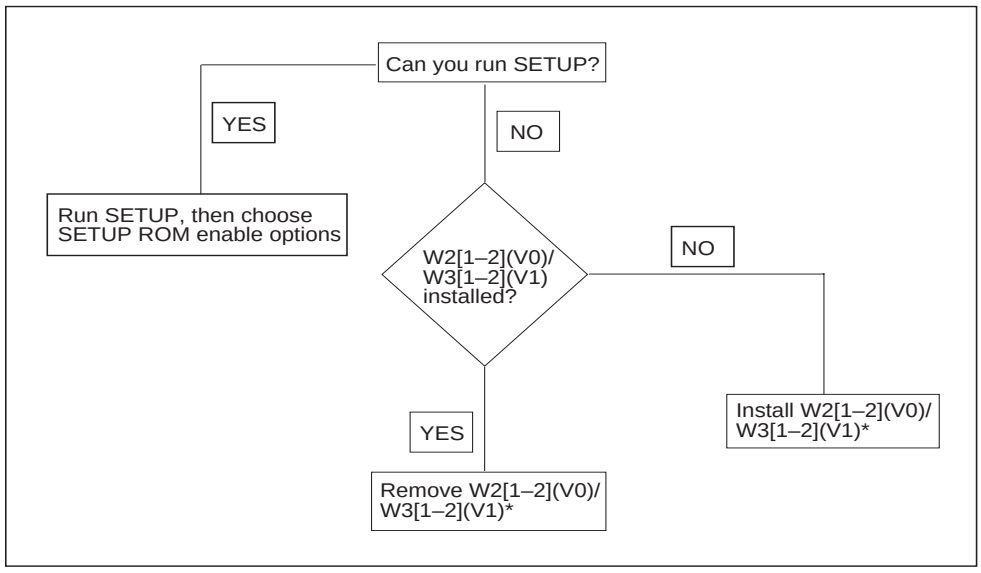
To verify the SETUP program's state for the C0000h-CFFFFh regions, remove the USESETUP W2[9-10] and install W2[1-2] and W3[1-2]. This jumper installation enables the video BIOS areas. To allow for serial console use, disable the video BIOS areas by removing W2[9-10] and W2[1-2]/W3[1-2]. See Table 7-1 and Figure 7-3 as reference guides for disabling and enabling the video BIOS and changing ROM enable.

Table 7-1 Video BIOS disabling and enabling options in SETUP (C0000h-C7FFFh, C8000h-CFFFFh ROM Enable)

Current SETUP state of C0000h-C7FFFh, C8000h-CFFFFh (ROM Enable)	Current jumper state of W2[1-2](V0)/ W3[1-2](V1)	Desired state	SETUP option
Disabled	On	Enabled	Change SETUP to enabled *or* remove W2[1-2](V0)/ W3[1-2](V1)
Disabled	Off	Enabled	Change SETUP to enabled *or* install W2[1-2](V0)/ W3[1-2](V1)
Enabled	On	Disabled	Change SETUP to disabled *or* remove W2[1-2](V0)/ W3[1-2](V1)
Enabled	Off	Disabled	Change SETUP to disabled *or* install W2[1-2](V0)/ W3[1-2](V1)

Note Octagon strongly recommends that you configure both the ROM Enable SETUP option and the jumpers, W2[1-2] and W3[1-2] at the same time.

Figure 7-3 Changing ROM Enable flowchart



*= If the SETUP state is unknown, you may need to change W2[1-2] and W3[1-2] one at a time.

Re-establishing communications when the console is not working

If the ROM Enables SETUP state and jumpers W2[1-2]/W3[1-2] were not configured at the same time, then proceed with Steps A through C:

Step A

1. Remove USESETUP W2[9-10].
2. Install W2[1-2]/W3[1-2].
3. Reboot the system.

If Step A does not work, then follow Step B.

Step B

1. Make sure the BIOS jumper W2[5-6] is on. To use the BIOS in SSD1, install W2[5-6]. To use the BIOS in SSD0, remove W2[5-6].
2. Reboot the system.

If Step B does not work, then follow Step C.

Step C

1. Remove W2[1-2]/W3[1-2].
2. Attach a serial cable to COM1.
3. Run PC SmartLINK at 9600 baud.
4. Boot the system.
5. Program a new video BIOS if needed.
6. Run SETUP and set the ROM Enable SETUP states accordingly.
7. Re-install the USESETUP jumper W2[9-10].

Chapter 8: SSDs, DRAM, and battery backup

≡ Description

Before you can save and boot your application from the PC-510, you must first configure the system for your particular application requirements.

≡ SSD0 (optional)

SSD0 is an optional feature and is not installed on the standard version of the PC-510.

WARNING!

Incorrect installation of SSD0 will destroy the chip. To install SSD0, be sure to match the notch in the SSD0 chip with the notch in the SSD0 marked silkscreen on the PC-510.

A flash, SRAM, or EPROM device may be installed on the PC-510. Jumper blocks W2[7,8] and W5 must be set appropriately. See Table 8-1 for settings.

Selecting SSD0 device type

Table 8-1 SSD0 device selection jumpers: W5, W2[7-8]

Pins	Description
W5[1-3, 2-4, 5-7, 8-10] W2[7-8]	SRAM with battery backup*
W5[1-2, 3-4, 5-6, 9-10] W2[7-8]	Flash
W5[1-2, 3-4, 5-6, 9-10]	EPROM**

* = default, pins jumpered
** = W2[7-8] is not jumpered

≡ SSD0 replaced with an SRAM device

Before replacing SSD0 with an SRAM device, do the following steps:

1. Since SSD0 is to be replaced with an unprogrammed device, the PC-510 must be configured to boot from SSD1. Run SETSSD.EXE to change the boot device:

   ```
   PC510 C:\> SETSSD SSD1 SSD0
   ```

2. Power off the PC-510 and then make sure W2[5-6] is jumpered in order to boot from the BIOS on SSD1.

3. Jumper W5[1-2, 3-4, 5-6, 9-10] and W2[7-8] for a flash device.
4. Install a 512K SRAM into SSD0 at socket U13.
5. Power on the PC-510 and format the flash device. See also the *Managing SSDs* chapter for more information.

Note SRAM contents are sometimes affected by system noise. Therefore, the use of SRAM is not recommended in electrically noisy environments, especially when systems are critical. The SSD0 supports SRAM devices which are available only under OEM contract.

The SSD0 socket also supports flash and EPROM devices. By default, SSD0 reserves 192 KB for the system/video BIOS and 320 KB for a DOS drive. When an SRAM or flash device is used, the DOS drive is read/writeable through PICO FA. After PFORMAT has run, the SETSSD/SSD0BIOS- option allows the DOS drives on SSD0 to be the full size, 512 KB.

WARNING!

Alignment of an SRAM, flash, or EPROM device into SSD0 is critical. Be certain to properly align pin 1 of either the SRAM, flash, or EPROM device with pin 1 of SSD0 on the PC-510.

≡ SSD0 replaced with a flash device

Before replacing SSD0 with a flash device, do the following steps:

1. Power off the PC-510 and then make sure W2[5-6] is jumpered in order to boot from the BIOS on SSD1.
2. Since SSD0 is to be replaced with an unprogrammed device, the PC-510 must be configured to boot from SSD1. Run SETSSD.EXE to change the boot device:

   ```
   PC510 C:\> SETSSD SSD1 SSD0
   ```

3. Power off the PC-510 and install a 512K flash into SSD0 at socket U13. Both W5[1-2, 3-4, 5-6, 9-10] and W2[7-8] must be jumpered for a flash device.

≡ Selecting an SSD BIOS

Each SSD may contain a system BIOS and a video BIOS. To select an SSD BIOS in SSD1, add jumper W2[5-6]. To use SSD0 BIOS, remove jumper W2[5-6]. See Table 8-2 for the proper settings. To program the system BIOS/video BIOS, refer to the *Managing SSDs* chapter.

Table 8-2 Selecting an SSD BIOS: W2[5-6]

State	Result
On	Use SSD1 BIOS
Off	Use SSD0 BIOS

SSD0 replaced with an EPROM/OTPROM

1. Follow steps one through three in the *SSD0 replaced with a flash device* section and use a 512K flash.
2. Power off the PC-510 and remove the flash from socket U13.
3. Use an off-card programmer to program a 512K EPROM/OTPROM. Use the flash as the master copy.
4. Insert the programmed EPROM/OTPROM into socket U13.
5. Remove jumper W2[7-8] for EPROM USE.
6. Power on the PC-510.
7. The new SSD0 device is now ready to be used as a bootable, read-only DOS drive.

≡ SSD1

Generally, SSD1 is meant for storing the application programs to be executed on powerup. The programs are automatically loaded into DOS memory and executed. The standard version of the PC-510 comes with a 2 MB flash soldered on-board, while the optional version contains a 1 MB flash soldered on-board. Your application programs can be saved to flash using the PICO FA driver which makes the flash device a read/write disk on your PC-510. Saving your programs onto the read/write disk allows you to do this up to 100,000 times, allowing updates to your application programs. These devices are erased automatically during the programming process.

SSD1 can be accessed directly as a read/write DOS drive with the PICO FA driver. Also, it can be accessed directly as a read/write DOS drive when the PICOFA.SYS driver is loaded. While this is convenient for product development, the flash, however, has a limited number of writes allowed. Therefore, Octagon does not recommend SSD1 be used as a data logging device. Refer to the *Software utilities* appendix for information on supported flash devices and a description of PICO FA.

≡ DRAM

The standard version of the PC-510 is shipped with 1 MB of DRAM on-card. The PC-510 can also be configured with either 4 or 16 MB of surface mounted DRAM. The on-card DRAM socket holds up to a 16 MB dual in-line memory module (DIMM). The card supports fast page mode (FPM) or extended data out (EDO) types of memory. These

can be symmetric or asymmetric configurations. You may order EDO DIMM memory modules from Octagon Systems. These memory modules, including a 16 MB version, are also available from third party electronic component distributors. See the following for ordering information:

Description	Manufacturer	Manufacturer's P/N
4 MB EDO DIMM memory module	Octagon	4583
	IBM	IBM11S1325LPB-70
	Kinsgton	KTM1X32V-70DEG
	PNY Engineering	321007EDM1G02TB
8 MB EDO DIMM memory module	Octagon	4584
	IBM	IBM11S2325LPB-70
	Kingston	KTM2X32V-70DEG
	PNY Engineering	322007EDM1G04TB
16 MB EDO DIMM memory module	Octagon	4582
	IBM	IBM11S4325LPB-70
	PNY Engineering	324007EDS4G08TL
32 MB EDO DIMM memory module	Octagon	Call Octagon

≡ Battery backup for SSD0 SRAM and real time calendar clock

Located at J18, the AT battery backs up the CMOS real time clock and SSD0 SRAM data.

Installing an AT battery

1. Power off the PC-510.
2. Install the 3.6V AT clock battery at the J18 connector. Refer to the component diagram in the *Quick start* chapter for the location of J18.

Note See the *Accessories* appendix for mating information on the battery connector.

Chapter 9: External drives

≡ Description

The PC-510 is compatible with all common floppy disk drives used on desktop PCs. The PC-510 also drives any standard IDE or EIDE hard drives that have 16-bit IDE interfaces. The BIOS extension ROM for the hard drive is supplied on the card so that no additional software is needed. The floppy drives use DMA channel 2.

≡ Floppy disk controller

The PC-510 can interface directly to one or two 3.5 in. or 5.25 in. floppy drives via the connector at J9.

Note See the *Accessories* appendix for connector information for the floppy disk connector.

Note If you wish to add a second floppy drive to your system, you must use a floppy drive cable which has two connectors.

Power requirements

The PC-510 requires +5V for operation. You must also supply power to the floppy drive(s) through an external source. Refer to your floppy drive manual for specific instructions.

Installing a floppy disk drive

1. Disconnect power to the PC-510.
2. Insert one end of your cable into the rear of the floppy drive. Make sure pin 1 on the cable is connected to pin 1 on the drive.
3. Insert the other end of the cable into J9 on the PC-510.
4. Connect power to the floppy drive.
5. Run SETUP in the \UTILS subdirectory to setup the AT BIOS. You can execute this program either by pressing <BACKSPACE><S> during system bootup or by executing the file SETUP.EXE. This file is found on the PC-510 BIOS drive and also on the PC-510 utility disk. The system steps you through the configuration. Also, refer to the *SETUP programs* chapter for more information on the AT BIOS SETUP program.

Note If floppy is twisted on the connector, then answer "no" to Swap Floppy A and B.

≡ Hard disk controller

The PC-510 will drive up to 4 GB hard drives that have 16-bit IDE interfaces via a 44-pin connector at J10.

Note See the *Accessories* appendix for connector information for the IDE hard drive connector.

Installing a hard drive

1. Disconnect power to the PC-510.
2. Insert one end of the Octagon hard drive adapter cable into the rear of the hard drive. Make sure pin 1 on the cable is connected to pin 1 on the hard drive port.
3. Insert the other end of the IDE cable into J10 on the PC-510. Make sure pin 1 on the cable is connected to pin 1 on the PC-510.
4. Execute the BIOS SETUP program to configure your system for a hard drive. You can execute this program either by pressing <BACK-SPACE><S> during system bootup or by executing the file SETUP.EXE. This file is found on the PC-510 BIOS drive and the PC-510 utility disk. The system steps you through the configuration. Also, refer to the *SETUP programs* chapter for more information on the BIOS SETUP program.
5. If you want to boot the system from the hard drive, you need to format the drive accordingly.

≡ Booting with ROM-DOS

If you want to boot from a floppy/hard drive with ROM-DOS, do the following steps:

1. Boot from the PC-510 utility disk.
2. Execute the following command:

   SYS C:

3. The system copies COMMAND.COM as well as a hidden file to the hard drive.

Chapter 10: IRQ routing and opto IRQs

≡ Interrupt routing

The PC-510 provides a flexible method of enabling, disabling, and routing system interrupts via an "in system" programmable logic device. The logic device not only reduces the number of physical jumpers, but it also reduces the possibility of choosing the incorrect jumper configuration. For example, upon configuration the electronic jumpers remain set until they are reprogrammed for a different configuration.

This device also allows some of the PC/104 bus interrupts and some of the on-board generated interrupts to be routed to other IRQs of the programmable interrupt controller. This routing matrix requires the user to run the SETIRQ utility program to update the routing matrix with the desired IRQ routes.

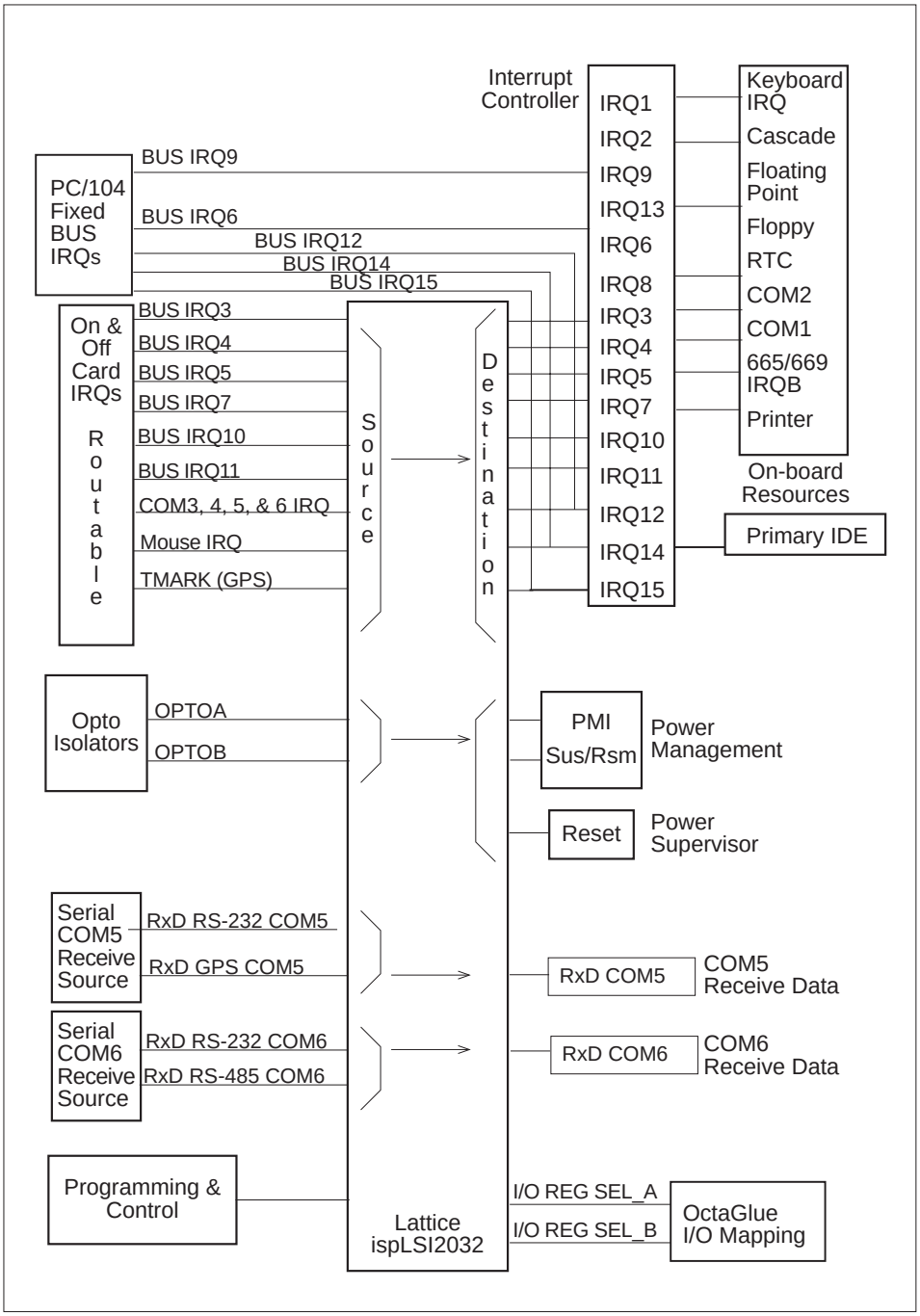
In addition to IRQ routing, the I/O range select A and select B bits can be set so that the base addresses in COM5 and COM6, EZ I/O 1 and EZ I/O 2, and COM3 through COM6 IRQ status registers can be moved to different locations. These can also be read at I/O address 0A9h bits 4 and 5.

See also the SETIRQ.DOC file in the \IRQ directory on the PC-510 utility disk for more information. The utility disk contains several ISP files to program into the matrix. If these are not sufficient, call Octagon's Technical Support at 303-426-4521 for new ISP files that may have become available.

Note If an output is not routed as a signal, then the output or destination is neither driven high nor low, but is in a high impedance mode.

Note When you program a new IRQ routing matrix, the printer port must be set to bi-directional mode. Also, any field devices connected to the printer port must be disconnected.

Figure 10-1 Interrupt routing matrix



≡ Opto IRQs

OPTOA and OPTOB are the two optically isolated channels and are accessible at J17. These channels are configurable to drive either the SUSPEND/RESUME or the PMI signal. Also, either OPTOA or OPTOB can be routed through the interrupt routing matrix to generate a system reset. The opto-isolation allows the input source to extend as far as 50 feet from the card. A +5V signal activates the SUSPEND/RESUME, PMI or system reset signal. Noise filtering is built-in and the isolation from the system ground is 500V. A voltage greater than 3.1V at 5.0 mA guarantees a SUSPEND/RESUME or a PMI interrupt or a system reset.

When signaling for SUSPEND/RESUME, PMI, or system reset, the voltage is applied in a pulse period greater than 50 µS. The interrupt matrix chip requires that the input voltage remains stable until the interrupt is acknowledged. At that time, the interrupt source can be rearmed by returning the input to 0 volts.

Note See the *Accessories* appendix for mating information on the OPTOA and OPTOB connectors.

The interrupt routing matrix provides flexibility to the interrupt structure which allows connection between the lower-ordered ISA interrupts and the unused higher-ordered interrupts. Caution must be used when configuring the jumper options.

Note Bus IRQ6 can be inadvertently routed to two interrupts. This is not an acceptable configuration. The application software must also be aware of the interrupt that is set for the particular resource.

≡ Interrupt routing matrix defaults

The 510_001.ISP file lists the interrupt routing matrix defaults. See the SETIRQ.DOC file on the PC-510 utility disk for more information.

≡ Programming

SETIRQ 510_001.ISP

See the \IRQ\SETIRQ.DOC directory on the PC-510 utility disk for additional PC-510 ISP files and their functional descriptions in the SETIRQ.DOC file.

≡ Master disable

When W3[9-10] is jumpered, the outputs from the interrupt matrix chip are tri-stated (high). The chip does not program when this jumper is installed.

Both I/O range select A and I/O range select B can be adjusted via the ISP and SETIRQ files. The I/O range select changes the EZ I/O, COM5 and COM6 base addresses. See SETIRQ.DOC for more information.

The IORG SEL A (I/O register select A) and IORG SEL B (I/O register select B) select the base address for serial ports 5 and 6, as well as for

the EZ I/O and the interrupt status register.

Table 10-1 Interrupt status port (ISP) map setting at I/O location 0A9h

I/O range select A (bit 5)	**I/O range select B (bit 4)**	**COM5**	**COM6**	**EZ I/O 1**	**EZ I/O 2**	**Interrupt status register**
0	1	120-127h	128-12F	134-137h	130-133h	138-13F
0	0	140-147h	148-14F	154-157h	150-153h	158-15F
1	0	340-347h	348-34F	354-357h	350-353h	358-35F
1	1	320-327h*	328-32F*	334-337h*	330-333h*	338-33F*

* = default settings

Chapter 11: *EZ I/O*

≡ Description

Octagon EZ I/O digital I/O lines can be used to sense switch closures, turn on lamps and LEDs, and interface with other devices that have TTL input or output such as printers and scales. The EZ I/O drives the Octagon MPB series opto-isolation module racks directly, controlling AC and DC loads to 240V at 3A. Figure 11-1 shows typical EZ I/O configurations. The EZ I/O ports have the following specifications:

- Each EZ I/O chip has 24 I/O lines, grouped into 3 ports of 8 bits
- 48 I/O lines available
- Each bit is programmable as either 5V input or 5V output
- Read back state of each pin
- Easy-to-program
- Each line can sink and source 15 mA

Figure 11-1 Typical EZ I/O configurations

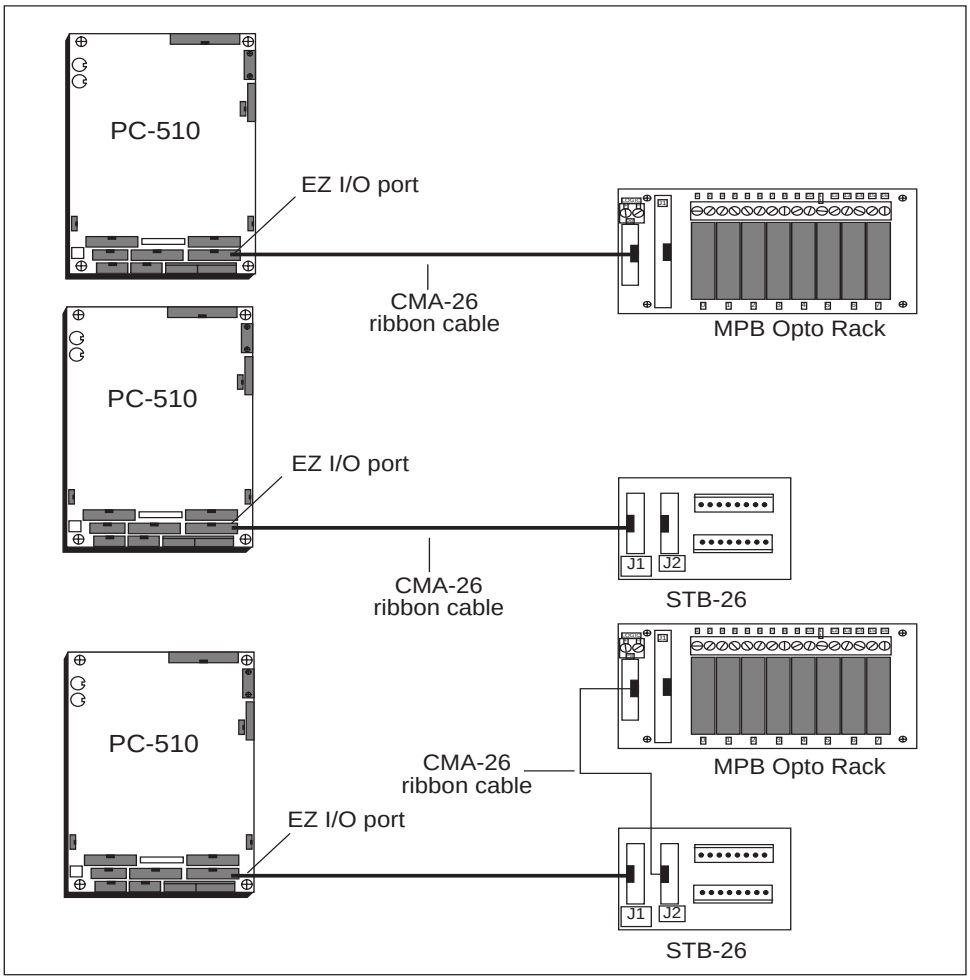


Table 11-1 EZ I/O connectors: J15, J16

Pin	Function	Pin	Function	Pin	Function
	Port A		**Port B**		**Port C**
19	bit 0	10	bit 0	13	bit 0
21	bit 1	8	bit 1	16	bit 1
23	bit 2	4	bit 2	15	bit 2
25	bit 3	6	bit 3	17	bit 3
24	bit 4	1	bit 4	14	bit 4
22	bit 5	3	bit 5	11	bit 5
20	bit 6	5	bit 6	12	bit 6
18	bit 7	7	bit 7	9	bit 7
				2	+5V safe
				26	Gnd

≡ EZ I/O options

The PC-510 standard version is supplied with two Octagon EZ I/O digital I/O chips for a total of 48 I/O lines. Under OEM contract, the EZ I/O ports can be eliminated or only one port can be installed for 24 I/O lines.

Table 11-2 EZ I/O port options

	Standard feature	Option 1	Option 2
EZI/O 1	Installed	Installed	Not installed
EZI/O 2	Installed	Not installed	Not installed
Total I/O lines	48	24	0

Note See the *Accessories* appendix for connector information for the EZ I/O 1 and EZ I/O 2 connectors.

≡ Pulling the I/O lines high or low

Jumper block W4 pulls the I/O lines at ports A, B, and C high or low. This allows a known state upon powerup. The default configuration pulls all of the I/O lines high. Note that 10K ohm resistor networks are used to configure the I/O lines as high or low.

Table 11-3 EZ I/O pull-up/pull-down jumpers: W4

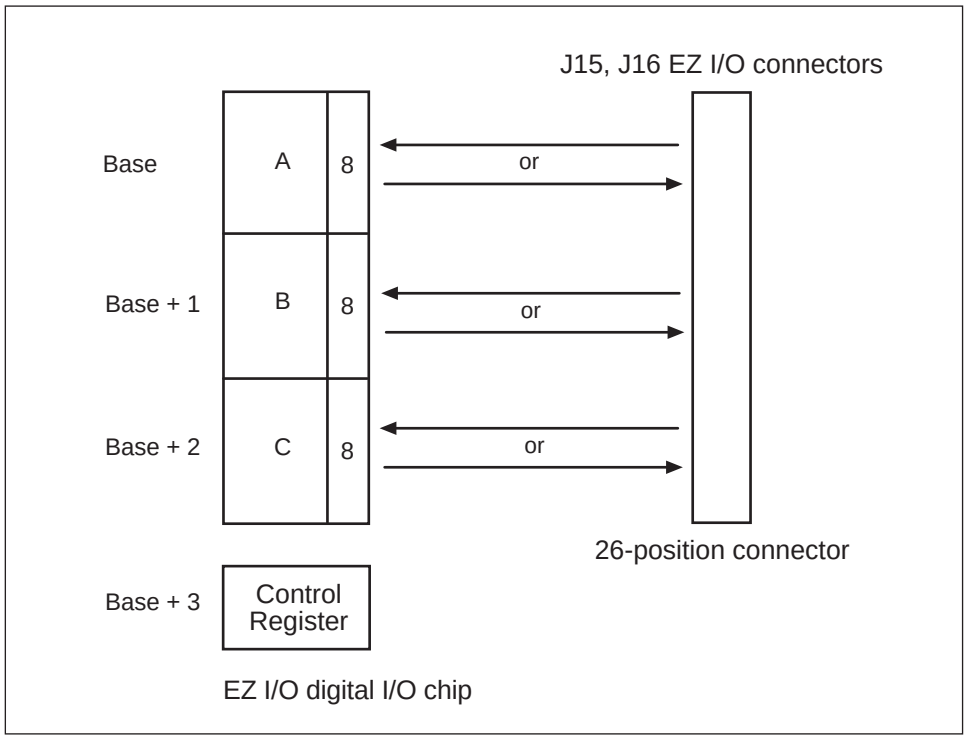
Pins	Label	Description
[1–2]*		EZ I/O 1 pull up to +5V
[2–4]		EZ I/O 1 pull down to Gnd
[5–6]*		EZ I/O 2 pull up to +5V
[6–8]		EZ I/O 2 pull down to Gnd
[9–10]*	U	User option jumper 1

* = default, pins jumpered

≡ Organization of ports

Each EZ I/O digital port has a total of 24 I/O lines connected to a 26-pin header. The lines are configured into three groups: ports A, B and C, each group consisting of 8 bits. Any of the lines at ports A, B or C can be configured individually as inputs or outputs.

Figure 11-2 Organization of ports



Port addressing

Ports A, B, C and the control register are addressable.

Table 11-4 EZ I/O port address

Port	I/O address
A	Base address
B	Base address + 1
C	Base address + 2
Control register	Base address + 3

Base I/O address

The base I/O address for EZ I/O 1 is 334h (default) and the base I/O address for EZ I/O 2 is 330h (default) but can be changed through OctaGlue PCS_2 to one of four addresses. Refer to the *Interrupt routing* section in the *IRQ routing and opto IRQs* chapter to change the base address of the EZ I/O chip.

Based on the I/O range select A and B, you can determine the port addresses for EZ I/O 1 and EZ I/O 2 by reading 0A9h bit 4 and 0A9h bit 5. Refer to Table 11-5.

Table 11-5 Reading EZ I/O 1 and EZ I/O 2 port addresses at I/O location 0A9h

I/O range select A (bit 5)	I/O range select B (bit 4)	EZ I/O 2 base address	EZ I/O 1 base address
0	1	130-133h	134-138
0	0	150-153h	154-158
1	0	350-353h	354-358
1	1	330-333h*	334-338*

* = default settings

≡ Configuring and programming the EZ I/O ports

J15 and J16, the digital I/O connectors, each have an Octagon EZ I/O digital chip associated with them. The EZ I/O chip has three ports with eight parallel I/O lines (bits) per port. This port can use one of four base I/O addresses. All lines can be individually programmed as all inputs, all outputs or individually as inputs or outputs. You can alter which bits are inputs or outputs by writing a control command to the control register of the EZ I/O. When a line is configured as an output, it can sink a maximum of 15 mA at 0.4V or can source 15 mA at 2.4V. On powerup and software or hardware reset, all digital I/O lines at J15 and J16 are reset as inputs.

Programming the EZ I/O

Follow these steps to program the EZ I/O chip:

1. Configure the EZ I/O port bit directions, either as inputs or outputs.
2. Write to port A, B, or C with the desired level or read the bit level from the desired port.

Configuring the EZ I/O

Follow these steps to configure the EZ I/O chip

1. Write a "3" to the control register (base address + 3). This places the I/O chip in "direction" mode:

   (default base address = 330h)

   ```
   OUT 333h, 2  (control register, direction mode)
   ```

2. Set the direction of each bit. A "0" written to the corresponding line indicates an input and a "1" bit indicates an output. Each bit corresponds to the equivalent I/O line.

Table 11-6 EZ I/O port byte

bit 7	bit 6	bit 5	bit 4	bit 3	bit 2	bit 1	bit 0	EZ I/O port I/O line
x								7
	x							6
		x						5
			x					4
				x				3
					x			2
						x		1
							x	0

For example, writing 00011100 to port C (base address + 2) will configure port C I/O lines 0, 1, 5, 6, and 7 to be inputs and lines 2, 3, and 4 to be outputs:

```
OUT 332h, 1Ch (00011100 binary = 1C hexadecimal)
```

3. Write a "3" to the control register (base register + 3). This places the I/O chip back into "operation" mode:

   ```
   OUT 333h, 3    (control register)
   ```

Writing and reading from EZ I/O

Writing to or reading from the desired EZ I/O port is accomplished with single program statements:

1. To write a bit pattern to the desired EZ I/O port:

   ```
   OUT 332h, FFh
   ```

   All bits of port C go high; all input bits are unaffected.

2. To read a bit pattern from the desired EZ I/O port:

   ```
   PORTC = INP(332h)
   ```

   The byte read from port C is assigned to variable port C.

EZ I/O output program examples

To configure ports A, B, and C as all outputs, issue the commands:

```
OUT 333h, 2    'Direction' Mode
OUT 330h, FFh  'PortA'
OUT 331h, FFh  'PortB'
OUT 332h, FFh  'PortC'
OUT 333h, 3    'Operation' Mode
```

Note With CAMBASIC, Octagon's multitasking industrial language, you can also accomplish the same configuration and outputs with one statement. Enter:

```
CONFIG EZ I/O &330, &0, &FF, &0, &FF, &0, &FF
```

Ports A, B, and C will now output all "1"s after issuing the following commands:

```
OUT 330h, FFh (portA)
OUT 331h, FFh (portB)
OUT 332h, FFh (portC)
```

or all "0"s after:

```
OUT 330h, 0 (portA)
OUT 331h, 0 (portB)
OUT 332h, 0 (portC)
```

EZ I/O input program examples

To configure ports A and C as inputs and port B as outputs, issue the following commands:

```
OUT 333h, 2    'Direction Mode'
OUT 330h, 0
OUT 331h, FF
OUT 332h, 0
OUT 333h, 3    'Operation Mode'
```

To read ports A and C, issue the following commands:

```
PORTA = INP(330h)   (port A)
PORTC = INP(333h)   (port B)
```

≡ Enhanced INT 17h function definitions

This section provides definitions for the following functions: Initialize EZ I/O 1, Write EZ I/O 1, Read EZ I/O 1, Initialize EZ I/O 2, Write EZ I/O 2, and Read EZ I/O 2.

Initialize EZ I/O 1

Function: efh

Subfunction: 00h

Purpose: To set the directions and to program the initial values of an EZ I/O port.

Calling registers:

Ah	efh			
AL	00h			
	DI	Port A configuration		
		xxxxxxxx	xxxxxxxxB	
		xxxxxxx		Initial data for port A
			xxxxxxxxB	direction; 1->output, 0->input
	BX	Port B configuration		
		xxxxxxxx	xxxxxxxxB	
		xxxxxxxx		Initial data for port B
			xxxxxxxxB	direction; 1->output, 0->input
	CX	Port C configuration		
		xxxxxxxx	xxxxxxxxB	
		xxxxxxxx		Initial data for port C
			xxxxxxxxB	direction; 1->output, 0->input
	DX	ffffh		

Return registers: Carry flag cleared if successful
Carry flag set if error
AL Error code

Comments: This function is used to initialize the first EZ I/O (i.e., the EZ I/O that has the higher I/O address when two EZ I/O chips are present on a board) before normal use.

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
     mov   ax,0ef00h
     mov   di,00ffh   /*port A all outputs, init data=all 0's */
     mov   bx,55ffh   /*port B all outputs, init data=55h*/
     mov   cx,0000h   /*port C all inputs*
     mov   dx,0ffffh
     int   17h
      }
```

Write EZ I/O 1

Function: efh

Subfunction: 01h

Purpose: To write a value of an EZ I/O port.

Calling registers:

AH efh
AL 01h
DI Port A mask and data
xxxxxxxx xxxxxxxxB
xxxxxxxx Mask for port A; 1->bit to be changed
xxxxxxxxB Data for port A
BX Port B mask and data
xxxxxxxx xxxxxxxxB
xxxxxxxx Mask for port B; 1->bit to be changed
xxxxxxxxB Data for port B
CX Port C mask and data
xxxxxxxx xxxxxxxxB
xxxxxxxx Mask for port C; 1->bit to be changed
xxxxxxxxB Data for port C
DX ffffh

Return registers: Carry flag cleared if successful
Carry flag set if error
AL Error code

Comments: This function is used to initialize the first EZ I/O (i.e., the EZ I/O that has the higher I/O address when two EZ I/O chips are present on a board).

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
    mov   ax,0ef01h
    mov   di,00ffh   /*port A: no change */
    mov   bx,8000h   /*port B: bit 7=0, other bits unchanged*/
    mov   cx,0202h   /*port C: bit 1=1, other bits unchanged*
    mov   dx,0ffffh
    int   17h
     }
```

Read EZ I/O 1

Function: efh

Subfunction: 02h

Purpose: To read from an EZ I/O port.

Calling registers:

AH efh

AL 02h
xxxxxxxx Data for port C
DX ffffh

Return registers: Carry flag cleared if successful
AL Port A data
Ah Port B data
BL Port C data
Carry flag set if error
AL Error code

Comments: This function is used to read from the first EZ I/O (i.e., the EZ I/O that has the higher I/O address when two EZ I/O chips are present on a board).

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
unsigned char aData, bData, cData;
asm {
    mov   ax,0ef02h
    mov   dx,0ffffh
    int   17h
    mov    aData,al
    mov    bData,ah
    mov    cData,bl
     }
```

Initialize EZ I/O 2

Function: efh

Subfunction: 03h

Purpose: To set the directions and to program the initial values of an EZ I/O port.

Calling registers:

AH efh
AL 00h
DI Port A configuration
xxxxxxxx xxxxxxxxB
xxxxxxxx Initial data for port A
xxxxxxxxB direction; 1->output, 0->input
BX Port B configuration
xxxxxxxx xxxxxxxxB
xxxxxxxx Initial data for port B
xxxxxxxxB direction; 1->output, 0->input
CX Port C configuration
xxxxxxxx xxxxxxxxB
xxxxxxxx Initial data for port C
xxxxxxxxB direction; 1->output, 0->input
DX ffffh

Return registers: Carry flag cleared if successful
Carry flag set if error
AL Error code

Comments: This function is used to initialize the second EZ I/O (i.e., the EZ I/O that has the lower I/O address when two EZ I/O chips are present on a board) before normal use.

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
     mov   ax,0ef03h
     mov   di,00ffh   /*port A all outputs, init data=all 0's */
     mov   bx,55ffh   /*port B all outputs, init data=55h*/
     mov   cx,0000h   /*port C all inputs*
     mov   dx,0ffffh
     int   17h
      }
```

Write EZ I/O 2

Function: efh

Subfunction: 04h

Purpose: To write a value to an EZ I/O port.

Calling registers:

AH efh
AL 04h
DI Port A mask and data
xxxxxxxx xxxxxxxxB
xxxxxxxx Mask for port A; 1->bit to be changed
xxxxxxxxB Data for port A
BX Port B mask and data
xxxxxxxx xxxxxxxxB
xxxxxxxx Mask for port B; 1->bit to be changed
xxxxxxxxB Data for port B
CX Port C mask and data
xxxxxxxx xxxxxxxxB
xxxxxxxx Mask for port C; 1->bit to be changed
xxxxxxxxB Data for port C
DX ffffh

Return registers: Carry flag cleared if successful
Carry flag set if error
AL Error code

Comments: This function is used to write to the second EZ I/O (i.e., the EZ I/O that has the lower I/O address when two EZ I/O chips are present on a board).

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
```

```
    mov   ax,0ef04h
    mov   di,00ffh   /*port A: no change */
    mov   bx,8000h    /*port B: bit 7=0, other bits unchanged*/
    mov   cx,0202h    /*port C: bit 1=1, other bits unchanged*
    mov   dx,0ffffh
    int   17h
     }
```

Read EZ I/O 2

Function: efh

Subfunction: 05h

Purpose: To read from an EZ I/O port.

Calling registers:

AH	efh	
AL	05h	
	xxxxxxxx	Data for port C
DX	ffffh	

Return registers: Carry flag cleared if successful
AL Port A data
AH Port B data
BL Port C data
Carry flag set if error
AL Error code

Comments: This function is used to read from the second EZ I/O (i.e.,the EZ I/O that has the lower I/O address when two EZ I/O chips are present on a board).

Programming Example:

```
/* Inline assembly code for Borland C++ 3.1 */
unsigned char aData, bData, cData;
asm {
    mov   ax,0ef05h
    mov   dx,0ffffh
    int   17h
    mov   aData,al
    mov   bData,ah
    mov   cData,bl
     }
```

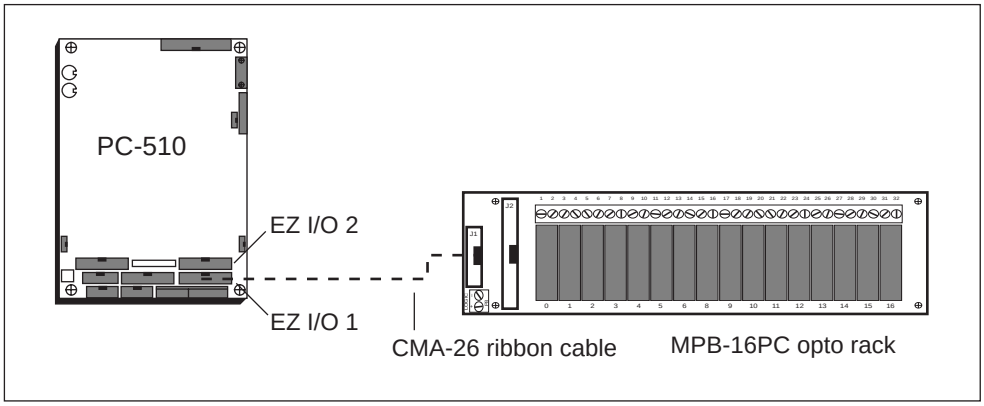
≡ Opto-module rack interface

You can interface digital I/O lines to an 8-, 16-, or 24-position opto-module rack. One end of the CMA-26 cable plugs into the EZ I/O connector and the other plugs into an MPB-8, MPB-16, or an MPB-24 opto rack. Refer to the *MPB opto racks data sheet* for more information.

You can also use a CMA-26 cable to connect the EZ I/O port to an STB-26 terminal board and then to the opto rack. The STB-26 has two 26-pin connectors, one of which would connect to the EZ I/O port, the other would connect to the opto rack. Refer to the opto rack diagrams below.

For either configuration, run a separate power line to +5V and ground on the opto-rack.

Figure 11-3 MPB-16PC opto rack hookup



Use the following table to determine the corresponding opto-channel position for ports A, B, and C for EZ I/O 1 (J15) and EZ I/O 2 (J16).

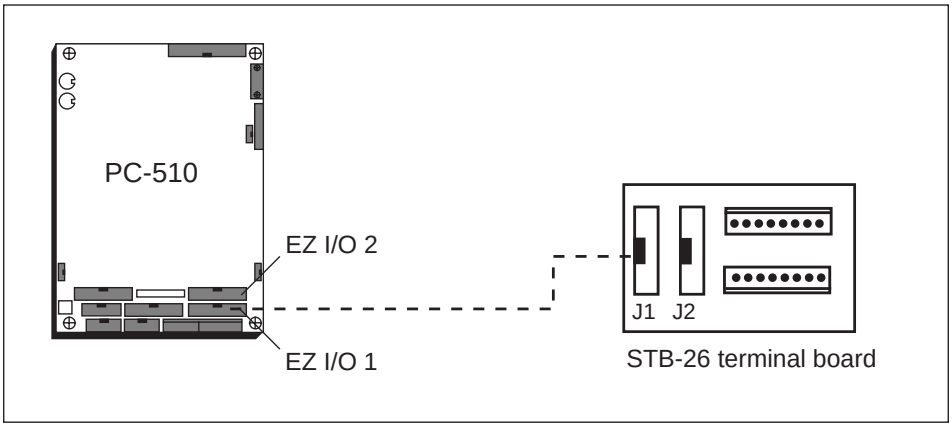
Table 11-7 EZ I/O opto-rack interface

MPB opto rack	EZ I/O port	Connector pin
Opto-module position	**Port C**	
0	bit 0	13
1	bit 1	16
2	bit 2	15
3 **MPB-08**	bit 3	17
4	bit 4	14
5	bit 5	11
6	bit 6	12
7	bit 7	9
Opto-module position	**Port A**	
8	bit 0	19
9	bit 1	21
10	bit 2	23
11 **MPB-16**	bit 3	25
12	bit 4	24
13	bit 5	22
14	bit 6	20
15	bit 7	18
Opto-module position	**Port B**	
16	bit 0	10
17	bit 1	8
18	bit 2	4
19 **MPB-24**	bit 3	6
20	bit 4	1
21	bit 5	3
22	bit 6	5
23	bit 7	7

≡ Interfacing to switches and other devices

The STB-26 terminal board provides a convenient way of interfacing switches or other digital I/O devices to the EZ I/O digital port. I/O lines at the EZ I/O connector can be connected to an STB-26 with a CMA-26 cable. Parallel I/O devices are then connected to the screw terminals on the STB-26. Refer to the *STB-26 product sheet* for more information.

Figure 11-4 PC-510 interfacing with an STB-26 terminal board



Chapter 12: LED signaling and "beep" codes

≡ Description

The PC-510 has a bicolor LED that is used by the BIOS to signal system status.

Immediately after the PC-510 powers on, both LEDs are lit and display an orange color. Upon completion of the boot sequence, the amber LED turns off and the green LED remains on.

If a failure occurs during the boot sequence, visual beep codes are displayed to the LEDs. The visual beep codes are defined in the following table. Also, if a speaker is installed at J1, the beep codes are audible.

The bicolor LED also indicates memory suspend status. Upon entering memory suspension, the green LED turns off and the amber LED turns on. On a resume condition, the amber LED turns off and the green LED turns on.

When the system enters the cool down clocking state, the green LED and the amber LED turn on. When the system exits the cool down clocking state, the amber LED turns off and the green LED remains on.

Table 12-1 Phoenix BIOS beep codes

Diagnostic port output	Beep codes	Description of test or failure
01h		80286 register test in-progress
02h	1-1-3	CMOS write/read test in-progress
03h	1-1-4	BIOS ROM checksum in-progress
04h	1-2-1	Programmable interval timer test in-progress or failure
05h	1-2-2	DMA initialization in-progress or failure
06h	1-2-3	DMA page register write/read test in-progress or failure
08h	1-3-1	RAM refresh verification in-progress or failure
09h		1st 64K RAM test in-progress
0Ah	1-3-3	1st 64K RAM chip or data line failure multi-bit
0Bh	1-3-4	1st 64K RAM odd/even logic failure
0Ch	1-4-1	1st 64K RAM address line failure
0Dh	1-4-2	1st 64K RAM parity test in-progress or failure
10h	2-1-1	1st 64K RAM chip or data line failure-bit 0
11h	2-1-2	1st 64K RAM chip or data line failure-bit 1
12h	2-1-3	1st 64K RAM chip or data line failure-bit 2
13h	2-1-4	1st 64K RAM chip or data line failure-bit 3
14h	2-2-1	1st 64K RAM chip or data line failure-bit 4
15h	2-2-2	1st 64K RAM chip or data line failure-bit 5
16h	2-2-3	1st 64K RAM chip or data line failure-bit 6
17h	2-2-4	1st 64K RAM chip or data line failure-bit 7
18h	2-3-1	1st 64K RAM chip or data line failure-bit 8
19h	2-3-2	1st 64K RAM chip or data line failure-bit 9
1Ah	2-3-3	1st 64K RAM chip or data line failure-bit A
1Bh	2-3-4	1st 64K RAM chip or data line failure-bit B
1Ch	2-4-1	1st 64K RAM chip or data line failure-bit C
1Dh	2-4-2	1st 64K RAM chip or data line failure-bit D
1Eh	2-4-3	1st 64K RAM chip or data line failure-bit E
1Fh	2-4-4	1st 64K RAM chip or data line failure-bit F

Table 12-1 Phoenix BIOS beep codes (cont'd)

Diagnostic port output	Beep codes	Description of test or failure
20h	3-1-1	Slave DMA register test in-progress or failure
21h	3-1-2	Master DMA register test in-progress or failure
22h	3-1-3	Master interrupt mask reg. test in-progress or failure
23h	3-1-4	Slave interrupt mask reg. test in-progress or failure
25h	N/A	Interrupt vector loading in-progress
27h	3-2-4	Keyboard controller test in-progress or failure
28h	N/A	CMOS power-fail and checksum checks in-progress
29h	N/A	CMOS config info. validation in-progress
2Bh	3-3-4	Screen memory test in-progress or failure
2Ch	3-4-1	Screen initialization in-progress or failure
2Dh	3-4-2	Screen retrace tests in-progress or failure
2Eh	N/A	Search for video ROM in-progress
30h	N/A	Screen believed operable:
30h	N/A	Screen believed running w/video ROM
31h	N/A	Monochromatic screen believed operable
32h	N/A	40-column color screen believed operable
33h	N/A	80-column color screen believed operable
34h	4-2-1	Timer tick interrupt test in-progress or failure
35h	4-2-2	Shutdown test in-progress or failure
36h	4-2-3	Gate A20 failure
37h	4-2-4	Unexpected interrupt in protected mode
38h	4-3-1	RAM test in-progress or failure above address 0FFFFh
3Ah	4-3-3	Interval timer channel 2 test in-progress or failure
3Bh	4-3-4	Time-of-day clock test in-progress or failure
3Ch	4-4-1	Serial port test in-progress or failure
3Dh	4-4-2	Parallel port test in-progress or failure
3Eh	4-4-3	Math coprocessor test in-progress or failure
50h	N/A	Beginning of CSET_INIT
51h	N/A	Loading the RCM table
52h	N/A	Loading the FCM table, doing DMC
53h	N/A	Entering CSET_BFR_VIDROM (before video ROM)
54h	N/A	Entering CSET_BFR_SIZMEM (before memory sizing)
55h	N/A	Entering CSET_AFT_MTEST (after memory test)
56h	N/A	Entering CSET_AFT_CMCFG (after CMOS configuration check)
57h	N/A	Entering CSET_BFR_OPROM (before option ROM scan)

Table 12-2 Additional error codes for Phoenix BIOS

Diagnostic port output	Beep codes	Description of test or failure
C0h	N/A	Entry to power management initialization
C1h	N/A	Return from power management initialization
C2h	N/A	Entry to cache initialization
C3h	N/A	Return from cache initialization
D7h	N/A	Using defaults from ROM
D9h	N/A	Using EEPROM values
DFh	N/A	Exit CMOS initialization
E0h	N/A	Reset
E1h	N/A	BIOS determined it is an actual reset
E7h	N/A	Going to CMOS initialization
E8h	N/A	Returned from CMOS initialization
E9h	N/A	Entry to chipset initialization
EAh	N/A	Exit from chipset initialization
F0h	N/A	Loading chipset from EEPROM or defaults
F1h	N/A	Completed chipset load
F3h	N/A	Loading mvb specific values
F4h	N/A	Completed mvb load
F9h	N/A	Starting memory autosizing
FAh	N/A	Completed memory autosizing

Chapter 13: CRTs and flat panels

≡ Description

The PC-510 supports a variety of high-performance flat panels and SVGA CRT monitors. The video section has 2 MB of video DRAM for high resolution displays and simultaneous CRT and flat panel operation. The video controller circuit operates on the local bus at full processor speed allowing for faster execution of programs such as Windows. Standard VGA monitors with analog inputs are connected using a VGA-12 cable connected to J20. Flat panel displays are connected using a 50-pin connector at J14. Refer to the VGA 65550 utility disk for additional information on flat panel displays.

≡ Video features

Below is a list of standard video features installed on the PC-510:

- High performance Chips & Technologies VGA 65550 video controller
- 2 MB DRAM for display buffering
- CRT support with resolutions to 1024 x 768 at 75 Hz
- Flat panel support with resolutions the following resolutions:
  - — 640 x 480 x 24 bpp
  - — 800 x 600 x 24 bpp
  - — 1024 x 768 x 16 bpp
- Support for plasma, EL and LCD displays
  - — 3V and 5V flat panel support (jumper selectable)
  - — Flat panel power sequencing
  - — Software adjustable positive bias voltage supply for passive LCD panels (negative bias voltage supply is optional)
- PC-video interface for full motion video overlay
- Local bus interface for fast execution
- 120MHz/133MHz option for enhanced temperature performance

≡ Video options

The standard version PC-510 has all of the above video features installed. Under OEM contract, the user has the option to eliminate all or specific portions of the video section. The following table lists video features that the end-user can consider as either standard or optional.

Table 13-1 Video controller and associated CRT, flat panel, and PC video circuitry

Standard features	Optional features
Installed	No video circuitry installed
Installed	CRT circuitry not installed
Installed	Flat panel circuitry not installed
Installed	PC-video interface not installed
Installed	Positive display bias supply not installed (+21 to +29 VDC)*
Not installed	Negative display bias supply (–21 to –29 VDC)*

* = Other bias voltage ranges are factory optional.

≡ Programming the video BIOS

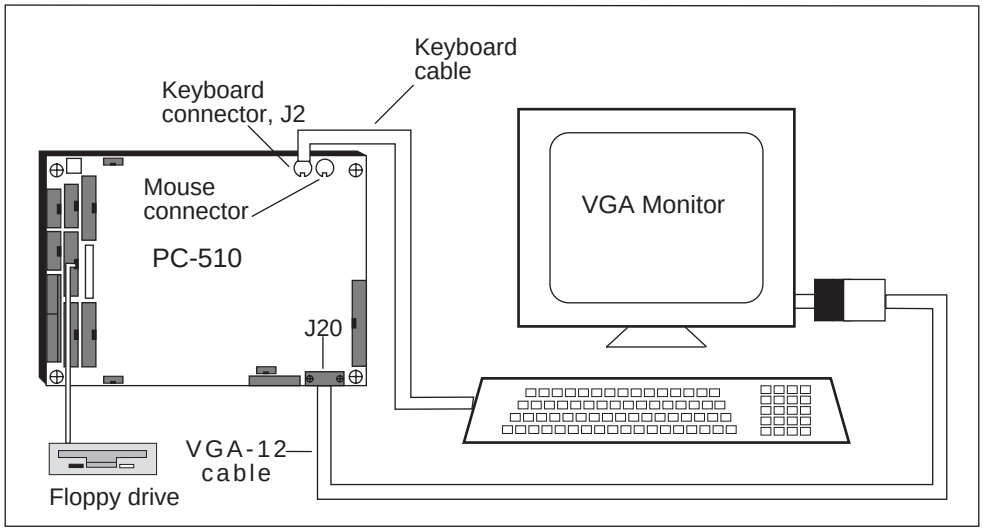
The PC-510 is factory configured and programmed for a VGA analog monitor. If you wish to use a flat panel display, you must reprogram the video BIOS for the appropriate display.

If you are using a standard VGA and have not previously reprogrammed the video BIOS, skip to the section *Connecting the monitor/display*.

1. Attach a standard VGA monitor, an AT/PS/2 compatible keyboard, and a floppy drive to the PC-510.
2. Refer to Figure 13-1 for the correct cables and locations of the keyboard, VGA monitor, and floppy drive connectors.

Note If monitor and keyboard are not available, connect the PC-510 to your PC by using a remote serial console. Refer to the *Serial Console* section in the *Console devices* chapter.

Figure 13-1 The PC-510, a VGA monitor, and an AT/PS/2 compatible keyboard



3. Power on the PC-510.

Note If you are using a flat panel display, refer to the README.DOC file on the VGA 65550 utility disk for a list of the supported displays. If your particular display is not currently listed, please contact Octagon Technical Support (303-426-4521) for assistance.

4. Install the 65550 utility disk in the floppy drive. If a floppy drive is unavailable, then download the PGMVIDEO.EXE and *.DAT files for the flat panel display (e.g., S64P80*.DAT) from your PC to the PC-510.

Note To download files to the PC-510, refer to the *Transferring files/remote disks* chapter.

5. To program the PC-510 for the appropriate monitor/display, type the following:

   <drive>:PGMVIDEO <drive>:<*filename*> SSD1 /P

Note The above command programs the video BIOS in SSD1. To program the video BIOS in SSD0, enter the following command:

<drive>:PGMVIDEO <drive>:<*filename*> SSD0 /P

The <drive> designator includes the drive and path where files are located.

6. A message similar to the following should appear on your display:

```
PGMVIDEO v1.00
Octagon Systems (c) Copyright 1996
This utility programs a new video BIOS into an SSD.
Programming the SSD1 video BIOS from the file
s64p80.dat.
Video BIOS source file checksum = ea00h
```

```
Erasing the video BIOS area of SSD1.
Erase complete.

Programming the flash.
. . .
Change the BIOSDEV jumpers to use this new BIOS.
You must perform a hard reset to use this new BIOS.
```

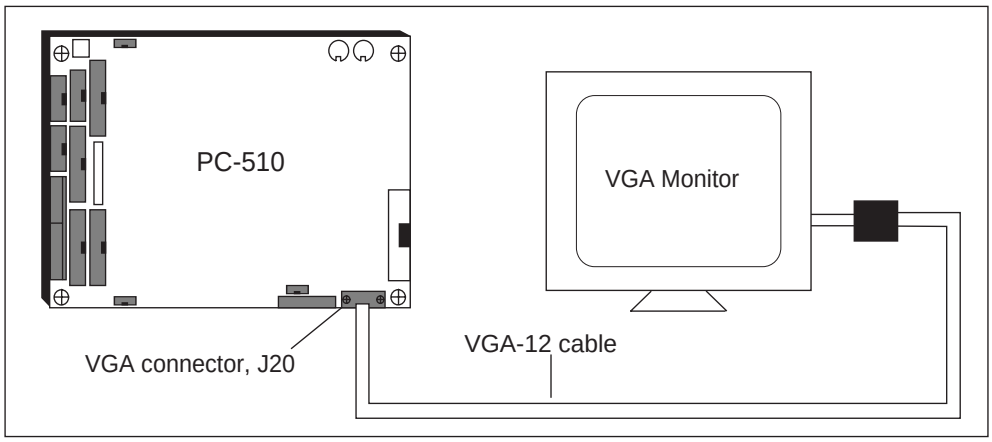
7. Power off the PC-510 and attach the appropriate flat panel display. To build the correct cable for your flat panel, refer to the wiring diagram text file specific to your flat panel on the 65550 utility disk.

≡ Connecting the monitor/display

The PC-510 supports both an analog monitor and/or a flat panel display. The CT.COM and FP.COM programs allow you to toggle between the monitor and the flat panel. If the flat panel supports simultaneous mode, the SM.COM program will allow you to display images from both the monitor and the flat panel at the same time. These programs are on the VGA 65550 utility disk in the \UTILS subdirectory along with other diagnostic and configuration utilities. Refer to the README.DOC file.

Analog monitor

Figure 13-2 The PC-510 and a VGA monitor



1. Use a VGA-12 adapter cable with the standard VGA monitor.
2. Plug the VGA-12 adapter cable into J20 on the PC-510.
3. Plug the cable into the VGA cable of the monitor.

Note See the *Accessories* appendix for connector information for the SVGA connector.

Flat panel display

Text files are located on the 65550 utility disk. These text files include wiring diagrams specific to individual flat panels. Refer to the specific text file associated with your flat panel to build your cable.

Note The maximum recommended cable length for a flat panel configuration is 18 in.

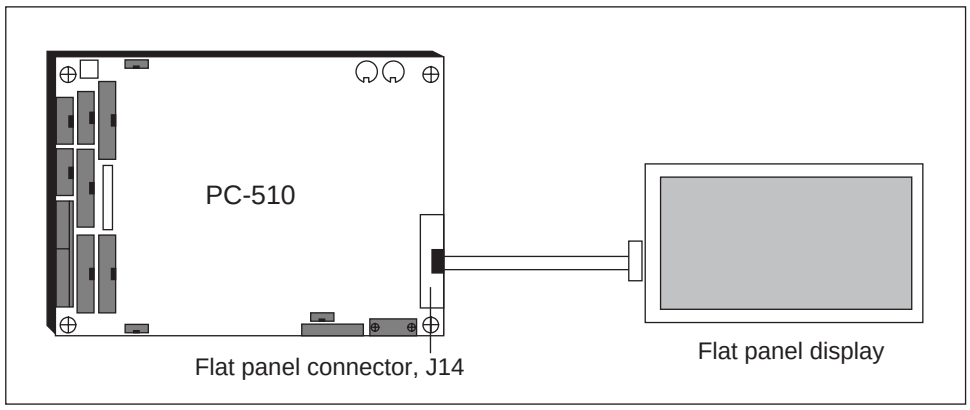
WARNING!

Before connecting your flat panel to the PC-510, check your flat panel for bias voltage requirements. By default, the PC-510 comes with a bias voltage range of +21 to +29V.

1. Refer to the text file associated with your flat panel to determine the supply voltage.
2. Connect an adapter cable from the flat panel to the flat panel connector located at J14 on your PC-510.
3. Refer to the diagram below, Figure 13-3.

Note See the *Accessories* appendix for connector information for the flat panel connector.

Figure 13-3 The PC-510 and a flat panel display



Flat panels requiring bias voltage

To determine if your flat panel requires bias voltage, refer to the text file on the 65550 utility disk, which is specific to your flat panel.

The factory default configuration for the bias voltage ranges from +21 to +29 VDC. Other bias voltage ranges and negative polarity are factory configurable. To verify bias voltage, connect a DC voltage meter input lead to J14 pin 3 and a reference lead to J14 pin 6. Pin 3 verifies the voltage level and pin 6 is used as a ground reference.

2. Power on the PC-510.
3. Run LCDBIAS.EXE.
4. A message similar to the following should appear on your display:

```
PhoenixBIOS(TM) A486 Version 1.03
Copyright (C) 1985-1994 Phoenix Technologies,Ltd.
All Rights Reserved
```

5. Press <CTRL><+> to raise the voltage or <CTRL><-> to lower the voltage. Raise or lower the voltage until you obtain a good contrast display with no washout.

   To confirm the LCD bias voltage, place a voltmeter on ground at J14, pin 6 and also on positive at J14, pin 3.

6. The VEESAFE voltage may require additional adjustments in order to obtain the proper contrast. Use LCDBIASDW or LCDBIASUP to obtain the proper contrast.

WARNING!

Since improper voltage levels can severely damage the flat panel, make sure the PC-510 is configured for the correct bias voltage before it is connected to the panel.

LCD bias control examples

To change the flat panel bias voltage inside your application, use the INT 17h functions below.

1. LCDBIAS UP. Write the following program to move the voltage up one step:

```
mov       ah,0eeh    ; LCDBIAS control
mov       a1,00h     ; up
mov       dx,0ffffh
int       17h
```

2. LCDBIAS DOWN. Write the following program to move the voltage down one step:

```
mov       ah,0eeh    ; LCDBIAS control
mov       a1,01h     ; down
mov       dx,0ffffh
int       17h
```

≡ Flat panel considerations

Jumper options are available on the PC-510 to accommodate different flat panel interfaces. W8 allows direct support of 3V and 5V flat panels. W9 supports shift clock 180° out of phase. Refer to the wiring diagrams specific to your flat panel to determine the correct jumper settings. All wiring diagrams are found in the .txt files on the 65550 utility disk.

Flat panel interface voltage select: W8

The PC-510 supports flat panel interface at either 5V or 3.3V. W8[1-2] enables flat panel interface at 5V (default). W8[3-4] enables flat panel interface at 3.3V.

Table 13-2 Flat panel interface voltage select: W8

Pins	Description
[1–2]	5V*
[3–4]	3.3V

* = default, pins jumpered

Inverted shift clock signal voltage level select: W9

The PC-510 provides an inverted shift clock signal for flat panels, such as electro-luminescent (EL) displays, at either 5V or 3.3V. W9[1-2] enables the PC-510 to output an inverted shift clock signal at 3.3V. W9[3-4] enables the PC-510 to output an inverted shift clock signal at 5V (default).

Table 13-3 Inverted shift clock signal voltage level select: W9

Pins	Description
[1–2]	3.3V
[3–4]	5V*

* = default, pins jumpered

Chapter 14: GPS interface

≡ Description

The PC-510 provides a global positioning system (GPS) interface to allow direct connection to an optional Rockwell Jupiter GPS module. COM5 interfaces with the Rockwell Jupiter receiver. The option to receive the Jupiter GPS data is field configurable and is determined through the SETIRQ utility program. COM6 can optionally be used as an auxiliary port to directly process the RTCM SC-104 messages for DGPE connections. This option is factory configurable and is not intended for field configuration. COM6 can interface to TTL or RS-232 levels. The antenna's power level to the Jupiter module is jumper selectable for 5V or 12V. Contact Rockwell at (800) 854-8099 or (714) 833-6996 for more information concerning the Rockwell Jupiter GPS module.

GPS receivers are suitable for a wide range of applications such as:

- Handheld GPS receiver
- Automotive
- Marine navigation
- Aviation
- Railroad
- Trucking
- Surveying
- Timing

The PC-510 RTC backup battery supports the GPS interface to maintain time, date, last known location and GPS almanac data. This allows for rapid time to first fix (warm start) upon system power on. The GPS interface shares the data transmit and receive connections.

Note See the *Accessories* appendix for connector information for GPS and Jupiter module connectors.

≡ Mounting the GPS module to the PC-510

The Jupiter mounting kit is sold separately. The kit contains the following contents:

- 4 threaded hex stainless steel standoffs (4-40 x 3/8")
- 8 screws (4-40 x 1/4")
- 8 internal star lock washers
- 1 interface cable
- *Jupiter GPS product sheet*

WARNING!

The GPS receiver module contains electronic components that are static sensitive. To avoid damaging the module and its components:

- **Make sure the power supply to the PC-510 is turned OFF. Damage to the PC-510, the GPS module, and the interface cable may occur if the power is ON.**
- **Ground yourself before handling the GPS module.**

To install the GPS module to the PC-510 board:

1. Refer to the dimensions diagram, Figure 14-1, of the GPS module for the location of the various connectors and the dimensions of the four .125" mounting holes.
2. Use the #4 standoffs, washers, and screws and place them in the four holes on the PC-510 board.
3. Power is supplied to the GPS module through the interface cable at J13.
4. Connect one end of the cable to J13 and connect the other end to the Jupiter module.
5. Set the antenna power level. W6[1–2](default) is for 12V operation, W6[1–3] is for 5V operation.

WARNING!

When connecting the interface cable to the PC-510, make sure that all header pins and socket connectors are properly aligned.

≡ GPS interface port options

The standard version of the PC-510 installs COM5 and COM6. Under OEM contract, COM5 can share the data transmit and receive connections with the GPS connector. COM6 can be ordered to route RTCM SC-104 differential correction data to the GPS receiver. The GPS interface can be ordered and custom tailored to the user's application.

Routing the GPS data

Use the SETIRQ program to allow COM5 to receive the GPS data. Refer to the *IRQ routing and opto irqs* chapter.

Table 14-1 GPS interface default and optional features

Location	Default features	Optional features using SETIRQ*
COM5	4–wire industrial interface	GPS interface (field configurable)
COM6	4–wire industrial interface or RS–485	RS–485
GPS connector (J13)	Installed	Not installed

* = Factory configurable options are not available with the GPS interface.

Table 14-2 Jupiter GPS mode

Jupiter pin	PC-510 standard	PC-510 optional
GPIO2	no pull–ups/pulldown*	pull–up/pull–down
GPIO3	no pull–ups/pulldown*	pull–up/pull–down

* = In this pin state, the Jupiter module configures the GPS mode from the Jupiter SRAM/EEPROM configuration.

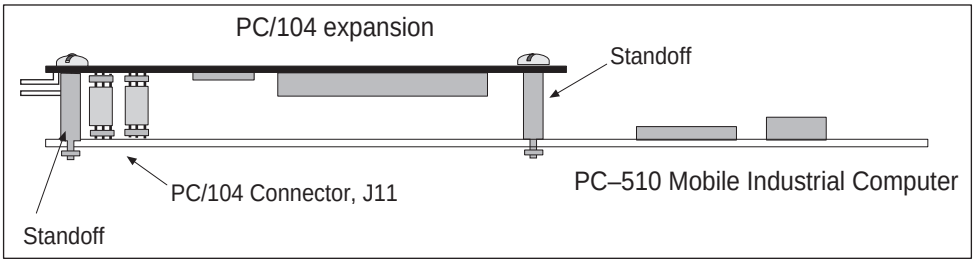
Chapter 15: PC/104 expansion

≡ Description

This connector allows you to interface to one or two PC/104 form factor modules including hard disks, A/D converters, digital I/O, serial ports, etc. The PC-510 supports 8- and 16-bit and provides ±12V from the power supply at P8, P9. These modules can be stacked on top of the PC-510 to form a highly integrated control system.

Note See the *Accessories* appendix for connector information on the PC/104 connector.

Figure 15-1 Typical PC/104 expansion module stack



WARNING!

When installing any PC/104 expansion module, avoid excessively flexing the PC-510 board. Mate pins correctly and use the required mounting hardware.

Overview: Section 3 – System management

Section 3 provides information on managing the PC-510 in the areas of internal control, CPU power management, and troubleshooting. The following chapters are included:

Chapter 16: Watchdog timer and hardware reset
Chapter 17: Serial EEPROM and CMOS RAM
Chapter 18: Transferring files/remote disks
Chapter 19: Managing SSDs
Chapter 20: User-defined jumper
Chapter 21: CPU power management
Chapter 22: Troubleshooting

Chapter 16: Watchdog timer and hardware reset

≡ Description

The watchdog timer is a fail-safe against program crashes or processor lockups. It times out every 1.6 seconds (1.6 sec. typical, 1.00 sec. min., 2.25 sec. max.) unless reset by the software. The watchdog timer can be controlled through the enhanced INT 17h interface which is a built-in function on the PC-510.

≡ Enhanced INT 17h function definitions

This section provides definitions for the following functions: Enable watchdog, Strobe watchdog, and Disable watchdog.

Enable watchdog

Function: fdh

Subfunction: 01h

Purpose: To enable the watchdog.

Calling registers:

AH	fdh
AL	01h
DX	ffffh

Return registers: None

Comments: This function enables the watchdog. Once the watchdog is enabled, it has to be strobed at a period of not less than 1.6 seconds or until the watchdog is disabled. Otherwise, a system reset will occur.

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
mov  ax,0fd01h
mov  dx,0ffffh
int  17h
}
```

Strobe watchdog

Function: fdh

Subfunction: 02h

Purpose: To strobe the watchdog.

Calling registers:
AH fdh
AL 02h
DX ffffh

Return registers: None

Comments: This function strobes the watchdog. Once the watch dog is enabled, it has to be strobed at a period of not less than 1.6 seconds or until the watchdog is disabled. Otherwise, a system reset will occur.

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
mov ax,0fd02h
mov dx,0ffffh
int 17h
    }
```

The watchdog timer can also be strobed by reading address 20Ch. This may be faster than strobing the watchdog timer with an interrupts function call, for example:

```
A=INP(20Ch)
```

Disable watchdog

Function: fdh

Subfunction: 03h

Purpose: To disable the watchdog.

Calling registers:
AH fdh
AL 03h
DX ffffh

Return registers: None

Comments: This function disables the watchdog. Once the watchdog is enabled, it has to be strobed at a period of not less than 1.6 seconds or until the watchdog is disabled. Otherwise, a system reset will occur.

Programming example:

```
/* Inline assembly code for Borland C++ 3.1 */
asm {
     mov  ax,0fd03h
     mov  dx,0ffffh
     int  17h
     }
```

≡ Hardware reset

The PC-510 has a button which allows you to reset the system without turning off the power. This provides a more complete reset than the <CTRL><ALT><DEL> method. The RESET command also accomplishes the same thing as the reset button. It is also possible to issue a hardware reset through the opto-isolated inputs, either OPTOA or OPTOB channels at J17. See the *IRQ routing and opto irqs* chapter for more information on opto channels. Refer to the component diagram in the *Quick start* chapter for the location of the reset button.

WARNING!

When using COM1 as the console, the <CTRL><ALT> <DEL> commands on the host system keyboard only reset the host system. Use the RESET command to issue a hardware reset on the PC-510.

Chapter 17: Serial EEPROM and CMOS RAM

≡ Description

Up to 768 words of user-definable data can be saved in the serial EEPROM. The serial EEPROM does not require battery backup to maintain the data when the system power is off. The serial EEPROM is easily accessible via software interrupts by most programming languages.

The calendar/clock provides the user with 128 bytes of user-defined CMOS RAM. This RAM requires battery backup to maintain data. If a battery is not desirable, this data can be stored in serial EEPROM, written to CMOS RAM on powerup, changed and written back to serial EEPROM.

≡ Enhanced INT 17h function definitions

This section provides definitions for both serial EEPROM and CMOS RAM functions. The serial EEPROM definitions include the following functions: Read a single word from serial EEPROM, Write a single word to serial EEPROM, Read multiple words from serial EEPROM, Write multiple words to serial EEPROM, and Return serial EEPROM size.

The CMOS RAM definitions include the following functions: Read extended CMOS RAM, Write extended CMOS RAM, Check CMOS battery, Copy contents of serial EEPROM to extended CMOS RAM, and Copy contents of extended CMOS RAM to serial EEPROM.

≡ Serial EEPROM

Read a single word from the serial EEPROM

Function: fch

Subfunction: 00h

Purpose: To read a single word from the on-board serial EEPROM.

Calling registers:

AH	fch
AL	00h
BX	Word address (zero based)
DX	ffffh (relative to user area)

Return registers: Carry flag cleared if successful
AX Word read
Carry flag set if error
AL Error code

Error code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function reads a word from the user area of the serial EEPROM.

Programming example:

```
/* Read word 2 */
unsigned int seeData;
/* Inline assembly code for Borland C++ 3.1 */
asm {
mov  ax,0fc00h
mov  bx,02h     /* Read word 2 */
mov  dx,0ffffh
int  17h
mov  seeData,ax /* store data in c environment */
    }
```

Write a single word to the serial EEPROM

Function: fch

Subfunction: 01h

Purpose: To write a single word to the on-board serial EEPROM.

Calling registers: AH fch
AL 01h
BX Word address (zero based)
CX Data word to write
DX ffffh (relative to user area)

Return registers: Carry flag cleared if successful
Carry flag set if error
AL Error code

Error code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function writes a word to the user area of the serial EEPROM.

Programming example:

```
/* Write 0x1234 to word 3*/
unsigned int seeData = 0x1234;
/* Inline assembly code for Borland C++ 3.1 */
asm {
     mov   ax,0fc01h
     mov   bx,03h     /* Write word 3 */
     mov   cx,seeData /* Get write data from
                         c environment */
     mov   dx,0ffffh
     int   17h
    }
```

Read multiple words from the serial EEPROM

Function: fch

Subfunction: 02h

Purpose: To read multiple words from the on-board serial EEPROM.

Calling registers:

AH	fch
AL	02h
BX	Word address (zero based)
CX	Word count
DX	ffffh (relative to user area)
ES:DI	Destination pointer

Return registers:

Carry flag cleared if successful

AX	Word read

Carry flag set if error

AL	Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function reads multiple words from the user area of the serial EEPROM.

Programming example:

```
/* Read 10 words starting at word 5 */
unsigned int far *seeDataPtr = new unsigned int[10];
/* Allocate storage*/
/* Inline assembly code for Borland C++ 3.1 */
asm {
    mov   ax,0fc02h
    mov   bx,05h     /* Read starts at word 5 */
    mov   cx,10      /* Read 10 words */
    mov   dx,0ffffh
    les   di,seeDataPtr
    int   17h
    }
```

Write multiple words to the serial EEPROM

Function: fch

Subfunction: 03h

Purpose: To write multiple words to the on-board serial EEPROM.

Calling registers:

AH	fch
AL	03h
BX	Word address (zero based)
CX	Word count
DX	ffffh (user area relative address)
DS:SI	Source pointer

Return registers:

Carry flag cleared if successful
Carry flag set if error
AL Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function writes multiple words to the user area of the serial EEPROM.

Programming example:

```
/* Write 8 words starting at word 6*/
unsigned int far *seeDataPtr = new unsigned int[8];
/* Allocate storage*/
    unsigned int far* tmpPtr = seeDataPtr;
    for(int i=0;i<8;i++)
    *seeDataPtr = i;/* initialize data */
/* Inline assembly code for Borland C++ 3.1 */
    asm {
    push ds
    mov  ax,0fc03h
    mov  bx,06h     /* Write starts at word 6 */
    mov  cx,8       /* Write 8 words */
    mov  dx,0ffffh
    lds  si,seeDataPtr
    int  17h
    pop  ds
          }
```

Return serial EEPROM size

Function: fch

Subfunction: 04h

Purpose: To obtain the size of the on-board serial EEPROM.

Calling registers: AH fch
AL 04h
DX ffffh

Return registers: Carry flag cleared if successful
AX Size of the serial EEPROM (in words)
BX Size available to user (in words)
Carry flag set if error
AL Error code

Error code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function returns the size (in words) of the serial EEPROM. Since the user cannot access all of the serial EEPROM, this function determines how much space is available to the user. This avoids the user from accessing unavailable addresses.

Programming example:

```
unsigned int seeUserSize;
/* Inline assembly code for Borland C++ 3.1 */
asm {
     mov   ax,0fc04h
     mov   dx,0ffffh
     int   17h
     mov   seeUserSize,bx
     }
```

≡ CMOS RAM

Read extended CMOS RAM

Function: fbh

Subfunction: 06h

Purpose: To read a single byte from the extended CMOS RAM.

Calling registers: AH fbh
AL 06h
BL CMOS index (0-127)
DX ffffh

Return registers: Carry flag cleared if successful
BH CMOS data
Carry flag set if error
AL Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function reads a single byte from the extended CMOS RAM area.

Programming example:

```
unsigned char cmosByteSave;
/* Inline assembly code for Borland C++ 3.1 */
    asm {
          mov   ax,0fb06h
          mov   bl,0 /* byte 0 */
          mov   dx,0ffffh
          int   17h
          mov   cmosByteSave,bh
        }
    printf("The CMOS byte read = %02x\n", cmosByteSave)
```

Write extended CMOS RAM

Function: fbh

Subfunction: 07h

Purpose: To write a single byte to extended CMOS RAM area.

Calling registers:

AH	fbh
AL	07h
BL	CMOS index (0-127)
BH	CMOS data
DX	ffffh

Return registers: Carry flag cleared if successful
Carry flag set if error
AL Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function writes a single byte to the extended CMOS RAM area.

Programming example:

```
/* Writes 0x44 to index 3 of extended CMOS RAM */
/* Inline assembly code for Borland C++ 3.1 */
   asm {
         mov   ax,0fb07h
         mov   bl,3       /* Write byte 3 */
         mov   bh,44h     /* cmos data */
         mov   dx,0ffffh
         int   17h
       }
```

Check CMOS battery

Function: fbh

Subfunction: 08h

Purpose: To check CMOS battery condition.

Calling registers:
AH fbh
AL 08h
DX ffffh

Return registers:
Carry flag cleared if successful
ZF set = battery okay, ZF clear = battery bad
AL copy of CMOS register 0Eh at powerup time
Carry flag set if error
AL Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function reports the condition of the CMOS battery. This is useful to determine if extended CMOS data (contents) should be relied upon or refreshed from EEPROM.

Programming example:

```
/* Reports the condition of the CMOS battery */
   unsigned int cmosflag;
/* Inline assembly code for Borland C++ 3.1 */
   asm {
         mov   ax,0fb08h
         mov   dx,0ffffh
         int   17h
         mov   cmosflag,al
       }
printf("The CMOS byte 0E at powerup time  = %02x\n",
cmosflag)
```

Copy contents of serial EEPROM to extended CMOS RAM

Function: fbh

Subfunction: 09h

Purpose: To copy contents of serial EEPROM extended CMOS storage to extended CMOS RAM.

Calling registers:
AH fbh
AL 09h
DX ffffh

Return registers:
Carry flag cleared if successful
Carry flag set if error
AL Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function copies the contents of the serial EEPROM to extended CMOS RAM. The extended CMOS can now be read/written using the 06 and 07 functions.

Programming example:

```
/* Copies contents of serial EEPROM to extended
   CMOS RAM */
/* Inline assembly code for Borland C++ 3.1 */
    asm {
    mov  ax,0fb09h
    mov  dx,0ffffh
    int  17h
         }
```

Copy contents of extended CMOS RAM to serial EEPROM

Function: fbh

Subfunction: 0Ah

Purpose: To copy contents of the current extended CMOS RAM data to the serial EEPROM.

Calling registers:
AH fbh
AL 0Ah
DX ffffh

Return registers:
Carry flag cleared if successful
Carry flag set if error
AL Error code

Error Code	Meaning
ffh	Unknown error
01h	Function not implemented
02h	Defective serial EEPROM
03h	Illegal access

Comments: This function copies the contents of the extended CMOS RAM to serial EEPROM. Use the 09 function to retrieve the contents.

Programming example:

```
/* Copies contents of the extended CMOS RAM to
   serial EEPROM */
/* Inline assembly code for Borland C++ 3.1 */
    asm {
    mov  ax,0fb0Ah
    mov  dx,0ffffh
    int  17h
         }
```

Chapter 18: Transferring files/remote disks

≡ Transferring files between the PC-510 and your PC

Once you have established communications between your PC and the PC-510, you can serially download files to any read/write drive used by the PC-510. You can also upload files from the PC-510 to your desktop PC for editing and debugging.

There are two methods to download files through the serial port to the PC-510:

1. The TRANSFER utility is used to download files, one at a time, to the PC-510 using the XMODEM protocol. TRANSFER.EXE resides on the PC-510 BIOS drive and on the PC-510 utility disk and is used to send or receive files via the serial port (e.g., COM1). TRANSFER.EXE uses the XMODEM protocol, as does PC SmartLINK. (See the note below on XMODEM).

2. REMDISK/REMSERV utilities allow access to all of the files on a remote disk drive. REMDISK.EXE and REMSERV.EXE are located on the PC-510 BIOS drive and the PC-510 utility disk. Once these programs are executed, single or multiple files can then be transferred to and from the PC-510 using DOS COPY or XCOPY commands.

   TRANSFER.EXE, REMDISK.EXE and REMSERV.EXE are located on the PC-510 BIOS drive, in the DOS directory, and on the PC-510 utility disk in the \DOS directory. Refer to the *Software utilities* appendix for more information on these programs.

Note XMODEM only transfers files in which the file size is exactly on a 128 byte boundary. If the file size does not fall exactly on the boundary, XMODEM automatically rounds the file size up to the next 128 byte boundary with padding characters. For example, a file with a size of 10,000 bytes, will be rounded up to 10,112 bytes, transferred, and written with the new file size. In most cases, this is not a concern, but in some instances the XMODEM padding causes problems. The padding problems become apparent when an application program is expecting a specific file size or is expecting characters other than the padding characters to be at the end of the file.

≡ Transferring files to the PC-510

The following steps detail the procedures for transferring files from your PC to the virtual drive on the PC-510. In order to transfer files from your PC to the PC-510, you must execute the TRANSFER program from both the PC-510 and your PC.

1. Connect a 9-pin serial cable with a null modem adapter between COM1 of your PC to COM1 of the PC-510, using a VTC-20F cable.
2. Execute the TRANSFER program from the PC-510 to receive a file from your PC.

   TRANSFER /COM1 /R /V <drive>*filename.ext*

   <drive> is the drive on the PC-510 where the file will be transferred.

   /R specifies to receive a file (default).

   filename.ext is the name of the file on the PC-510 which you are receiving from your PC.

   COM1 specifies the serial port on the PC-510.

   /V enables "R" characters upon receiving a block and "T" upon transferring a block. Do not use /V when using a serial console.
3. Execute the TRANSFER program from your PC to send a file to the PC-510. /S specifies send to file.

   TRANSFER /COM1 /S /V <drive><path>*filename.ext*

   filename.ext is the name of the file on the PC which you are sending to the PC-510.

Note An alternate method of transferring a file is to press <ALT><D>, when you use PC SmartLINK.

Note Transfer will time-out if the program has not been started after approximately 40 seconds. It displays the following message:

```
Failed to receive <drive>filename.ext
Deleting <drive>filename.ext
```

Also, you may speed up the transfer using the /Bnnnn switch to increase the baud rate. Example: /B57600. When you use a serial console, do not use the /B option on the PC-510. Instead, change the serial console baud rate in SETUP.

≡ Transferring files from the PC-510

In order to transfer files from your PC to the PC-510, you must execute the TRANSFER program from both the PC-510 and your PC.

1. Connect a 9-pin serial cable with a null modem adapter between COM1 of your PC to COM1 of the PC-510, using a VTC-20F cable.
2. Execute the TRANSFER program from the PC-510 to send a file to your PC.

   TRANSFER /COM1 /S /V *filename.ext*

   filename.ext is the name of the file on the PC-510 which you are sending to your PC.

   /V enables "R" characters on receiving a block and "T" on transferring a block.

   /COM1 /S /V: Send in verbose mode
3. Execute the TRANSFER program from your PC to receive a file from the PC-510.

   TRANSFER /COM1 /R /V *filename.ext*

   filename.ext is the name of the file on the PC which you are receiving from the PC-510.

   /COM1 /R /V: Receive in verbose mode

Note Transfer will time-out if the program has not been started after approximately 40 seconds. It displays the following message:

```
Failed to receive <drive>filename.ext
Deleting <drive>filename.ext
```

Also, you may speed up the transfer using the /Bnnnn switch to increase the baud rate. Example: /B57600.

≡ Downloading files to the PC-510 using PC SmartLINK

The following information on downloading files between the PC-510 and your PC uses the example program DEMO.EXE. This file is on the PC-510 utility disk in the \DEMO directory.

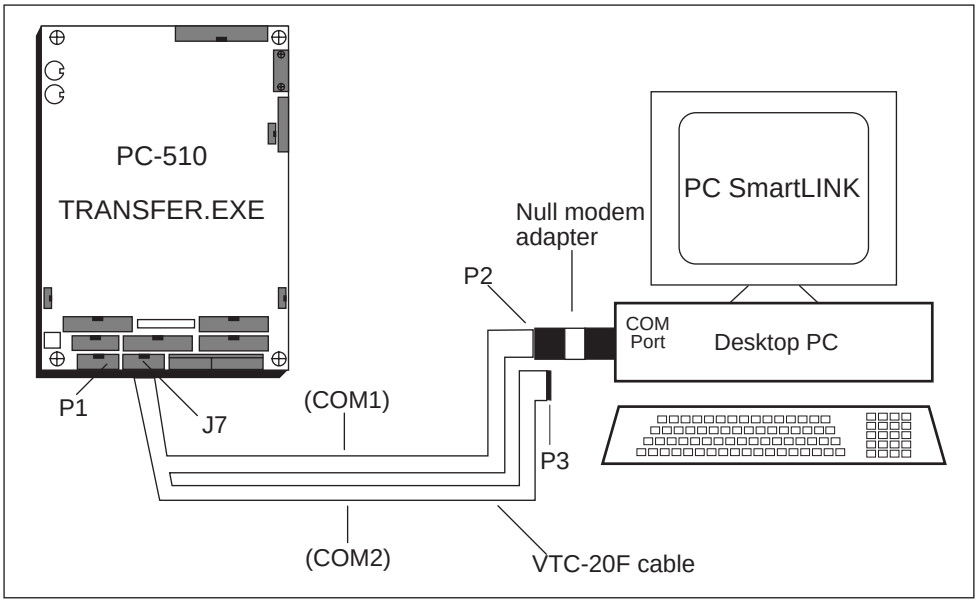
The following procedures assume you are using PC SmartLINK. For other communication programs, refer to those programs instructions for performing Xmodem file transfer to a target system.

Hardware and software requirements:

- Desktop PC, running PC SmartLINK, connected by a VTC-20F cable and a null modem adapter to COM1 of the PC-510.

1. Connect the equipment according to the following diagram:

Figure 18-1 Downloading files using TRANSFER.EXE



2. Start PC SmartLINK and power on the PC-510.

Note PC SmartLINK is a DOS application. File transfer problems will occur when running in Windows. If you are using Windows on your PC, restart the PC in MS-DOS mode before running SmartLINK.

3. Execute the TRANSFER.EXE program from the PC-510 by entering:

```
PC510 C:\> TRANSFER DEMO.EXE
```

The following message is displayed from the PC-510:

```
Receiving DEMO.EXE . . .
```

4. Execute the following steps using PC SmartLINK:
   - Press <ALT><D> to enter the download screen.
   - Type in the name of the file to transfer, e.g.:
     C:\MPC\DEMO\DEMO.EXE
   - To begin the transfer:
     — either press **ENTER** (default download START);
     — tab to **START**;
     — click on the **START** button in the download screen.
   - When the file transfer is completed, press <ESC> twice to return to the main PC SmartLINK screen.

Note TRANSFER.EXE will time-out if the transfer has not been started within approximately 40 seconds. If the time-out occurs, the following message from the PC-510 is displayed:

```
Failed to receive DEMO.EXE!
Deleting DEMO.EXE
```

5. When the file transfer is complete, type the following DOS command to view the drive directory and confirm that your file has been transferred to the PC-510:

   ```
   PC510 C:\> DIR
   ```

   The system will display the contents of drive contents:

   ```
   Volume in drive is <label>
   Directory of <drive>\

   DEMOEXE   27264 06-07-96   2:57p

         1 file(s)     27264 bytes
   ```

6. To execute the program you have just downloaded, type the following command:

   ```
   PC510 C:\> DEMO
   ```

   The DEMO program displays a message on your PC.

≡ Remote disks

Downloading files to the PC-510 using REMDISK/REMSERV

The following represents a method of using REMDISK/REMSERV with PC-510 with one serial cable.

Refer to the *Software utilities* appendix for specific information on using REMDISK.EXE and REMSERV.EXE

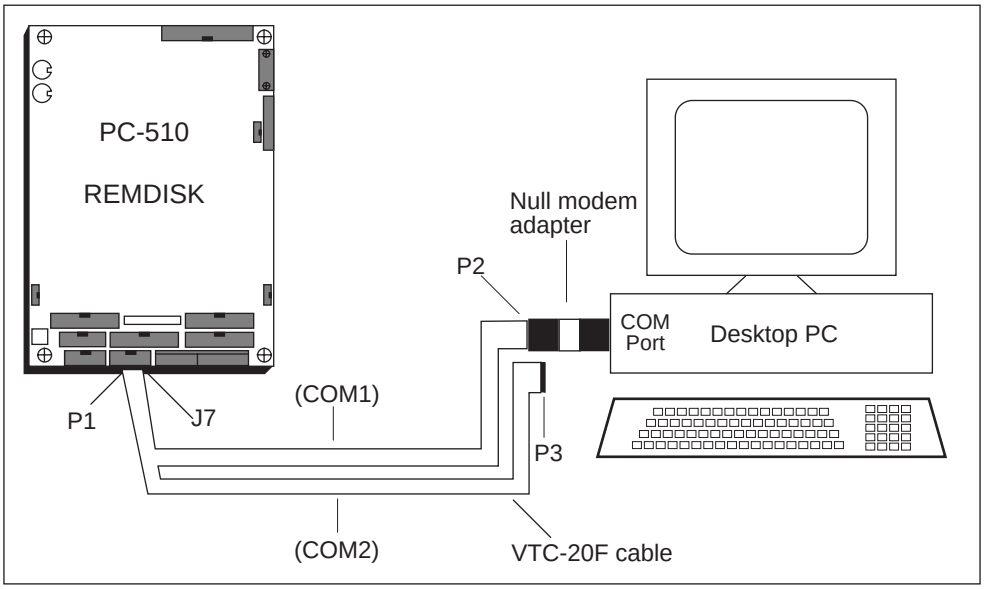
PC-510 with one serial cable

Hardware and software requirements:

- Desktop PC, running REMSERV, connected by a VTC-20F cable and a null modem adapter to COM1 or COM2 of the PC-510.
- A PC-510 system, including a keyboard, and VGA monitor, running REMDISK from COM1 or COM2.

1. Connect the equipment and load the appropriate software on each system as per the following diagram:

Figure 18-2 Downloading files to the PC-510 with one serial cable using REMDISK/REMSERV



2. On the PC-510 system, execute REMDISK.EXE by entering:

   ```
   PC510 C:\> REMDISK
   ```

   The following message is displayed on the PC-510 monitor:

   ```
   Remote Disk v1.0
   Copyright (c) 1990-1994 Datalight, Inc.
   All rights reserved.
   Installed as Drive F:   /COM1   /B115+   /T3
   ```

Note REMDISK assigns the remote drive as the last drive in the system. In this case, drive F: was assigned.

3. Execute REMSERV.EXE on the desktop PC:

   ```
   C:\> REMSERV C:
   ```

   The following message is displayed on the PC:

   ```
   REMSERV v1.0
   Copyright (c) 1990-1994 Datalight, Inc.
   All rights reserved.
   Using COM1 at 115K+ baud. Accessing Drive C:
   Time-out is 2 seconds
   Press <Esc> to Exit.(There may be a delay before exit
   occurs)
   ```

4. Files are transferred to the PC-510 read/write drives by using the DOS COPY and XCOPY commands. From the PC-510 system, enter:

```
PC510 C:\> COPY F:\MPC\PC510\DEMO.EXE
PC510 C:\> DIR
PC510 C:\> DEMO.EXE
```

The DEMO program displays a message on the PC-510 monitor.

5. When finished, on the PC-510 system, execute:

   ```
   PC510 C:\> REMDISK /U
   ```

   This unloads REMDISK from the PC-510.

6. On the desktop PC, press <ESC> to exit REMSERV.

Chapter 19: Managing SSDs

≡ PICO FA flash file system

By default the PICO FA extended BIOS is loaded at system boot. A message similar to the following is displayed on your screen as the system boots each PICO FA drive found:

```
PhoenixBIOS(TM) A486 Version x.xx
Copyright (C) 1985-1994
Phoenix Technologies, Ltd.
```

The PICO FA extended BIOS allows the PC-510 to boot from the flash file system on-board the PC-510. These drives are "simulated" hard drives that look like a standard hard drive on a PC. In some instances it will be necessary to disable the PICO FA extended BIOS. This is done by removing jumper W3[3-4]. W3[3-4] works with the D8000-DFFFF ROM enable in SETUP. Octagon recommends that you use this jumper to disable or enable the PICO FA BIOS region and leave the D8000-DFFF ROMSETSSD enable in SETUP as the default.

Note When installing Windows 95 or Windows NT operating system, it is necessary to disable the PICO FA flash file system.

Phoenix's PICO FA™ includes an extended BIOS (PICOFA.IMG), a device driver (PICOFA.SYS), a format utility (PFORMAT.EXE), and a test utility (TESTRFA.EXE).

Use the device driver PICOFA.SYS to access SSDs when booting from a floppy or hard drive, when the extended BIOS (PICOFA.IMG) is disabled.

≡ Defining SSDs using SETSSD

SETSSD allows the user to set or change the PICO FA drive (SSD) order. PICO FA drives are "simulated" hard drives. They can exist before or after any IDE drives and can appear in any order. By setting the order, the SSDs may be accessed as C:, D:, etc. The standard version of the PC-510 ships with SSD1. SSD0 is supplied with the optional version of the PC-510. To install SSD0, see the *SSD0* section in the *SSDs, DRAM, and battery backup* chapter.

The following examples demonstrate how to define SSD drive order:

- To set SSD0 first and SSD1 second, enter the following command:

```
PC510 C:\> SETSSD SSD0 SSD1
```

Note SSD0 is C: and SSD1 is D:. Drive designators will change depending on the SETSSD settings.

- To set SSD1 first and SSD0 second, enter the following command:

```
PC510 C:\> SETSSD SSD1 SSD0
```

Note In the above example SSD1 is C: and SSD0 is D:. Drive designators will change depending on the SETSSD settings.

- To use only SSD1, enter the following command:

```
PC510 C:\> SETSSD SSD1
```

If there are other hard drives on the system, add the **/before** option to place the order of the SSDs before the hard drives, or add the **/after** option to place the SSDs after the hard drives. For example,

- To set SSD0 as the first drive, SSD1 as the second drive, and an IDE drive as the third drive, enter the following command:

```
PC510 C:\> SETSSD SSD0 SSD1 /before
```

- To set the IDE drive as first in order, SSD1 as second, and SSD0 as third, enter the following command:

```
PC510 C:\> SETSSD SSD1 SSD0 /after
```

In the last example, the IDE drive is C:, SSD1 is D: and SSD0 is E:. Other drive letter designations may be added by device drivers (such as VDISK.SYS), which are in the CONFIG.SYS file on the boot drive.

The boot drive is based upon the drive order set by the SETSSD command and by SETUP's "boot sequence" option. If the boot sequence is set to "A: THEN C:," the system will look for a floppy diskette in drive A:. If a diskette is not installed, or a floppy is not defined, the boot drive will be the first drive specified in the SETSSD command. If the boot sequence is set to "C: ONLY," the check for a diskette is bypassed.

Note The SETSSD parameters may also be overwritten by removing the USESETUP jumper and resetting the system. If the parameters specified at the PICO FA first/second drive prompt are different from the previous SETSSD command, and you answered "No" to the "Save" prompt, the SETSSD output will not be accurate. Therefore, we recommend that you answer "Yes" to the save option to prevent confusion.

Note After you run SETSSD and the drive order has changed, the new parameters will take effect after a reset.

The drive order affects the number entered at the PFORMAT H*n* command. See the *Using PFORMAT to format an SSD* section in this chapter.

Note Optional parameters such as /QNX-, QNX+, /SSD0BIOS-, and SSD0BIOS+ can be used to modify PICOFA usage of SSD0 and SSD1. For more information on these parameters, see the SETSSD.EXE support command in the *Software utilities* appendix.

≡ Using PFORMAT to format an SSD

Formatting SSD1

This section describes how to format SSD1.

> **WARNING!**
>
> **Reformatting SSD1 requires the use of a floppy or a hard disk to restore system files.**

1. Define the SSD order with the SETSSD command. Since the command input varies depending upon the parameters you need to enter, see the SETSSD command in the *Software utilities* appendix.
2. To begin formatting SSD1, execute PFORMAT as follows:

   PC510 C:\> **PFORMAT H***n*

   where *n* is the hard drive sequence number. This number includes IDE drives and SSDs.

   For example, if you have 0 IDE drives and SETSSD shows:

   [HDDs] SSD0 SSD1

   then enter:

   PC510 C:\> **PFORMAT H1**

   On the other hand, if you have 1 IDE drive, enter:

   PC510 C:\> **PFORMAT H2**

Note If the drive had not been formatted previously, reset the system before accessing the drive. This allows DOS to recognize the drive and add a letter designation to it.

Note PFORMAT.EXE must be downloaded from the PC-510 utility disk. This file is located in the \UTILS directory.

Note PFORMAT.EXE will not format IDE/ATA drives.

≡ Using SYS to make an SSD bootable

Adding operating system startup files (using SYS)

To add the system files, issue the following operating systems command:

C:\> **SYS** *d:*

where *d:* specifies the drive letter.

For example, if your system has 1 IDE drive, and SETSSD shows "[HDDs] SSD0 SSD1," then SSD1 should be drive E:. To SYS this drive, use the "SYS *d:*" command.

Note SYS.COM must be downloaded from the PC-510 utility disk. This file is located in the \DOS directory.

Note If you are adding the MS-DOS operating system to SSD1, you must first boot from an MS-DOS bootable device (floppy or hard drive).

Note If you are not booting from ROM-DOS, and wish to SYS ROM-DOS back to the drive, the SYS command requires you to issue the following ROM-DOS commands: COMMAND.COM, ROM-DOS.SYS and SYS.COM.

≡ Changing boot SSD

Autoexecuting your application

This section describes how to autoexecute your application.

1. To autoexecute your application in SSD1, use the SETSSD command to define your SSD as the boot device. Since you need to define the order of SSD1 as the first of the SSDs (and before any IDE drives), enter the following command:

   ```
   PC510 C:\>SETSSD SSD1 SSD0 /before
   ```

2. Add your application to SSD1, and modify the AUTOEXEC.BAT program to include your application.

3. Reset the system. SSD1 is now drive C: and your application should begin execution.

Note If the SETUP option "Boot Sequence" is set to "A: THEN C:", remove any floppy in drive A: before resetting the system.

Note The SETSSD options are not used when W2[9-10] is not jumpered.

≡ Using SETSSD and TESTRFA to test an SSD

To test SSD0 and SSD1 (i.e., destroying all drive data on the SSD1), follow the steps below:

1. Run SETSSD.EXE to determine which socket to use with TESTRFA. The socket (either 0 or 1) depends on the order of the SSDs. The first SETSSD' SSD is socket 0 and the second SSD is socket 1. To configure the order of the SSDs, see the *Defining SSDs using SETSSD* section in this chapter.

For example, running SETSSD with no parameters may give the following output:

```
PC510 C:> SETSSD

[FDDs] SSD1 SSD0 [HDDs]
```

In the above example, SSD1 is the first SSD which means TESTRFA is socket 0, and SSD0 is the second SSD which means TESTRFA is socket 1.

2. Execute TESTRFA /Sn where n is the socket determined in step 1. For SSD0 in the above example, enter:

   TESTRFA /S1 /E

   For SSD1 in the above example, enter:

   TESTRFA /S0 /E

≡ Making copies of the PC-510 SSD

GETIMG.EXE is used to capture an image from an existing PICO FA drive. This is used to program SSD drives on other target systems from one "development" system.

1. To make a copy of the PC-510 to a local file, enter:

   GETIMG SSD1 <*filename*>

2. To make a copy of the PC-510 SSD to a remote file:

   a. Establish serial communications between the PC-510 and the desktop PC using SmartLINK.

   b. On the PC-510 enter:

      GETIMG SSD1 <*filename*>**/COM1**

   c. On the desktop PC:, exit SmartLINK by pressing <ALT><X> and then enter:

      GETIMGH <*filename*>**/COM1**

   d. Write the image, <*filename*>, to the host drive.

≡ Programming copies of the PC-510 SSD

PGMIMG.EXE is used to program an image from an existing PICO FA drive to other SSDs on target systems.

1. Run GETIMG.EXE to make a copy of the PC-510 SSD to a local file or GETIMGH.EXE to make a copy of the PC-510 SSD to a remote file. Refer to the above section, *Making copies of the PC-510 SSD*.
2. To program a copy of the PC-510 image to a target system from a host system:
   a. Establish serial communications between the PC-510 and the desktop PC using SmartLINK.
   b. On the PC-510, enter:

      PGMIMG SSD1 <*filename*>**/COM1**

   c. On the desktop PC:, exit SmartLINK by pressing <ALT><X> and then enter:

      PGMIMGH <*filename*>**/COM1**

   Write the image, <*filename*>, to the host drive.

≡ Programming a new BIOS into SSD1

To program a new BIOS into SSD1, issue one of the following commands:

PGMBIOS *filename* **SSD1**

or

PGMBIOS SSD0 SSD1

Note You may need to use the /P option when issuing the PGMBIOS command if the BIOSDEV jumper W2[5-6] is set to boot from the SSD being programmed.

You can create a new BIOS file (for adding your own extended BIOS), by running MAKEBIOS.BAT from the utility disk.

To boot using the new BIOS in SSD1, be certain that W2[5-6] is jumpered. To boot using BIOS in SSD0, be certain that W2[5-6] is **not** jumpered.

≡ Programming the video BIOS into an SSD

SSD0 and SSD1 can also contain the video BIOS. If you choose to use a monitor other than the default or flat panel display, you can reprogram the video BIOS by entering the following:

<drive>:PGMVIDEO <drive>:S64P80.DAT SSD1 /P

For a complete description on programming the video BIOS, see the *Programming the video BIOS* section in the *CRTs and flat panel displays* chapter. Refer also to this support command in the *Software utilities* appendix.

Chapter 20: User-defined jumper

≡ User-defined jumper

Jumpers W4[9-10] and W3[5-6] are user-defined jumper. For program direction, read the jumper by code in your program.

Table 20-1 User option jumper 1: W4

Pin	Label	Description
[9-10]*	U	User option jumper 1

* = default

Table 20-2 User option jumper 2: W3

Pin	Label	Description
[5-6]*	U2	User option jumper 2

* = default

Read jumpers

This section provides the definition for the Read jumpers function.

Function: fbh

Subfunction: 0Bh

Purpose: To read the on-board jumper settings.

Calling registers:

Ah	fbh
AL	0Bh
DX	ffffh

Return registers:

AL	Jumper information
bit	**state**
7	Not used
6	Not used
5	Not used
4	Not used
3	Not used
2	Not used
1	User option jumper U2
0	User option jumper U

Comments: This function returns the jumper settings.

Programming example:

```
/* The following example program reads the user defined
jumper */
unsigned char jumpers;
asm {
      mov      ax,0fb0bh
      mov      dx,0ffffh
      int      17h
      mov      jumpers, al
     }
    if(jumpers & 1)       /* look at bit 2*/
       printf("User jumper U installed\n);
    else
       printf("User jumper U not installed\n);

    /* note: jumper 2 not available on all boards */
    if (jumpers & 2)
       printf("User jumper U2 installed\n);
    else
       printf("User jumper U2 not installed\n);
```

Chapter 21: CPU power management

≡ Description

The power demands of a system can severely limit an application due to thermal constraints or the raw power usage in a battery-operated application. In order to maintain speed and efficiency, a software-controlled, power management system must be tailored to the application. Even if your application is operating within specified limits, a power management system may improve the life and reliability of your system by reducing thermal stress to the CPU.

The advance power management functions include:

- SUSPEND/RESUME operation via SMI input and software
- Slowing down the CPU by dividing the clock
- Contextual Save to Disk

Power management can be enabled in the PC-510 SETUP program and is adjusted with the PMISETUP program. DOS-supplied advanced power management (APM) programs, such as POWER.EXE are also supported. See the PC-510 utility disk for a list of example programs located in the \EXAMPLES directory. For more information on using the SETUP utility, refer to the *SETUP programs* chapter. For more information on using the PMISETUP utility, see the *PMISETUP* section later in this chapter.

≡ Power management overview

Power management is implemented via the software management interface (SMI) function, and provides multiple levels of management. The firmware is also capable of cooperative power management with an APM compatible driver or application, such as POWER.EXE. Cooperative power management allows power aware applications to control the power state of the system without depending on interrupts or device access to indicate that the CPU is actively executing application code. At the hardware level, the power management system cannot detect CPU activity except by monitoring bus activity such as interrupts or access to specific memory or I/O address ranges.

The hardware is capable of minimal levels of power management without interacting with the firmware at all. Once configured by the firmware, the DOZE timer and the CPU activity monitor (cool-down clocking mechanism) can slow the system clock to reduce power consumption. The DOZE timer monitors specific bus activity and reduces the system clock after periods of inactivity. The CDC mechanism simply guarantees that the CPU spends some specified portion of time at a reduced clock speed, either due to DOZE mode of firmware controlled reduced clock mode, or by forcing cool-down periods if neither of these occur.

In a stand-alone environment (no APM software active), the firmware works in conjunction with the hardware timers and monitoring functions to identify periods when certain devices or the entire system are inactive. Individual timers are supported for specific devices, including the hard disk, floppy disk and serial ports. Whenever these devices are not accessed for a specified period, they are powered down to reduce system power consumption. Whenever none of the monitored system devices has been accessed for a specified period of time, the performance of the system is reduced or the system is stopped altogether to further reduce power consumption.

In a cooperative environment, devices are still controlled by the firmware, but the CPU is never slowed or stopped without the consent of the APM software. Rather, the firmware notifies the software when a timer has expired or some other event has occurred which should place the system in a reduced power mode. The APM software polls the firmware for such events. Once an event has occurred, the software initiates the reduced power mode by acknowledging the event back to the firmware. The firmware then initiates the reduced power mode. The APM software can inquire "APM aware" applications to ensure that the reduced power mode is acceptable.

≡ Hardware controlled modes

The firmware assumes that keyboard, disk, and video access should prevent the system from entering DOZE mode. In addition, specific interrupts can be configured to reset the DOZE timer. DOZE mode is typically a reduced clock operation, but a stopped-clock mode is also supported. If the slow-clock mode is selected, the CPU clock is slowed from 33 MHz to 8 MHz. If stopped-clock mode is selected, the secondary DOZE timer is configured to restart the CPU clock whenever the timer interrupt occurs. This allows the CPU to maintain the system clock while in stopped-clock mode even though the CPU clock remains stopped for more than 90% of the time.

The CPU activity monitor (cool-down clocking mechanism) is intended to prevent thermal run-away in low airflow environments. It essentially counts the time that the CPU operates in full-speed mode and the time spent in reduced clock mode. If full-speed mode is maintained for a period of time that could cause excessive heat build-up, then the clock is reduced for a cool-down period to maintain an equilibrium level. The CPU clock is shifted from 33 MHz to 16.5 MHz for a pre-determined amount of time, back to 33 MHz, and then the CDC cycle begins again.

≡ Device power management

The hard disk, floppy disk, and serial ports are power managed on an individual basis. For each device, the firmware configures a hardware timer that is reset each time the device is accessed. When the device goes unaccessed for the duration of the timer, an SMI is generated to notify the firmware that the device is inactive. The firmware can then SUSPEND that device.

Before a device is SUSPENDed, or powered down, its context is saved in memory so that it can be restored to its active state when it is powered up. The timer is disabled on SUSPEND to prevent repetitive triggering, and the chipset is configured to generate another SMI when the device is accessed again. That SMI allows the firmware to restore power to the device and restore its context.

After the device power is restored by a triggering event, such as a keyboard stroke, the access SMI is disabled and the timer is restarted. This cycle may then be repeated. The status of each device is maintained to ensure that a powered-down device is not accessed for power-down repeatedly.

Devices other than the disks and serial ports are not monitored for activity, but can be individually powered down in reduced power states at the system level.

≡ System power management

At the system level, power management is very similar to the device level management, with a couple of exceptions. Cooperative management is supported, allowing an APM driver, such as POWER.EXE, to control the actual power state transitions. This is done by identifying power management events and reporting them to the APM driver via a polling mechanism. Power state transitions then occur at the request of the APM driver. Individual device states in the various system power states can be configured via CMOS locations to the extent at which the firmware has the ability to control them. For example, the video can remain ON during STANDBY, which makes STANDBY mode more transparent to the user, or it can be powered OFF during STANDBY to further reduce power. The parallel port may be powered OFF in STANDBY, or remain ON in STANDBY and powered OFF in SUSPEND, but on return to full speed it must be powered ON because there is no access SMI available. The disks and serial ports, on the other hand, may remain powered OFF after the system RESUMEs and can be powered ON when accessed.

The IDLE timer can be reset by numerous sources, including device accesses and interrupts. Note that it is possible for the IDLE timer configuration to be of shorter duration than the device timers. This means that the system can be deemed IDLE even though some of the devices are still active. When this occurs, the device power states are set according to their configuration in CMOS.

Note that the APM interface prevents the system from entering STANDBY or SUSPEND modes directly. These modes will be entered, but that will occur through the APM interface (INT 15h) at the request of the APM driver.

SUSPEND mode is the lowest power state that the system can attain while still powered. The CPU clock is stopped and all controllable devices are powered down. Because the devices are powered down and the CPU is not running, only an external event can cause the system to

RESUME normal operation. These events include the SUSPEND/ RESUME input (J17[3-4], OPTOB), the COM2 RI signal (Ring Indicator), and interrupts from selected sources located in the .PMI file. The devices which are powered ON when the system RESUMEs are specified in CMOS, loaded from the .PMI file. Devices which do not have associated access SMIs, must be powered up. In addition, since the CPU was stopped, the system time must be updated. If an APM driver is operating, it has the responsibility of updating the time when notified to do so. Otherwise, the firmware will update the DOS compatible system time if configured to do so. For operating systems with DOS compatible system clocks, this function should be disabled in CMOS. Since the clock does not run in SUSPEND mode and the system is not restarted by IRQ0 to maintain the time of day, the time must be reset when the system resumes. Normally, the BIOS can read the actual time from the real time clock and restore the operating system's timer from that value. However, some operating systems do not support the update methods utilized by the BIOS for this function. The time update can be enabled or disabled using the PC-510 SETUP program. In SETUP, the following options are available:

Power Management:	ENABLED or DISABLED
DOZE Clock (Slow, Stop):	SLOW or STOP
Time Updated After Suspend:	ENABLED or DISABLED

How to initiate the SUSPEND/RESUME option

1. In PC-510 SETUP and in a .PMI file, enable power management and select the following options:

   SETUP:

Power Management:	ENABLED
DOZE Clock (Slow, Stop):	SLOW
Time Updated After Suspend:	ENABLED

   TEST.PMI file:

pmi-enable=Y	Enables the power management

2. If SUSPEND is to be generated by:
   - A time-out, then in the same .PMI file, set the time delay, in minutes, for the "suspend-delay" option.

     TEST.PMI file:

suspend-delay=xx	Sets delay time before SUSPEND (x=0-31 minutes)

   - The external SUSPEND/RESUME signal, refer to the *Reset and remote suspend/resume* section in this chapter for signal requirements to be applied to J17.

3. In the same .PMI file, select any signal that will cause the system to resume. The options include IRQs, COM2 RI, and External PMI signal (EPMI), J17. Refer to the *IRQ routing and opto IRQs* chapter for the EPMI connection and signal requirements.

   The input used depends upon the ISP setup. The following are the default signals at J17:

   J17[1-2] OPTOA PMI
   J17[3-4] OPTOB SUSPEND/RESUME

   TEST.PMI file:

irq1-resume-reset=Y	Enables RESUME if IRQ1 occurs (keyboard input)
irq4-resume-reset=Y	Enables RESUME if IRQ4 occurs (COM1 input)
RI-resume-reset=Y	Enables RESUME if RI occurs (COM2 ring indicator)
RI-transitions=5	Specifies number of RI transitions (n) for RESUME (COM2 ring indicator)
EPMI-resume-reset=Y	Enables RESUME if EPMI occurs (external PMI signal)

4. Load the .PMI file changes by including the .PMI file on the PMISETUP command line. PMISETUP is located in the \UTILS directory:

   ```
   PC510 C:\> PMISETUP TEST.PMI
   ```

5. Hardware reset the system for the PMISETUP options to take effect. The PC-510 system is now ready for SUSPEND/RESUME.

6. Initiate a SUSPEND/RESUME input signal at J17[3-4] or allow the "suspend-delay" timer to expire. Refer to the *IRQ routing and opto IRQs* chapter for the EPMI connection and signal requirements.

7. The PC-510 system enters the SUSPEND mode, powering down any devices that can be powered down.

8. A system RESUME is generated by any event defined in the .PMI file or the when an external RESUME signal is applied at J17[3-4]. If a VGA monitor is attached, the video will return. If a hard drive is attached, the drive will not spin up until accessed.

Note The default signals at J17 are [1-2] PMI and [3-4] SUSPEND/RESUME. These signals may be changed by reprogramming the IRQ matrix. See the *IRQ routing and opto IRQs* chapter for more information on the IRQ matrix.

WAKEIRQ8.EXE is a sample TSR that wakes the CPU, using the CMOS clock, from SUSPEND mode after a 30 second delay. WAKEIRQ8.EXE and WAKEIRQ8 files are available in the \EXAMPLES directory on the PC-510 utility disk.

Refer to the default .PMI file in the *Power management configuration* section in this chapter for all of the power management options.

STANDBY mode is similar to hardware DOZE mode, except that it is firmware controlled and devices may be power managed as well as the CPU clock. STANDBY is controlled by software, such as POWER.EXE. Since the CPU may still be executing in STANDBY mode, access events may RESUME the system in addition to external inputs, such as interrupts. The firmware must configure the chipset to report these events to the firmware via an SMI. This allows the hardware to restore the CPU clock while notifying the firmware to restore power to the managed devices. On RESUME from STANDBY mode, all devices which cannot generate an access SMI are powered up and those which can generate an access SMI are powered up if specified in CMOS. Any device access or specified interrupt can cause the system to RESUME.

How to initiate the STANDBY option

1. In the PC-510 SETUP and in a .PMI file, enable power management and select the following options:

   SETUP:

Power Management:	ENABLED
DOZE Clock (Slow, Stop):	SLOW
Time Updated After Suspend:	ENABLED

   TEST.PMI:

pmi-enable=Y	Enables the power management
standby-delay=xx	Sets delay time before STANDBY (x=0-31 minutes)
fdd-to=xx	Sets the on-card (LPT1) floppy disk drive time-out value (x=0-31 minutes)
hdd-to=xx	Sets the hard drive time-out value (x=0-31 minutes)
COM1-to=xx	Sets the COM1 time-out value (x=0-31 minutes)
COM2-to=xx	Sets the COM2 time-out value (x=0-31 minutes)

   Set the time delay, in minutes, for the "standby-delay" option and devices to be powered down, such as drives and serial ports.

Note The hard drive and floppy drives are actually controlled by firmware and not by software such as POWER.EXE. The floppy must be on-card, controlled from the LPT1 port.

2. In the same .PMI file, select any signal that will cause the system to resume. The options only include IRQs.

TEST.PMI file:

irq1-standby-reset=Y	Enables reset of STANDBY mode if IRQ1 occurs
irq3-standby-reset=Y	Enables reset of STANDBY mode if IRQ3 occurs
irq4-standby-reset=Y	Enables reset of STANDBY mode if IRQ4 occurs
irq5-standby-reset=Y	Enables reset of STANDBY mode if IRQ5 occurs
irq6-standby-reset=Y	Enables reset of STANDBY mode if IRQ6 occurs
irq7-standby-reset=Y	Enables reset of STANDBY mode if IRQ7 occurs
irq8-standby-reset=Y	Enables reset of STANDBY mode if IRQ8 occurs
irq14-standby-reset=Y	Enables reset of STANDBY mode if IRQ14 occurs

3. Load the .PMI file changes by including the .PMI file on the PMISETUP command line. PMISETUP is located in the \UTILS directory:

   ```
   PC510 C:\> PMISETUP TEST.PMI
   ```

4. Hardware reset the system for the PMISETUP options to take effect. The PC-510 system is now ready to enter the STANDBY mode.

5. Initiate APM software, such as POWER.EXE.

6. The PC-510 system enters the SUSPEND mode as determined by the APM software, powering down any devices that can be powered down.

7. A system RESUME is generated by any event defined in the .PMI file or when an external RESUME signal is applied. If a VGA monitor is attached, the video will return. If a hard drive is attached, the drive will not spin up until accessed.

   Refer to the default .PMI file in the *Power management configuration* section in this chapter for all of the power management options.

≡ Save to disk

The firmware provides an additional SUSPEND mode which supports removal of system power. This mode is initiated through software or by the external power management input. In this mode, the context of the entire system is saved on the hard disk so that it can be restored completely when power is restored to the system. The system context includes all of the system memory, video memory, and the states of the hardware registers in all devices (interrupt controllers, DMA controllers, serial ports, keyboard controller, etc.). The firmware can only save and restore devices of which it is "aware", meaning those that are on-board and most standard VGA video controllers. This function may not be

fully functional for some extended system configurations. This function will only work with a hard drive and not with the on-board SSD flash drive or with a flash drive card.

After a Save To Disk function has been completed, the system must be reset to restore the context. After saving the context of the system to disk, all devices are powered down and the CPU is SUSPENDed. The validity of the system context on the hard disk is identified by marking a bit in the configuration EEPROM. On the next system reset, the validity of the context is checked in EEPROM and, if valid, is restored to the system memory and devices.

In order for the Save to Disk function to execute, the hard disk must be prepared using the PHDISK.EXE program. A special partition is saved on the disk which must be big enough to hold the system context. Generally speaking, this means the size of the installed system memory (typically 1 to 17 MB DRAM) plus the size of the video memory (typically 512 KB to 1 MB). However, a larger partition may be created in order to support additional system memory to be added at a later time.

WARNING!

PHDISK.EXE provides the same function as FDISK, but it also creates a special partition for the Save to Disk option. This will destroy all existing data on your hard drive.

The Save To Disk function may be disabled. If it is disabled, then the power management firmware will, upon detection of the external PMI signal (J17[3-4]), execute an interrupt 15h with register AX set to 0AA55h and register DX set to 1234h. This indicates a power down request when the PMI input signal is generated. PFHINT15.EXE is a sample TSR that prints "PFH" to the screen when the PMI signal is generated but the "save to disk" option is disabled. The PFHINT15.EXE and PFHINT15.CPP files are located in the \EXAMPLES directory on the PC-510 utility disk.

How to initiate the save to disk option

1. Use PHDISK.EXE, located in the \UTILS directory on the PC-510 utility disk, to prepare the hard drive.
2. In PC-510 SETUP and in a .PMI file, enable power management and select the following options:

   SETUP:

Power Management:	ENABLED
DOZE Clock (Slow, Stop):	SLOW
Time Updated After Suspend:	ENABLED

TEST.PMI:

pmi-enable=Y	Enables the power management
save-to-disk=Y	Enables save to disk feature

3. Load the .PMI file changes by including the .PMI file on the PMISETUP command line. PMISETUP is located in the \UTILS directory:

```
PC510 C:\> PMISETUP TEST.PMI
```

4. Hardware reset the system for the PMISETUP options to take effect. The PC-510 system is now ready to Save to Disk.

5. Initiate a PMI input signal at J17[1-2]. Refer to the *IRQ routing and opto IRQs* chapter for the PMI connection and signal generation.

Note The default signals at J17 are [1-2] PMI and [3-4] SUSPEND/RESUME signal. These signals may be changed by reprogramming the IRQ matrix. See the *IRQ routing and opto IRQs* chapter for more information on the IRQ matrix.

6. The system now performs a contextual save, saving all relevant information to the special disk partition.

7. The system will respond with "Please turn off your computer." Power down the system. The CPU enters SUSPEND mode. The validity of the system context on the hard disk is identified by marking a bit in the configuration EEPROM.

8. When the system is powered on, the validity of the context is checked in EEPROM. If valid, the system's context is restored to the system memory and devices, back to where it was before the PMI signal was generated.

≡ Power management configuration

The power management functions can be globally enabled or disabled in CMOS. The PC-510 SETUP.EXE and PMISETUP.EXE utilities provide an option for enabling or disabling power management.

Enabling power management

Whichever utility, SETUP or PMISETUP, is configured and saved (or loaded) last, that configuration is used for enabling or disabling power management. In other words, if the power management option is disabled in SETUP and then later a .PMI file which shows pmi-enable = Y is loaded with PMISETUP, the power management option in SETUP will now show power management as being enabled.

In PC-510 SETUP, the following options are available:

Power Management:	ENABLED or DISABLED
DOZE Clock (Slow, Stop):	SLOW or STOP

Time Updated After Suspend: ENABLED or DISABLED

In a .PMI file, the following option is available:

pmi-enable=Y/N Disables/enables the power management code

System timers

The system timers define the delays associated with power state transitions in the system. Three managed system power modes (in addition to full on) are supported, DOZE, STANDBY, and SUSPEND. Individual timers for system devices, including floppy disk, hard disk, and serial ports are also provided. The timers are described below:

In a .PMI file, the following options are available:

fdd-to=xx	Sets the on-card (LPT1) floppy disk drive time-out value (x=0-31 minutes)
hdd-to=xx	Sets the hard drive time-out value (x=0-31 minutes)
COM1-to=xx	Sets the COM1 time-out value (x=0-31 minutes)
COM2-to=xx	Sets the COM2 time-out value (x=0-31 minutes)
doze-delay=x	Sets DOZE time-out before STANDBY(x=0,2,8 seconds)
standby-delay=xx	Sets delay time before STANDBY (x=0-31 minutes)
suspend-delay=xx	Sets delay time before SUSPEND (x=0-31 minutes)

Doze timer enable and resets

The DOZE mode may be selected to be a SLOW clock or STOP clock mode and is determined in power management SETUP. Numerous sources may reset the DOZE timer, preventing entry to DOZE mode. The BIOS assumes that video, floppy, hard disk, and keyboard accesses should all reset the DOZE timer. In addition, various interrupts can be configured to reset the timer. DOZE timer 0 is used for all DOZE reset selections. DOZE timer 1 is used for the special case of the timer interrupt in a STOP clock mode. In this mode, DOZE timer 1 is configured for a 4 millisecond time-out, with only IRQ0 configured to reset DOZE timer 1. This allows the CPU to resume normal operation for 4 mS on each IRQ0 in order to maintain the time of day.

In the PC-510 SETUP, the following options are available:

Power Management: ENABLED or DISABLED
DOZE Clock (Slow, Stop): SLOW or STOP
Time Updated After Suspend: ENABLED or DISABLED

Interrupts that reset DOZE are configured in a .PMI file:

irq0-reset-doze=Y/N	Enables reset of DOZE clock if IRQ0 occurs
irq3-reset-doze=Y/N	Enables reset of DOZE clock if IRQ3 occurs
irq4-reset-doze=Y/N	Enables reset of DOZE clock if IRQ4 occurs
irq5-reset-doze=Y/N	Enables reset of DOZE clock if IRQ5 occurs
irq7-reset-doze=Y/N	Enables reset of DOZE clock if IRQ7 occurs
irq8-reset-doze=Y/N	Enables reset of DOZE clock if IRQ8 occurs
irq12-reset-doze=Y/N	Enables reset of DOZE clock if IRQ12 occurs
irq13-reset-doze=Y/N	Enables reset of DOZE clock if IRQ13 occurs

IDLE timer resets

The IDLE timer monitors system activity to prevent the system from entering STANDBY or SUSPEND modes if bus activity indicates that the system is busy. Access to these devices will also cause the system to RESUME from STANDBY mode. The bus activities that are monitored are configured in a .PMI file:

EPMI-reset-idle=Y/N	Enables reset of IDLE timer if EPMI occurs
LCD-reset-idle=Y/N	LCD/VGA access resets IDLE timer
COM1-reset-idle=Y/N	Enables reset of IDLE timer if COM1 access occurs
COM2-reset-idle=Y/N	Enables reset of IDLE timer if COM2 access occurs
LPT-reset-idle=Y/N	Enables reset of IDLE timer if LPT access occurs
KBD-reset-idle=Y/N	Enables reset of IDLE timer if Keyboard access occurs
FDD-reset-idle=Y/N	Enables reset of IDLE timer if Floppy Disk Drive access occurs
HDD-reset-idle=Y/N	Enables reset of IDLE timer if Hard Disk Drive access occurs

Interrupts in the system can also reset the IDLE timer to prevent entry into reduced power modes. These interrupts should be enabled to reset the IDLE timer if they indicate that the system is active. The interrupts to reset the IDLE timer are configured in a .PMI file:

irq0-reset-idle=Y/N	Enables reset of IDLE clock if IRQ0 occurs
irq1-reset-idle=Y/N	Enables reset of IDLE clock if IRQ1 occurs
irq3-reset-idle=Y/N	Enables reset of IDLE clock if IRQ3 occurs
irq4-reset-idle=Y/N	Enables reset of IDLE clock if IRQ4 occurs
irq5-reset-idle=Y/N	Enables reset of IDLE clock if IRQ5 occurs
irq6-reset-idle=Y/N	Enables reset of IDLE clock if IRQ6 occurs

irq7-reset-idle=Y/N	Enables reset of IDLE clock if IRQ7 occurs
irq8-reset-idle=Y/N	Enables reset of IDLE clock if IRQ8 occurs
irq9-reset-idle=Y/N	Enables reset of IDLE clock if IRQ9 occurs
irq10-reset-idle=Y/N	Enables reset of IDLE clock if IRQ10 occurs
irq11-reset-idle=Y/N	Enables reset of IDLE clock if IRQ11 occurs
irq12-reset-idle=Y/N	Enables reset of IDLE clock if IRQ12 occurs
irq13-reset-idle=Y/N	Enables reset of IDLE clock if IRQ13 occurs
irq14-reset-idle=Y/N	Enables reset of IDLE clock if IRQ14 occurs
irq15-reset-idle=Y/N	Enables reset of IDLE clock if IRQ15 occurs

RESUME from STANDBY

The events which can resume the system from STANDBY mode to full power can also be selected. Access to the primary devices can resume the system if access to those devices are selected to reset the IDLE timer. In addition, interrupts can be selected to resume the system from STANDBY mode. The interrupts to resume from STANDBY are configured in a .PMI file:

irq0-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ0 occurs
irq1-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ1 occurs
irq3-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ3 occurs
irq4-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ4 occurs
irq5-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ5 occurs
irq6-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ6 occurs
irq7-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ7 occurs
irq8-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ8 occurs
irq9-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ9 occurs
irq10-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ10 occurs
irq11-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ11 occurs
irq12-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ12 occurs
irq13-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ13 occurs
irq14-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ14 occurs
irq15-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ15 occurs

When the system resumes from STANDBY mode, the CPU clock is restored to full speed. In addition, some or all of the devices are restored to full power. The video (if suspended in STANDBY mode) and parallel port, are always powered up. The following devices may be held in SUSPEND until they are accessed:

- COM1
- COM2

- On-board floppy disk (LPT1 port)
- Hard disk

RESUME from SUSPEND

SUSPEND mode is the lowest power mode supported by power management. In this mode all devices are powered down and the CPU is placed in SUSPEND mode and the clock is stopped. In addition to the SUSPEND/RESUME input, the activities that may resume the system from SUSPEND mode can be selected in the .PMI file.

The Ring Indicator from COM2 can RESUME the system after a specified number of transitions. This function may be enabled and the number of transitions specified in the .PMI file.

RI-resume-reset=Y/N	Enables RESUME if RI occurs (COM2 ring indicator)
RI-transitions=n	Specifies number of RI transitions (n) for RESUME (COM2 ring indicator)

The EPMI (External PMI OPTOA, J17[1-2]) input can also cause the system to RESUME. This function is enabled in the .PMI file.

EPMI-resume-reset=Y/N	Enables RESUME timer if EPMI occurs

Finally, interrupts may cause the system to RESUME. This is particularly useful for activities such as a key on the keyboard being pressed. If any interrupt is to cause the system to RESUME, then the interrupt must be selected in the .PMI file.

resume-irqs-enable=Y/N	Enables RESUME from RESUME IRQ group
irq1-resume-reset=Y/N	Enables RESUME if IRQ1 occurs
irq3-resume-reset=Y/N	Enables RESUME if IRQ3 occurs
irq4-resume-reset=Y/N	Enables RESUME if IRQ4 occurs
irq5-resume-reset=Y/N	Enables RESUME if IRQ5 occurs
irq7-resume-reset=Y/N	Enables RESUME if IRQ7 occurs
irq8-resume-reset=Y/N	Enables RESUME if IRQ8 occurs
irq9-resume-reset=Y/N	Enables RESUME if IRQ9 occurs
irq10-resume-reset=Y/N	Enables RESUME if IRQ10 occurs
irq11-resume-reset=Y/N	Enables RESUME if IRQ11 occurs
irq12-resume-reset=Y/N	Enables RESUME if IRQ12 occurs
irq14-resume-reset=Y/N	Enables RESUME if IRQ14 occurs
irq15-resume-reset=Y/N	Enables RESUME if IRQ15 occurs

Remote suspend/resume inputs

The PC-510 provides a remote suspend/resume input. The opto-isolated input is located at J17[3-4]. The opto requires a 5V input pulse and then triggers a "suspend" or "resume from suspend" on the trailing edge of the pulse. The minimum pulse width for a 5V pulse is 50 µS in order to signal either suspend or resume.

If the required options are selected in PMISETUP.EXE, other devices, such as the input from a serial port or the ring indicator from a modem connected to COM2, will cause the PC-510 to resume.

First Suspend/Resume Pulse:

The on-board SVGA ceases to display video and the hard drive spins down.

Second Suspend/Resume Pulse:

The video returns but the hard drive does not spin up again until accessed.

Note See the *Accessories* appendix for connector information on the remote suspend/resume connector.

External PMI interrupt

In case of a power failure, the power management code is capable of properly resetting the system, saving the state of the system to disk, or generating an INT 15h. The power failure is signaled by activation of the external power management input, J17[1-2]. Once activated, the system either performs a System Reset, performs a Save to Disk operation, or generates an INT 15h. These functions are enabled in a .PMI file.

1. System Reset

   The PMI file contains:

pfh-enable=Y	Enables power fail options
pfh-reset=Y	Enables system reset

2. Save to Disk

   The PMI file contains:

pfh-enable=Y	Enables power fail options
pfh-reset=N	Disables system reset
save-to-disk=Y	Enables save to disk feature

   Refer to the *Save to disk* section in this chapter for more information.

3. INT 15h

   The PMI file contains:

pfh-enable=Y	Enables power fail options
pfh-reset=N	Disables system reset
save-to-disk=N	Disables save to disk feature

4. To disable all three options:

   The PMI file contains:

   pfh-enable=N Disables power fail options

Thermal management

Automatic thermal management of the CPU is provided by measuring the full speed operation of the CPU verses a thermal equilibrium value. During thermal management, CPU activity is monitored and the activity is considered against other criteria. When determined that the activity level has exceeded a certain level, the CPU speed is divided in half from 33 MHz to 16.5 MHz for about 30 seconds, the CPU speed is increased to 33 MHz and the thermal management cycle begins again. If thermal management is disabled, the CPU will run "full on" without any intervention from the firmware. Default configuration from Octagon Systems has thermal management enabled.

WARNING!

Due to the heat generated by the 586 processor, it is highly recommended that thermal management is always enabled and the CPU *not* run in "full on" condition. If thermal management is enabled and DOZE is enabled, the PC-510 will operate to the published temperature specifications. If thermal management is disabled, care must be taken not to damage or shorten the life of the CPU. Adequate ventilation, preferably with a fan and ample room around the CPU and card cage must be provided. Please contact Octagon Technical Support if the thermal management is to be disabled to discuss your situation.

The option for thermal management is in a .PMI file:

thermal-management=Y/N Enables thermal management features (cool-down clocking)

Bitblt engine

W2[3-4] toggles the CPU clock speed between 120 and 133 MHz. When pins 3 and 4 are jumpered, the CPU clock speed operates at 133 MHz. When pins 3 and 4 are not jumpered, then the CPU clock speed operates at 120 MHz.

W2[3-4] optimizes the PC-510's temperature performance when the CPU is operating in accelerated GUI environment. When power management is enabled, you **must** remove W2[3-4] to use the video accelerator. This ensures that the PC-510's operating temperature is between –40°C and +70°C.

However, if power consumption is not a major concern for your system when using the video accelerator function, Octagon Systems strongly recommends that you disable power management and install W2[3-4]. This enables the CPU to operate at full clock speed (133 MHz) and still maintain the PC-510's temperature performance range between –40°C and +45°C.

Table 21-1 Enhanced mode, CPU clock speed: W2[3-4]

Video accelerator	Power management	W2[3-4]	Operating clock speed	
Yes	Yes	Jumpered	133 MHz	Not recommended
Yes	Yes	Not jumpered	120 MHz	Recommended
Yes	No	Jumpered	133 MHz	Recommended
No	Don't care	Don't care		

≡ PMISETUP

The PMISETUP program allows modification of the 82C465 registers and optionally the serial EEPROM data associated with the 82C465/ CMOS registers. The command line format for the PMISETUP program is as follows:

PMISETUP *inputfilename* [**/SHOWALL**] [**/DEFAULT**] [**/P**] [**/?**]

PMISETUP will parse a file using KEYWORD=nn[type] options. One keyword can be specified per line, characters after a semicolon ";" will be regarded as comments. Blank lines are ignored. If multiple lines contain the same keyword, the last value will be used. Keywords and values are not case sensitive.

A sample input file, TEST.PMI, is as follows:

pmi-enable=Y	Disables/enables the power management code
doze-delay=2	Sets DOZE time-out to 2 seconds before standby
hdd-to=10	Sets the hard drive time-out to 10 minutes.

Load the .PMI file changes by including the .PMI file on the PMISETUP command line. PMISETUP is located in the \UTILS directory:

```
PC510 C:\> PMISETUP TEST.PMI
```

The output from PMISETUP will show all selectable options and their current values even when not specified when the /SHOWALL option is used.

When the /DEFAULT option is used, default settings are first loaded before the keywords are parsed. Refer to the default PMI configuration later in this chapter.

When the /P option is used with the /SHOWALL, the display pauses between each displayed page of information.

When the /? option is used, all other options are ignored and a "help display" is presented to the user. A <CR> keystroke between each page is necessary to continue to the next page of help.

If an error occurs during parsing, the line in question will be displayed and an ERRORLEVEL returned. For example:

```
>> Parameter out of range error.  Line follows:
hdd-to=50
The correct range is 0-31 minutes
```

or

```
>> Unknown keyword error in input file line 7.  Line follows:
standbuy-delay=10
Standby was spelled incorrectly.
```

The following ERRORLEVELs will be returned:

0 — No errors occurred.

1 — Unable to save to serial EEPROM.

2 — Configuration file not found.

3 — Parsing error or out of range error.

In PMISETUP, the following options are available and can be included in a .PMI file which is loaded by PMISETUP.EXE. PMISETUP.EXE is located in the \UTILS directory:

The following are the keywords which are used. To disable options, either an "N" or "0" is used, depending on the option.

pmi-enable=Y/N	Disables/enables the power management code
fdd-to=xx	Sets the on-card (LPT1) floppy disk drive time-out value (x=0-31 minutes)
hdd-to=xx	Sets the hard drive time-out value (x=0-31 minutes)
COM1-to=xx	Sets the COM1 time-out value (x=0-31 minutes)
COM2-to=xx	Sets the COM2 time-out value (x=0-31 minutes)
doze-delay=x	Sets DOZE time-out before STANDBY (x=0,2,8 seconds)
standby-delay=xx	Sets delay time before STANDBY (x=0-31 minutes)
suspend-delay=xx	Sets delay time before SUSPEND (x=0-31 minutes)

irq0-reset-doze=Y/N	Enables reset of DOZE clock if IRQ0 occurs
irq3-reset-doze=Y/N	Enables reset of DOZE clock if IRQ3 occurs
irq4-reset-doze=Y/N	Enables reset of DOZE clock if IRQ4 occurs
irq5-reset-doze=Y/N	Enables reset of DOZE clock if IRQ5 occurs
irq7-reset-doze=Y/N	Enables reset of DOZE clock if IRQ7 occurs

irq8-reset-doze=Y/N	Enables reset of DOZE clock if IRQ8 occurs
irq12-reset-doze=Y/N	Enables reset of DOZE clock if IRQ12 occurs
irq13-reset-doze=Y/N	Enables reset of DOZE clock if IRQ13 occurs
irq0-reset-idle=Y/N	Enables reset of IDLE clock if IRQ0 occurs
irq1-reset-idle=Y/N	Enables reset of IDLE clock if IRQ1 occurs
irq3-reset-idle=Y/N	Enables reset of IDLE clock if IRQ3 occurs
irq4-reset-idle=Y/N	Enables reset of IDLE clock if IRQ4 occurs
irq5-reset-idle=Y/N	Enables reset of IDLE clock if IRQ5 occurs
irq6-reset-idle=Y/N	Enables reset of IDLE clock if IRQ6 occurs
irq7-reset-idle=Y/N	Enables reset of IDLE clock if IRQ7 occurs
irq8-reset-idle=Y/N	Enables reset of IDLE clock if IRQ8 occurs
irq9-reset-idle=Y/N	Enables reset of IDLE clock if IRQ9 occurs
irq10-reset-idle=Y/N	Enables reset of IDLE clock if IRQ10 occurs
irq11-reset-idle=Y/N	Enables reset of IDLE clock if IRQ11 occurs
irq12-reset-idle=Y/N	Enables reset of IDLE clock if IRQ12 occurs
irq13-reset-idle=Y/N	Enables reset of IDLE clock if IRQ13 occurs
irq14-reset-idle=Y/N	Enables reset of IDLE clock if IRQ14 occurs
irq15-reset-idle=Y/N	Enables reset of IDLE clock if IRQ15 occurs
save-to-disk=Y/N	Enables save to disk feature
thermal-management=Y/N	Enables thermal management features (CDC)
irq0-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ0 occurs
irq1-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ1 occurs
irq3-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ3 occurs
irq4-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ4 occurs
irq5-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ5 occurs
irq6-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ6 occurs
irq7-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ7 occurs
irq8-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ8 occurs
irq9-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ9 occurs
irq10-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ10 occurs
irq11-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ11 occurs
irq12-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ12 occurs
irq13-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ13 occurs
irq14-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ14 occurs
irq15-standby-reset=Y/N	Enables reset of STANDBY mode if IRQ15 occurs
resume-irqs-enable=Y/N	Enables RESUME from RESUME IRQ group

irq1-resume-reset=Y/N	Enables RESUME if IRQ1 occurs
irq3-resume-reset=Y/N	Enables RESUME if IRQ3 occurs
irq4-resume-reset=Y/N	Enables RESUME if IRQ4 occurs
irq5-resume-reset=Y/N	Enables RESUME if IRQ5 occurs
irq7-resume-reset=Y/N	Enables RESUME if IRQ7 occurs
irq8-resume-reset=Y/N	Enables RESUME if IRQ8 occurs
irq9-resume-reset=Y/N	Enables RESUME if IRQ9 occurs
irq10-resume-reset=Y/N	Enables RESUME if IRQ10 occurs
irq11-resume-reset=Y/N	Enables RESUME if IRQ11 occurs
irq12-resume-reset=Y/N	Enables RESUME if IRQ12 occurs
irq14-resume-reset=Y/N	Enables RESUME if IRQ14 occurs
irq15-resume-reset=Y/N	Enables RESUME if IRQ15 occurs

RI-resume-reset=Y/N	Enables RESUME if RI occurs (COM2 ring indicator)
RI-transitions=n	Specifies number of RI transitions (n) for RESUME (COM2 ring indicator)
EPMI-resume-reset=Y/N	Enables RESUME timer if EPMI occurs
EPMI-reset-idle=Y/N	Enables reset of IDLE timer if EPMI occurs
LCD-reset-idle=Y/N	LCD/VGA access resets IDLE timer
COM1-reset-idle=Y/N	Enables reset of IDLE timer if COM1 access occurs
COM2-reset-idle=Y/N	Enables reset of IDLE timer if COM2 access occurs
LPT-reset-idle=Y/N	Enables reset of IDLE timer if LPT access occurs
KBD-reset-idle=Y/N	Enables reset of IDLE timer if Keyboard access occurs
FDD-reset-idle=Y/N	Enables reset of IDLE timer if Floppy Disk access occurs
HDD-reset-idle=Y/N	Enables reset of IDLE timer if Hard Disk Drive access occurs
pfh-enable=Y/N	Enables power fail options
pfh-reset=Y/N	Enables power fail reset

PMISETUP default PMI configuration

pmi-enable = Y
fdd-to = 0
hdd-to = 0
COM1-to = 0
COM2-to = 0
doze-delay = 8
standby-delay = 0

```
suspend-delay = 0
irq0-reset-doze = N
irq3-reset-doze = N
irq4-reset-doze = Y
irq5-reset-doze = N
irq7-reset-doze = N
irq8-reset-doze = N
irq12-reset-doze = N
irq13-reset-doze = Y
irq0-reset-idle = N
irq1-reset-idle = Y
irq3-reset-idle = Y
irq4-reset-idle = Y
irq5-reset-idle = Y
irq6-reset-idle = N
irq7-reset-idle = Y
irq8-reset-idle = Y
irq9-reset-idle = N
irq10-reset-idle = N
irq11-reset-idle = N
irq12-reset-idle = N
irq13-reset-idle = Y
irq14-reset-idle = Y
irq15-reset-idle = N
save-to-disk = N
thermal-management = Y
irq0-standby-reset = N
irq1-standby-reset = Y
irq3-standby-reset = Y
irq4-standby-reset = Y
irq5-standby-reset = Y
irq6-standby-reset = Y
irq7-standby-reset = Y
irq8-standby-reset = Y
irq9-standby-reset = N
irq10-standby-reset = N
irq11-standby-reset = N
irq12-standby-reset = N
irq13-standby-reset = N
irq14-standby-reset = Y
irq15-standby-reset = N
resume-irqs-enable = Y
irq1-resume-reset = Y
irq3-resume-reset = Y
irq4-resume-reset = Y
irq5-resume-reset = N
irq7-resume-reset = N
irq8-resume-reset = Y
irq9-resume-reset = N
irq10-resume-reset = N
irq11-resume-reset = N
irq12-resume-reset = N
```

```
irq14-resume-reset = N
irq15-resume-reset = N
RI-resume-reset = Y
RI-transitions = 5
EPMI-resume-reset = Y
EPMI-reset-idle = Y
LCD-reset-idle = Y
COM1-reset-idle = Y
COM2-reset-idle = Y
LPT-reset-idle = Y
KBD-reset-idle = Y
FDD-reset-idle = Y
HDD-reset-idle = Y
CDC-beep = Y
COM1-suspend=Y
COM2-suspend=Y
COM1-buffer-suspend=Y
COM2-buffer-suspend=Y
```

Chapter 22: Troubleshooting

If your system is not working properly, check the following items:

No screen activity – checking console serial communications

If you do not get the sign-on message after bootup:

1. Make sure all PC/104 cards are removed from the PC-510. This ensures that other cards are not interacting with the PC-510.
2. Change W2[1-2]/W3[1-2]. Depending upon your current ROM enable and jumper state, these jumpers disable the video section. See the *Console devices* chapter for further instructions on how to enable/disable the video BIOS device.
3. The VTC-20F serial cable turns the PC-510 serial port into a 9-pin AT serial port. Make sure a null modem adapter is installed on the other end, and that the assembly is inserted into the proper serial port on the PC. Make sure the VTC-20F serial cable is connected to J7 of the PC-510.
4. Make sure your power module provides +5V (+/-0.25V) and at least 2.5A of current.
5. After verifying the above conditions, you can monitor voltage levels by connecting an oscilloscope between the TxD* line on J7 (pin 5) and ground. After powerup, you should see a burst of activity on the oscilloscope screen. The voltage level should switch between +/-8V. This test verifies that the CPU is active and that the transmit from COM1 is functional.

Garbled serial console screen activity

If you do get activity on your console screen but the message is garbled, check the following:

1. Remove USESETUP W2[9-10] to force 9600, N, 8, 1 for COM1.
2. If you are using PC SmartLINK, make sure you have configured the software for 9600 baud and have selected the correct serial port for communicating with your PC. Refer to the PC SmartLINK manual for information on selecting the baud rate.
3. If you are using communications software other than PC SmartLINK, Octagon cannot guarantee the operation. Make sure that the software parameters are set to match those of the PC-510: 9600 baud, 8 bits, 1 stop bit, no parity.

System generates a BIOS message but locks up when booting from SSD1

1. Remove W2[9-10] and reboot. When PICO FA prompts you, select SSD1 as the first drive and second drive.
2. Display the directory of SSD1 and verify that all the necessary boot files exist. Copy any missing files to SSD1.
3. If no files are missing, remake SSD1 to overwrite any files which may have become corrupted. In addition, you may want to do a **PFORMAT** and **SYS** to SSD1.
4. If SSD1 does not boot, install a floppy in the system, reboot from it, and remake SSD1.

PICO FA reports a drive, but issuing a DIR generates an error message

1. The SSD may not be formatted. Run either of the following:

   PFORMAT H*n*

   or

   PFORMAT H*n* **/m**

   where *n* represents the hard drive number.

For more information, see the on *Save and run programs* chapter.

PICO FA does not report the drive

1. Run SETSSD and make sure it is correct.
2. Make sure that W3[3-4] is jumpered or that PICOFA.SYS is in your CONFIG.SYS file of your floppy hard drive.
3. Install a jumper on W2[9-10].
4. Reboot your system.

System will not recognize hard drive

1. Run SETUP and confirm that on-board IDE interface is enabled.
2. Try changing Primary Master Fixed Disk to User and specify Heads, Sectors, and Cylinders.
3. Check hard drive Master/Slave jumpers.

System locks up after powerdown/powerup

If the power supply does not drain below 0.7V, the CMOS components on the card will act like diodes and forward bias. This is typically caused by using power supplies that have large output capacitors. Either use a different power supply that discharges faster, leave the power off until the supply has adequate time to discharge or place a 100 ohm, large wattage resistor across the output capacitor.

≡ Technical assistance

Carefully recheck your system before calling Technical Support. Run as many tests as possible; the more information you can provide, the easier it will be for the Technical Support staff to help you solve the problem.

For technical assistance, please call 303-426-4521.

Overview: Section 4 – Appendices

Section 4 contains a series of appendices which provides additional information about the PC-510.

Appendix A: Technical data
Appendix B: Software utilities
Appendix C: Third party support
Appendix D : Accessories

Appendix A: *Technical data*

≡ Technical specifications

CPU

586-133 MHz
(120MHz jumper selectable for temperature enhancement)

Local bus clock

66MHz
(40MHz when in 120MHz mode)

BIOS

AT compatible with industrial extensions.

DRAM

1 MB DRAM is soldered on-card (standard). Field expandable to 48 MB using 32 MB DIMM (optional). On-card DRAM of 4 MB or 16 MB is available under OEM contract.

Floppy drive

Floppy drive support via the floppy drive connector.

Hard drive

Hard drive BIOS supported using external hard drive controller which allows extended IDE drives larger than 528 MB.

Solid-state disk 0

Supports a 512K EPROM or 512K flash. 512K SRAM is available under OEM contract.

Solid-state disk 1

2 MB flash soldered on-card. 1 MB flash soldered on-card is available under OEM contract.

ROM-DOS

DOS 6.22 compatible.

Serial I/O

COM1 through COM6 are 16C550 compatible.

Parallel port

LPT1 is PC compatible with multifunctional capability.

Battery backup

AT style battery.

Power requirements

5V ±0.25V
586 processor

Full speed:	1.84 Amps typical
Slow clock:	770 mA typical
Stop clock:	660 mA typical
Suspend:	540 mA typical

Voltage supervisor

Reset threshold: +5V supply > 4.65V typical

Environmental specifications

-40° to 70° C operating
-55° to 90° C nonoperating
RH 5% to 95%, noncondensing

Size

5.75" x 8.00" x 0.9375"

Watchdog timer

Default time-out is typically 1.6 seconds (1.0 seconds minimum) software enabled and strobed. Disabled on powerup and reset. Controls are through built-in, enhanced INT 17h function calls.

Bus mastering

Bus mastering is supported.

Table A-1 PC-510 memory map

Address	Description
00000h-9FFFFh	System memory
A0000h-BFFFFh	Off–card memory
C0000h-C7FFFh	Video BIOS, 1st 32 KB
C8000h-CFFFFh	Video BIOS, 2nd 32KB
D0000h-D7FFFh	Off–card memory
D8000h-DFFFFh	PICOFA BIOS extension area
E0000h-E7FFFh	32 KB BIOS extension area (reserved for power management)
E8000h-EFFFFh	32 KB SSD memory paging window
F0000h-FFFFFh	64 KB BIOS area
100000h-2FFFFFh	47 MB addressable extended memory

Table A-2 PC-510 I/O map

Hex range	Function
0000-00A7h*	System I/O functions
00A8-00AFh*	Red LED Control: D7 = 1 (LED on); D7 = 0 (LED off). Also functions as default status register.
00A8-00AFh	82C602A buffer enable (read)
00A8-00AFh	Green LED Control: D6 = 1 (LED on); D6 = 0 (LED off)
00B0-00FFh	System I/O functions
0100-0207h	Off–card I/O space
0208-020Bh	OctaGlue register 0 (read/write access) (no SEEP clk)
020C-020Fh	OctaGlue register 1 (read/write access) (watchdog IOR strobe) (no SEEP clk)
0210-0213h	OctaGlue register 0 (read access) (SEEP clk)
0214-0217h	OctaGlue register 1 (read access) (serial EEPROM, read/write access) (watchdog IOR strobe)
0278-027Bh	Bidirectional parallel port (LPT1)
02F8-02FFh	COM2, configurable in SETUP
0378-037Bh	Bidirectional parallel port (LPT1), configurable in SETUP
03F8-03FFh	COM1, configurable in SETUP
0320-0327h	COM5 default configurable with SETIRQ_. Alternate addresses are 120-13F, 340-35F, and 140-15F.
0328-032Fh	COM6 default configurable with SETIRQ_. Alternate base addresses are 128-12F, 348-34F, and 148-14F.
0334-0337h	EZ I/O 1 default configurable with SETIRQ_. Alternate addresses are 134-137, 154-157, and 354-357.
0330-0333h	EZ I/O 2 default configurable with SETIRQ_. Alternate base addresses are 130-133, 150-153, and 350-353.
0338-033Fh	Interrupt status default location. Alternate addresses are 138-13F, 158-15F, and 358-35F.

* = default port addresses

Table A-3 I/O map (Latched registered outputs via OctaGlue: Address at X0A8h)

Function	Port 0A8H position
Green LED	Bit 7, I/O read/write: 0 = on; 1 = off
Amber LED	Bit 6, I/O read/write: 0 = on; 1 = off
Extended CMOS enable	Bit 5, I/O read/write: 0 = on; 1 = off
MAX 211 enable for ring indicate	Bit 4, I/O read/write: 0 = on; 1 = off
Super I/O enable	Bit 3, I/O read/write: 0 = on; 1 = off
LCD bias up	Bit 2, I/O read/write: 0 = on; 1 = off
LCD bias down	Bit 1, I/O read/write: 0 = on; 1 = off
Interrupt routing matrix program enable	Bit 0, I/O read/write: 0 = on; 1 = off

Table A-4 I/O map (Configuration inputs via OctaGlue: Address at X0A9h)

Function	Label	Description
IOREGSEL_A		Bit 5 I/O read: 0 = on, 1 = off
IOREGSEL_B		Bit 4, I/O read: 0 = on, 1 = off
RS–485		Bit 3, I/O read: 0 = on, 1 = off
User–option 1	U2	Bit 1, I/O read: 0 = on, 1 = off
User–option 2	U	Bit 0, I/O read: 0 = on, 1 = off

Table A-5 COM1 available addresses

COM1 available addresses	
220h	2F8h
228h	338h
238h	3E8h
2E0h	3F8h*
2E8h	

* = default

Table A-6 COM2 available addresses

COM2 available addresses	
220h	2F8h*
228h	338h
238h	3E8h
2E0h	3F8h
2E8h	

* = default

Table A-7 Available LPT1 port addresses

LPT1 port addresses
278H
378H*
3BCH

* = default

≡ Jumper settings

Table A-8 RS-485 termination select jumper: W1

Pins	Description
[1–2]	No function, used for shunt storage
[3–4]	No function, used for shunt storage
[5–6]*	No function, used for shunt storage
[7–8]	RS–485 terminated(–), idle line at space
[9–10]	RS–485 terminated(+), idle line at space
[7–9]*	RS–485 terminated(–), idle line at mark
[8–10]*	RS–485 terminated(+), idle line at mark

* = default, pins jumpered.

Table A-9 BIOS and boot option jumper: W2

Pins	Label	Description
[1–2]*	V0	C0000–C7FFF BIOS region toggle** (video BIOS region 1)
[3–4]	E	Enhanced mode, CPU clock speed: on = 133MHz; off = 120MHz
[5–6]*	B	BIOS device: on = SSD1; off = SSD0
[7–8]*	T	SSD0 type: on = flash/SRAM; off = EPROM
[9–10]*	S	Use SETUP information: on = EEPROM; off = BIOS default

* = default, pins jumpered
** = Toggles in BIOS extension areas work in combination with toggles in the SETUP BIOS extension areas. See the *Console devices* chapter for more information on the BIOS regions.

Table A-10 Auxiliary option jumper: W3

Pins	Label	Description
[1–2]*	V1	C8000–CFFFF BIOS region toggle** (video BIOS region 2)
[3–4]*	X	D8000–DFFFF BIOS region toggle*** (PICO FA)
[5–6]*	U2	User option jumper 2
[7–8]*	VE	VGA controller: on = enabled; off = disabled
[9–10]	I	IRQ matrix: on = disabled; off = enabled

* = factory default, pins jumpered
** = Toggles in BIOS extension areas work in combination with toggles in the SETUP BIOS extension areas. See the *Console devices* chapter for more information on BIOS regions.
*** = Enables or disables PICO Flash Array extended BIOS.

Table A-11 EZ I/O pull-up/pull-down, user option jumper: W4

Pins	Label	Description
[1–2]*		EZ I/O 1 pull up to +5V
[2–4]		EZ I/O 1 pull down to Gnd
[5–6]*		EZ I/O 2 pull up to +5V
[6–8]		EZ I/O 2 pull down to Gnd
[9–10]*	U	User option jumper 1

* = default, pins jumpered

Table A-12 SRAM battery backup jumper: W5

Pins	Description
W5[1-3, 2-4, 5-7, 8-10] W2[7-8]	SRAM with battery backup*
W5[1-2, 3-4, 5-6, 9-10] W2[7-8]	Flash
W5[1-2, 3-4, 5-6, 9-10]	EPROM**

* = default, pins jumpered
** = W2[7-8] is not jumpered

Table A-13 Jupiter module antenna voltage select: W6

Pins	Description
[1–2]	12V*
[1–3]	5V

* = default, pins jumpered

Table A-14 Flat panel interface voltage select: W8

Pins	Description
[1–2]	5V*
[3–4]	3.3V

* = default, pins jumpered

Table A-15 Inverted shift clock signal voltage level select: W9

Pins	Description
[1–2]	3.3V
[3–4]	5V*

* = default, pins jumpered

≡ Connector pinouts

Table A-16 Power connector: P8, P9

Pin	Description (P8)	Pin	Description (P9)
1	N.C.	1	Gnd
2	+5V	2	Gnd
3	+12V	3	–5V
4	–12V	4	+5V
5	Gnd	5	+5V
6	Gnd	6	+5V

Table A-17 Speaker connector: J1

Pin	Function
1	Speaker drive
2	NC
3	Gnd
4	+5V Safe

Table A-18 Keyboard connector: J2

Pin	Function
1	Keyboard data
2	NC
3	Gnd
4	+5V Safe
5	Keyboard clock
6	NC
7	SHLD0
8	SHLD1

Table A-19 Mouse connector: J3

Pin	Function
1	Mouse data
2	NC
3	Gnd
4	+5V Safe
5	Mouse clock
6	NC
7	SHLD0
8	SHLD1

Table A-20 AT and industrial serial for COM3 and COM4: J4

Pin	COM3 (standard) AT serial	COM3 (optional) industrial serial	Pin	COM3 (standard) AT serial	COM3 (optional) industrial serial
1	DCD	—	2	DSR	—
3	RxD*	RxD*	4	RTS	RTS
5	TxD*	TxD*	6	CTS	CTS
7	DTR	DTR**	8	RI	—
9	Gnd	Gnd	10	+5V Safe	+5V Safe

Pin	COM4 (standard) AT serial	COM4 (optional) industrial serial	Pin	COM4 (standard) AT serial	COM4 (optional) industrial serial
11	DCD	—	12	DSR	—
13	RxD*	RxD*	14	RTS	RTS
15	TxD*	TxD*	16	CTS	CTS
17	DTR	DTR**	18	RI	—
19	Gnd	Gnd	20	+5V Safe	+5V Safe

* = active low

** = pulled high to +5V

Table A-21 AT and industrial serial for COM5 and COM6: J5

Pin	COM5 (standard) AT serial	COM5 (optional) routed from GPS J9	Pin	COM5 (standard) AT serial	COM5 (optional) routed from GPS J9
1	NC	—	2	NC	—
3	RxD*	RxD GPS (pin 11)	4	RTS	—
5	TxD*	TxD GPS (pin 12)	6	CTS	—
7	NC	M RST (pin 5)	8	NC	—
9	Gnd	—	10	+5V Safe	—

Pin	COM6 (standard) industrial serial	COM6 (optional) RS-485	Pin	COM6 (standard) industrial serial	COM6 (optional) RS-485	COM6 (optional) routed from J13
11	—	RS-485(+)	12	NC	—	
13	RxD*	—	14	RTS	—	TxD GPS
15	TxD*	—	16	CTS	—	RxD GPS (pin 14)
17	—	RS-485 (–)	18	NC	—	
19	Gnd	Gnd	20	+5V Safe	+5V Safe	

* = active low

Table A-22 LPT1 as printer connector: J6

Pin	DB-25 pin	Function	Pin	DB-25 pin	Function
1	1	STB*	14	20	Gnd
2	14	AFD*	15	8	DATA6
3	2	DATA0	16	21	Gnd
4	15	ERR*	17	9	DATA7
5	3	DATA1	18	22	Gnd
6	16	INIT*	19	10	ACK*
7	4	DATA2	20	23	Gnd
8	17	SLIN*	21	11	BUSY
9	5	DATA3	22	24	Gnd
10	18	Gnd	23	12	PE
11	6	DATA4	24	25	Gnd
12	19	Gnd	25	13	SLCT
13	7	DATA5	26	NC	+5V Safe

* = active low

Table A-23 AT and industrial serial for COM1 and COM2: J7

Pin	COM1 (standard) AT serial	COM1 (optional) industrial serial	Pin	COM1 (standard) AT serial	COM1 (optional) industrial serial
1	DCD	—	2	DSR	—
3	RxD*	RxD*	4	RTS	RTS
5	TxD*	TxD*	6	CTS	CTS
7	DTR	DTR**	8	RI	•
9	Gnd	Gnd	10	+5V Safe	+5V Safe

Pin	COM2 (standard) AT serial	COM2 (optional) industrial serial	Pin	COM2 (standard) AT serial	COM2 (optional) industrial serial
11	DCD	—	12	DSR	—
13	RxD*	RxD*	14	RTS	RTS
15	TxD*	TxD*	16	CTS	CTS
17	DTR	DTR**	18	RI***	RI***
19	Gnd	Gnd	20	+5V Safe	+5V Safe

* = active low; ** = pulled high to +5V; *** = RI on COM used to resume suspended operation. Refer to the *Watchdog timer and hardware resest* and the *CPU power management* chapters.

Table A-24 Floppy drive connector: J9

Pin	Function	Pin	Function
1	Gnd	2	DSEL
3	Gnd	4	NC
5	Gnd	6	NC
7	+5V Safe, Gnd**	8	Index*
9	+5V Safe, Gnd**	10	MTR1 On*
11	+5V Safe, Gnd**	12	DS2
13	Gnd	14	DS1*
15	Gnd	16	MTR2 On*
17	Gnd	18	Dir In*
19	Gnd	20	Step*
21	Gnd	22	WR Data*
23	Gnd	24	WR Gate*
25	Gnd	26	TRK 0*
27	Gnd	28	WP*
29	Gnd	30	RD Data*
31	Gnd	32	Side 1*
33	Gnd	34	Disk change

* = active low

** = +5V Safe is factory optional, Gnd is factory default

Table A-25 IDE hard drive connector: J10

Pin	Function	Pin	Function
1	Reset*	2	Gnd
3	Data 7	4	Data 8
5	Data 6	6	Data 9
7	Data 5	8	Data 10
9	Data 4	10	Data 11
11	Data 3	12	Data 12
13	Data 2	14	Data 13
15	Data 1	16	Data 14
17	Data 0	18	Data 15
19	Gnd	20	Key
21	Reserved	22	Gnd
23	IOWR*	24	Gnd
25	IORD*	26	Gnd
27	IOCHRDY	28	+5V
29	NC	30	Gnd
31	IRQ14	32	NC
33	A1	34	NC
35	A0	36	A2
37	CS0	38	CS1
39	NC	40	Gnd
41	+5V	42	+5V
43	Gnd	44	+5V

* = active low

Table A-26 PC/104 signal assignments: J11

Pin	Row A	Row B	Row C	Row D
0	—	—	Gnd	Gnd
1	IOCHK*	Gnd	SBHE*	MEMCS16*
2	SD7	RESETDRV	LA23	IOCS16*
3	SD6	+5V	LA22	IRQ10
4	SD5	IRQ9	LA21	IRQ11
5	SD4	–5V	LA20	IRQ12
6	SD3	DRQ2	LA19	IRQ15
7	SD2	–12V	LA18	IRQ14
8	SD1	0 WS**	LA17	DACK0*
9	SD0	+12VDC	MEMR*	DRQ0
10	IOCHRDY	Key	MEMW*	DACK5*
11	AEN	SMEMW*	SD8	DRQ5
12	SA19	SMEMR*	SD9	DACK6*
13	SA18	IOW*	SD10	DRQ6
14	SA17	IOR*	SD11	DACK7*
15	SA16	DACK3*	SD12	DRQ7
16	SA15	DRQ3	SD13	+5V
17	SA14	DACK1*	SD14	Master*
18	SA13	DRQ1	SD15	Gnd
19	SA12	Refresh*	Key	Gnd
20	SA11	SYSCLK	—	—
21	SA10	IRQ7	—	—
22	SA9	IRQ6	—	—
23	SA8	IRQ5	—	—
24	SA7	IRQ4	—	—
25	SA6	IRQ3	—	—
26	SA5	DACK2*	—	—
27	SA4	TC	—	—
28	SA3	Bale	—	—
29	SA2	+5V	—	—
30	SA1	OSC	—	—
31	SA0	Gnd	—	—
32	Gnd	Gnd	—	—

* = active low
** = wait state

Table A-27 GPS (Jupiter) connector: J13

Pin	Description	Pin	Description
1	PREAMP	2	PWRIN 5
3	VBATT	4	PWRIN 3/NC
5	M RST	6	GPIO1/NC
7	GPIO2	8	GPIO3
9	GPIO4/NC	10	Gnd0
11	SDO1	12	SDI1
13	Gnd1	14	SDO2
15	SDI2	16	Gnd2
17	NC*	18	Gnd3
19	TMark	20	Reserved/NC

Table A-28 Flat panel connector: J14

Pin	Function	Pin	Function
1	VDDSAFE +5V	2	+12VEESAFE
3	VEESAFE	4	Inverted SHFCLK
5	ENABKL	6	Gnd
7	M	8	DE, (optional, R select)
9	Gnd	10	LP
11	FLM	12	Gnd
13	SHFCLK	14	Gnd
15	P0	16	P1
17	Gnd	18	P2
19	P3	20	Gnd
21	P4	22	P5
23	Gnd	24	P6
25	P7	26	Gnd
27	P8	28	P9
29	Gnd	30	P10
31	P11	32	Gnd
33	P12	34	P13
35	Gnd	36	P14
37	P15	38	Gnd
39	P16	40	P17
41	Gnd	42	P18
43	P19	44	Gnd
45	P20	46	P21
47	Gnd	48	P22
49	P23	50	Gnd

Table A-29 EZ I/O 1 connector (J15) and EZ I/O 2 connector (J16)

Pin	Function	Pin	Function	Pin	Function
	Port A		**Port B**		**Port C**
19	bit 0	10	bit 0	13	bit 0
21	bit 1	8	bit 1	16	bit 1
23	bit 2	4	bit 2	15	bit 2
25	bit 3	6	bit 3	17	bit 3
24	bit 4	1	bit 4	14	bit 4
22	bit 5	3	bit 5	11	bit 5
20	bit 6	5	bit 6	12	bit 6
18	bit 7	7	bit 7	9	bit 7
				2	+5V safe
				26	Gnd

Table A-30 OPTOA and OPTOB: J17

OPTO A: PMI J17[1–2]*	OPTO B: SUSPEND/RESUME J17[3–4]*
pin 1—positive input	pin 3—postive input
pin 2—negative input	pin4—negative input

Table A-31 Battery connector: J18

Pin	Function
1	Battery
2	Key
3	Gnd
4	Gnd

Table A-32 PC video connector: J19

Pin	Function	Pin	Function
1	NC	2	Gnd
3	NC	4	Gnd
5	VR7	6	Gnd
7	VR6	8	Gnd
9	VLCK	10	Gnd
11	VREF	12	Gnd
13	HREF	14	Gnd
15	NC	16	Gnd
17	NC	18	Gnd
19	VSYNC	20	Gnd
21	HSYNC	22	Gnd
23	NC	24	Gnd
25	NC	26	Gnd
27	NC	28	Gnd
29	PCLK	30	Gnd
31	Color key	32	Gnd
33	VR2	34	VR3
35	Gnd	36	VR4
37	VR5	38	Gnd
39	VG2	40	VG3
41	Gnd	42	VG4
43	VG5	44	Gnd
45	VG6	46	VG7
47	Gnd	48	VB2
49	VB3	50	Gnd
51	VB4	52	VB5
53	Gnd	54	VB6
55	VB7	56	Gnd
57	NC	58	NC
59	NC	60	NC

Table A-33 SVGA connector: J20

Pin	Function	Pin	Function
1	Red	2	Green
3	Blue	4	NC
5	Gnd	6	Gnd
7	Gnd	8	Gnd
9	+5V Safe	10	Gnd
11	NC	12	DDCD
13	Horizontal sync	14	Vertical sync
15	Clk DDC	16	Gnd

≡ Tie wrap holes

Additional .125" mounting holes are on the PC-510 board for the use of .100" wide nylon tie wraps. These tie wraps loop around the SSD0 DIP device and also the DIMM memory expansion device. This feature will increase the ruggedness and the retention ability in high vibration environments. Nylon tie wraps are available from a hardware specialty supplier such as Richco, phone number: 1-800-621-1892. The following letters specify the length of the tie wrap:

L=5.75", V=8.00", X=18.00"

Appendix B: Software utilities

≡ Introduction

The PC-510 ROM-DOS and Software Utility Disk comes with the utilities listed below. Some of these utilities are also available on the PC-510 BIOS drive. This appendix describes the utilities and their use.

Support commands:

- COM1CON.EXE
- GETBIOS.EXE
- GETIMG.EXE
- GETIMGH.EXE
- I17HNDLR.EXE
- LCDBIAS.EXE
- LPT1CON.COM
- PFORMAT.EXE
- PGMBIOS.EXE
- PGMIMG.EXE
- PGMIMGH.EXE
- PGMVIDEO.EXE
- PHDISK.EXE
- PMISETUP.EXE
- REMDISK.EXE
- REMQUIT.COM
- REMSERV.EXE
- RESET.COM
- SCONSOLE.EXE
- SETIRQ.EXE
- SETSSD.EXE
- SETUP.COM
- TESTRFA.EXE
- TRANSFER.EXE

Support device drivers:

- PICOFA.SYS
- HIMEM.SYS
- VDISK.SYS

Note Other utilities are included from ROM-DOS and are not mentioned in this section. Please refer to your ROM-DOS manual.

≡ GETBIOS.EXE

Purpose

This support command stores the BIOS information in a specific file.

Syntax

GETBIOS SSD*x filename*

Parameters

- **SSD***x* specifies the target SSD that stores the BIOS. The variable *x* represents a value from 0 to 1.
- *filename* specifies the output file for saving or programming.

≡ GETIMG.EXE

Purpose 1

This support command captures an image of an SSD and places it into a local file.

Syntax 1

GETIMG SSD*x filename*

Purpose 2

This support command captures an image of an SSD and transfers it to a host PC running **GETIMGH**.

Syntax 2

GETIMG SSD*x* /**COM***x* [/**B***xx*] [/**I***xx*]

Purpose 3

This support command captures an image of an SSD and transfers it to a host PC running GETIMGH. A non-standard serial port I/O address is used and the IRQ value must be specified.

Syntax 3

GETIMG SSD*x* **/U***xxxx* [**/B***xx*] [**/I***xx*]

Parameters

- **SSD***x* specifies the target SSD for file saving or programming. The variable *x* represents a value from 0 to 1.
- *filename* specifies the output file for saving or programming.
- **/COM***x* specifies the PC COM port for serial transfer where *x* represents a value from 1 to 4.
- **/U***xxxx* specifies the UART base address to use for serial transfer. The base address, 100-3FF, is in hexadecimal format.
- /**B***xx* specifies baud rate of transfer where *xx* can be (300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115 (115200)). The default is 38400 when using a /**COM***x* switch.
- **/I***xx* specifies the interrupt to which the UART is connected. The value *x* represents a variable from 3 to 15.

Remarks

GETIMG compatibility:

The following devices share the same image and can be used interchangeably: Atmel's AT29C040 and AT29C040A; SST's 28SF040; 512K EPROM; and 512K SRAM. Use an EPROM to make the drive read-only.

Because the AMD 512K, 1MB, and 2MB have a different structure, they cannot be used in any other type of device. An image from a 512K AMD flash can only be used on other 512K AMD flashes.

≡ GETIMGH.EXE

Purpose 1

This support command transfers an SSD image from a target PC running **GETIMG** and saves the image to a host file.

Syntax 1

GETIMGH *filename* **/COM***x* [**/B***xx*] [**/I***xx*]

Purpose 2

This support command transfers an SSD image from a target PC running GETIMG and saves the image to a host file via a serial UART connection. A non-standard serial port address is used and the IRQ value must be specified.

Syntax 2

GETIMGH *filename* **/U***xxx* [**/B***xx*] **/I***xx*

Parameters

- *filename* specifies the output file for saving or programming and it also represents the host filename.
- /**COM***x* specifies the PC COM port for serial transfer. The variable *x* represents a value from 1 to 4.
- /**U***xxx* specifies the UART base address to use for serial transfer. The base address, 100-3FF, is in hexadecimal format.
- /**B***xx* specifies baud rate of transfer where *xx* can be (300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115 (115200)). The default is 38400 when using a /**COM***x* switch. If COM1 is the console, the baud rate defaults to the current console baud rate.
- /**I***xx* specifies the interrupt to which the UART. The variable *x* represents a value from 3 to 15.

See also

GETIMG.EXE for details on image compatibility.

≡ HIMEM.SYS

Purpose

This device driver manages extended memory and the high memory Area (HMA) in a 286, 386, or greater PS/2 system. HIMEM prevents programs from simultaneously using the same area of memory for two different purposes. HIMEM supports the eXtended Memory Specification (XMS) 2.0. HIMEM is installed as a device driver in CONFIG.SYS.

Syntax

DEVICE=[*d*:] [*path*] **HIMEM.SYS** [/machine:*n*]

Remarks

The HIMEM driver can be used to allow ROM-DOS to run in High Memory.

HIMEM supports a default of 32 handles.

HIMEM should not be used with older versions of VDISK. Current versions of VDISK will use XMS memory if it is available.

HIMEM recognizes PS/2 style machines A20 line control. HIMEM determines whether to use the PS/2 A20 control or the AT A20 control method automatically by calling INT 15h, function C0h (get system configuration).

The automatic detection can be overridden with the "/Machine:*n*" command line switch. Replacing "*n*" with 1 designates the PC AT A20 control method. Replacing "*n*" with 2 designates the PS/2 method.

Example 1

```
DEVICE=HIMEM.SYS
```

The above command installs the XMS device driver. Once this driver is installed, accessing the HMA and Extended Memory (XMS) areas are legal. The Extended Memory area can contain up to 2 Gigabytes of memory. Typical systems have 4, 8, or 16 MB XMS memory installed.

Example 2

```
DEVICE=HIMEM.SYS /machine:1
```

This example forces the use of the AT style A20 line control.

The HIMEM driver will fail to load if either the machine does not have memory above the 1 MB boundary or the BIOS does not provide support for it. It will also fail to load if another XMS manager has been installed previously.

≡ I17HNDLR.EXE

Purpose

This support command allows the system to use the INT 17 functions when the extended BIOS area is disabled (i.e., W2[9-10] is not jumpered) or when it is reprogrammed with another BIOS.

Syntax

I17HNDLR

Remarks

This command is used if the extended BIOS area (D800-DFFF) is not used. The I17HNDLR allows the system to use the INT 17 functions.

≡ LCDBIAS.EXE

Purpose

This support command adjusts the LCD bias voltage to obtain the best contrast for the LCD flat panel. The LCD TSR (Terminate and Stay Resident) works in combination with the INT 17 extended BIOS/TSR. Press <CTRL><+> to increase the voltage <CTRL><-> to decrease the voltage. These keystrokes adjust the voltage within the PC-510's pre-defined voltage range (factory default is +22V to +30V). The <-> and <+> are on the 101 "key enhanced" numeric keypad. The <-> and <+> are also on the local keyboard as well as the <CTRL> keystroke.

Syntax

LCDBIAS [**/D**] [**/R**] [**/U**]

Parameters

- /**D** shows a display of "<" or ">" when the LCDBIAS TSR detects a <CTRL><-> or <CTRL><+>. This display may interfere with graphics based programs.
- /**R** reinstalls the TSR when detection occurs of a previous TSR copy of the LCD bias.
- /**U** uninstalls the TSR. /U only removes the vectors and not the memory usage of the TSR. TSRs must be removed in the order of last installed, first removed.

Example 1

To install the LCDBIAS TSR and its display after the LCD bias voltage has been adjusted, enter the following command:

LCDBIAS /D

Example 2

To install the LCDBIAS TSR only and *not* a display of its adjust characters, enter:

```
LCDBIAS
```

Example 3

If possible, to uninstall the LCDBIAS TSR, enter this command:

```
LCDBIAS /U
```

Remarks

If the INT 17 extended BIOS/TSR has not been previously installed, then the LCD TSR will not install.

See also

I17HNDLR.EXE and also the *CRTs and flat panels* chapter.

≡ LPT1CON.COM

Purpose

This support command redirects the video to the LPT1 port.

Syntax

```
LPT1CON
```

Remarks

If you have a 2010 interface board and an LCD display connected to the LPT1 port, executing the DISPLAY.EXE and LPT1CON.COM programs allow you to use the display as the system console. You must reset your system to change the video to the original parameters.

≡ PFORMAT.EXE

Purpose

This support command formats preformatted or unformatted drives.

Syntax

PFORMAT <*drive*> [**/C**] [**/M**] [**/V**]

Parameters

- *drive* can be specified as **C:** through **Z:** for preformatted drives. For preformatted or unformatted drives, specify *drive* as **H0** through **H9**, where 0 through 9 represent the hard drive number.
- **/C** is an optional parameter that specifies no confirmation before formatting.
- **/M** is an optional parameter that specifies PICO FA is to write an MBR. This is required for unformatted drives using non-AMD flash devices.
- **/V** is an optional parameter that specifies a volume label is to be placed on disk.

Example 1

To place a volume label on disk for preformatted drive D:, enter:

```
PFORMAT d: /V
```

Example 2

To have PICO FA write an MBR to drive H0, enter:

```
PFORMAT H0 /M
```

≡ PGMBIOS.EXE

Purpose

This support command programs a new system BIOS into the PC-510.

Syntax

PGMBIOS [*filename* | **SSD***x*] **SSD***y* [**/?**]

Parameters

- *filename* specifies the BIOS .DAT file to program into flash.
- **SSD***x* specifies the source SSD for BIOS. The variable *x* represents a value from 0 to 1.
- **SSD***y* specifies the target SSD for BIOS. The variable *y* represents a value from 0 to 1.
- **/?** requests a help menu.

Example 1

To program the BIOSFILE.BIN files into the SSD1 BIOS area, enter:

```
PGMBIOS BIOSFILE.BIN SSD1
```

Example 2

To program the AT BIOS and extended BIOS from SSD0 to SSD1, enter:

```
PGMBIOS SSD0 SSD1
```

≡ PGMIMG.EXE

Purpose 1

This support command programs a local file image to an SSD.

Syntax 1

PGMIMG SSD*x filename*

Purpose 2

This support command programs a local file image to an SSD and transfers it to a host PC running **PGMIMGH**.

Syntax 2

PGMIMG SSD*x* **/COM***x* [**B***xx*] [**I***xx*]

Purpose 3

This support command programs a local file image to an SSD and transfers it to a host PC running PGMIMGH. A non-standard serial port I/O address is used and the IRQ value must be specified.

Syntax 3

PGMIMG SSD*x* **/U***xxxx* [**B***xx*] **/I***xx*

Parameters

- *filename* specifies the input file programming.
- **SSD***x* specifies the target SSD for image. The variable *x* represents a value from 0 to 1.
- **/COM***x* specifies the PC COM port for serial transfer. The variable *x* represents a value from 1 to 4.
- **/U***xxx* specifies the UART base address to use for serial transfer. The base address, 100-3FF is in hexadecimal format.
- /**B***xx* specifies baud rate of transfer where *xx* can be (300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115 (115200)). The default is 38400 when using a /**COM***x* switch. If COM1 is the console, the baud rate defaults to the current console baud rate.
- **/I***xx* specifies the interrupt to which the UART base address is connected. The variable *x* represents a value from 3 to 15.

≡ PGMIMGH.EXE

Purpose 1

This support command programs an image file from a target PC running PGMIMG.

Syntax 1

PGMIMGH *filename* **/COM***x* [**/B***xx*] [**/I***xx*]

Purpose 2

This support command transfers an SSD image to a target computer via a serial UART connection and programs the image to an SSD. A non-standard serial port address is used and the IRQ must be specified.

Syntax 2

PGMIMGH *filename* **/U***xxx* [**/B***xx*] **/I***xx*

Parameters

- *filename* specifies the input file for programming and it also represents the host filename.
- **/COM***x* specifies the PC COM port for serial transfer. The variable x represents a value from 1 to 4.
- **/U***xxx* specifies the UART base address to use for serial transfer. The base address, 100-3FF is in hexadecimal format.
- /**B***xx* specifies baud rate of transfer where *b* can be (300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115 (115200)). The default is 38400 when using a /**COM***x* switch. If COM1 is the console, the baud rate defaults to the current console baud rate.
- **/I***xx* specifies the interrupt to which the UART base address is connected. The variable x represents a value from 3 to 15.

See also

See PGMIMG.EXE. See also, GETIMG for image compatibility.

≡ PGMVIDEO.EXE

Purpose

This support command programs a video BIOS into the BIOS area of an SSD. A new video BIOS is required for a different flat panel display.

Syntax

PGMVIDEO VIDEO.DAT SSD*n* [**/P**] [**/C**]

Parameters

- videobios.dat is the filename of the new video BIOS. For a complete listing, see the VGA 65550 utility disk.
- SSD*n* is the SSD which programs the video BIOS into SSD0 or SSD1. The BIOS is then selected by adjusting the BIOSDEV jumper, W2[5-6].
- /**P** reprograms the current video BIOS. Normally, PGMVIDEO by itself can not reprogram the current video BIOS.

- /**C** reprograms the video BIOS if the checksum of the video BIOS is not correct. /C is usually a failure condition for a video BIOS when the system will not use the new video BIOS. By default, the video BIOS to be programmed must initially pass the checksum test.

Example 1

To program the S64P80.DAT video BIOS (which operates the Sharp 64P80 flat panel and CRT in simultaneous display mode) into SSD1 whether or not the current video BIOS is in SSD1, enter the following command:

```
PGMVIDEO S64P80.DAT SSD1 /P
```

Remarks

The video BIOS is typically 40K and resides in the C0000-C7FFF and C8000-CBFFF areas. To use the new video BIOS, set the BIOSDEV jumper, W2[5-6], to the programmed SSD. Also, enable the video BIOS areas, C0000-C7FFF and C8000-CBFFF. To enable the video BIOS areas, change the jumpers on W2[1-2] and W3[1-2] or change the ROM enable options in SETUP. Change the ROM enable options and jumpers W2[1-2] and W3[1-2] accordingly to accommodate your current ROM enable and jumper states. For complete instructions on enabling and disabling the video BIOS, see the *Console devices* chapter.

If the video BIOS is programmed and no display results occur, then adjust W2[1-2] and W3[7-9] by trying four options: on on, on off, off on, or off off (refer to Table 7-4). Also, confirm that the VGA disable jumper, W3[5-6] is installed. If the display still does not work, then check the cabling and/or the video BIOS, programmed for your flat panel. To restore the CRT/VGA display, reprogram the default video BIOS by using the serial console to access the PC-510.

See also

For more information on supported video BIOS files, see the VGA 65550 utility disk and its README.TXT file. See the *SETUP programs* and the *Console devices* chapters for more information on enabling/disabling the video BIOS.

≡ PHDISK.EXE

Purpose

This support command creates a Save to Disk partition on an IDE hard drive.

Syntax

PHDISK

Remarks

This program modifies the partition table on an IDE hard drive so that a "save to disk" can be performed. The size of the partition includes system information such as interrupt controllers, floppy disk controller, etc. It also includes video RAM and system DRAM contents. Since the DRAM contents are included, the size of system DRAM (at the time PHDISK is executed) is used in calculating the size of the partition. A 4 MB DRAM system requires more than 6 MB of partition space. Once created, it cannot be enlarged without destroying other partitions.

WARNING!

If a partition already exists on the hard drive, this program will destroy it! Execute PHDISK first, then install other partitions using FDISK or other OS partitioning programs.

To use the save to disk feature, the PMISETUP SAVE-TO-DISK option must be set to Y. The IDE drive must also be the first drive, therefore the SETSSD /after option should be used. The save to disk feature works with true IDE drives only.

See the FDISK command in your DOS manual for more information about partitions.

See the *SETUP programs* chapter for information on PMISETUP. See the *CPU power management* chapter for more information on save to disk.

See also

PMISETUP.EXE (save-to-disk), SETSSD.EXE.

≡ PICOFA.SYS

Purpose

An alternate way to access the on-board SSD. By using this driver, it is possible to free up the address area at D8000h-DffffH by removing jumper *x*.

Syntax

PICOFA.SYS

Remarks

This command will not allow booting from an SSD.

≡ PMISETUP.EXE

Purpose

This support command allows modification of the power management options.

Syntax

PMISETUP *inputfile* [**/SHOWALL**] [**/DEFAULT**] [**/P**] [**/?**]

Parameters

- *inputfile* specifies the file containing PMISETUP commands.
- /**SHOWALL** specifies to show all of the power management options on screen.
- /**DEFAULT** specifies the BIOS defaults that are to be loaded first before the *inputfile* is used.
- **/P** specifies to enable pausing between screens for viewing when using the **/SHOWALL** option.
- **/?** displays a short help screen for the PMISETUP program. No other arguments are to be included on the command line when the **/?** is used.

See also

SLOW.PMI, QUICK.PMI in the /EXAMPLES directory provided on the PC-510 utility disk.

Also, see the *PMISETUP* section in the *SETUP programs* chapter.

≡ REMDISK.EXE

Purpose

This support command allows access to a disk drive on a remote system via a serial cable and standard PC style (8250 UART) serial port.

Syntax

REMDISK [**/U**] [**/?**] [**/B***nnnn*] [**+**] [**/COM***n*]

Parameters

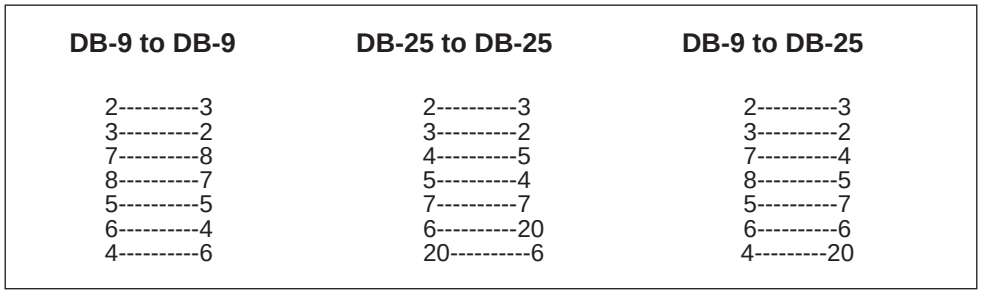
- **/U** tells REMDISK to unload itself from memory, thereby disabling the new drive letter and freeing the memory occupied by REMDISK. The option can only be used when REMDISK is installed from the DOS command line. A Remote Disk installed via CONFIG.SYS cannot be unloaded.
- **/?** displays a short help screen for the REMDISK program. No other arguments are to be included on the command line when the **/?** is used.
- **/B***nnnn* selects the baud rate for transmission. Available baud rates are 300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, and 115k. The default baud rate is 115k.
- **+** is an optional argument which specifies packet style transmission. This is recommended for any baud rates over 19200. The default for this option is to include the **+** for packet transmission.
- **COM***n* is an optional argument which selects the communication port. Available ports are 1 and 2. COM1 is the default port.

Note To use the Remote Disk, both the REMDISK and the REMSERV programs must be running on their respective systems. Both programs must use the same baud rate and packet or non-packet style transmission. It does not matter which program is installed first.

Remarks

In a Remote Disk setup, one system, the one that will share its drives, is termed the Server. The other system, the one that will access and use the remote drives, is called the Client. The serial ports on both systems must be connected via a null modem cable. A cabling diagram for a standard cable is shown below.

Figure B-1 Cabling diagram for a standard cable



Run REMDISK.EXE on the Client system. This program creates a new drive letter for the Client. REMDISK will use the next available system drive letter. For example, if the last assigned drive was D:, REMDISK will create a drive E:. This drive acts in all ways just like any other drive, except for the fact that it requires the serial port to do its job.

REMDISK.EXE can be installed using a **DEVICE=** command in CONFIG.SYS or from the DOS prompt.

Example 1

To install the REMDISK program from CONFIG.SYS at 19200, on COM1, using packet style transmission, enter the following in CONFIG.SYS and then reboot the system (remember to include the full path to find REMDISK.EXE if not located in the root directory):

```
DEVICE=REMDISK.EXE /B19200 +
```

Example 2

To display a help screen for REMDISK, enter the following at the DOS prompt:

```
REMDISK /?
```

Example 3

To install REMDISK from the DOS prompt or from a batch file (like AUTOEXEC.BAT) at 9600 baud, without packet style transmission, on COM2, enter the following;

```
REMDISK /B9600 /COM2
```

Example 4

To unload the REMDISK installed from the batch file or the DOS prompt, type:

```
REMDISK /U
```

See also

REMSERV.EXE

≡ REMQUIT.COM

Purpose

This support command cancels a REMSERV session on a remote system.

Syntax

REMQUIT

Remarks

Once a REMDISK/REMSERV connection is no longer needed, the REMQUIT command is used (on the same CPU running REMDISK) to cancel the REMSERV command. You may also press the ESC key if you have access to a local keyboard to the CPU running REMSERV.

See also

REMSERV.EXE, REMDISK.EXE

≡ REMSERV.EXE

Purpose

This support command makes a single drive at a time on the server system available to the Client. The available drive can be changed at any time by quitting the REMSERV program and then running the program again with a new drive letter.

Syntax

REMSERV.EXE *d:* [**/B***nnnn*] [**+**] [**/COM***n*] [**/S**]

Parameters

- *d:* represents the letter of the drive that the Server will make available to the Client.
- **/B***nnnn* selects the baud rate for transmission. Available baud rates are 300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, and 115k. The default baud rate is 115k.
- **+** is an optional argument which specifies packet style transmission. This is recommended for any baud rates over 19200. The default for this option is to include the **+** for packet transmission.
- **COM***n* is an optional argument which selects the communication port. Available ports are 1 and 2. COM1 is the default port.
- **/S** instructs REMSERV to run silently, that is without any screen output.
- **/?** is an unlisted option which is used to print a short help screen for the REMSERV program. If the **/?** is used, the drive letter argument is omitted, for example:

  ```
  REMSERV /?
  ```

Example 1

To select drive B: as the available Server drive at 115K baud, packet style transmission, using COM1, you would enter the following:

```
REMSERV B:
```

Example 2

To set drive C: as the Server disk at 9600 baud, without packet style transmission, on COM2, you would enter the following:

```
REMSERV C: /B9600 /COM2
```

Note The Server program can be terminated at any time by pressing the <ESC> key. The Client can then no longer access the Server's drive until the REMSERV program is run again.

See also

REMDISK.EXE

≡ RESET.COM

Purpose

This support command enables the watchdog timer and allows time-out to expire, thus restarting the system.

Syntax

RESET

Remarks

The RESET command also restarts all the expansion I/O cards on the bus. This differs from a <CTRL><ALT><DEL> reboot of the system which only restarts the system but not the expansion cards. The RESET button on the PC-510 also accomplishes the same thing as the RESET command.

≡ SCONSOLE.EXE

Purpose

This support command checks whether the system is running on a serial console.

Syntax

SCONSOLE

Remarks

This command is useful in batch programs to detect if the serial console is in use.

≡ SETIRQ.EXE

Purpose

This support command programs new IRQ matrix files in the PC-510 utility disk. The matrix file remaps bus IRQs, RS-232/485 data, EZ I/O, and COM5 and COM6 base address options.

Syntax

SETIRQ mapfile.isp

Parameters

- mapfile.isp is the ISP file found in the IRQ directory of the utility disk.

Example

To program the factory default map file, enter:

SETIRQ 510_001.ISP

≡ SETSSD.EXE

Purpose

This support command configures PICO FA device order.

Syntax

SETSSD [**SSD***n*] [**SSD***m*] [**/before** | **/after**] [**/NoSSD**] [**/?**] [**/D**] [**/QNX+** | **/QNX-**] [**/SSD0BIOS+** | **/SSD0BIOS-**]

Parameters

- **SSD***n* specifies one SSD.
- **SSD***m* specifies two SSDs.
- **/before** is an optional parameter that indicates the SSDs are to be allocated before any hard drives. The first SSD specified will be the boot device.
- **/after** is an optional parameter that indicates the SSDs are to be allocated after any hard drives. The hard drive will be the boot device. This is the default.

- **/NoSSD** is an optional parameter that specifies that no SSDs are to be allocated.
- **/?** displays a short help screen for the SETSSD program. No other arguments are to be included on the command line when the **/?** is used.
- **/D** is an optional parameter that specifies SETSSD to use its defaults.
- /**QNX+** enables the QNX drive option.
- /**QNX-** disables the QNX drive option (default).
- /**SSD0BIOS+** reserves the BIOS area of SSD0 (default).
- /**SSD0BIOS-** does not reserve the BIOS area of SSD0.

Example 1

Enter the following command to enable the QNX drive compatible mode:

```
SETSSD SSD1 SSD0 /QNX+
```

Once the mode is set, the drive is no longer readable by Phoenix PICOFA as a DOS drive. The system can boot from the QNX drive in SSD1, when the system is programmed with a QNX drive image.

Example 2

To enable the PICOFA compatible mode, enter the following command:

```
SETSSD SSD1 SSD0 /QNX-
```

If the SSDs were programmed with a QNX drive image, use PFORMAT to reformat the SSD.

Remarks

If the boot order in SETUP is set to "A: THEN C:," the system tries to boot from a floppy (if one exists) and then it tries to boot from the C: drive. The C: drive can be either an SSD or an HDD depending upon which switch, **/before** or **/after**, was selected. If the boot order is set to "C: ONLY," the floppy check is not performed. You may override the order of the SSD by removing the USESETUP jumper.

When /QNX+ is enabled and when PICO FA reports to SSD1, PICO FA communicates "+QNX/ROM." When /SSD0BIOS- is enabled and when PICO FA reports to SSD0, PICO FA communicates "-FULL." Drives PFORMATTED with /SSD0BIOS+ are not recognized when /SSD0BIOS- is used. Drives PFORMATTED with /SSD0BIOS- are not recognized when /SSD0BIOS+ is used. When this option is changed, use PFORMAT again to reformat the SSD0 drive.

See also

See the *SETSSD* section in the *SETUP programs* chapter. See also the *Third party support* appendix for more details on QNX usage.

≡ SETUP.COM

Purpose

This support command configures various system parameters, including serial ports, a parallel port, and a floppy and hard drive.

Syntax

SETUP [**/D**]

Parameter

- **/D** returns all setup values to default values.

Remarks

From the directory where this utility file is located, enter:

SETUP

After the copyright message displays, the main menu appears:

```
                OCTAGON SYSTEMS CORPORATION
                  PC510 SETUP UTILITY Vx.x
            (c) Phoenix Technologies, Ltd. 1985, 1995
 ____________________________________________________________
  (Press SPACE to CHANGE, ENTER to ACCEPT, ESC to EXIT)


Serial Console on COM1:          ENABLED
 COM1 Console Baud Rate:         9600
Power on memory test:            ENABLED
Boot Sequence:                   C: ONLY
Serial Port COM1:                ENABLED
  Serial Port COM1 Address:      3F8h (default)
COM2:                            ENABLED
  Serial Port COM2 Address:      2F8h
Parallel (LPT) Port:             ENABLED
 Parallel Port Mode:             Bidirectional Printer Port
 Parallel Port Address:          378h
Number of floppy drives:         1
 Onboard Floppy Controller:      ENABLED
 Swap drives A and B:            NO
Floppy drive 1 size:             3.5", 1.44 MB
Onboard IDE Interface:           ENABLED
Primary Master Fixed Disk:       AUTO
```

```
Primary Slave Fixed Disk:       NONE
Secondary Master Fixed Disk:    NONE
Secondary Slave Fixed Disk:     NONE
Internal CPU cache:             ENABLED
Limit CPU to half speed         NO
SETUP Entry via Hotkey:         ENABLED
Power Management:               ENABLED
  Doze Clock (slow, stop):      SLOW
  Time Update after Suspend:    ENABLED
DIMM Module Type:               EDO
Enable ROM at C0000h-C7FFFh:    ENABLED
Enable ROM at C8000h-CFFFFh:    ENABLED
Enable ROM at D8000h-DFFFFh:    ENABLED
Shadow C0000h-C7FFFh:           ENABLED
Shadow C8000h-CFFFFh:           ENABLED
Shadow D0000h-D7FFFh:           DISABLED
Shadow D8000h-DFFFFh:           DISABLED

Press ENTER to SAVE the changes or
Press ESC to EXIT without saving the changes.

Options Saved.

You must reset for these options to take effect.
PC510 C:\>
```

Note Executing SETUP /D will change all setup parameters to default values.

See also

See the *SETUP programs* chapter for more information. You may also enter SETUP at post time by entering the "backspace" and "s" keys.

≡TESTRFA.EXE

Purpose

This support command tests PICO FA drives.

Syntax

TESTRFA [**/S***n*] [**/A**] [**/E**] [**/F**]

Parameters

- **/S***n* is an optional parameter that specifies the socket to be tested. The variable *n* represents a value from 0 to 1, where 0 represents the first* PICO FA drive and 1 represents the second* PICO FA drive.

  * = As apparently set by the SETSSD command.

- **/A** is an optional parameter that specifies all sockets are to be tested.
- **/E** is an optional parameter that specifies test writing to every byte.
- **/F** is an optional parameter that specifies a "full" test. This option is equivalent to **/A** and **/E** combined.
- No parameters on the command line will display a help message.

> **WARNING!**
>
> **After this program is executed, the drive tested will require reformatting using the PFORMAT program.**

See also

SETSSD.EXE, PFORMAT.EXE

≡ TRANSFER.EXE

Purpose

This support command transfers files to or from the PC-510 over a serial port.

Syntax

TRANSFER *filepath* [**/S** | **/R**] [**/B***xxxx*] [**/V**] [**/COM***x*]

Parameters

- *filepath* specifies the file pathname to send or receive.
- /**S** specifies to send the file.
- /**R** specifies to receive the file. This is the default.
- /**B***xxxx* specifies baud rate of transfer where *xxxx* can be (300, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115 (115200)). The default is 9600 when using a /**COM***x* switch. If COM1 is the console, the baud rate defaults to the current console baud rate.
- /**V** enables the display of "R" when a block (128 bytes) is received, or "T" when a block is transmitted.

Note Do not use /**V** when COM1 is the console device.

- /**COM***x* specifies the serial port to use where *x* represents a value from 1-4. The default is 1.

Example 1

To send a file named C:\MPC\DEMO\DEMO.EXE on the PC-510 when using COM1 as the console, enter the following command:

```
TRANSFER D:DEMO.EXE
```

On the remote PC executing SmartLINK, press <ALT> <D>, type C:\MPC\DEMO\DEMO.EXE, and then press ENTER.

Example 2

To send a file named D:DEMO.BAS to the file C:\TEST.BAS on the remote PC when using COM1 as the console, enter the following on the PC-510:

```
TRANSFER /S D:DEMO.BAS
```

On the remote PC executing SmartLINK, press <ALT> <U>, type C:\TEST.BAS, and then press <ENTER>.

Example 3

To send a file named C:\DEMO\DEMO.EXE from a remote PC to the file named D:\DEMO.EXE on the PC-510 at 57600 baud with a serial cable from COM2 on the remote PC and COM1 on the PC-510, enter the following command on the PC-510:

```
TRANSFER  D:\DEMO.EXE /R /V /B57600
```

Then enter the following command on the remote PC:

```
TRANSFER  C:\DEMO\DEMO.EXE /S /V /COM2 /B57600
```

To receive a file named D:\MYAPP.EXE from the PC-510 and name it C:\APPS\MYAPP2.EXE on the remote PC over a serial cable connected to COM1 on both systems at 9600 baud, enter the following command on the PC-510:

```
TRANSFER  D:\MYAPP.EXE /S
```

Then enter the following command on the remote PC:

```
TRANSFER  C:\APPS\MYAPP2.EXE
```

Remarks

The TRANSFER command communicates with other XMODEM compatible file transfer programs.

The serial port on the PC-510 requires a null modem adapter when connected to a serial port on the remote PC. See the *Serial ports* chapter more information.

The maximum baud rate is dependent on the processor speeds of the remote PC and the PC-510.

The received file size is rounded up to the nearest 128 byte boundary.

See also

REMDISK.EXE, REMSERV.EXE

≡ VDISK.SYS

Purpose

This device driver allows the user to use memory as a disk.

Syntax

DEVICE= VDISK [*size* [*secs* [*dirs*]]] [**/E**] [**/NOTIFEXT**]

Parameters

- *size* specifies the size of the VDISK in kilo (K) bytes. The default is 64K if base memory is selected. Otherwise, if /E is entered, then the size of the VDISK is all available extended memory (size is 64K smaller if DOS is loaded HIGH). The memory selected will be allocated from the DOS memory pool, decreasing the amount of memory available for programs, unless the extended memory switch is used.
- *secs* specifies the sector size in bytes. The default is 512 bytes per sector. This value must be 128, 256, 512 or 1024. All other values are not valid and the default of 512 bytes will be used.
- *dirs* specifies the number of root directory entries. The default is 64 directory entries. There may be any number of root directory entries between 2 and 1024. If an odd number is given, it will be rounded up to the nearest multiple of 16, in order to fill the entire sector.
- **/E** causes VDISK to use extended memory (memory above the 1 MB boundary) instead of DOS program memory for the disk.
- **/NOTIFEXT** causes the virtual drive to not be installed if extended memory exists.

Note Interrupts are turned off during the transfer of data from extended memory to conventional memory.

The VDISK increases the resident size of DOS.

Remarks

VDISK allows the user to partition some of the computer's memory as a disk. This disk is called a RAM disk or Virtual Disk. A RAM disk is much faster than either a floppy or hard disk. The RAM drive can use either standard DOS program memory or extended memory (above 1 MB) for the disk.

Any data on the VDISK is lost when the system power is turned off.

Example 1

```
DEVICE=VDISK.SYS
```

The above example builds a 64K RAM disk in DOS memory.

Example 2

```
DEVICE=C:\DOS\VDISK.SYS 220 /E
```

This example builds a 220K RAM disk in extended memory. The VDISK device driver is loaded from the C: drive and the \DOS directory. VDISK assumes the default 512 byte sector size, and 64 directory entries.

Example 3

```
DEVICE=VDISK.SYS 45 128 18
```

The above example builds a 45K RAM disk in DOS memory. There will be 128 byte sectors and 18 root directory entries.

Example 4

```
DEVICE=VDISK.SYS /E
```

On a 2 MB system, the above example allocates a 1024K drive in extended memory (960K is allocated if DOS is loaded HIGH).

Appendix C: Third party support

≡ Using QNX on the PC-510

To use QNX on the PC-510, follow the steps below:

1. Boot from a floppy or a hard drive that has QNX installed on your system.
2. Program SSD1 with the QNX image. See the *Programming QNX into SSD1* section below.
3. To boot from SSD1 with QNX, execute SETSSD SSD1 /QNX+.

Programming QNX into SSD1

The PC-510 contains a reserved 192K area located in front of the SSD1 flash. The EFSYS.510 driver from Octagon reserves this space automatically. Use the sample files from Octagon's QNX utility disk to program QNX into SSD1.

Note When QNX+ is in the SETSSD command line, i.e.

```
SETSSD SSD1 SSD0/QNX+
```

then the QNX drive option is enabled. Once your system is in the QNX mode, SSD1 cannot be used as a drive from DOS. TESTRFA will not work on SSD1.

≡ Using M-Systems DiskOnChip (DOC)

To use the M-systems DiskOnChip (DOC) module with your PC-510, follow these steps:

1. Run:
   ```
   SETSSD SSD1 /before
   ```
2. Power off the PC-510.
3. Confirm that the BIOSDEV jumper is set to SSD1.
4. Make sure SSD0 is jumpered for flash by configuring W5[1-2, 3-4, 5-6, 9-10] W2[7-8].
5. Install the DOC module into SSD0. Make sure to orient pin 1 on the DOC module with pin 1 on SSD0.

WARNING!

Installing the DOC module into the wrong position on SSD0 of the PC-510 board will permanently damage the DOC module.

6. Power on the PC-510.
7. Execute:
   DOCPRGO /F:OCT1202.BIN /W

Note The DOCPRGO.EXE and the OCT1202.BIN are on the DOC utility disk.

8. Reset your system.
9. Execute:
   TFORMAT 2 /BOOTSIZE:128K

Note To access the DOC module, execute the TFORMAT command line at the same time you execute the operating system.

10. Reset your system.
11. Access the DOC drive as drive D:.

Note If a hard disk is installed, change Step 9 to the following command:
TFORMAT 3 /BOOTSIZE:128K
Then access the DOC drive as drive E: (Step 10).

Booting from the DOC drive

1. Add an operating system to the DOC. For ROM DOS, use the SYS command.
2. Execute:
   SETSSD SSD1 /after
3. Reset the system.

Appendix D: Accessories

Table D-1 PC-510 mating connectors

Connector	Name	Description	Mating receptacle
J1 J17 J18	Speaker OPTOA/OPTOB Battery	4-pin, in-line connector	DuPont BERG #65039-033 housing #48235-000 crimp to wire pins
J2 J3	Keyboard Mouse	6-pin DIN receptacle	AMP #212437-4 shield/housing #212435-7 ferrule #66728-5 pin contacts #212800-1 cord guard
J7 J4 J5	COM1/COM2 COM3/COM4 COM5/COM6	20-pin shrouded header	AMP #746288-4 receptacle #499252-2 strain relief
J6 J15 J16	LPT1 printer EZ I/O 1 EZ I/O 2	26-pin shrouded header	AMP #746288-6 receptacle #499252-3 strain relief
P8, P9	Power	6-pin connector	Molex #90331-X101 housing #08-50-0276 crimp terminal
J9	Floppy	34-pin shrouded header	AMP #746288-8 receptacle #499252-6 strain relief
J10	IDE hard drive	44-position 2mm x 2 header	AMP #111626-0 receptacle
J11	PC/104 interface	PC/104 8- or 16-bit receptacle	Samtec #ESQ-132-14-G-D (8-bit) #ESQ-120-14-G-D (16-bit)
J13	GPS	20-position 2mm x 2 header	AMP #111626-4 receptacle
J14	Flat panel	50-pin shrouded header	AMP #1-746288-0 receptacle #499252-4 strain relief
J19	PC-Video	60-pin shrouded header	AMP #1-111196-2 receptacle
J20	SVGA CRT analog	16-pin shrouded header	AMP #746288-3 receptacle #499252-8 strain relief

Table D-2 Cables and terminal board

Product	Description	Octagon part number
VTC-20F	Dual serial cable	4866
Null modem adapter	9-pin to 9-pin	2470
VGA-12	VGA monitor cable	4865
CMA-26-12	12" cable for EZ I/O port	2776
CMA-26-24	24" cable for EZ I/O port	1257
3.5" hard drive adapter	2mm connector to 2.5", 3.5" hard drive	4080
STB-26	Terminal board, 26-position	2905

Table D-3 Memory devices

Product	Description	Octagon part number
4 MB DIMM	EDO DIMM memory module	4583
8 MB DIMM	EDO DIMM memory module	4584
16 MB DIMM	EDO DIMM memory module	4582
29C040	512K flash EPROM, 32-pin	4321
32 MB DIMM	EDO DIMM memory module	Call Octagon Systems

Table D-4 LCD displays and keypads

Product	Description	Octagon part number
LCD–4 x 20	LCD display w/cable, 40 character	2783
LCD–4 x 40	LCD display w/cable, 80 character	2784
2010	LCD display/keypad interface	3909
KP-1	Keypad w/cable, 16-key, low cost	1218
KP-2-16	Keypad w/cable, 16-key, relegendable	1736

Table D-5 Opto rack and modules

Product	Description	Octagon part number
MPB-16PC	PC opto rack, 16-position	3389
G4-IAC5	AC input, 90-140 VAC	2395
G4-IAC5A	AC input, 180-280 VAC	2396
G4-IDC5	DC input, 15-32 VDC	2397
G4-IDC5B	DC input, 4-16 VDC	2511
G4-IDC5D	DC input, 2.5-28 VDC	2529
G4-OAC5	AC output, 12-140 VAC	2398
G4-OAC5A	AC output, 12-280 VAC	2399
G4-ODC5	DC output, 5-60 VDC	2400
G4-ODC5A	DC output, 5-200 VDC	2503
G4-ODC5R	DC output, dry contact output	3013

Table D-6 Miscellaneous part numbers

Product	Description	Octagon part number
AT battery	Calendar/clock battery backup	3186
PC SmartLINK IV	Terminal emulation software	3447
CAMBASIC	Multitasking, industrial control programming language	4059
Jupiter installation kit	Rockwell jupiter GPS hardware and cable kit	4867

Warranty

Octagon Systems Corporation (Octagon), warrants that its standard hardware products will be free from defects in materials and workmanship under normal use and service for the current established warranty period. Octagon's obligation under this warranty shall not arise until Buyer returns the defective product, freight prepaid to Octagon's facility or another specified location. Octagon's only responsibility under this warranty is, at its option, to replace or repair, free of charge, any defective component part of such products.

Limitations on warranty

The warranty set forth above does not extend to and shall not apply to:

1. Products, including software, which have been repaired or altered by other than Octagon personnel, unless Buyer has properly altered or repaired the products in accordance with procedures previously approved in writing by Octagon.
2. Products which have been subject to power supply reversal, misuse, neglect, accident, or improper installation.
3. The design, capability, capacity, or suitability for use of the Software. Software is licensed on an "AS IS" basis without warranty.

The warranty and remedies set forth above are in lieu of all other warranties expressed or implied, oral or written, either in fact or by operation of law, statutory or otherwise, including warranties of merchantability and fitness for a particular purpose, which Octagon specifically disclaims. Octagon neither assumes nor authorizes any other liability in connection with the sale, installation or use of its products. Octagon shall have no liability for incidental or consequential damages of any kind arising out of the sale, delay in delivery, installation, or use of its products.

Service policy

1. If a product should fail during the warranty period, it will be repaired free of charge. For out of warranty repairs, the customer will be invoiced for repair charges at current standard labor and materials rates.
2. Customers that return products for repairs, within the warranty period, and the product is found to be free of defect, may be liable for the minimum current repair charge.

Returning a product for repair

Upon determining that repair services are required, the customer must:

1. Obtain an RMA (Return Material Authorization) number from the Customer Service Department, 303-430–1500.
2. If the request is for an out of warranty repair, a purchase order number or other acceptable information must be supplied by the customer.
3. Include a list of problems encountered along with your name, address, telephone, and RMA number.
4. Carefully package the product in an antistatic bag. (Failure to package in antistatic material will VOID all warranties.) Then package in a safe container for shipping.
5. Write RMA number on the outside of the box.
6. For products under warranty, the customer pays for shipping to Octagon. Octagon pays for shipping back to customer.
7. Other conditions and limitations may apply to international shipments.

Note PRODUCTS RETURNED TO OCTAGON FREIGHT COLLECT OR WITHOUT AN RMA NUMBER CANNOT BE ACCEPTED AND WILL BE RETURNED FREIGHT COLLECT.

Returns

There will be a 15% restocking charge on returned product that is unopened and unused, if Octagon accepts such a return. Returns will not be accepted 30 days after purchase. Opened and/or used products, non-standard products, software and printed materials are not returnable without prior written agreement.

Governing law

This agreement is made in, governed by and shall be construed in accordance with the laws of the State of Colorado.

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