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Rotary Actuated Air Gripper

MHR2, MDHR2/MHR3, MDHR3

2-finger type **3-finger type**

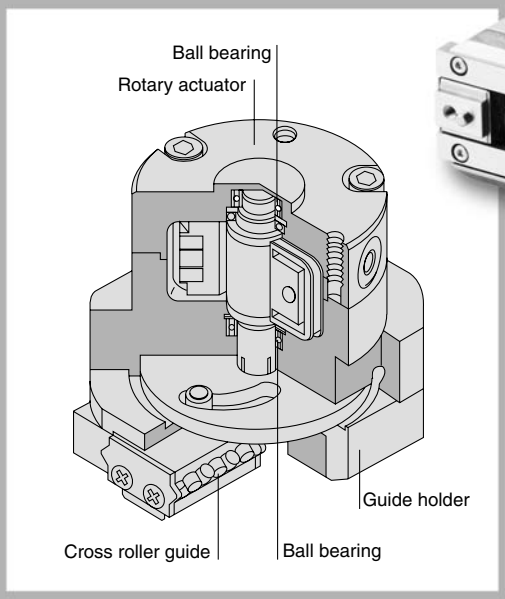
High Precision - Repeatability ±0.01 mm

Parallel opening and closing mechanism utilizing a cross roller guide produces smooth operation without play, with high precision and long life.

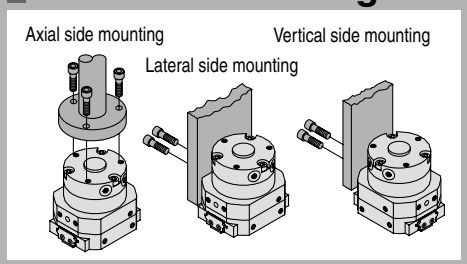
Low Profile

Using rotary actuators in the part of actuating portion enables a design compact.





Universal mounting



MDHR2 ***MDHR3***



■ Possible to mount solid state switch with indicator light D-M9. Easy to locate switch to optimum set point.

High rigidity

Fingers operate smoothly as the holder maintains the guide from the outside and prevents finger displacement.

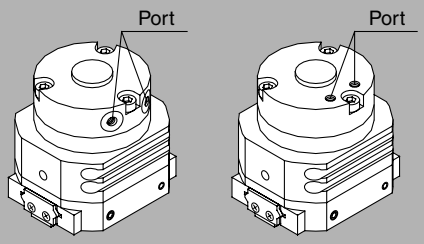


Applicable for Clean Series.

Refer to “Pneumatic Clean Series” catalog for details.

Internal/External gripping capability

Connection port on 2 sides



Series Variations

			(Nominal size) 10	15	20	30	Auto switch	
Rotary actuated air gripper	2-finger type	MHR2	●	●	●	●		P. 491 to P. 503
		MDHR2	●	●	●	●	●	
	3-finger type	MHR3	●	●				P. 504 to P. 511
		MDHR3	●	●			●	
Clean Series Rotary actuated air gripper	2-finger type	11-22-MHR2	●	●	●	●		Refer to the “Pneumatic Clean Series” catalog.
		11-22-MDHR2	●	●	●	●	●	
	3-finger type	11-22-MHR3	●	●				
		11-22-MDHR3	●	●			●	

Rotary Actuated Air Gripper/2-Finger Type

Series MHR2/MDHR2

Size: 10, 15, 20, 30

How to Order

Without auto switch

MHR 2 – 10 R – ☐

With auto switch (Built-in magnet)

MDHR 2 – 10 R – M9N S – ☐

With magnet
(For auto switch)

Number of fingers

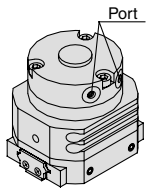
2	2 fingers

Nominal size

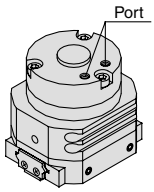
10
15
20
30

Connecting port

R: Body side



E: Axial side



Number of auto switches

Nil	2 pcs.
S	1 pc.

Made to Order
Refer to page 492 for details.

Applicable Auto Switch/Refer to pages 761 to 809 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage			Auto switch model		Lead wire length (m)*				Pre-wired connector	Applicable load	
								Electrical entry direction		0.5 (Nil)	1 (M)	3 (L)	5 (Z)			
					DC		AC	Perpendicular	In-line							
Solid state switch	—	Grommet	Yes	3-wire (NPN)	24V	5V,12V	—	**M9NV**	**M9N**	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire (PNP)				**M9PV**	**M9P**	●	●	●	○	○		
				2-wire		12V		**M9BV**	**M9B**	●	●	●	○	○	—	

∗ Lead wire length symbols: 0.5 m ····· Nil (Example) M9N
1 m ····· M (Example) M9NM
3 m ····· L (Example) M9NL
5 m ····· Z (Example) M9NZ

∗ Solid state auto switches marked with a "○" symbol are produced upon receipt of order.



Model/Specifications

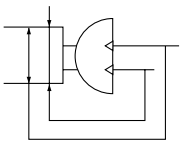
Nominal size		10	15	20	30
Action		Double acting			
Gripping force (N) (1) **(Effective value) at 0.5 MPa**	**External grip**	12	24	33	58
	Internal grip	12	25	34	59
Opening/ Closing stroke (Both sides)	**Finger closing width (mm)**	10	14	16	19
	Finger opening width (mm)	16	22	28	37
	Stroke (mm)	6	8	12	18
Mass (g) (2)		100 (95)	180 (175)	390 (380)	760 (740)
Connection port		M3 X 0.5		M5 X 0.8	
Repeatability		±0.01mm			
Fluid		Air			
Operating pressure		0.2 to 0.6 MPa	0.15 to 0.6 MPa		
Ambient and fluid temperature		0 to 60°C			
Max. operating frequency		180 c.p.m			
Lubrication		Non-lube			

Note 1) Refer to page 494 “Effective Gripping Force” for details of Gripping force at each gripping point. Value of effective gripping force is measured at the middle of opening/closing stroke.

Note 2) ( ) Value shows MDHR mass, but it does not include auto switch mass.

When the finger opening/closing speed is set as the total stroke of 0.2 seconds or more, it may cause the product to stick or completely stop its movement.

JIS Symbol



Made to Order

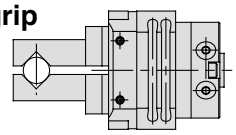
(Refer to pages 683 to 713 for details.)

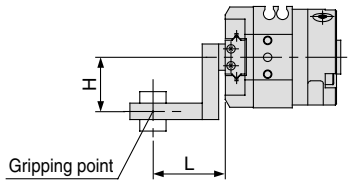
Symbol	Specifications/Description
-X32	Countermeasure for condensation
-X63	Fluorine grease

Gripping Point

- Workpiece gripping point should be within the gripping point range: The range shown for each operating pressure given in the graphs to the right.
- When the gripping point distance becomes large, the finger attachment applies an excessively large load to the finger sliding section, causing excessive play of the fingers and possibly leading to premature failure.

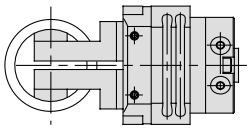
External grip

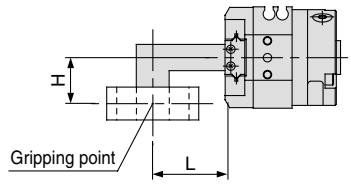




L: Distance to the gripping point
H: Overhang distance

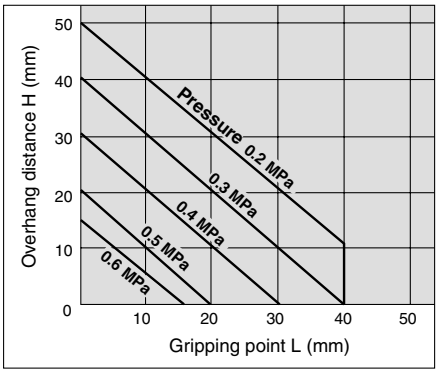
Internal grip



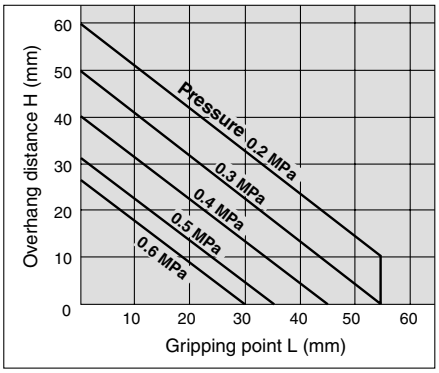


Limitation of Gripping: External Grip/Internal Grip

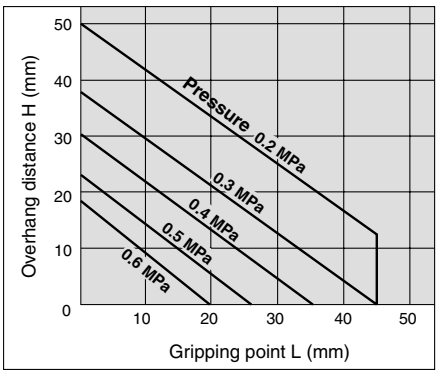
MHR2-10/MDHR2-10



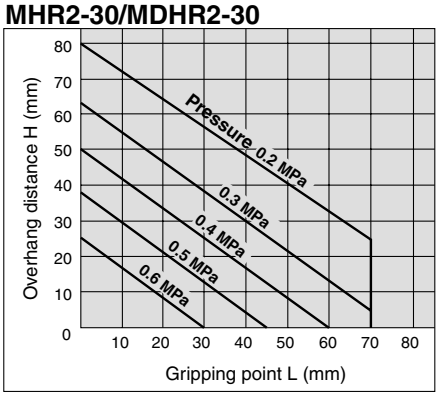
MHR2-20/MDHR2-20



MHR2-15/MDHR2-15



MHR2-30/MDHR2-30

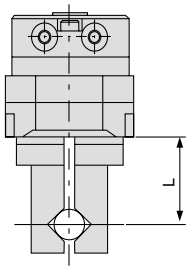


Effective Gripping Force

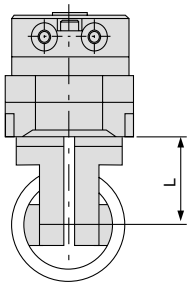
Guidelines for the selection of the gripper with respect to component mass

- Although conditions differ according to the workpiece shape and the coefficient of friction between the attachments and the workpiece, select a model that can provide a gripping force of 10 to 20 times the workpiece mass, or more.
- If high acceleration, deceleration or impact forces are encountered during motion a further margin of safety should be considered.

External grip



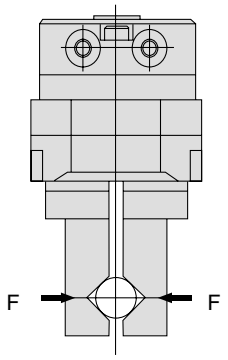
Internal grip



L: Gripping point length (mm)

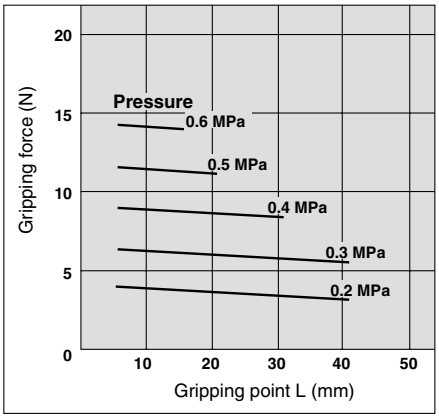
- **Indication of effective gripping force**

The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when both fingers and attachments are in full contact with the workpiece as shown in the figure below.

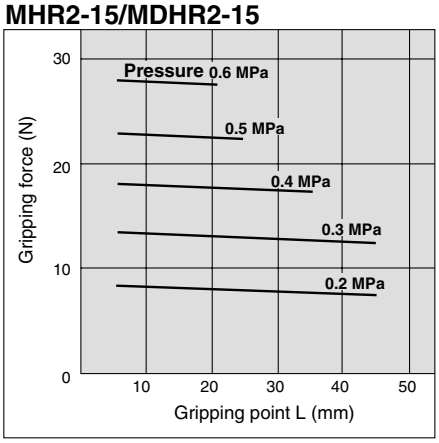


External Grip

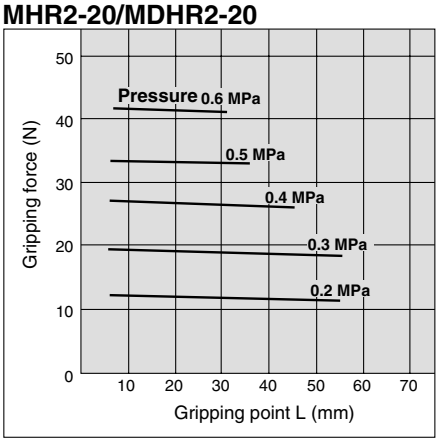
MHR2-10/MDHR2-10



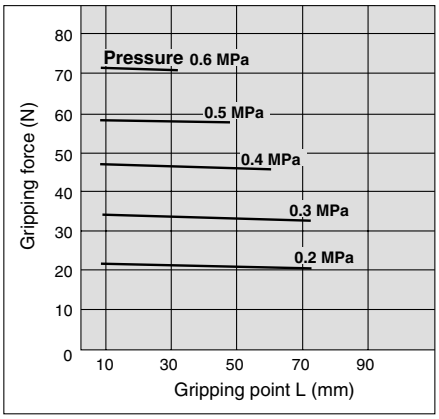
MHR2-15/MDHR2-15



MHR2-20/MDHR2-20

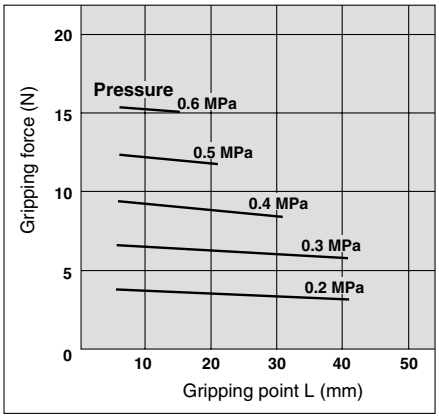


MHR2-30/MDHR2-30

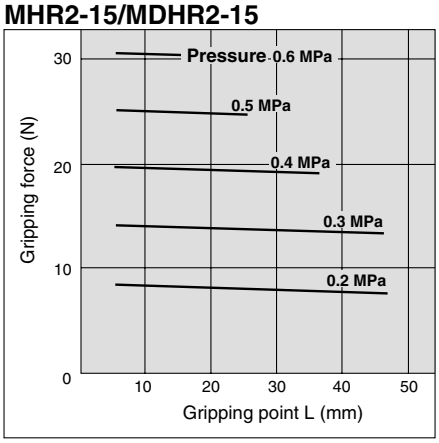


Internal Grip

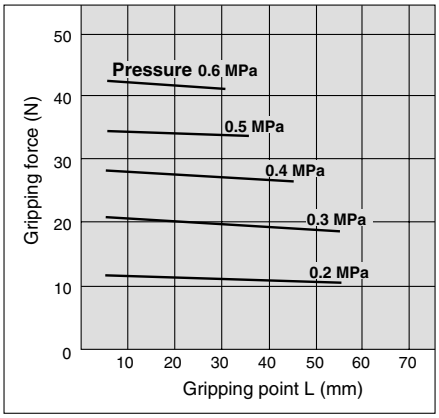
MHR2-10/MDHR2-10



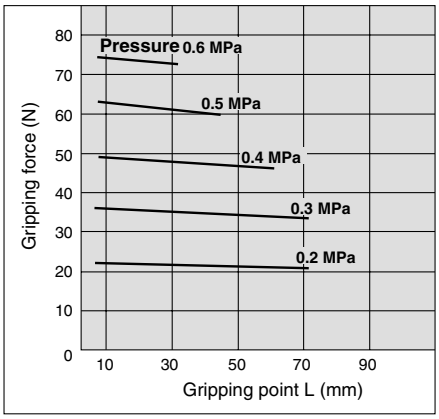
MHR2-15/MDHR2-15



MHR2-20/MDHR2-20

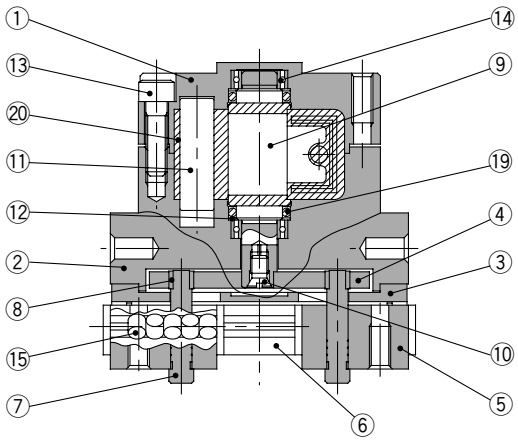


MHR2-30/MDHR2-30

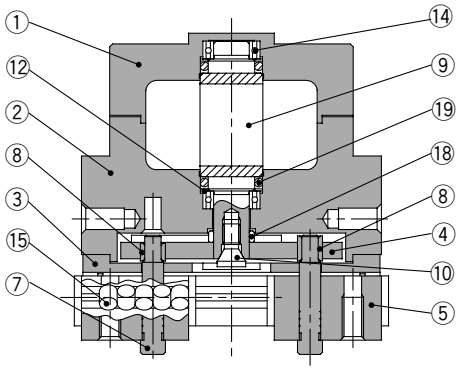


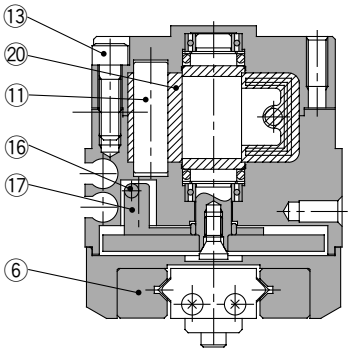
Construction

MHR2



MDHR2





Component Parts

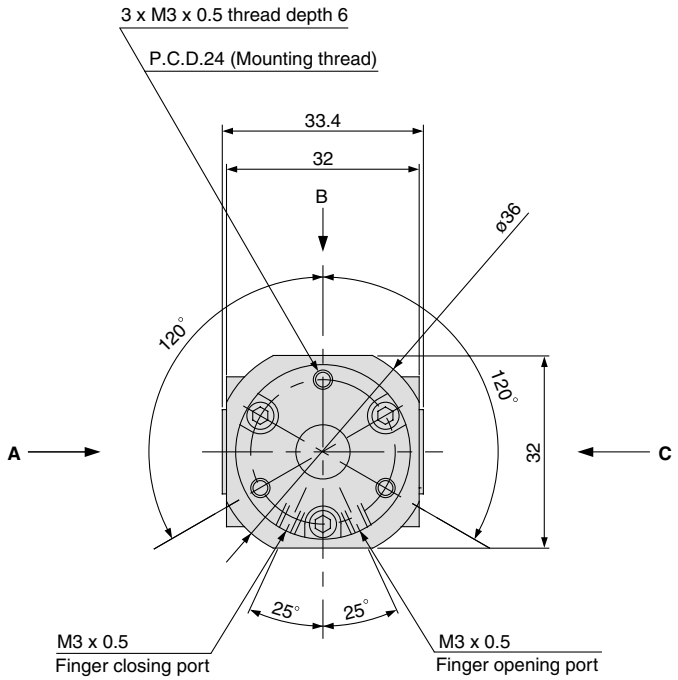
No.	Description	Material	Note
1	**Body**	Aluminum alloy	Hard anodized
2	**Adaptor body**	Aluminum alloy	Hard anodized
3	**Guide holder**	Stainless steel	
4	**Cam**	Cold rolled steel	Nitriding
5	**Finger assembly**	Stainless steel	Heat treated
6	**Guide**	Stainless steel	Heat treated
7	**Pin**	Carbon steel	Heat treated Electroless nickel plated
8	**Pin roller**	Stainless steel	Nitriding
9	**Vane shaft**	Stainless steel, NBR	M□HR2-30 is carbon steel NBR
10	**Joint bolt**	Chrome molybdenum steel	Zinc chromated

Component Parts

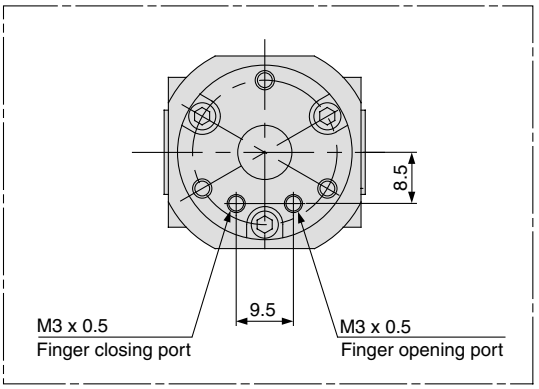
No.	Description	Material	Note
11	**Stopper**	Resin	
12	**Back-up ring**	Stainless steel plate	
13	**Hexagon socket head bolt**	Stainless steel	
14	**Bearing**	High carbon chrome bearing steel	
15	**Cylindrical roller**	—	
16	**Magnet**	Stainless steel	
17	**Magnet holder**	Aluminum alloy	Hard anodized
18	**Roller**	Stainless steel	
19	**O-ring**	NBR	
20	**Stopper seal**	NBR	

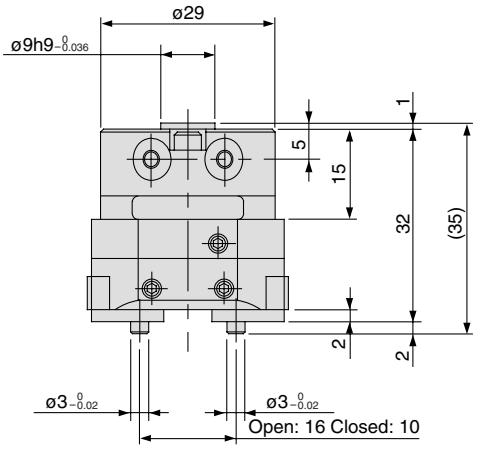
Nominal Size 10

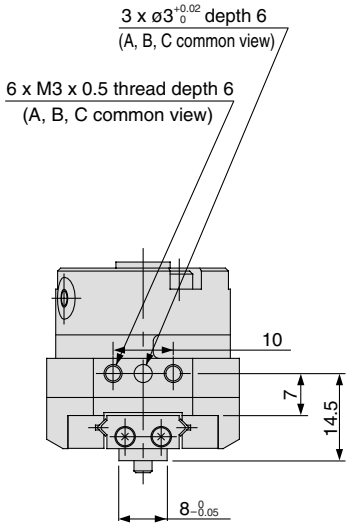
Without auto switch : MHR2-10R

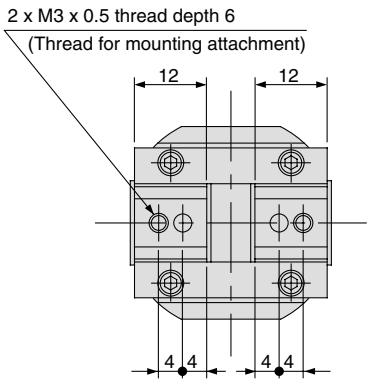


MHR2-10E Port Location

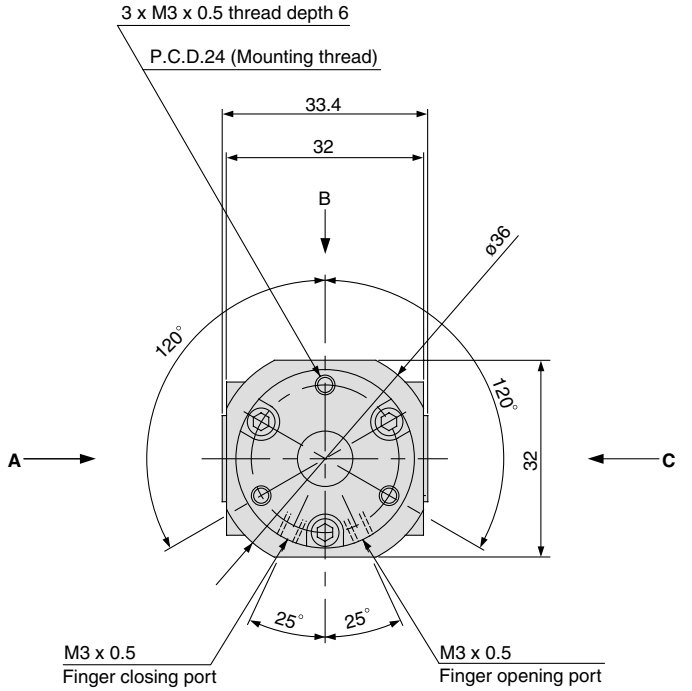




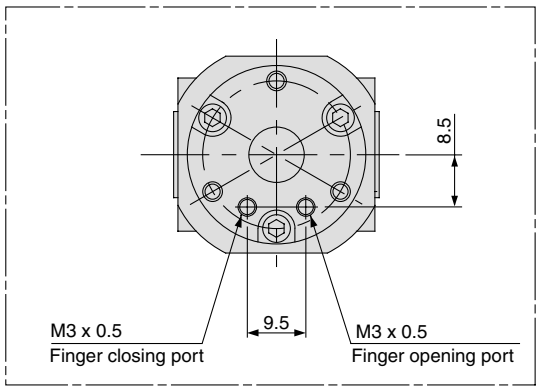


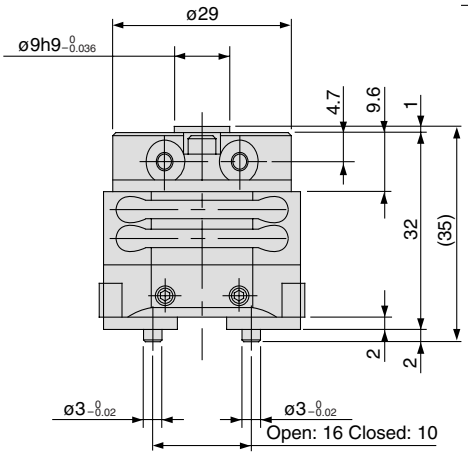


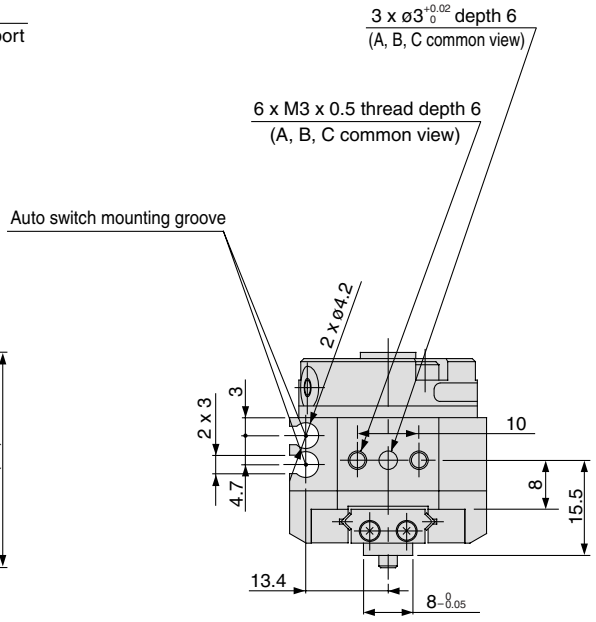
With auto switch (Built-in magnet) : MDHR2-10R

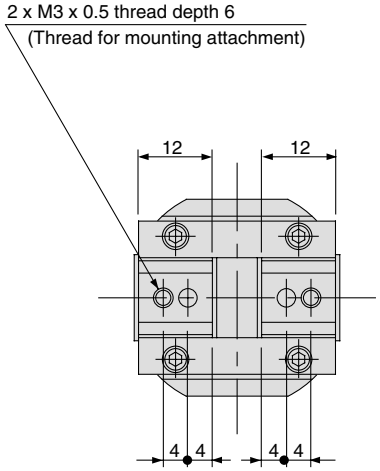


MDHR2-10E Port Location



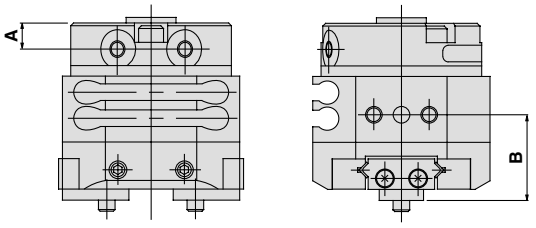






Dimensional Differences between MHR and MDHR

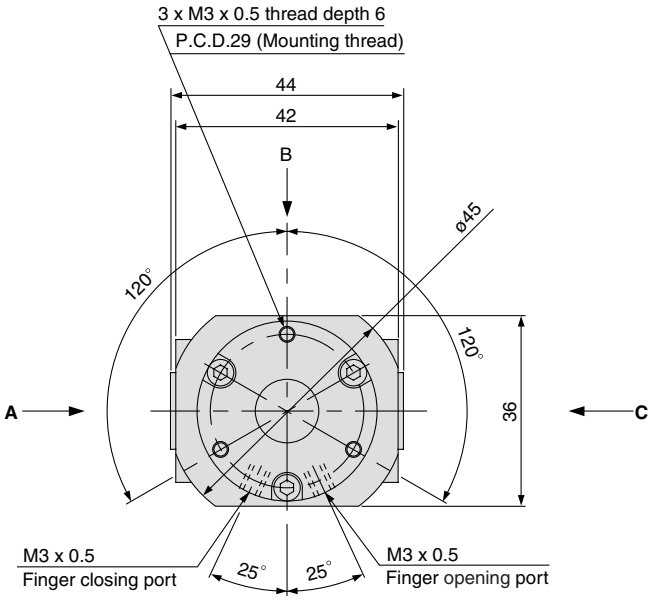
The following dimensions are different between series MHR and MDHR. And also, body shapes are different depending on auto switch mounting groove.



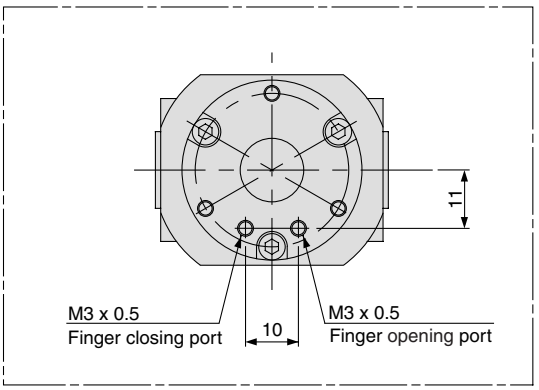
Model		A	B
MHR2	-10R	5	14.5
	-10E	—	14.5
MDHR2	-10R	4.7	15.5
	-10E	—	15.5

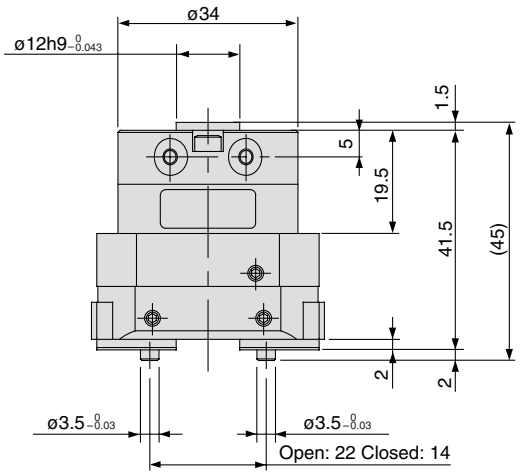
Nominal Size 15

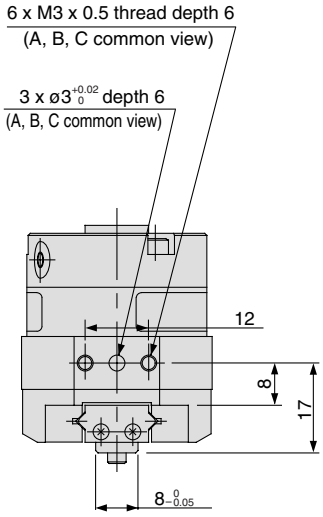
Without auto switch : MHR2-15R

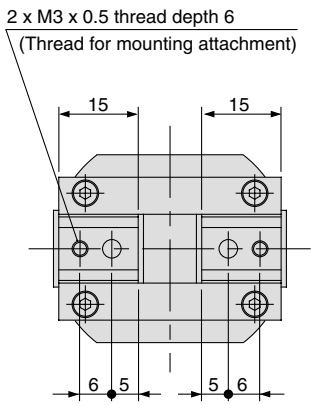


MHR2-15E Port Location

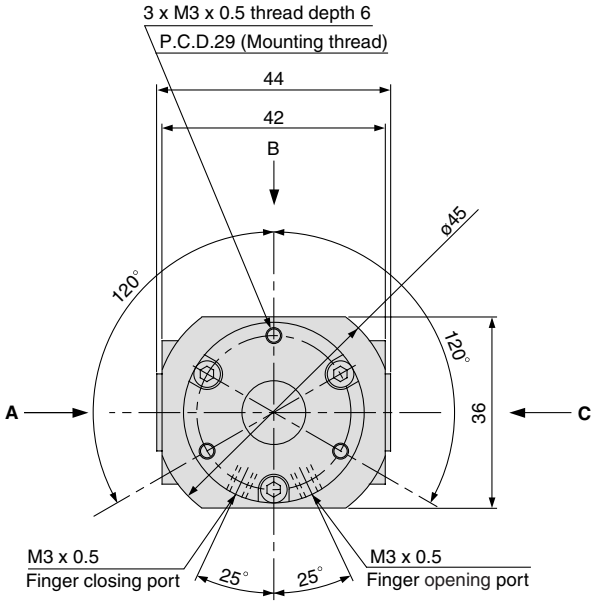




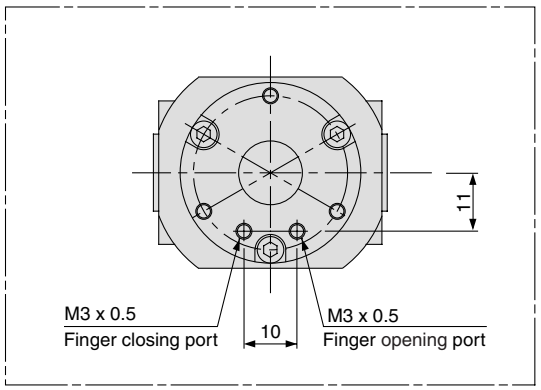


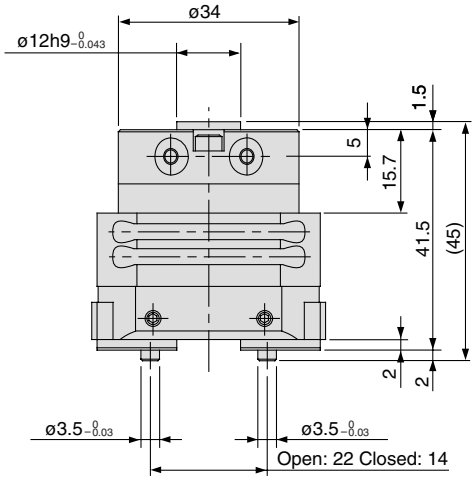


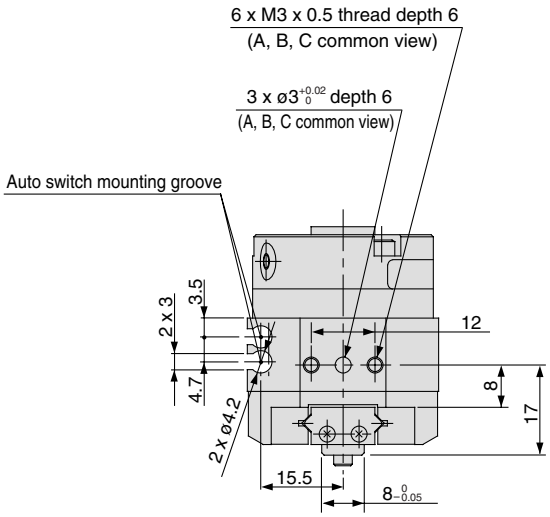
With auto switch (Built-in magnet) : MDHR2-15R

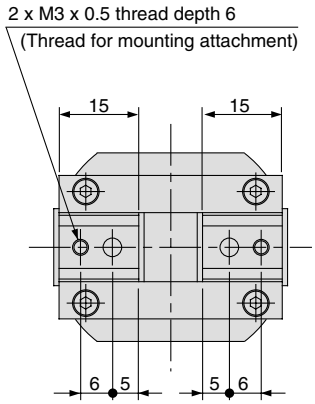


MDHR2-15E Port Location



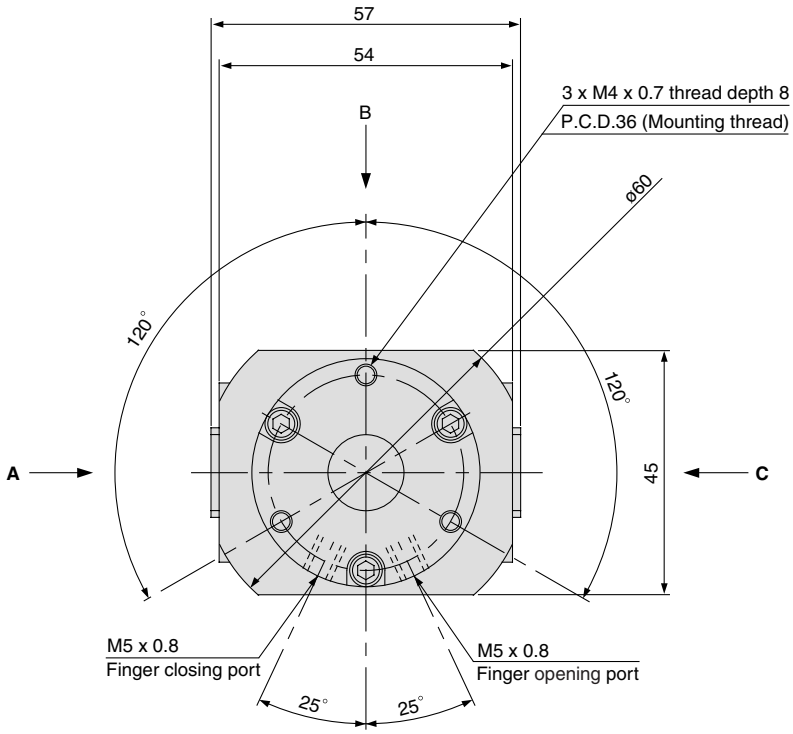




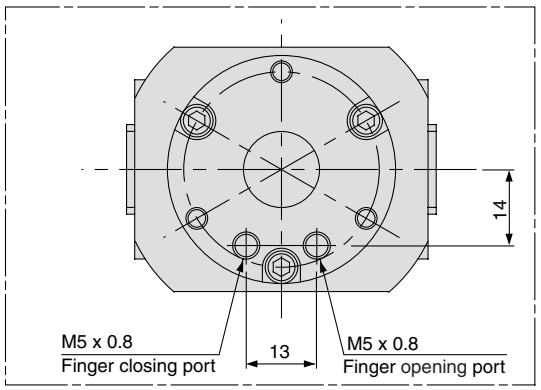


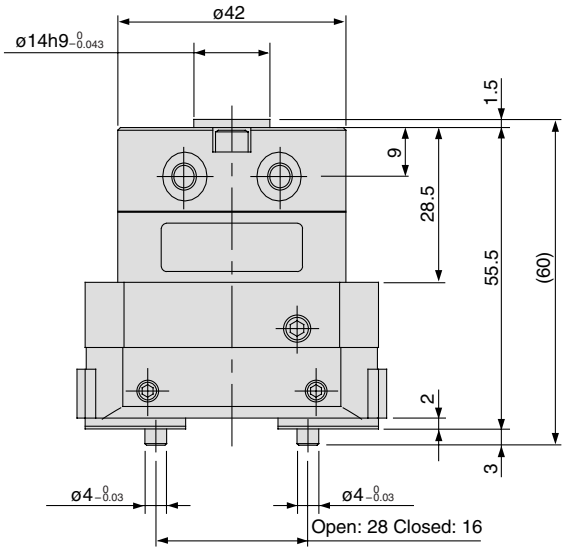
Nominal Size 20

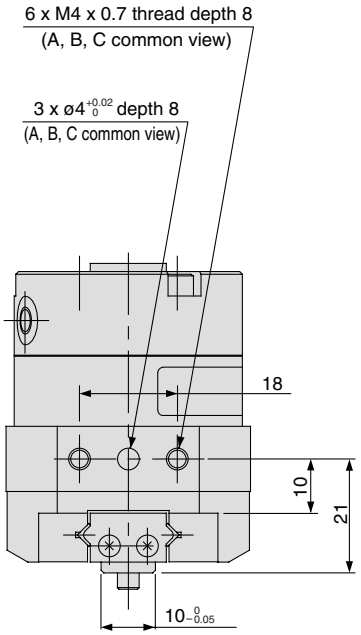
Without auto switch : MHR2-20R

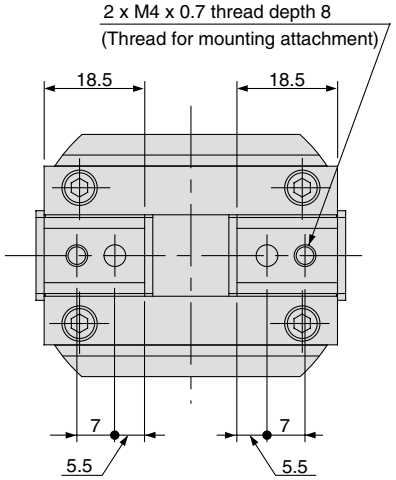


MHR2-20E Port Location

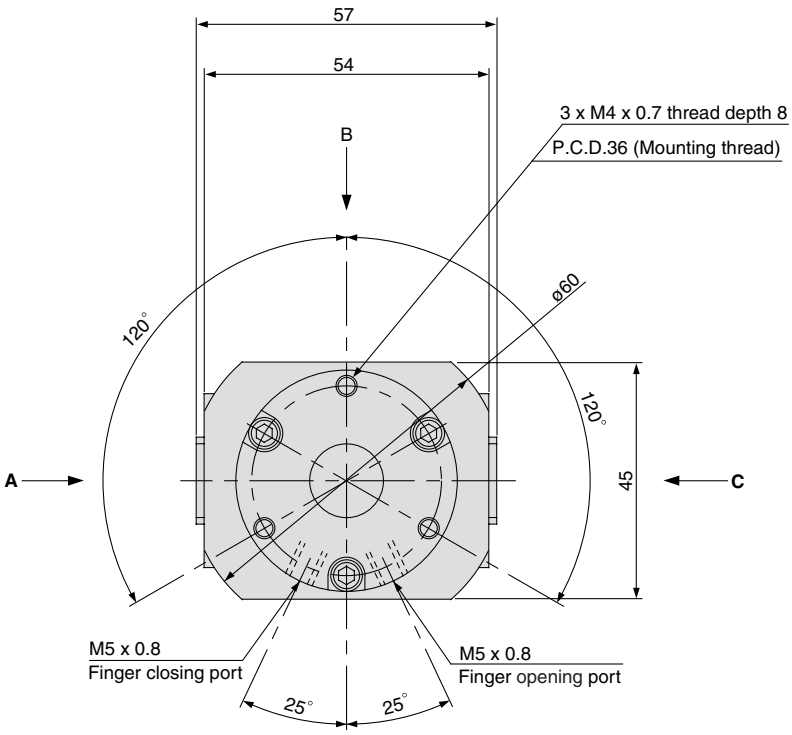




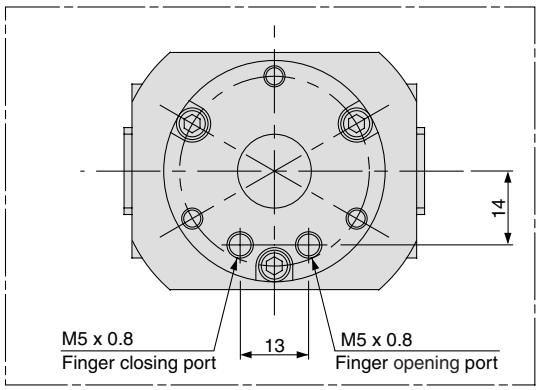


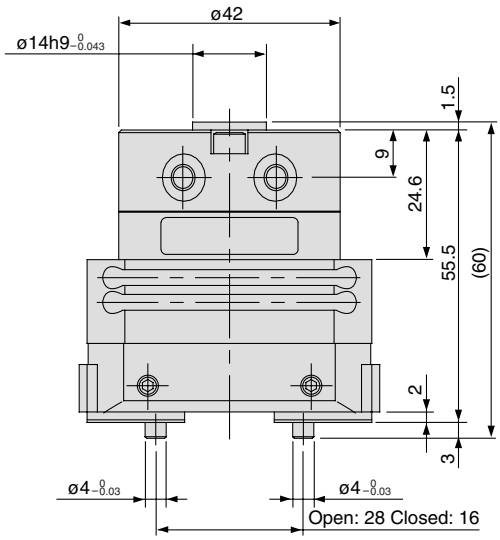


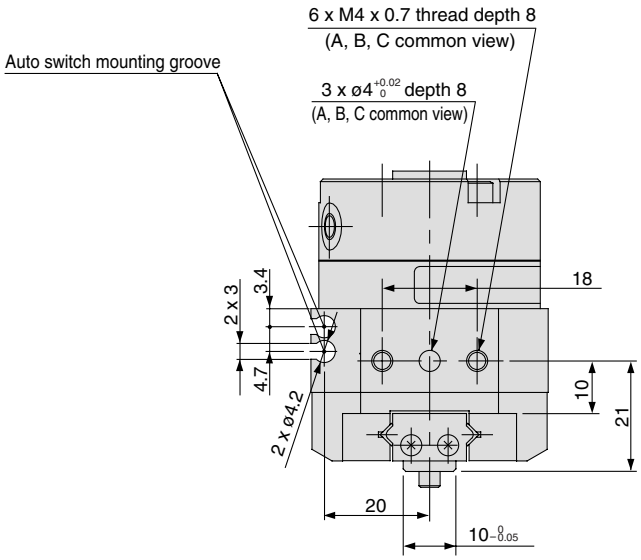
With auto switch (Built-in magnet) : MDHR2-20R

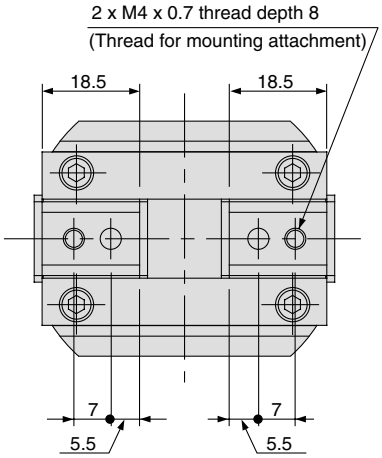


MDHR2-20E Port Location



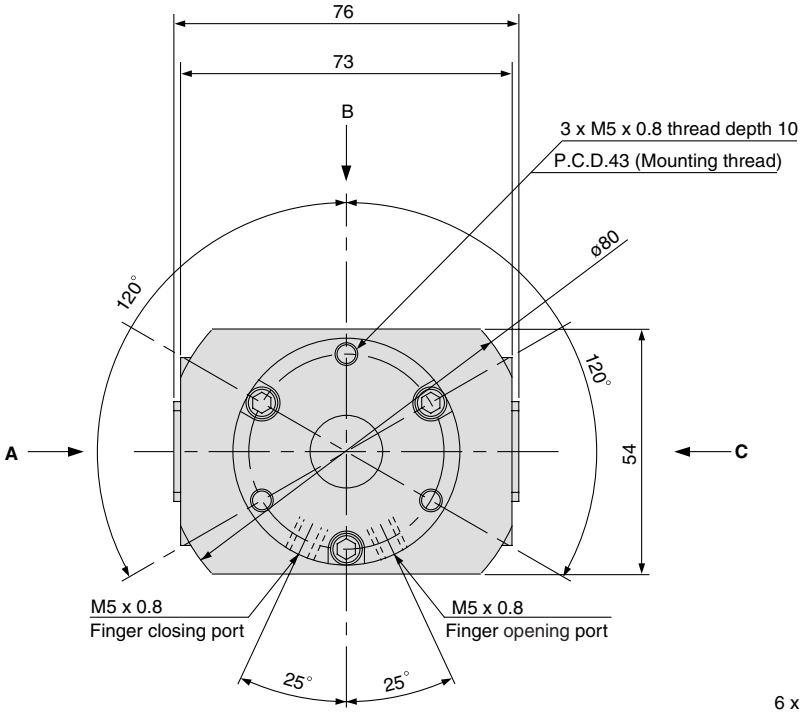




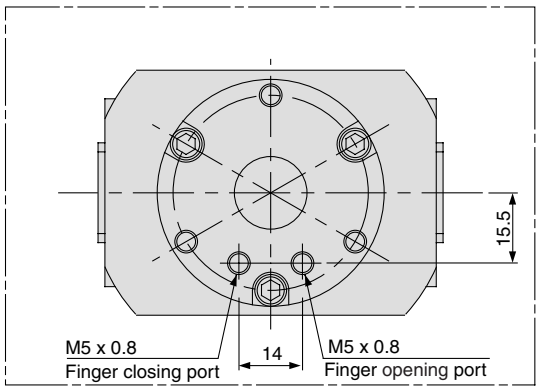


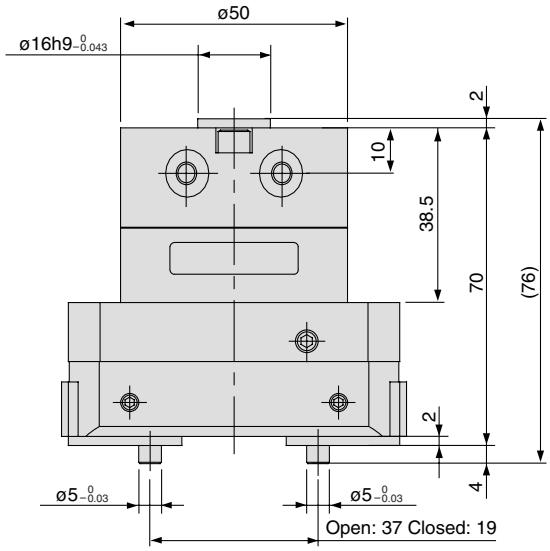
Nominal Size 30

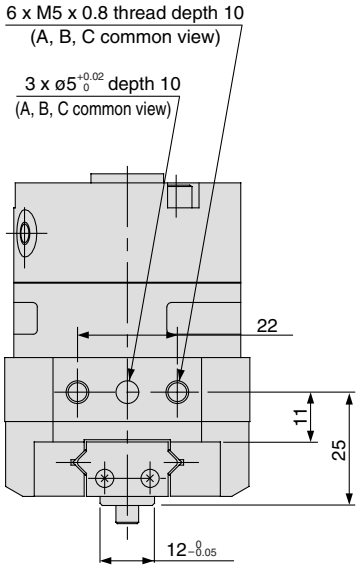
Without auto switch : MHR2-30R

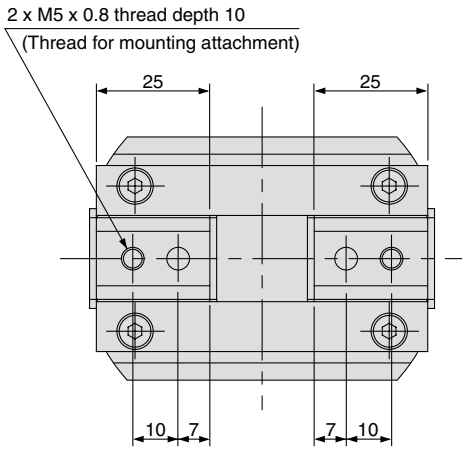


MHR2-30E Port Location

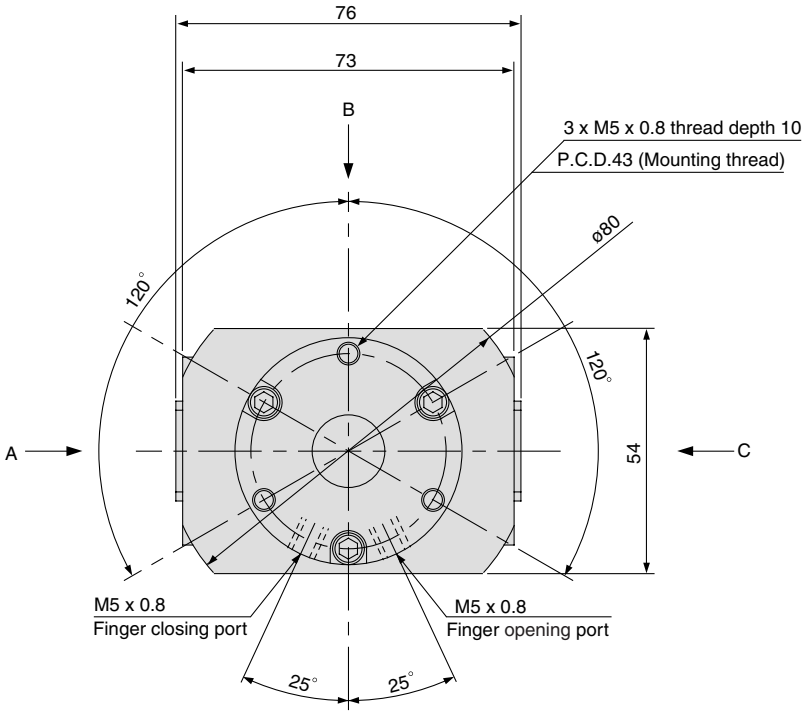




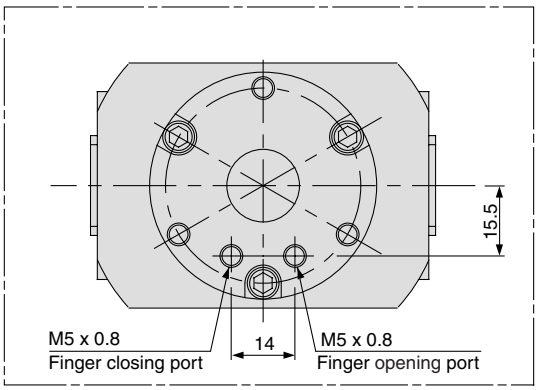


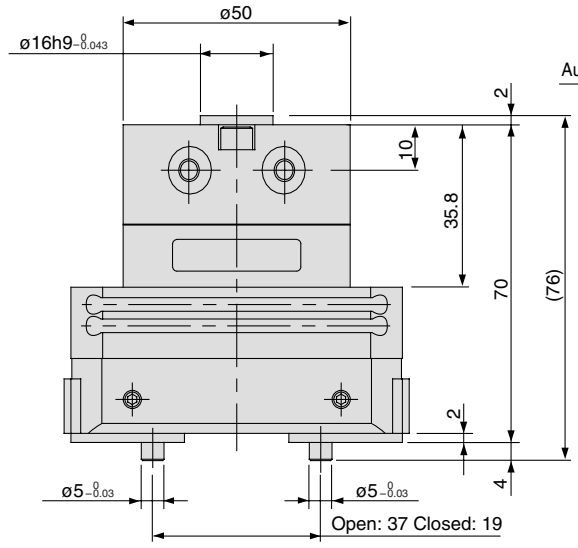


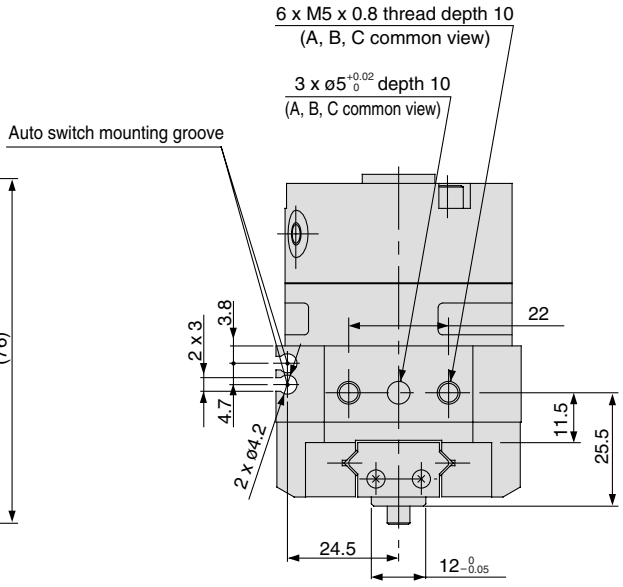
With auto switch (Built-in magnet) : MDHR2-30R

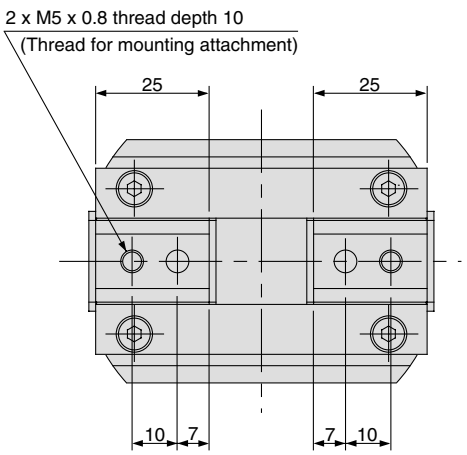


MDHR2-30E Port Location



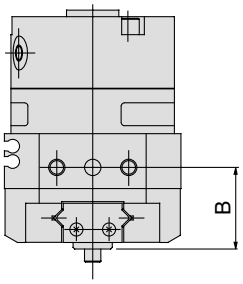






Dimensional Differences between MHR and MDHR

The following dimensions are different between series MHR and MDHR. And also, body shapes are different depending on auto switch mounting groove.



Model	B
MHR2-30□	25
MDHR2-30□	25.5

Rotary Actuated Air Gripper/3-Finger Type

Series MHR3/MDHR3

Size: 10, 15

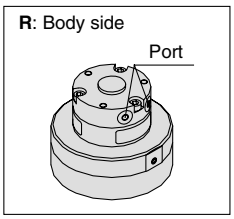
How to Order

Without auto switch MHR 3 – 10 R –

With auto switch (Built-in magnet) MDHR 3 – 10 R – M9N S –

Connecting port

R	Body side



With magnet (For auto switch)

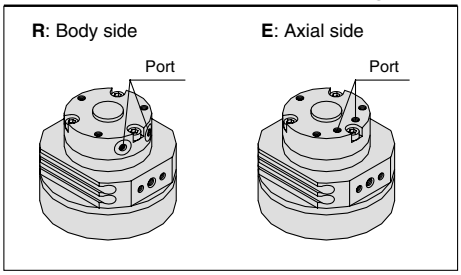
Number of fingers

3	3 fingers

Nominal size

10
15

Connecting port



Made to Order
Refer to page 505 for details.

Number of auto switches

NIL	2 pcs.
S	1 pc.

Applicable Auto Switch/Refer to pages 761 to 809 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage			Auto switch model		Lead wire length (m)*				Pre-wired connector	Applicable load	
								Electrical entry direction		0.5 (Nil)	1 (M)	3 (L)	5 (Z)			
					DC		AC	Perpendicular	In-line							
Solid state switch	—	Grommet	Yes	3-wire(NPN)	24V	5V, 12V	—	M9NV	M9N	●	●	●	○	○	IC circuit	Relay, PLC
				3-wire(PNP)				M9PV	M9P	●	●	●	○	○		
				2-wire		12V		M9BV	M9B	●	●	●	○	○	—	

* Lead wire length symbols: 0.5 m ····· Nil (Example) M9N
1 m ····· M (Example) M9NM
3 m ····· L (Example) M9NL
5 m ····· Z (Example) M9NZ

* Solid state auto switches marked with a "○" symbol are produced upon receipt of order.



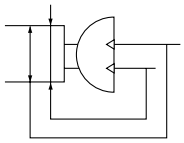
Model/Specifications

Nominal size		10	15
Action		Double acting	
Holding force (N) (Effective value) (1) **at 0.5 MPa**	**External grip**	7	13
	Internal grip	6.5	12
Opening/Closing stroke (Diameter)	**Finger closing width (mm)**	16	19
	Finger opening width (mm)	22	27
	Stroke (mm)	6	8
Mass (g) (2)		120 (125)	225 (230)
Connection port		M3 x 0.5	
Repeatability		± 0.01 mm	
Fluid		Air	
Operating pressure		0.2 to 0.6 MPa	0.15 to 0.6 MPa
Ambient and fluid temperature		0 to 60 °C	
Max. operating frequency		180 c.p.m	
Lubrication		Non-lube	

Note 1) Refer to page 506 “Effective Gripping Force” for details of gripping force at each gripping point.
Valve of effective gripping force is measured at the middle of opening/closing stroke.
Note 2) ( ) Value shows MDHR mass, but it does not include auto switch mass.

When the finger opening/closing speed is set as the total stroke of 0.2 seconds or more, it may cause the product to stick or completely stop its movement.

JIS Symbol



Made to Order

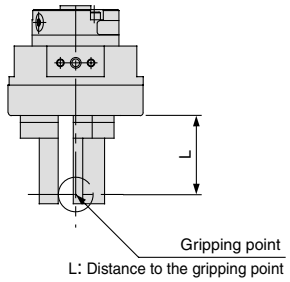
Made to Order

Refer to page 683 to 713 for details.

Symbol	Specifications/Description
-X32	Countermeasure for condensation
-X63	Fluorine grease

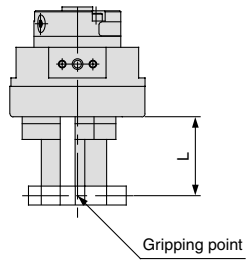
Gripping Point

External grip



L: Distance to the gripping point

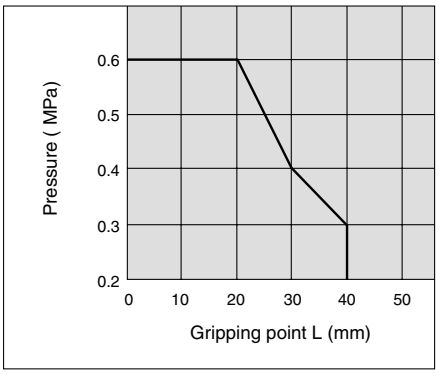
Internal grip



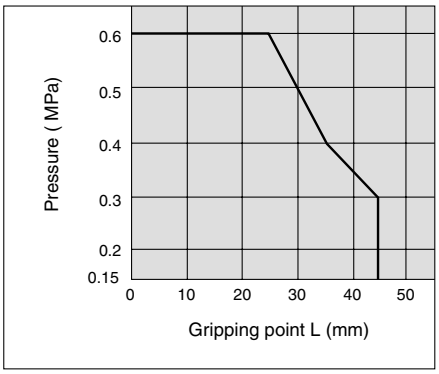
Limitation of Gripping: External Grip/Internal Grip

- Workpiece gripping point should be within the gripping point range: L shown below, by operating pressure.
- When the gripping point distance becomes large, the finger attachment applies an excessively large load to the finger sliding section, causing excessive play of the fingers and possibly leading to premature failure.

MHR3-10R/MDHR3-10□



MHR3-15R/MDHR3-15□

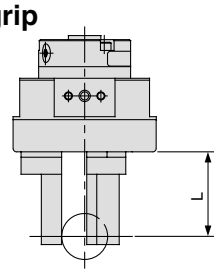


Effective Gripping Force

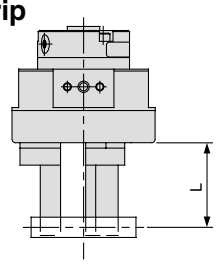
Guidelines for the selection of the gripper with respect to component mass

- Selection of the correct model depends upon the component mass, the coefficient of friction between the finger attachment and the component, and their respective configurations. A model should be selected with a gripping force of 7 to 14 times that of the component weight.
- If high acceleration, deceleration or impact forces are encountered during motion, a further margin of safety should be considered.

External grip



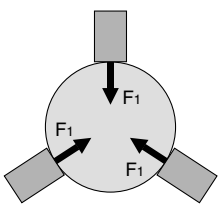
Internal grip



L: Gripping point length (mm)

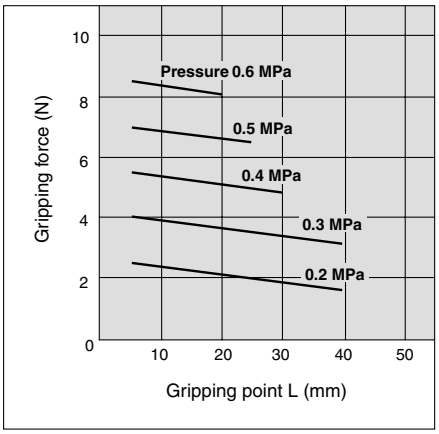
•Indication of effective gripping force

The effective gripping force shown in the graphs to the right is expressed as F, which is the thrust of one finger, when three fingers and attachments are in full contact with the workpiece as shown in the figure to the right.

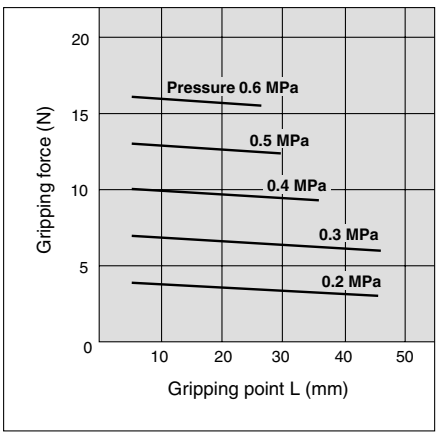


External Grip

MHR3-10R/MDHR3-10□

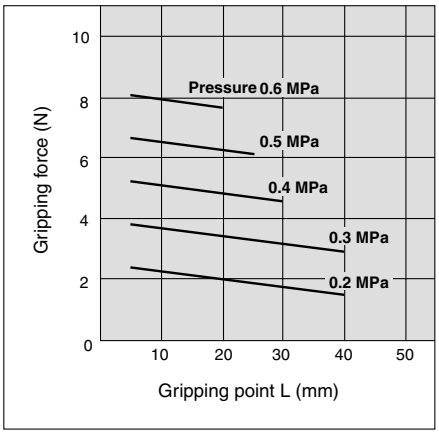


MHR3-15R/MDHR3-15□

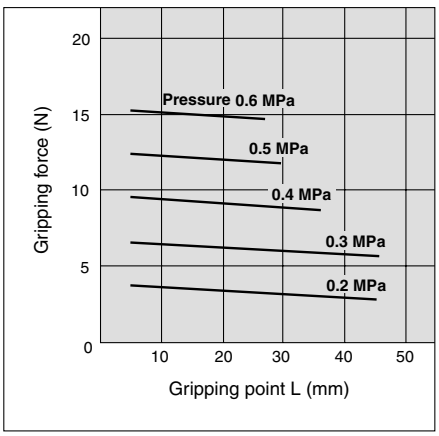


Internal Grip

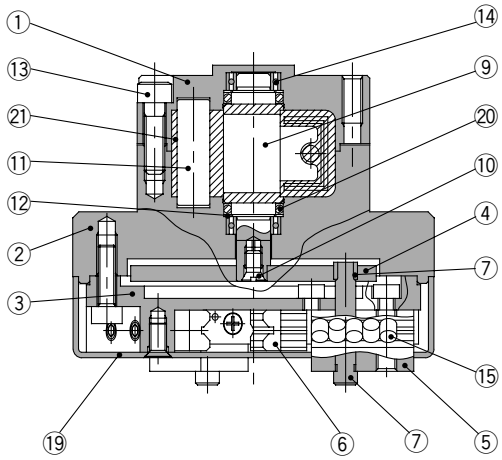
MHR3-10R/MDHR3-10□



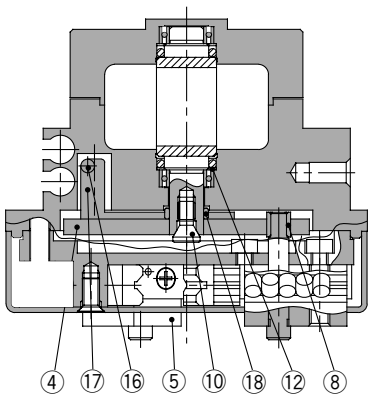
MHR3-15R/MDHR3-15□

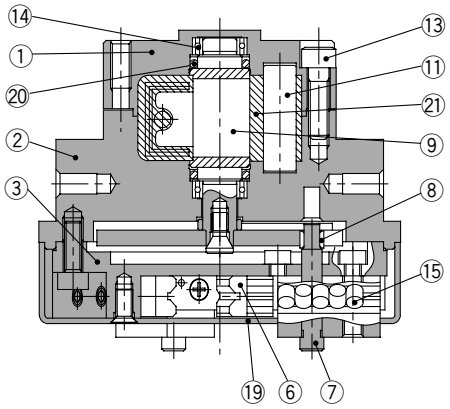


Construction



MDHR3





Component Parts

No.	Description	Material	Note
1	**Body**	Aluminum alloy	Hard anodized
2	**Adaptor body**	Aluminum alloy	Hard anodized
3	**Guide holder**	Stainless steel	
4	**Cam**	Cold rolled steel	Nitriding
5	**Finger assembly**	Stainless steel	Heat treated
6	**Guide**	Stainless steel	Heat treated
7	**Pin**	Carbon steel	Heat treated Electroless nickel plated
8	**Pin roller**	Stainless steel	Nitriding
9	**Vane shaft**	Stainless steel, NBR	
10	**Joint bolt**	Chrome molybdenum steel	Zinc chromated
11	**Stopper**	Resin	

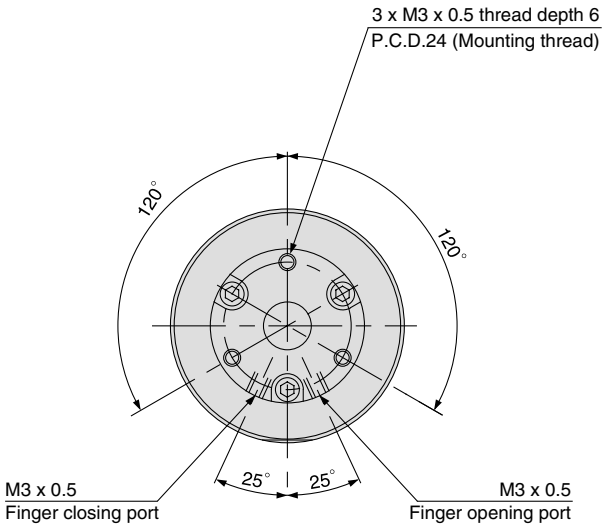
No.	Description	Material	Note
12	**Back-up ring**	Stainless steel plate	
13	**Hexagon socket head bolt**	Stainless steel	
14	**Bearing**	High carbon chrome bearing steel	
15	**Cylindrical roller**	Stainless steel	
16	**Magnet**	—	
17	**Magnet holder**	Aluminum alloy	Hard anodized
18	**Roller**	Stainless steel	
19	**Cover**	Aluminum alloy	Hard anodized
20	**O-ring**	NBR	
21	**Stopper seal**	NBR	

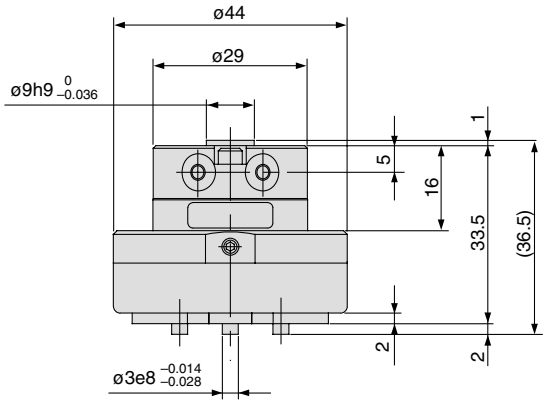
Replacement Parts

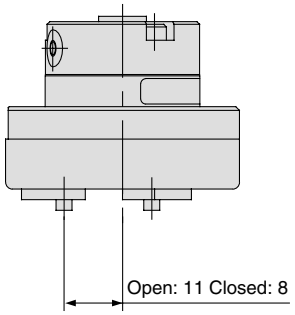
Description	**M□HR3-10□**	**M□HR3-15□**	Main parts
Cover	P3313128	P3313228	⑲

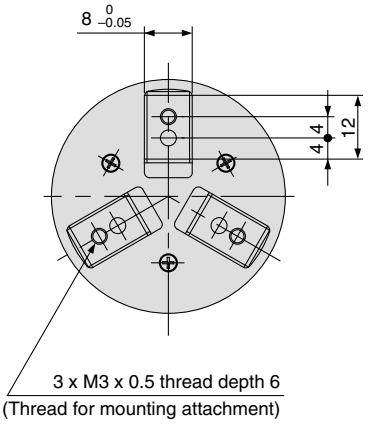
Nominal Size 10

Without auto switch: MHR3-10R

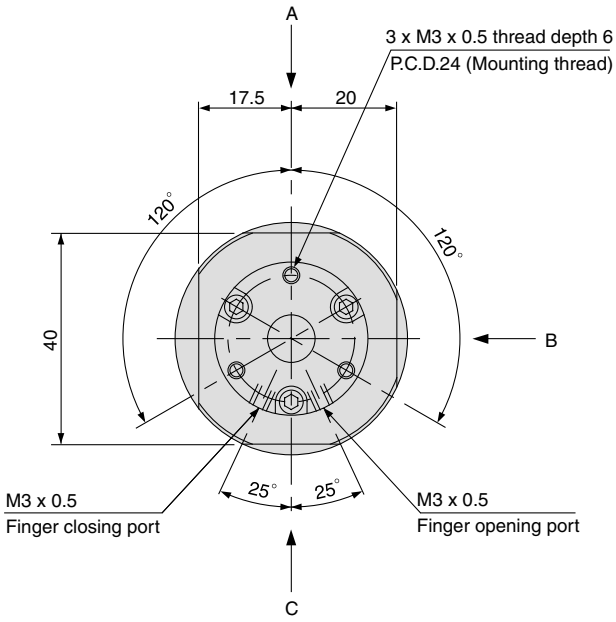




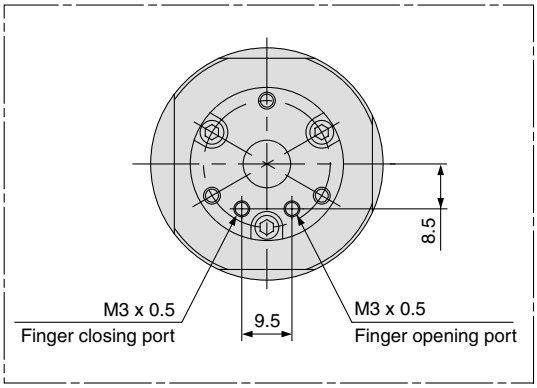


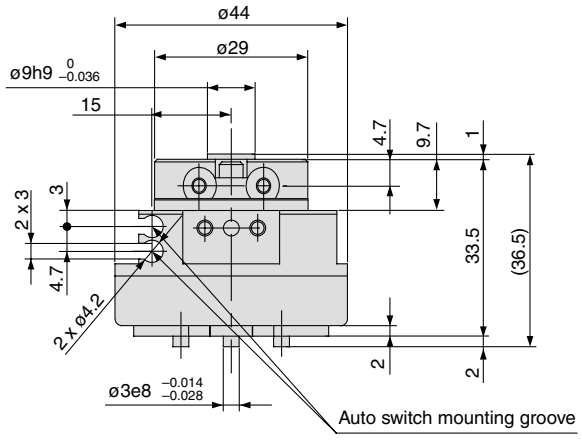


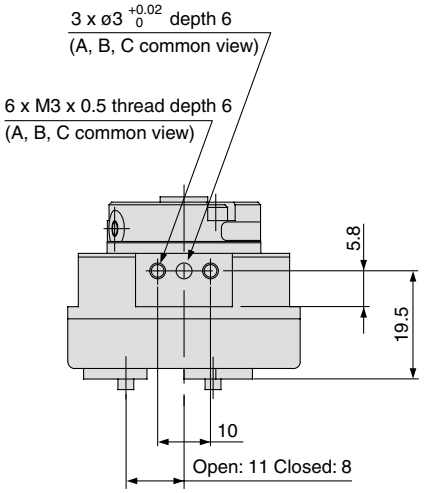
With auto switch (Built-in magnet): MDHR3-10R

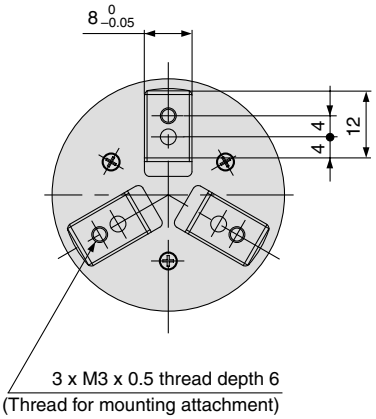


MDHR3-10E Port Location



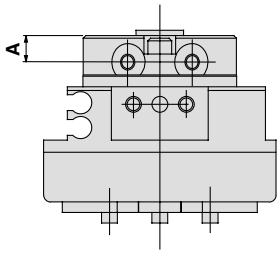






Dimensional Differences between MHR and MDHR

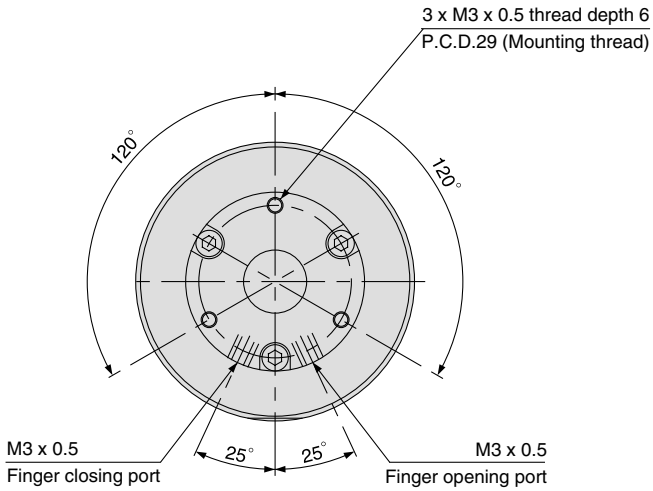
The following dimensions are different between series MHR and MDHR. And also, body shapes are different depending on auto switch mounting groove.

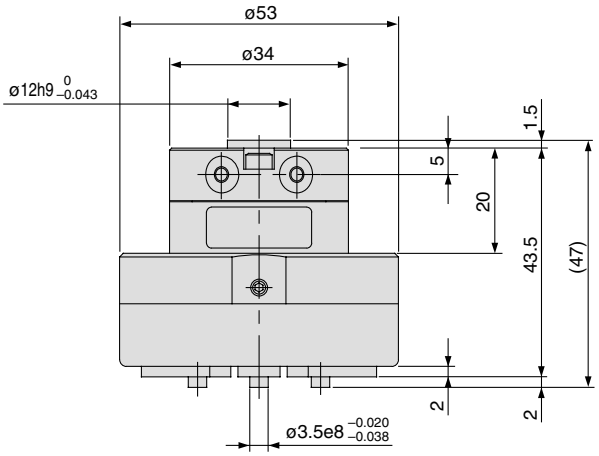


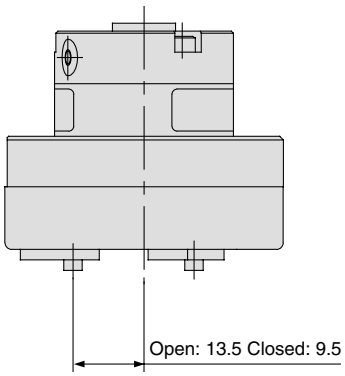
Model	A
MHR3-10R	5
MDHR3-10R	4.7

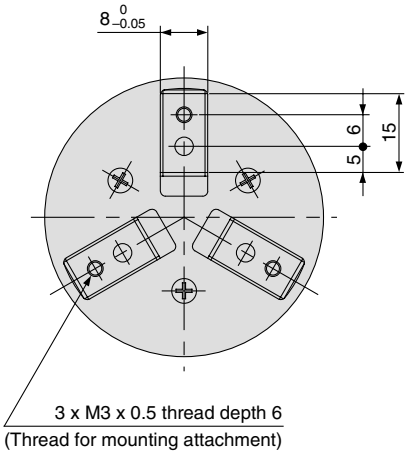
Nominal Size 15

Without auto switch: MHR3-15R

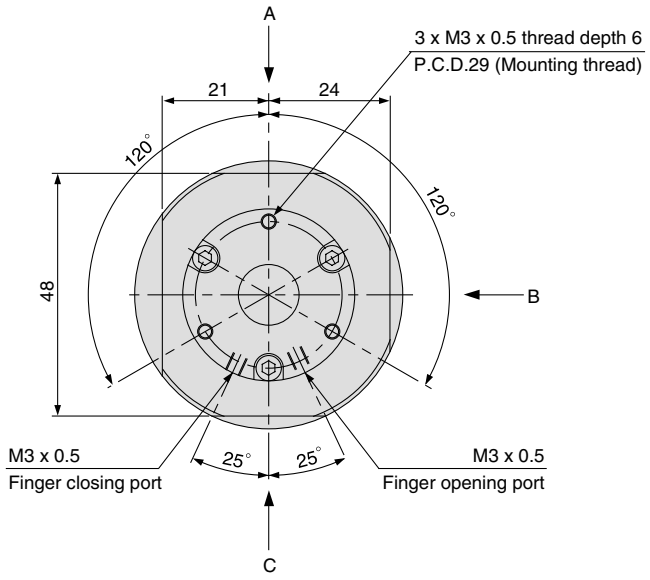




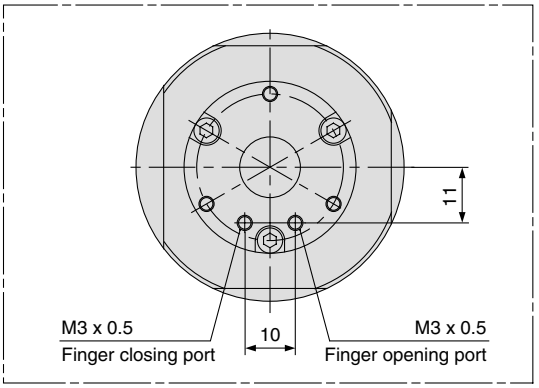


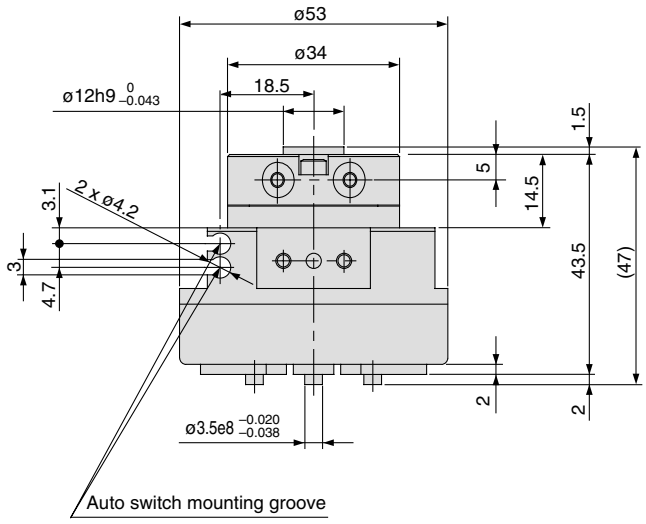


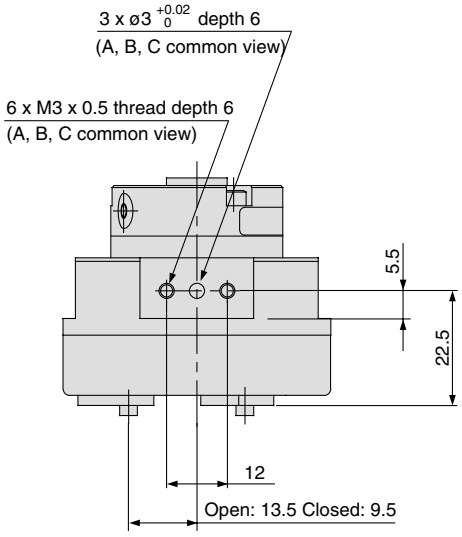
With auto switch (Built-in magnet): MDHR3-15R

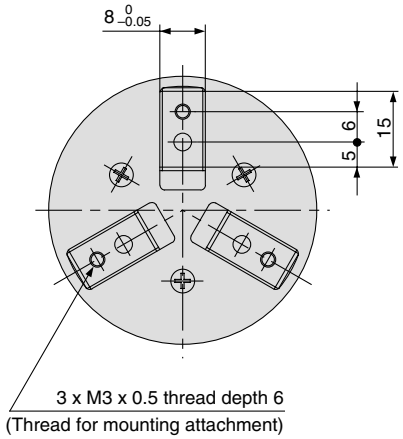


MDHR3-15E Port Location





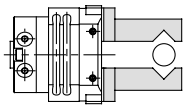
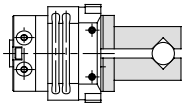
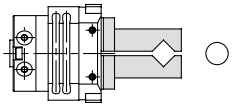
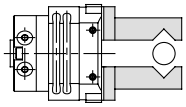
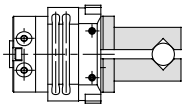
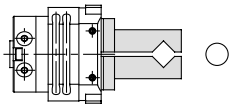
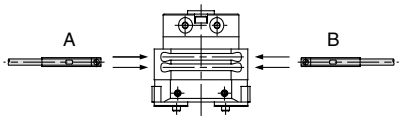
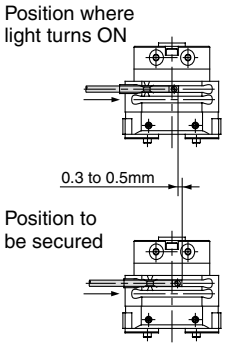
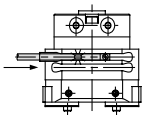
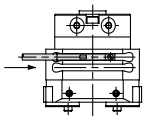
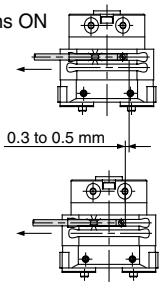




Series MDHR2/MDHR3
Auto Switch Installation Examples and Mounting Positions

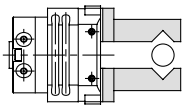
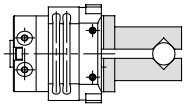
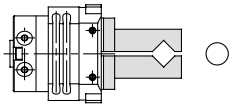
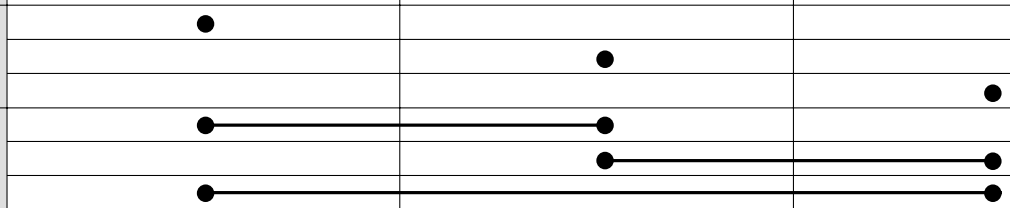
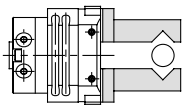
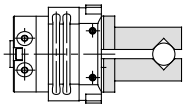
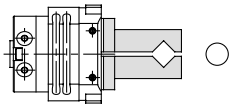
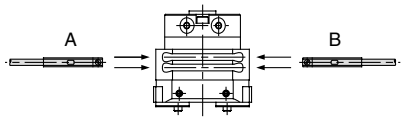
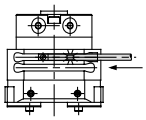
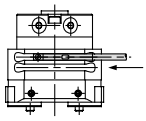
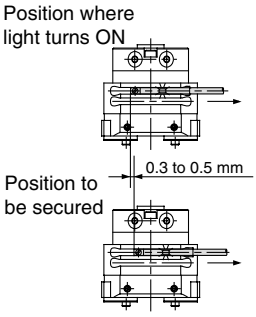
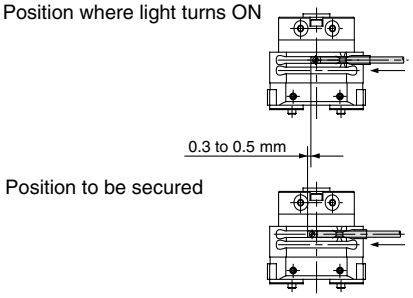
Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

1) Detection when Gripping Exterior of Workpiece/Auto Switch Mounted from Direction A

Detection example	1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released
Position to be detected	Position of fingers fully opened 	Position when gripping a workpiece 	Position of fingers fully closed 
Operation of auto switch	Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is held (Normal operation): Auto switch to turn OFF (Light not illuminating) When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light illuminating)
Detection combinations: One auto switch			
Detection combinations: Two auto switches			
How to determine auto switch installation position	Step 1) Fully open the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully close the fingers. 
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.	**In the case of mounting auto switch from A direction** Step 2) Insert the auto switch into the auto switch installation groove from direction A. 		
	Step 3) Slide the auto switch in the direction of the arrow until the light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.  Step 4) Slide the auto switch in the direction of the arrow until the indicator light goes out.  Step 5) Move the auto switch in the opposite direction, and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. 

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

2) Detection when Gripping Exterior of Workpiece/Auto Switch Mounted from Direction B

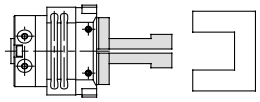
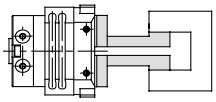
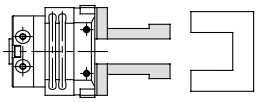
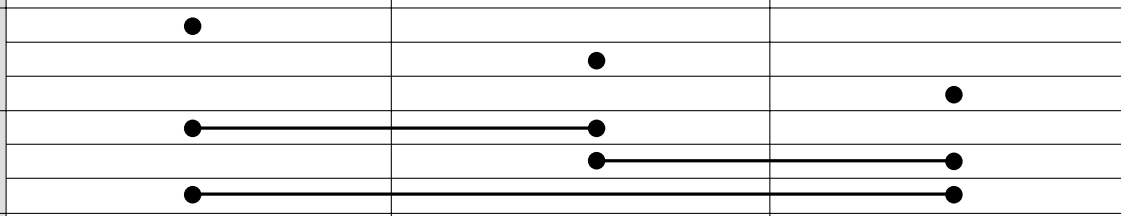
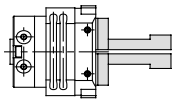
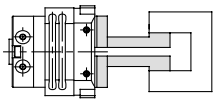
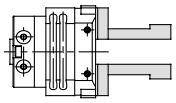
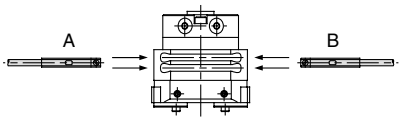
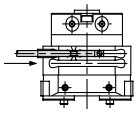
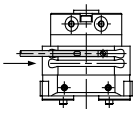
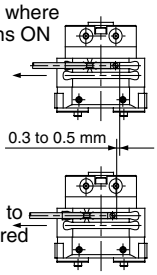
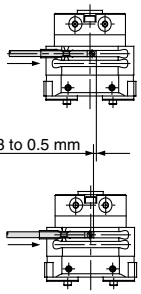
Detection example	1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released
Position to be detected	Position of fingers fully opened 	Position when gripping a workpiece 	Position of fingers fully closed 
Operation of auto switch	Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is held (Normal operation): Auto switch to turn OFF (Light not illuminating) When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light illuminating)
Detection combinations: One auto switch			
Detection combinations: Two auto switches			
How to determine auto switch installation position	Step 1) Fully open the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully close the fingers. 
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.	**In the case of mounting auto switch from B direction** Step 2) Insert the auto switch into the auto switch installation groove from direction B. 		
	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.  Step 4) Slide the auto switch in the direction of the arrow until the indicator light goes out  Step 5) Move the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. Move the switch an additional 0.3 to 0.5 mm in the direction of the arrow and fasten it. 

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

Series MDHR2/MDHR3
Auto Switch Installation Examples and Mounting Positions

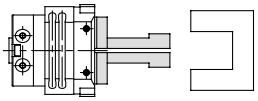
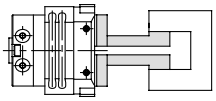
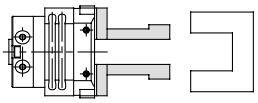
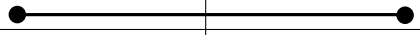
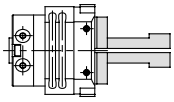
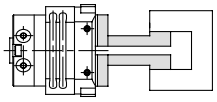
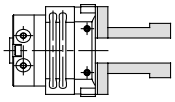
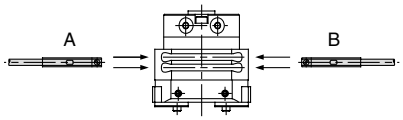
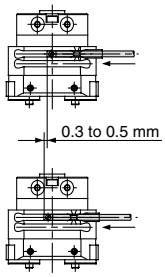
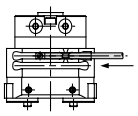
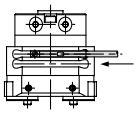
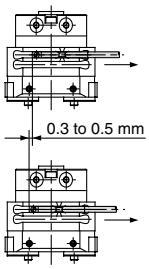
Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

3) Detection when Gripping Interior of Workpiece/Auto Switch Mounted from Direction A

Detection example	1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released
Position to be detected	Position of fingers fully closed 	Position when gripping a workpiece 	Position of fingers fully opened 
Operation of auto switch	Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is held (Normal operation): Auto switch to turn OFF (Light not illuminating) When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light illuminating)
Detection combinations: One auto switch			
Detection combinations: Two auto switches			
How to determine auto switch installation position	Step 1) Fully close the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully open the fingers. 
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.	**In the case of mounting auto switch from A direction** Step 2) Insert the auto switch into the auto switch installation groove from direction A. 		
	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.  Step 4) Slide the auto switch in the direction of the arrow until the indicator light goes out.  Step 5) Move the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. Position where light turns ON  Position to be secured	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. Move the switch an additional 0.3 to 0.5 mm in the direction of the arrow and fasten it. Position where light turns ON  Position to be secured

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

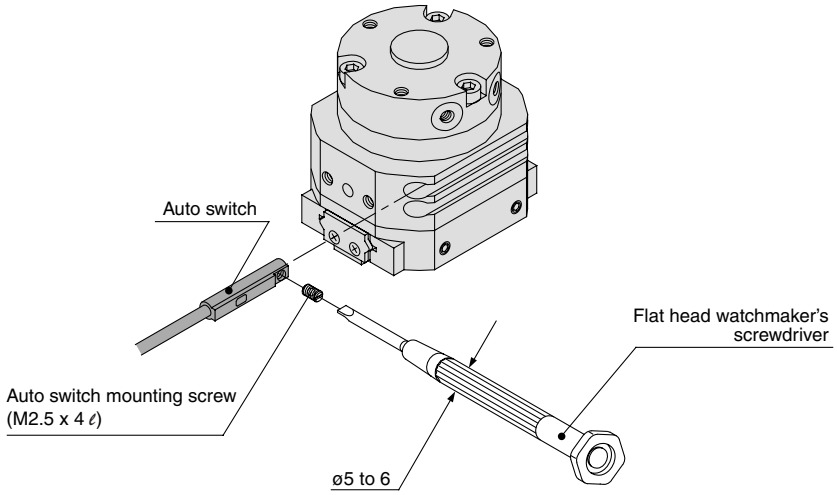
4) Detection when Gripping Interior of Workpiece/Auto Switch Mounted from Direction B

Detection example	1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released
Position to be detected	Position of fingers fully closed 	Position when gripping a workpiece 	Position of fingers fully opened 
Operation of auto switch	Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is held (Normal operation): Auto switch to turn OFF (Light not illuminating) When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light
Detection combinations: One auto switch			
Detection combinations: Two auto switches			
How to determine auto switch installation position	Step 1) Fully close the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully open the fingers. 
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.	**In the case of mounting auto switch from B direction** Step 2) Insert the auto switch into the auto switch installation groove from direction B. 		
	Step 3) Slide the auto switch in the direction of the arrow until the light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. Position where light turns ON 	Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates.  Step 4) Slide the auto switch in the direction of the arrow until the indicator light goes out.  Step 5) Move the auto switch in the opposite direction, and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. Position where light turns ON 

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

Auto Switch Mounting

To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.



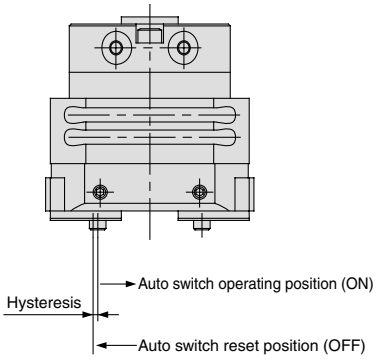
Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. The tightening torque should be about 0.05 to 0.15 N·m.

Auto Switch Hysteresis

Please refer to the table as a guide when setting auto switch positions.

Model	Hysteresis (Max. value) (mm)
MDHR2-10	0.3
MDHR2-15	0.2
MDHR2-20	0.6
MDHR2-30	0.3

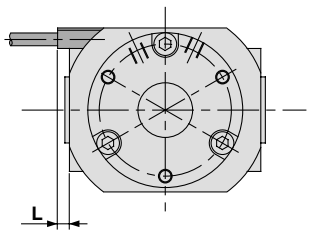
MDHR2



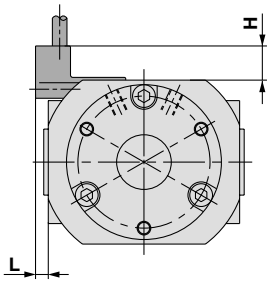
Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully open) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

MDHR2-10, 15



Auto switches of D-M9N, D-M9P and D-M9B are used.

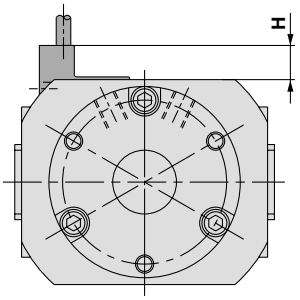


Auto switches of D-M9NV, D-M9PV and D-M9BV are used.

Max. Protrusion of Auto Switch from Edge of Body: L, H (mm)

Air gripper model \ Auto switch model		D-M9□	D-M9□V
MDHR2-10	**L**	2.6	0.6
	H	—	7
MDHR2-15	**L**	—	—
	H	—	7

MDHR2-20, 30



Auto switches of D-M9NV, D-M9PV and D-M9BV are used.

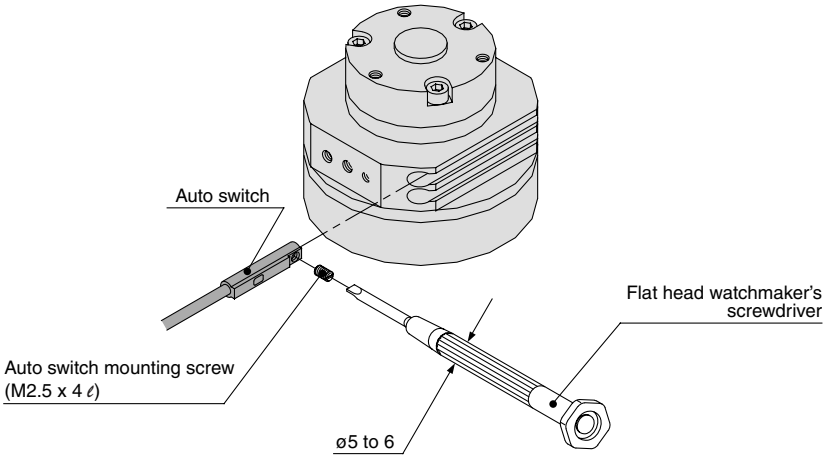
Max. Protrusion of Auto Switch from Edge of Body: H (mm)

Air gripper model \ Auto switch model	D-M9□V
MDHR2-20	7
MDHR2-30	7

The auto switch will not protrude in the case of D-M9□.

Auto Switch Mounting

To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.



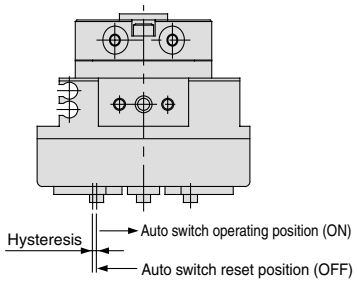
Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. The tightening torque should be about 0.05 to 0.15 N·m.

Auto Switch Hysteresis

Please refer to the table as a guide when setting auto switch positions.

Model	Hysteresis (Max.value) (mm)
MDHR3-10	0.2
MDHR3-15	0.5

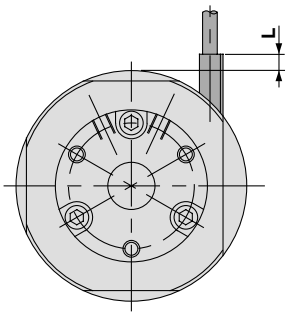
MDHR3



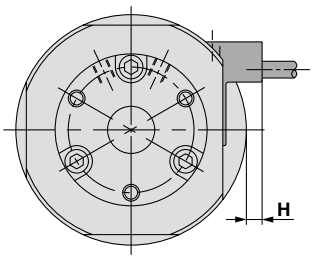
Protrusion of Auto Switch from Edge of Body

The maximum protrusion of an auto switch (when fingers are fully open) from the edge of the body is shown in the table below. Use the table as a guideline for mounting.

MDHR3-10



When auto switch D-M9□ is used

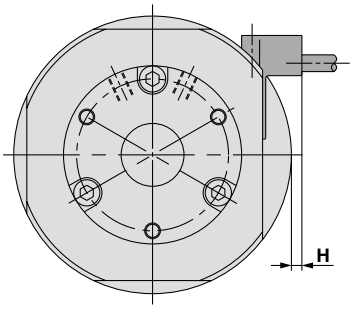


When auto switch D-M9□V is used

Max. Protrusion of Auto Switch from Edge of Body: L, H (mm)

Auto switch model	D-M9□	D-M9□V
L	—	—
H	—	2.5

MDHR3-15



When auto switch D-M9□V is used

Max. Protrusion of Auto Switch from Edge of Body: H (mm)

Auto switch model	D-M9□V
H	1.5

The auto switch will not protrude in the case of D-M9□.

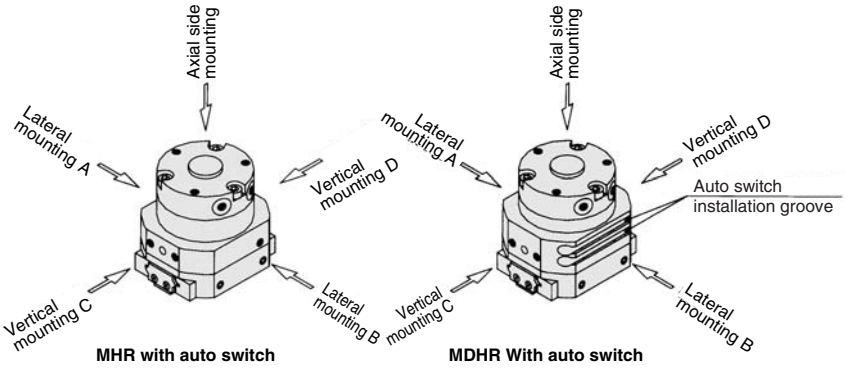
Specific Product Precautions

Be sure to read before handling.

Mounting Air Grippers/MHR2/MHR3

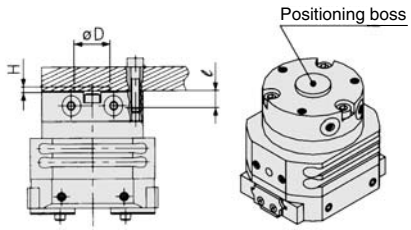
Mounting direction of each model is different. Refer to the table at right.

Model	Axial side mounting	Lateral mounting		Vertical mounting	
		A	B	C	D
MHR2-□	●	●	—	●	●
MHR3-□	●	—	—	—	—
MDHR2-□	●	●	—	●	●
MDHR3-□	●	●	●	—	●



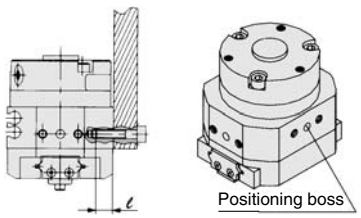
MHR with auto switch　　MDHR With auto switch

Axial side mounting



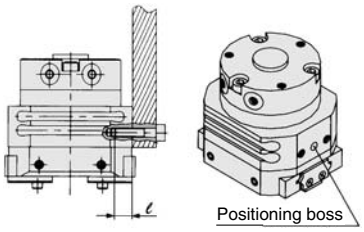
Model			Applicable bolt	Max. tightening torque N·m	Max. screw-in depth ℓmm	Positioning boss Dmm	Positioning boss Hmm
MHR	2	-10	M3 x 0.5	0.88	6	9h9 $^{0}_{-0.036}$	1
		-15				12h9 $^{0}_{-0.043}$	1.5
		-20	M4 x 0.7	2.1	8	14h9 $^{0}_{-0.043}$	
MDHR		-30	M5 x 0.8	4.3	10	16h9 $^{0}_{-0.043}$	2
	3	-10	M3 x 0.5	0.88	6	9h9 $^{0}_{-0.036}$	1
		-15				12h9 $^{0}_{-0.043}$	1.5

Lateral mounting



Model			Applicable bolt	Max. tightening torque N·m	Max. screw-in depth ℓmm	Positioning boss Bore Depth dmm	Positioning boss Bore Depth hmm
MHR	2	-10	M3 x 0.5	0.88	6	3 $^{+0.02}_{0}$	6
		-15					
		-20	M4 x 0.7	2.1	8	4 $^{+0.02}_{0}$	8
MDHR		-30	M5 x 0.8	4.3	10	5 $^{+0.02}_{0}$	10
	3	-10	M3 x 0.5	0.88	6	3 $^{+0.02}_{0}$	6
		-15					

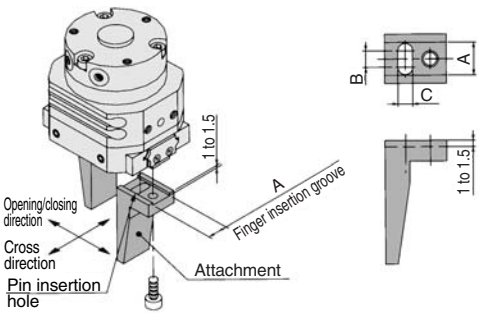
Vertical mounting



Model			Applicable bolt	Max. tightening torque N·m	Max. screw-in depth ℓmm	Positioning boss Bore Depth dmm	Positioning boss Bore Depth hmm
MHR	2	-10	M3 x 0.5	0.88	6	3 $^{+0.02}_{0}$	6
		-15					
		-20	M4 x 0.7	2.1	8	4 $^{+0.02}_{0}$	8
MDHR		-30	M5 x 0.8	4.3	10	5 $^{+0.02}_{0}$	10
	3	-10	M3 x 0.5	0.88	6	3 $^{+0.02}_{0}$	6
		-15					

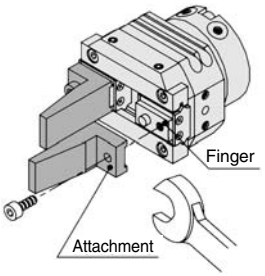
How to Locate Finger and Attachment

- **Positioning in the finger's open/close direction**
  Position the finger and the attachment by inserting the finger's pin into the attachment's pin insertion hole. Provide the following pin insertion hole dimensions: shaft-basis fitting dimension C for the open/close direction; slotted hole with relief B for the cross direction.
- **Positioning in the finger's cross direction**
  Position the finger and the attachment by placing the finger's width into the attachment's finger insertion groove A.



How to Mount the Attachment to the Finger

- To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
- Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.



Model			Applicable bolt	Max. tightening torque N·m
MHR	2	-10	M3 x 0.5	0.59
		-15		
		-20	M4 x 0.7	1.4
MDHR		-30	M5 x 0.8	2.8
	3	-10	M3 x 0.5	0.59
		-15		

Finger opening/closing speed: MHR2/MHR3

When the finger opening/closing speed is set as the total stroke of 0.2 seconds or more, it may cause the product to stick or completely stop its movement.

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